HW-1-Code-Figgins

January 15, 2021

```
[1]: using Plots, DataFrames, LinearAlgebra, LaTeXStrings, Latexify
```

0.1 Exercise 1

```
[2]: function second_deriv(u::Function, x, h)  (u(x + h) + u(x - h) - 2*u(x)) / h^2  end
```

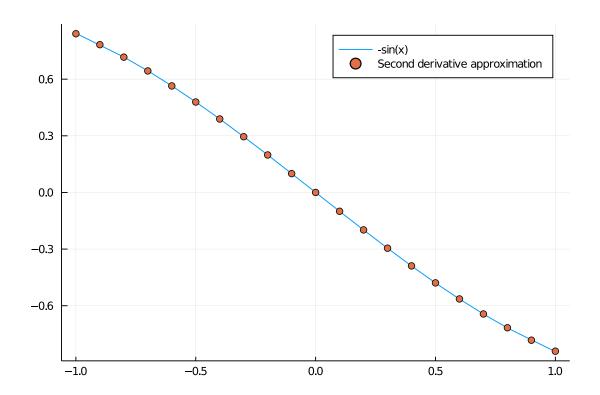
[2]: second_deriv (generic function with 1 method)

```
[3]: xs = -1:0.1:1
h = 0.1

# We can test our approximation using
# that second derivative of sin is - sin
sin_xx = [ second_deriv(sin, x, h) for x in xs]

plot(x -> -1*sin(x), -1, 1, label = "-sin(x)")
scatter!(xs, sin_xx, label = "Second derivative approximation")
```

[3]:



```
[4]: hs = [10.0^(-k) for k in 1:16]
x = /6

FDQ = [second_deriv(sin, x, h) for h in hs]
error = abs.(FDQ .+ sin(x)) # True value is -sin(x)
```

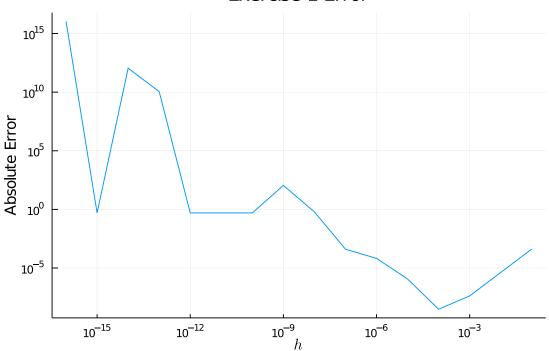
[4]: 16-element Array{Float64,1}:

- 0.00041652780258211175
- 4.166652633530443e-6
- 4.167449668690537e-8
- 3.0387354299499236e-9
- 1.1515932100691906e-6
- 6.657201129195434e-5
- 0.0003996389186794458
- 0.6102230246251563
- 111.52230246251564
 - 0.499999999999994
 - 0.499999999999994
 - 0.499999999999994
 - 1.1102230246751564e10
 - 1.1102230246246565e12
 - 0.499999999999994
 - 1.1102230246251566e16

```
[5]: df1 = DataFrame(h = hs, FDQ = FDQ, Error = error)
latexify(df1)
```

```
[5]:
             h
                                   FDQ
                                                             Error
           0.1
                   -0.49958347219741783
                                           0.00041652780258211175
          0.01
                    -0.4999958333473664
                                           4.166652633530443e - 6
         0.001
                                           4.167449668690537e - 8
                   -0.49999995832550326
        0.0001
                    -0.4999999969612645
                                          3.0387354299499236e - 9
       1.0e - 5
                      -0.50000115159321
                                          1.1515932100691906e - 6
       1.0e - 6
                     -0.499933427988708
                                           6.657201129195434e - 5
       1.0e - 7
                    -0.4996003610813205
                                            0.0003996389186794458
      1.0e - 8
                    -1.1102230246251563
                                               0.6102230246251563
      1.0e - 9
                     111.02230246251564
                                               111.52230246251564
      1.0e - 10
                                     0.0
                                              0.4999999999999999
      1.0e-11
                                     0.0
                                              0.4999999999999999
     1.0e - 12
                                     0.0
                                              0.4999999999999999
      1.0e - 13
                  1.1102230246251564e10
                                            1.1102230246751564e10
     1.0e - 14
                -1.1102230246251565e12
                                            1.1102230246246565e12
      1.0e - 15
                                     0.0
                                              0.4999999999999994
      1.0e - 16
                -1.1102230246251566e16
                                            1.1102230246251566e16
```

[6]: Exercise 1 Error



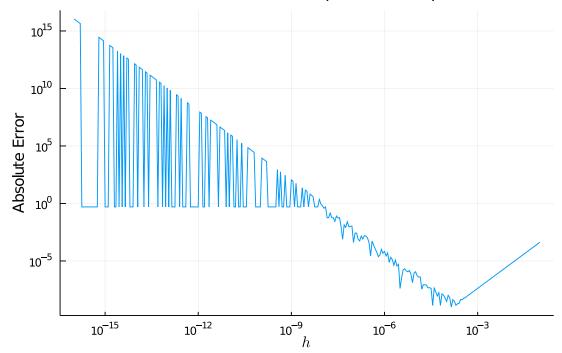
```
[7]: hs = [10.0^(-k) for k in 1:0.05:16]
x = /6

FDQ = [second_deriv(sin, x, h) for h in hs]
error = abs.(FDQ .+ sin(x)) # True value is -sin(x)

plot(hs, error, scale = :log10,
    label = false,
    xlabel = L"h",
    ylabel = "Absolute Error",
    title = "Exercise 1 Error (More Points)")
```

[7]:

Exercise 1 Error (More Points)



There are significant issues once we go smaller than $h \approx 10e - 7$

0.2 Exercise 2

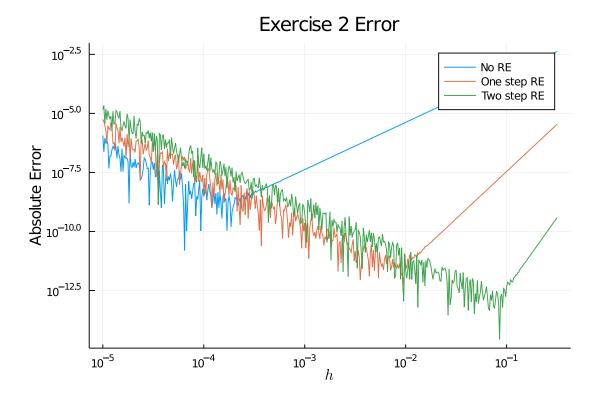
[8]: RE (generic function with 3 methods)

```
[9]: hs = [0.05, 0.1, 0.2]
      x = /6
      # No Richardson extrapolation
      raw_FDQ = [second_deriv(sin, x, h) for h in hs]
      raw_error = raw_FDQ .+ sin(x) # True value is -sin(x)
 [9]: 3-element Array{Float64,1}:
       0.00010415798651314256
       0.00041652780258211175
       0.0016644460310434872
[10]: # One step of Richardson extrapolation
      RE_1_FDQ = [RE(sin, x, h, second_deriv) for h in hs]
      RE_1_error = RE_1_FDQ .+ sin(x) # True value is -sin(x)
[10]: 3-element Array{Float64,1}:
       2.170097102016655e-9
       3.471449017133921e-8
       5.550597616532649e-7
[11]: ## RE on the RE
      RE_1(u, x, h) = RE(u, x, h, second_deriv)
      # Two steps of Richardson extrapolation
      RE_2_FDQ = [RE(sin, x, h, RE_1, 4,2) for h in hs]
      RE_2=rror = RE_2=FDQ + sin(x) # True value is -sin(x)
[11]: 3-element Array{Float64,1}:
       -5.636047184509607e-13
        4.709010958947601e-13
        2.4805379972292485e-11
[12]: df2 = DataFrame(h = hs,
                       NoRE = raw_FDQ,
                       Richardson1 = RE_1_FDQ,
                      Richardson2 = RE_2_FDQ)
      df2[1,[3,4]] = NaN
      latexify(df2)
[12]:
                           NoRE
                                          Richardson1
                                                                 Richardson2
         h
             -0.4998958420134868
                                                 \overline{NaN}
                                                                       \overline{NaN}
      0.05
       0.1
            -0.49958347219741783 \mid -0.4999999652855098
                                                       -0.4999999999952904
       0.2 \mid -0.49833555396895646 \mid -0.4999994449402383 \mid -0.4999999997519456
[13]: df2Errors = DataFrame(h = hs,
                       NoRE_Error = raw_error,
```

```
Richardson1_Error = RE_1_error,
Richardson2_Error = RE_2_error)
df2Errors[1,[3,4]] .= NaN
latexify(df2Errors)
```

```
[14]: hs = [10.0^{(-k)} \text{ for } k \text{ in } 0.5:0.01:5]
      # No Richardson extrapolation
      raw_FDQ = [second_deriv(sin, x, h) for h in hs]
      raw_error = abs.(raw_FDQ .+ sin(x)) # True value is -sin(x)
      # One step of Richardson extrapolation
      RE_1_FDQ = [RE(sin, x, h, second_deriv) for h in hs]
      RE_1_{error} = abs.(RE_1_{FDQ} .+ sin(x)) # True value is <math>-sin(x)
      # Two steps of Richardson extrapolation
      RE_2FDQ = [RE(sin, x, h, RE_1, 4, 2) for h in hs]
      RE_2_error = abs.(RE_2_FDQ .+ sin(x)) # True value is -sin(x)
      plot(hs, raw_error, scale = :log10,
          label = "No RE",
          xlabel = L"h",
          ylabel = "Absolute Error",
          title = "Exercise 2 Error")
      plot!(hs, RE_1_error, scale = :log10,
          label = "One step RE")
      plot!(hs, RE_2_error, scale = :log10,
          label = "Two step RE")
```

[14]:



0.3 Exercise 6

```
[15]: M = 25 \# Number of grid points

h = 1/M \# Step size
```

[15]: 0.04

```
[16]: ## Guess $f$ given a $u$

function make_matrix(M)
    # Step size
    h = 1/M

# Xjs of interest
    xjs = [j*h for j in 1:M]

# Defining diagonal
    diagA = [ -(1 + (xj + h/2)^2) - (1 + (xj - h/2)^2) for xj in xjs]
    diagB = [ (1 + (xj + h/2)^2) for xj in xjs[1:M-1]]

##Building Matrix
    A = Array(Tridiagonal(diagB, diagA, diagB))
    A[end, [M, M-1, M-2]] .= 3*h/2, -2*h, h/2
```

```
A = A \cdot / h^2
          return A
      end
      # Generate MxM approximation
      A = make_matrix(M)
[16]: 25×25 Array{Float64,2}:
       -1252.5
                   627.25
                                0.0
                                          0.0
                                                        0.0
                                                                  0.0
                                                                            0.0
         627.25 -1258.5
                                                        0.0
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                              631.25
                                          0.0
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                   631.25 -1268.5
           0.0
                                        637.25
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           0.0
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                              637.25 -1282.5
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                                                                        1225.25
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           0.0
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                                          0.0
                                                       12.5
                                                                -50.0
                                                                           37.5
[17]: # Define test function
      u(x) = (1 - x)^2
[17]: u (generic function with 1 method)
[18]: # Define true solution for test function
      true f(x) = 2*(3*x^2 - 2*x + 1)
[18]: true_f (generic function with 1 method)
[19]: function guess_f(u, M)
```

h = 1 / M

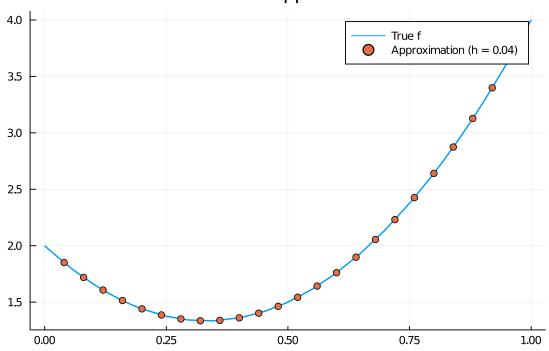
```
# Discretize u
          xjs = [j*h for j in 1:M]
          U = u.(xjs)
          # Approximate the F vector
          F_approx = make_matrix(M)*U
          # End points will be funky due to boundary conditions
          ## First end point has extra term
          F_approx[1] += (1+ (h/2)^2)/h^2
          ## Last is a derivative and isn't needed
          return F_approx[1:(M-1)]
      end
      f_approx = guess_f(u, M)
[19]: 24-element Array{Float64,1}:
       1.85040000000036
       1.719199999999546
       1.607199999999807
       1.514400000001938
       1.44079999999974
       1.3864000000000942
       1.3511999999999489
       1.335200000000043
       1.338399999999787
       1.360800000001539
       1.4024
       1.463200000000029
       1.5432000000000414
       1.642400000000066
       1.760799999999938
       1.8984000000000094
       2.0552000000000845
       2.2311999999999443
       2.42639999999987
       2.640800000000059
       2.874399999999517
       3.1271999999999984
       3.39920000000002
       3.69039999999985
[20]: plot(true_f, 0, 1,
          label = "True f",
```

```
linewidth = 1.5)

scatter!([j*h for j in 1:(M-1)],
   f_approx,
   label = "Approximation (h = $h)",
   title = "Exercise 6 approximation")
```

[20]:

Exercise 6 approximation



```
function get_infinity_error(M)
    # Discretize True Solution
    xjs = [j/M for j in 1:(M-1)]
    true_f_val = true_f.(xjs)
    f_approx = guess_f(u, M)

return maximum( abs.(true_f_val .- f_approx) )
end
```

[21]: get_infinity_error (generic function with 1 method)

[22]: get_infinity_error(1000)

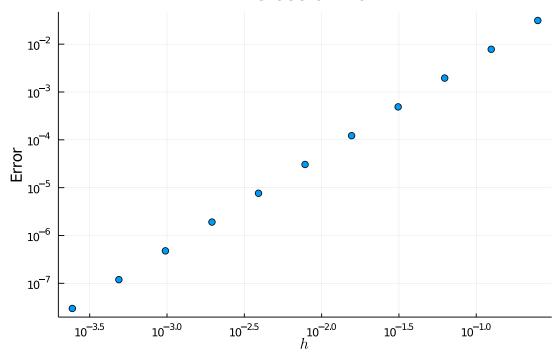
[22]: 5.007842034387977e-7

```
[23]: M_vec = [2^k for k in 2:12]
error_vec = []
for M in M_vec
    push!(error_vec, get_infinity_error(M))
end
```

Here's a simple attempt to plot the infinity norm error on our approximations. This is difficult to do for very small values of h since the size of the linear system grows as h increases.

[24]:

Exercise 6 Error



```
[25]: error_vec
```

- [25]: 11-element Array{Any,1}:
 - 0.03125
 - 0.0078125
 - 0.001953125
 - 0.00048828125

- 0.0001220703125
- 3.0517578125e-5
- 7.62939453125e-6
- 1.9073486328125e-6
- 4.76837158203125e-7
- 1.1920928955078125e-7
- 2.9802322387695312e-8

[26]: 1 ./ M_vec

[26]: 11-element Array{Float64,1}:

- 0.25
- 0.125
- 0.0625
- 0.03125
- 0.015625
- 0.0078125
- 0.00390625
- 0.001953125
- 0.0009765625
- 0.00048828125
- 0.000244140625