	Go to next item
. Using Newton's method, find an approximation recursive formula for $\sqrt{2}$. To help you, remember that $\sqrt{2}$ is the positive solution for x^2-2 , so you can use $f(x)=x^2-2$.	1 / 1 poi
$\bigcirc \ x_{k+1} = x_k - rac{2x_k}{x_k^2 - 2}$	
$egin{array}{c} O \ x_{k+1} = rac{x_k^2-2}{2x_k} \ O \ \end{array}$	
$igotimes x_{k+1} = rac{2x_k}{x_k^2-2}$ $igotimes x_{k+1} = x_k - rac{x_k^2-2}{2x_k}$	
✓ Correct	
Correct! By applying the formula $x_{k+1}=x_k-rac{f(x_k)}{f'(x_k)}$ with $f(x)=x^2\!-\!2$ and $f'(x)=2x$, you got the right result!	
Regarding the previous question, suppose you don't know any approximation for $\sqrt{2}$ and only that it is a positive real number such that $x^2=2$	2. 1/1 poi
Which value from the list below will result in the fastest convergence? 4	
○ ⁴○ ³	
 2 The initial value does not impact in the Newton's method convergence. 	
$igodown$ Correct $igodown$ Correct! We know that $\sqrt{2}$ is a number between 1 and 2, so 2 is the closest value in this list of options, therefore is the value that will	
converge faster!	
Let's continue investigating the method we are developing to compute the $\sqrt{2}$. Remember that we used the fact that $\sqrt{2}$ is one of the roots of	0/1
x^2-2 . What would happen if we have chosen a negative value as initial point?	0 / 1 poi
$lacksquare$ The algorithm would converge to $\sqrt{2}$.	
\bigcirc The algorithm would converge to the negative root of x^2-2 . \bigcirc The algorithm would converge to 0 .	
$oxed{\otimes}$ Incorrect In this case, the algorithm would converge to the negative root of x^2-2 , which is closer than the positive root.	
Did you know that it is possible to calculate the <i>reciprocal</i> of any number <i>without performing division?</i> (The reciprocal of a non-zero real number is $\frac{1}{a}$).	r a 0 / 1 poi
Setting a non-zero real number a , use the function $f(x)=a-rac{1}{x}=a$ $-x^{-1}$ to find such formula.	
This method was in fact used in older IBM computers to implement division in hardware! So, the iteration formula to find the reciprocal of a , in this case, is:	
$igcirc$ $x_{k+1}=2x_k ext{-}ax_k^2$	
$igcircle x_{k+1} = 2x_k + ax_k^2 \ igcolon x_{k+1} = 2x_k – x_k^2$	
$igotimes x_{k+1} = x_k – a x_k^2$	
Incorrect! Remember that we must apply the formula $x_{k+1}=x_k-rac{f(x_k)}{f'(x_k)}$ and that in this case $f(x)=a-rac{1}{x}$ and $f'(x)=rac{1}{x^2}!!$ Also, I meticulous with the manipulations you must perform to get the final formula!	be
Suppose we want to find the minimum value (suppose we already know that the minimum exists and is unique) of $x\log(x)$ where $x\in(0,+\infty)$ Using Newton's method, what recursion formula we must use?	o). 1/1 poi
Hint: $f(x) = x \log(x)$, $f'(x) = \log(x) + 1$ and $f''(x) = rac{1}{x}$	
$egin{aligned} igotimes x_{k+1} &= x_k - rac{x_k \log(x_k)}{\log(x_k) + 1} \ igotimes x_{k+1} &= x_k - x_k^2 \log(x_k) \end{aligned}$	
$\bigcirc \ x_{k+1} = x_k - \log(x_k)$	
$igotimes x_{k+1} = x_k - x_k \left(\log(x_k) + 1 ight)$ $igotimes$ Correct	
Correct! By applying the formula $x_{k+1} = x_k - rac{f'(x_k)}{f"(x_k)}$ you got the result!	
Regarding the <i>Second Derivative Test</i> to decide whether a point with $f'(x)=0$ is a local minimum or local maximum, check all that apply.	1 / 1 poi
\qed If $f``(x) < 0$ then x is a local minimum.	
If $f``(x)>0$ then x is a local minimum. $ extstyle $	
Correct! If $f'(x)=0$ and $f''(x)<0$ then x is a local maximum!	
lacksquare If $f''(x)=0$ then x is an inflection point. If $f''(x)=0$ then the test is inconclusive.	
\bigcirc Correct Correct! If $f'(x)=f''(x)=0$, then the test is inconclusive!	
Let $f(x,y)=x^2+y^3$, then the Hessian matrix, $H(x,y)$ is:	1 / 1 poi
$O(1) = \left[egin{array}{cc} 2x & 3y^2 \ 3y^2 & 2x \end{array} ight]$	
$leftilde{igotimes}_{H(x,y)} = \left[egin{array}{cc} 2 & 0 \ 0 & 6y \end{array} ight]$	
$H(x,y)=\left[egin{array}{cc} 0 & 2 \ 6y & 0 \end{array} ight]$	
\cap	
O $H(x,y)=\left[egin{array}{cc} 0 & 0 \ 0 & 0 \end{array} ight]$	
\bigcirc Correct $\left[egin{array}{ccccc} rac{\partial^2 f}{\partial x^2} & rac{\partial^2 f}{\partial x^2} \end{array} ight]$	
Correct! Using the formula $H(x,y)=\left[egin{array}{cc} rac{\partial^2 f}{\partial x^2} & rac{\partial^2 f}{\partial x\partial y} \ rac{\partial^2 f}{\partial y\partial x} & rac{\partial^2 f}{\partial y^2} \end{array} ight]$ it is straightforward to obtain the result!	
How many narameters has a Neural Network with.	- 1
How many parameters has a Neural Network with: • Input layer of size 3	1 / 1 poi
	1/1 poi
 Input layer of size 3 One hidden layer with 3 neurons 	1 / 1 poi
 Input layer of size 3 One hidden layer with 3 neurons One hidden layer with 2 neurons Output layer with size 1 An image is provided below:	1 / 1 poi
 Input layer of size 3 One hidden layer with 3 neurons One hidden layer with 2 neurons Output layer with size 1 	1/1 poi
• Input layer of size 3 • One hidden layer with 3 neurons • One hidden layer with 2 neurons • Output layer with size 1 An image is provided below: $x_1 \qquad \qquad x_1 \qquad \qquad x_1 \qquad \qquad x_2 \qquad \qquad x_1 \qquad \qquad x_2 \qquad \qquad x_3 \qquad \qquad x_4 \qquad \qquad x_4 \qquad \qquad x_5 \qquad \qquad x_6 \qquad \qquad $	1 / 1 poi
 Input layer of size 3 One hidden layer with 3 neurons One hidden layer with 2 neurons Output layer with size 1 An image is provided below:	1/1 poi
• Input layer of size 3 • One hidden layer with 3 neurons • One hidden layer with 2 neurons • Output layer with size 1 An image is provided below: $x_1 \qquad \qquad x_1 \qquad \qquad x_2 \qquad \qquad x_1 \qquad \qquad x_2 \qquad \qquad x_2 \qquad \qquad x_3 \qquad \qquad x_4 \qquad \qquad x_4 \qquad \qquad x_5 \qquad \qquad x_5 \qquad \qquad x_6 \qquad \qquad $	1/1 poi
• Input layer of size 3 • One hidden layer with 3 neurons • One hidden layer with 2 neurons • Output layer with size 1 An image is provided below: $x_1 \qquad \qquad x_2 \qquad \qquad x_3 \qquad \sigma(z_1^3)$	1/1 poi
• Input layer of size 3 • One hidden layer with 3 neurons • One hidden layer with 2 neurons • Output layer with size 1 An image is provided below: $x_1 \qquad \qquad x_1 \qquad \qquad x_2 \qquad \qquad x_3 \qquad \qquad x_4 \qquad \qquad x_4 \qquad \qquad x_4 \qquad \qquad x_5 \qquad \qquad x_5 \qquad \qquad x_6 \qquad \qquad $	1/1 poi
• Input layer of size 3 • One hidden layer with 3 neurons • One hidden layer with 2 neurons • Output layer with size 1 An image is provided below: $x_1 \qquad \qquad x_2 \qquad \qquad x_3 \qquad \qquad x_4 \qquad \qquad x_4 \qquad \qquad x_4 \qquad \qquad x_5 \qquad \qquad x_5 \qquad \qquad x_5 \qquad \qquad x_5 \qquad \qquad x_6 \qquad \qquad$	1 / 1 poi
• Input layer of size 3 • One hidden layer with 3 neurons • One hidden layer with 2 neurons • Output layer with size 1 An image is provided below: $x_1 \qquad \qquad x_2 \qquad \qquad x_3 \qquad \qquad x_4 \qquad \qquad x_4 \qquad \qquad x_4 \qquad \qquad x_5 \qquad \qquad x_5 \qquad \qquad x_5 \qquad \qquad x_5 \qquad \qquad x_6 \qquad \qquad$	1/1 poi
• Input layer of size 3 • One hidden layer with 3 neurons • One hidden layer with 2 neurons • Output layer with size 1 An image is provided below: $x_1 \qquad \qquad x_2 \qquad \qquad x_3 \qquad \qquad x_4 \qquad \qquad x_4 \qquad \qquad x_4 \qquad \qquad x_5 \qquad \qquad x_5 \qquad \qquad x_5 \qquad \qquad x_5 \qquad \qquad x_6 \qquad \qquad$	1/1 poi
• Input layer of size 3 • One hidden layer with 3 neurons • One hidden layer with 2 neurons • Output layer with size 1 An image is provided below: $x_1 \qquad \qquad x_2 \qquad \qquad x_3 \qquad \qquad x_4 \qquad \qquad x_4 \qquad \qquad x_4 \qquad \qquad x_5 \qquad \qquad x_5 \qquad \qquad x_5 \qquad \qquad x_6 \qquad \qquad$	1/1 poi
• Input layer of size 3 • One hidden layer with 3 neurons • One hidden layer with 2 neurons • Output layer with size 1 An image is provided below: x_1 x_2 x_3 x_3 x_3 x_3 x_4 x_4 x_5 x_4 x_5 x_5 x_5 x_5 x_5 x_5 x_5 x_6 x_7 x_8 x_8 x_9 x_9	
• Input layer of size 3 • One hidden layer with 3 neurons • One hidden layer with 2 neurons • Output layer with size 1 An image is provided below: $ x_1 \qquad x_2 \qquad x_3 \qquad x_4 \qquad x_5 \qquad x_5$	1/1 poi
• Input layer of size 3 • One hidden layer with 3 neurons • Output layer with 2 neurons • Output layer with size 1 An image is provided below: $x_1 \qquad \qquad x_2 \qquad \qquad x_3 \qquad \qquad x_4 \qquad \qquad x_4 \qquad \qquad x_5 \qquad \qquad x_5$	
• Input layer of size 3 • One hidden layer with 3 neurons • Output layer with size 1 An image is provided below: $x_1 = x_2 + x_3 = x_4 + x_4 = x_4 + x_5 = x_4 $	
• Input layer of size 3 • One hidden layer with 3 neurons • Output layer with 2 neurons • Output layer with size 1 An image is provided below: $ x_1 $	
• Input layer of size 3 • One hidden layer with 3 neurons • Output layer with 2 neurons • Output layer with size 1 An image is provided below: $x_1 $	
• Input layer of size 3 • One hidden layer with 3 neurons • One hidden layer with 3 neurons • Output layer with 2 neurons • Output layer with 3 neurons • Output layer of size 3 • Or 3 • Or or rect. • Or or rect. There are $3 \cdot 3 + 3 = 12$ parameters in the first hidden layer, $3 \cdot 2 + 2 = 8$ parameters in the second hidden layer and $2 + 1 = 3$ parameters in the output layer! Given the following Single Layer Perceptron with Sigmoid function as activation function, and log-loss as Loss Function (L), the value for $\frac{\partial L}{\partial \omega_0}$ is $\frac{\partial L}{\partial \omega_0}$ is $\frac{\partial L}{\partial \omega_0}$.	
• Input layer of size 3 • One hidden layer with 3 neurons • One hidden layer with 3 neurons • One hidden layer with size 1 An image is provided below: $ x_1 $	
• Input layer of size 3 • One hidden layer with 3 neurons • One hidden layer with 3 neurons • One hidden layer with size 1 An image is provided below: $x_1 $	
• Input layer of size 3 • One hidden layer with 3 neurons • One hidden layer with 3 neurons • One hidden layer with 3 neurons • Output layer with size 1 An image is provided below: $ x_1 $	
• Input layer of size 3 • One hidden layer with 3 neurons • One hidden layer with 3 neurons • One hidden layer with 2 neurons • Output layer with size 1 An image is provided below: $x_1 $	

10. Suppose you have a function f(x,y) with $abla f(x_0,y_0)=(0,0)$ and such that

Correct! The matrix in that point has two positive eigenvalues, therefore it is a local minimum!

We can't infer anything with the given information.

Then the point $\left(x_{0},y_{0}
ight)$ is a:

Local maximum.

Local minimum.

Saddle point.

⊘ Correct

 $H(x_0,y_0)=\left[egin{array}{cc} 2 & 0 \ 0 & 10 \end{array}
ight]$

1/1 point