



# **General Description**

The MAX1304-MAX1306/MAX1308-MAX1310/MAX1312-MAX1314 12-bit, analog-to-digital converters (ADCs) offer eight, four, or two independent input channels. Independent track-and-hold (T/H) circuitry provides simultaneous sampling for each channel. The MAX1304/ MAX1305/MAX1306 provide a 0 to +5V input range with ±6V fault-tolerant inputs. The MAX1308/MAX1309/ MAX1310 provide a ±5V input range with ±16.5V fault-tolerant inputs. The MAX1312/MAX1313/MAX1314 have a ±10V input range with ±16.5V fault-tolerant inputs. These ADCs convert two channels in 0.9µs, and up to eight channels in 1.98µs, with an 8-channel throughput of 456ksps per channel. Other features include a 20MHz T/H input bandwidth, internal clock, internal (+2.5V) or external (+2.0V to +3.0V) reference, and power-saving modes.

A 20MHz, 12-bit, bidirectional parallel data bus provides the conversion results and accepts digital inputs that activate each channel individually.

All devices operate from a +4.75V to +5.25V analog supply and a +2.7V to +5.25V digital supply and consume 57mA total supply current when fully operational.

Each device is available in a 48-pin 7mm x 7mm TQFP package and operates over the extended -40°C to +85°C temperature range.

# **Applications**

SIN/COS Position Encoder Multiphase Motor Control Multiphase Power Monitoring Power-Grid Synchronization Power-Factor Monitoring Vibration and Waveform Analysis

### **Selector Guide**

PART	INPUT RANGE (V)	CHANNEL COUNT
MAX1304ECM	0 to +5	8
MAX1305ECM	0 to +5	4
MAX1306ECM	0 to +5	2
MAX1308ECM	±5	8
MAX1309ECM	±5	4
MAX1310ECM	±5	2
MAX1312ECM	±10	8
MAX1313ECM	±10	4
MAX1314ECM	±10	2

Pin Configurations appear at end of data sheet.

### **Features**

- ♦ Up to Eight Channels of Simultaneous Sampling **8ns Aperture Delay** 100ps Channel-to-Channel T/H Match
- ♦ Extended Input Ranges 0 to +5V (MAX1304/MAX1305/MAX1306) -5V to +5V (MAX1308/MAX1309/MAX1310) -10V to +10V (MAX1312/MAX1313/MAX1314)
- **♦** Fast Conversion Time One Channel in 0.72µs Two Channels in 0.9µs Four Channels in 1.26µs Eight Channels in 1.98µs
- **♦** High Throughput 1075ksps/Channel for One Channel 901ksps/Channel for Two Channels 680ksps/Channel for Four Channels 456ksps/Channel for Eight Channels
- ♦ ±1 LSB INL, ±0.9 LSB DNL (max)
- ♦ 84dBc SFDR, -86dBc THD, 71dB SINAD,  $f_{IN} = 500kHz$  at 0.4dBFS
- ◆ 12-Bit, 20MHz, Parallel Interface
- ♦ Internal or External Clock
- ♦ +2.5V Internal Reference or +2.0V to +3.0V **External Reference**
- ◆ +5V Analog Supply, +3V to +5V Digital Supply 55mA Analog Supply Current 1.3mA Digital Supply Current **Shutdown and Power-Saving Modes**
- ♦ 48-Pin TQFP Package (7mm x 7mm Footprint)

# **Ordering Information**

PART	TEMP RANGE	PIN-PACKAGE
MAX1304ECM+	-40°C to +85°C	48 TQFP
MAX1304ECM/V+	-40°C to +85°C	48 TQFP
MAX1305ECM+	-40°C to +85°C	48 TQFP
MAX1306ECM+	-40°C to +85°C	48 TQFP
MAX1308ECM+	-40°C to +85°C	48 TQFP
MAX1308ECM/V+	-40°C to +85°C	48 TQFP
MAX1309ECM+	-40°C to +85°C	48 TQFP
MAX1309ECM/V+	-40°C to +85°C	48 TQFP
MAX1310ECM+	-40°C to +85°C	48 TQFP
MAX1312ECM+	-40°C to +85°C	48 TQFP
MAX1313ECM+	-40°C to +85°C	48 TQFP
MAX1314ECM+	-40°C to +85°C	48 TQFP
D + 1 1/DI- \ f		

+Denotes a lead(Pb)-free/RoHS-compliant package.

/V denotes an automotive qualified part.

Maxim Integrated Products 1

### **ABSOLUTE MAXIMUM RATINGS**

AV <sub>DD</sub> to AGND	0.3V to +6V
DV <sub>DD</sub> to DGND	0.3V to +6V
AGND to DGND	0.3V to +0.3V
CH0-CH7, I.C. to AGND (MAX	1304/MAX1305/MAX1306)±6V
CH0-CH7, I.C. to AGND (MAX1	308/MAX1309/MAX1310)±16.5V
CH0-CH7, I.C. to AGND (MAX1	312/MAX1313/MAX1314)±16.5V
	0.3V to (DV <sub>DD</sub> + 0.3V)
	GND0.3V to (DV <sub>DD</sub> + 0.3V)
CONVST, CLK, SHDN, CHSHDN	$ar{\text{I}}$ to DGND0.3V to (DV <sub>DD</sub> + 0.3V)
INTCLK/EXTCLK to AGND	0.3V to (AV <sub>DD</sub> + 0.3V)

	F <sub>MS</sub> , REF, MSV to AGND0.3' F+, COM, REF- to AGND0.3'	, 55
Ma	eximum Current into Any Pin Except ${ m AV}_{ m DD}$ ,	DV <sub>DD</sub> , AGND,
	DGND	±50mA
Cc	intinuous Power Dissipation ( $T_A = +70^{\circ}C$ )	
	TQFP (derate 22.7mW/°C above +70°C)	1818.2mW
Op	perating Temperature Range	40°C to +85°C
Ju	nction Temperature	+150°C
Sto	orage Temperature Range	65°C to +150°C
Le	ad Temperature (soldering, 10s)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

# **ELECTRICAL CHARACTERISTICS**

 $(AV_{DD} = +5V, DV_{DD} = +3V, AGND = DGND = 0, V_{REF} = V_{REFMS} = +2.5V$  (external reference),  $C_{REF} = C_{REFMS} = 0.1\mu F$ ,  $C_{REF+} = C_{REF-} = 0.1\mu F$ ,  $C_{REF-} = 2.2\mu F$  ||  $0.1\mu F$ ,  $C_{COM} = 2.2\mu F$  ||  $0.1\mu F$ ,  $C_{MSV} = 2.2\mu F$  ||  $0.1\mu F$  (unipolar devices), MSV = AGND (bipolar devices),  $f_{CLK} = 16.67 MHz$  50% duty cycle, INTCLK/EXTCLK = AGND (external clock), SHDN = DGND,  $T_{A} = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_{A} = +25^{\circ}C$ . See Figures 3 and 4.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS		
STATIC PERFORMANCE (Note 1)								
Resolution	N		12			Bits		
Integral Nonlinearity	INL	(Note 2)		±0.5	±1.0	LSB		
Differential Nonlinearity	DNL	No missing codes (Note 2)		±0.3	±0.9	LSB		
Offset Error		Unipolar, 0x000 to 0x001		±3	±16	LSB		
Oliset Elloi		Bipolar, 0xFFF to 0x000		±3	±16	LSB		
Offset-Error Matching		Unipolar, between all channels		±9	±20	LSB		
Onset-Error Matering		Bipolar, between all channels		±9	±20	LSB		
Officet Error Tomporature Drift		Unipolar, 0x000 to 0x001		7		nnm/0C		
Offset-Error Temperature Drift		Bipolar, 0xFFF to 0x000		7		ppm/°C		
Gain Error				±2	±16	LSB		
Gain-Error Matching		Between all channels		±3	±14	LSB		
Gain-Error Temperature Drift				4		ppm/°C		
DYNAMIC PERFORMANCE at fin	= 500kHz, <i>A</i>	AIN = -0.4dBFS (Note 2)						
Signal-to-Noise Ratio	SNR		68	71		dB		
Signal-to-Noise Plus Distortion	SINAD		68	71		dB		
Total Harmonic Distortion	THD			-86	-80	dBc		
Spurious-Free Dynamic Range	SFDR			84		dBc		
Channel-to-Channel Isolation			80	86		dB		
ANALOG INPUTS (CH0 through CH7)								
		MAX1304/MAX1305/MAX1306	0		+5			
Input Voltage	VCH	MAX1308/MAX1309/MAX1310	-5		+5	V		
		MAX1312/MAX1313/MAX1314	-10		+10			

# **ELECTRICAL CHARACTERISTICS (continued)**

 $(AV_{DD} = +5V,\ DV_{DD} = +3V,\ AGND = DGND = 0,\ V_{REF} = V_{REFMS} = +2.5V\ (external\ reference),\ C_{REF} = C_{REFMS} = 0.1\mu\text{F},\ C_{REF+} = C_{REF-} = 0.1\mu\text{F},\ C_{REF-} = 2.2\mu\text{F}\ II\ 0.1\mu\text{F},\ C_{COM} = 2.2\mu\text{F}\ II\ 0.1\mu\text{F},\ C_{MSV} = 2.2\mu\text{F}\ II\ 0.1\mu\text{F}\ (unipolar\ devices)},\ MSV = AGND\ (bipolar\ devices),\ f_{CLK} = 16.67\text{MHz}\ 50\%\ duty\ cycle,\ INTCLK/EXTCLK = AGND\ (external\ clock),\ SHDN = DGND,\ T_A = T_{MIN}\ to\ T_{MAX},\ unless\ otherwise\ noted.\ Typical\ values\ are\ at\ T_A = +25^{\circ}C.\ See\ Figures\ 3\ and\ 4.)$ 

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
		MAX1304/MAX1305/MAX1306			7.58		
Input Resistance (Note 3)	RcH	MAX1308/MAX1309MAX1310		8.66			kΩ
(Note 3)		MAX1312/MAX1313/MAX1314			14.26		
		MANA VA 2004 /MANA VA 2005 /MANA VA 2000	V <sub>CH</sub> = +5V		0.54	0.72	
		MAX1304/MAX1305/MAX1306	V <sub>CH</sub> = 0V	-0.157	-0.12		]
Input Current	lou	MAX1308/MAX1309/MAX1310	$V_{CH} = +5V$		0.29	0.39	A
(Note 3)	ICH	IVIAA 1300/IVIAA 1309/IVIAA 1310	$V_{CH} = -5V$	-1.16	-0.87		mA
		MAX1312/MAX1313/MAX1314	$V_{CH} = +10V$		0.56	0.74	]
		WAX 13 12/WAX 13 13/WAX 13 14	V <sub>CH</sub> = -10V	-1.13	-0.85		
Input Capacitance	Ссн				15		рF
TRACK/HOLD							
		One channel selected for conve	ersion		1075		<u> </u>
External-Clock Throughput Rate	fTH	Two channels selected for conv	version		901		ksps
(Note 4)	'IH	Four channels selected for conversion			680		Napa
		Eight channels selected for conversion		456			
	fтн	One channel selected for conversion		983			
Internal-Clock Throughput Rate		Two channels selected for con-		821		ksps	
(Note 4, Table 1)		Four channels selected for conversion		618		Kapa	
		Eight channels selected for conversion		413			
Small-Signal Bandwidth					20		MHz
Full-Power Bandwidth					20		MHz
Aperture Delay	t <sub>AD</sub>				8		ns
Aperture-Delay Matching					100		ps
Aperture Jitter	taj				50		psRMS
INTERNAL REFERENCE							
REF Output Voltage	$V_{REF}$			2.475	2.500	2.525	V
Reference Output-Voltage Temperature Drift					30		ppm/°C
REF <sub>MS</sub> Output Voltage	VREFMS			2.475	2.500	2.525	V
REF+ Output Voltage	V <sub>REF+</sub>				3.850		V
COM Output Voltage	V <sub>COM</sub>				2.600		V
REF- Output Voltage	V <sub>REF</sub> -				1.350		V
Differential Reference Voltage	V <sub>REF+</sub> -				2.500		V

# **ELECTRICAL CHARACTERISTICS (continued)**

 $(AV_{DD}=+5V,\ DV_{DD}=+3V,\ AGND=DGND=0,\ V_{REF}=V_{REFMS}=+2.5V$  (external reference),  $C_{REF}=C_{REFMS}=0.1\mu F,\ C_{REF+}=0.1\mu F,\$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
EXTERNAL REFERENCE (REF an	d REF <sub>MS</sub> a	re externally driven)	<b>.</b>			I.
REF Input Voltage Range	V <sub>REF</sub>		2.0	2.5	3.0	V
REF Input Resistance	RREF	(Note 5)		5		kΩ
REF Input Capacitance				15		рF
REF <sub>MS</sub> Input Voltage Range	VREFMS		2.0	2.5	3.0	V
REF <sub>MS</sub> Input Resistance	R <sub>REFMS</sub>	(Note 6)		5		kΩ
REF <sub>MS</sub> Input Capacitance				15		рF
REF+ Output Voltage	V <sub>REF+</sub>	V <sub>REF</sub> = +2.5V		3.850		V
COM Output Voltage	VCOM	V <sub>REF</sub> = +2.5V		2.600		V
REF- Output Voltage	V <sub>REF</sub> -	V <sub>REF</sub> = +2.5V		1.350		V
Differential Reference Voltage	V <sub>REF+</sub> -	V <sub>REF</sub> = +2.5V		2.500		V
DIGITAL INPUTS (D0-D7, RD, WR	CS, CLK,	SHDN, CHSHDN, CONVST)	•			•
Input-Voltage High	VIH		0.7 x DV <sub>E</sub>	DD_		V
Input-Voltage Low	VIL			0.3	3 x DV <sub>DD</sub>	V
Input Hysteresis				20		mV
Input Capacitance	CIN			15		рF
Input Current	IIN	V <sub>IN</sub> = 0 or DV <sub>DD</sub>		0.02	±1	μΑ
CLOCK-SELECT INPUT (INTCLK/I	XTCLK)		·			
Input-Voltage High	V <sub>IH</sub>		0.7 x AV <sub>D</sub>	D		V
Input-Voltage Low	VIL			0.3	3 x AV <sub>DD</sub>	V
DIGITAL OUTPUTS (D0-D11, EOC	, EOLC)					
Output-Voltage High	VoH	ISOURCE = 0.8mA, Figure 1	DV <sub>DD</sub> - 0.	6		V
Output-Voltage Low	V <sub>OL</sub>	I <sub>SINK</sub> = 1.6mA, Figure 1			0.4	V
D0-D11 Tri-State Leakage Current		$\overline{RD}$ = high or $\overline{CS}$ = high		0.06	1	μΑ
D0-D11 Tri-State Output Capacitance		$\overline{RD}$ = high or $\overline{CS}$ = high		15		pF
POWER SUPPLIES			<u>.</u>			
Analog Supply Voltage	AV <sub>DD</sub>		4.75		5.25	V
Digital Supply Voltage	DV <sub>DD</sub>		2.70		5.25	V
		MAX1304/MAX1305/MAX1306, all channels selected		55	60	
Analog Supply Current	I <sub>AVDD</sub>	MAX1308/MAX1309/MAX1310, all channels selected		54	60	mA
		MAX1312/MAX1313/MAX1314, all channels selected		54	60	

4 \_\_\_\_\_\_ /I/XI/M

# **ELECTRICAL CHARACTERISTICS (continued)**

 $(AV_{DD} = +5V,\ DV_{DD} = +3V,\ AGND = DGND = 0,\ V_{REF} = V_{REFMS} = +2.5V\ (external\ reference),\ C_{REF} = C_{REFMS} = 0.1\mu F,\ C_{REF+} = C_{REF-} = 0.1\mu F,\ C_{REF+} = 2.2\mu F \parallel 0.1\mu F,\ C_{COM} = 2.2\mu F \parallel 0.1\mu F,\ C_{MSV} = 2.2\mu F \parallel 0.1\mu F\ (unipolar\ devices),\ MSV = AGND\ (bipolar\ devices),\ f_{CLK} = 16.67MHz\ 50\%\ duty\ cycle,\ INTCLK/EXTCLK = AGND\ (external\ clock),\ SHDN = DGND,\ T_A = T_{MIN}\ to\ T_{MAX},\ unless\ otherwise\ noted.\ Typical\ values\ are\ at\ T_A = +25°C.\ See\ Figures\ 3\ and\ 4.)$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
		MAX1304/MAX1305/MAX1306, all channels selected		1.3	2.6	mA
Digital Supply Current (C <sub>LOAD</sub> = 100pF) (Note 7)	I <sub>DVDD</sub>	MAX1308/MAX1309/MAX1310, all channels selected		1.3	2.6	
		MAX1312/MAX1313/MAX1314, all channels selected		1.3	2.6	
Shutdown Current	lavdd	SHDN = DV <sub>DD</sub> , V <sub>CH</sub> = float		0.6	10	μΑ
(Note 8)	IDVDD	SHDN = $DV_{DD}$ , $\overline{RD} = \overline{WR} = high$		0.02	1	μΑ
Power-Supply Rejection Ratio	PSRR	$AV_{DD} = +4.75V \text{ to } +5.25V$		50		dB
TIMING CHARACTERISTICS (Figur	re 1)					
		Internal clock, Figure 7		800	900	ns
Time to First Conversion Result	tCONV	External clock, Figure 8		12		CLK Cycles
		Internal clock, Figure 7		200	225	ns
Time to Subsequent Conversions	tNEXT	External clock, Figure 8		3		CLK Cycles
CONVST Pulse-Width Low (Acquisition Time)	tACQ	(Note 9) Figures 6–10	0.1		1000.0	μs
CS Pulse Width	tcs	Figure 6	30			ns
RD Pulse-Width Low	trdl	Figures 7, 8, 9	30			ns
RD Pulse-Width High	trdh	Figures 7, 8, 9	30			ns
WR Pulse-Width Low	twrl	Figure 6	30			ns
CS to WR	tctw	Figure 6		(Note 10)		ns
WR to CS	twrc	Figure 6		(Note 10)		ns
CS to RD	tctr	Figures 7, 8, 9		(Note 10)		ns
RD to CS	trtc	Figures 7, 8, 9		(Note 10)		ns
Data Access Time (RD Low to Valid Data)	tACC	Figures 7, 8, 9			30	ns
Bus Relinquish Time (RD High)	treq	Figures 7, 8, 9	5		30	ns
CLK Rise to EOC Delay	tEOCD	Figure 8		20		ns
CLK Rise to EOLC Fall Delay	tEOLCD	Figure 8		20		ns
CONVST Fall to EOLC Rise Delay	tCVEOLCD	Figures 7, 8, 9		20		ns
		Internal clock, Figure 7	50			ns
EOC Pulse Width	t <sub>EOC</sub>	External clock, Figure 8		1		CLK Cycle

# **ELECTRICAL CHARACTERISTICS (continued)**

 $(AV_{DD} = +5V,\ DV_{DD} = +3V,\ AGND = DGND = 0,\ V_{REF} = V_{REFMS} = +2.5V\ (external\ reference),\ C_{REF} = C_{REFMS} = 0.1\mu F,\ C_{REF+} = C_{REF-} = 0.1\mu F,\ C_{REF+} = 2.2\mu F \parallel 0.1\mu F,\ C_{COM} = 2.2\mu F \parallel 0.1\mu F,\ C_{MSV} = 2.2\mu F \parallel 0.1\mu F\ (unipolar\ devices),\ MSV = AGND\ (bipolar\ devices),\ f_{CLK} = 16.67MHz\ 50\%\ duty\ cycle,\ INTCLK/EXTCLK = AGND\ (external\ clock),\ SHDN = DGND,\ T_A = T_{MIN}\ to\ T_{MAX},\ unless\ otherwise\ noted.\ Typical\ values\ are\ at\ T_A = +25°C.\ See\ Figures\ 3\ and\ 4.)$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Input-Data Setup Time	tDTW	Figure 6	10			ns
Input-Data Hold Time	twtD	Figure 6	10			ns
External CLK Period	tCLK	Figures 8, 9	0.05		10.00	μs
External CLK High Period	tCLKH	Logic sensitive to rising edges, Figures 8, 9	20			ns
External CLK Low Period	tCLKL	Logic sensitive to rising edges, Figures 8, 9	20			ns
External Clock Frequency	fCLK	(Note 11)	0.1		20	MHz
Internal Clock Frequency	fINT			15		MHz
CONVST High to CLK Edge	tCNTC	Figures 8, 9	20			ns

- Note 1: For the MAX1304/MAX1305/MAX1306,  $V_{IN} = 0$  to +5V. For the MAX1308/MAX1309/MAX1310,  $V_{IN} = -5V$  to +5V. For the MAX1312/MAX1313/MAX1314,  $V_{IN} = -10V$  to +10V.
- Note 2: All channel performance is guaranteed by correlation to a single channel test.
- Note 3: The analog input resistance is terminated to an internal bias point (Figure 5). Calculate the analog input current using:

$$I_{CH_{-}} = \frac{V_{CH_{-}} - V_{BIAS}}{R_{CH}}$$

for V<sub>CH</sub> within the input voltage range.

- Note 4: Throughput rate is given per channel. Throughput rate is a function of clock frequency (f<sub>CLK</sub>). The external clock throughput rate is specified with f<sub>CLK</sub> = 16.67MHz and the internal clock throughput rate is specified with f<sub>CLK</sub> = 15MHz. See the Data Throughput section for more information.
- Note 5: The REF input resistance is terminated to an internal +2.5V bias point (Figure 2). Calculate the REF input current using:

$$I_{REF} = \frac{V_{REF} - 2.5V}{R_{REF}}$$

for V<sub>REF</sub> within the input voltage range.

Note 6: The REFMs input resistance is terminated to an internal +2.5V bias point (Figure 2). Calculate the REFMs input current using:

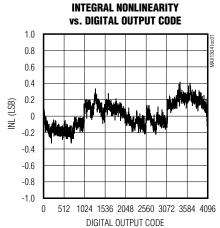
$$I_{REFMS} = \frac{V_{REFMS} - 2.5V}{R_{REFMS}}$$

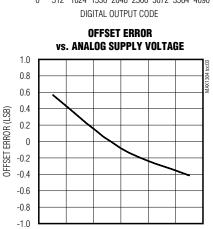
for V<sub>REFMS</sub> within the input voltage range.

- Note 7: All analog inputs are driven with a -0.4dBFS 500kHz sine wave.
- **Note 8:** Shutdown current is measured with the analog input floating. The large amplitude of the maximum shutdown current specification is due to automated test equipment limitations.
- Note 9: CONVST must remain low for at least the acquisition period. The maximum acquisition time is limited by internal capacitor droop.
- Note 10: CS to WR and CS to RD are internally AND together. Setup and hold times do not apply.
- Note 11: Minimum CLK frequency is limited only by the internal T/H droop rate. Limit the time between the rising edge of CONVST and the falling edge of EOLC to a maximum of 1ms.

# **Typical Operating Characteristics**

 $(AV_{DD} = +5V,\ DV_{DD} = +3V,\ AGND = DGND = 0,\ V_{REF} = V_{REFMS} = +2.5V\ (external\ reference),\ C_{REF} = C_{REFMS} = 0.1\mu\text{F},\ C_{REF+} = C_{REF+} = 0.1\mu\text{F},\ C_{REF+} = 0.1\mu\text{F},\ C_{REF+} = 2.2\mu\text{F}\ II\ 0.1\mu\text{F},\ C_{COM} = 2.2\mu\text{F}\ II\ 0.1\mu\text{F},\ C_{MSV} = 2.2\mu\text{F}\ II\ 0.1\mu\text{F}\ (unipolar\ devices)},\ MSV = AGND\ (bipolar\ devices),\ f_{CLK} = 16.67MHz\ 50\%\ duty\ cycle,\ INTCLK/EXTCLK = AGND\ (external\ clock),\ f_{IN} = 500kHz,\ A_{IN} = -0.4dBFS.\ T_{A} = +25^{\circ}\text{C},\ unless\ otherwise\ noted.}) (Figures\ 3\ and\ 4)$ 





4.8

4.7

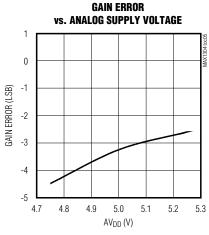
4.9

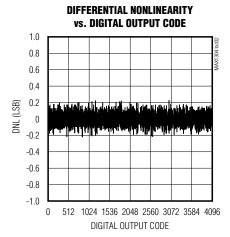
5.0 5.1

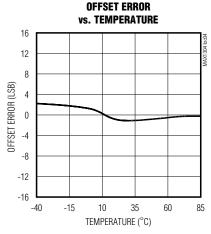
AV<sub>DD</sub> (V)

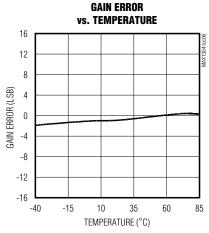
5.2

5.3









# Typical Operating Characteristics (continued)

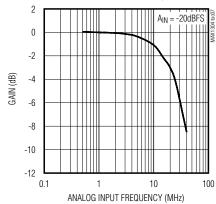
2

0

0.1

 $(AVDD=+5V,\,DVDD=+3V,\,AGND=DGND=0,\,VREF=VREFMS=+2.5V$  (external reference), CREF=CREFMS=0.1 $\mu$ F, CREF+=CREF-=0.1 $\mu$ F, CREF+-to-REF-=2.2 $\mu$ F || 0.1 $\mu$ F, CCOM=2.2 $\mu$ F || 0.1 $\mu$ F, CMSV=2.2 $\mu$ F || 0.1 $\mu$ F (unipolar devices), MSV=AGND (bipolar devices), fCLK=16.67MHz 50% duty cycle, INTCLK/EXTCLK=AGND (external clock), fIN=500kHz, AIN=-0.4dBFS. TA=+25°C, unless otherwise noted.) (Figures 3 and 4)





# -2 (gg) -4 NWO -6 -8 -10 -12

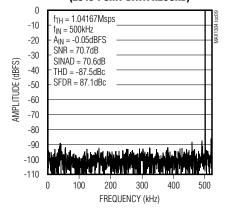
1

**LARGE-SIGNAL BANDWIDTH** 

**vs. Analog input frequency** 

 $A_{IN} = -0.5 dBFS$ 

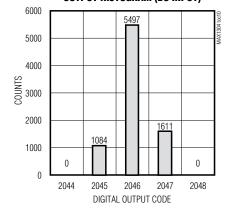
### FFT PLOT (2048-POINT DATA RECORD)



### **OUTPUT HISTOGRAM (DC INPUT)**

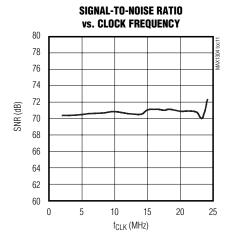
ANALOG INPUT FREQUENCY (MHz)

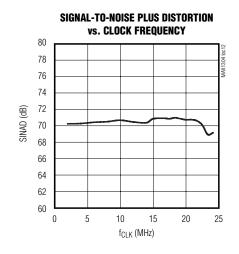
10

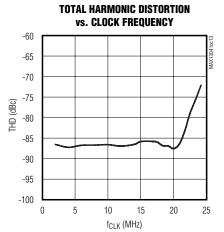


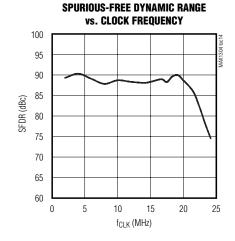
# Typical Operating Characteristics (continued)

 $(AV_{DD} = +5V, \, DV_{DD} = +3V, \, AGND = DGND = 0, \, V_{REF} = V_{REFMS} = +2.5V \, (external \, reference), \, C_{REF} = C_{REFMS} = 0.1 \mu F, \, C_{REF+} = C_{REF-} = 0.1 \mu F, \, C_{REF+-to-REF-} = 2.2 \mu F \, II \, 0.1 \mu F, \, C_{COM} = 2.2 \mu F \, II \, 0.1 \mu F, \, C_{MSV} = 2.2 \mu F \, II \, 0.1 \mu F \, (unipolar \, devices), \, MSV = AGND \, (bipolar \, devices), \, f_{CLK} = 16.67 MHz \, 50\% \, duty \, cycle, \, INTCLK/EXTCLK = AGND \, (external \, clock), \, f_{IN} = 500 kHz, \, A_{IN} = -0.4 dBFS. \, T_{A} = +25 ^{\circ}C, \, unless \, otherwise \, noted.) \, (Figures 3 \, and 4)$ 





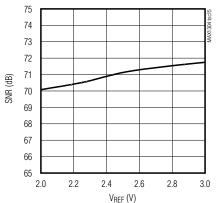




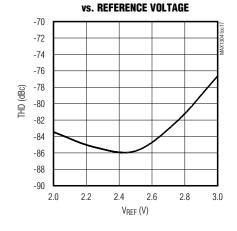
# Typical Operating Characteristics (continued)

 $(AV_{DD} = +5V, DV_{DD} = +3V, AGND = DGND = 0, V_{REF} = V_{REFMS} = +2.5V$  (external reference),  $C_{REF} = C_{REFMS} = 0.1\mu F$ ,  $C_{REF+} = 0.1\mu F$ , C

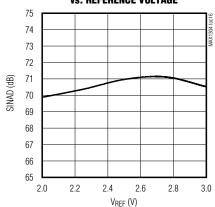




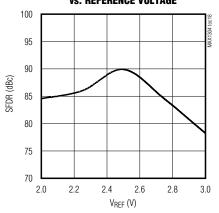
# TOTAL HARMONIC DISTORTION



# SIGNAL-TO-NOISE PLUS DISTORTION vs. REFERENCE VOLTAGE

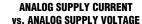


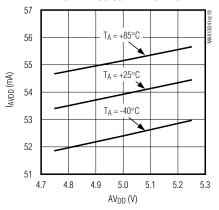
# SPURIOUS-FREE DYNAMIC RANGE vs. REFERENCE VOLTAGE



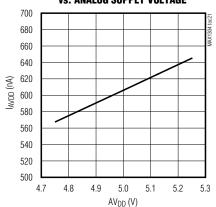
# Typical Operating Characteristics (continued)

 $(AV_{DD} = +5V,\ DV_{DD} = +3V,\ AGND = DGND = 0,\ V_{REF} = V_{REFMS} = +2.5V\ (external\ reference),\ C_{REF} = C_{REFMS} = 0.1\mu\text{F},\ C_{REF+} = C_{REF+} = 0.1\mu\text{F},\ C_{REF+} = 0.1\mu\text{F},\ C_{REF+} = 2.2\mu\text{F}\ II\ 0.1\mu\text{F},\ C_{COM} = 2.2\mu\text{F}\ II\ 0.1\mu\text{F},\ C_{MSV} = 2.2\mu\text{F}\ II\ 0.1\mu\text{F}\ (unipolar\ devices)},\ MSV = AGND\ (bipolar\ devices),\ f_{CLK} = 16.67MHz\ 50\%\ duty\ cycle,\ INTCLK/EXTCLK = AGND\ (external\ clock),\ f_{IN} = 500kHz,\ A_{IN} = -0.4dBFS.\ T_{A} = +25^{\circ}\text{C},\ unless\ otherwise\ noted.) (Figures\ 3\ and\ 4)$ 

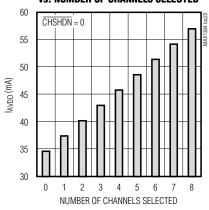




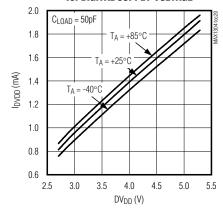
# ANALOG SHUTDOWN CURRENT vs. ANALOG SUPPLY VOLTAGE



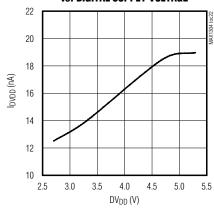
# ANALOG SUPPLY CURRENT vs. Number of Channels Selected



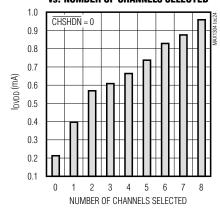
# DIGITAL SUPPLY CURRENT vs. DIGITAL SUPPLY VOLTAGE



# DIGITAL SHUTDOWN CURRENT vs. DIGITAL SUPPLY VOLTAGE

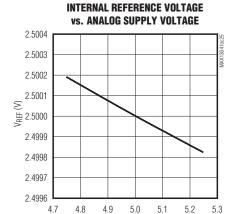


# DIGITAL SUPPLY CURRENT vs. Number of Channels Selected

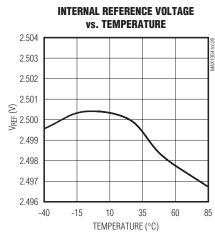


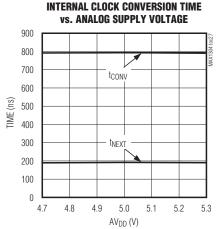
# Typical Operating Characteristics (continued)

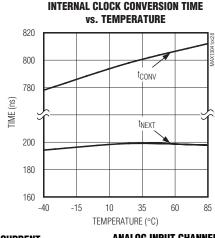
 $(AV_{DD} = +5V, \, DV_{DD} = +3V, \, AGND = DGND = 0, \, V_{REF} = V_{REFMS} = +2.5V \, (external \, reference), \, C_{REF} = C_{REFMS} = 0.1 \mu F, \, C_{REF+} = C_{REF-} = 0.1 \mu F, \, C_{REF-} = 2.2 \mu F \, II \, 0.1 \mu F, \, C_{COM} = 2.2 \mu F \, II \, 0.1 \mu F, \, C_{MSV} = 2.2 \mu F \, II \, 0.1 \mu F \, (unipolar \, devices), \, MSV = AGND \, (bipolar \, devices), \, C_{LK} = 16.67 MHz \, 50\% \, duty \, cycle, \, INTCLK/EXTCLK = AGND \, (external \, clock), \, f_{IN} = 500 kHz, \, A_{IN} = -0.4 dBFS. \, T_{A} = +25 ^{\circ}C, \, unless \, otherwise \, noted.) \, (Figures \, 3 \, and \, 4)$ 

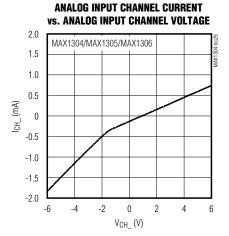


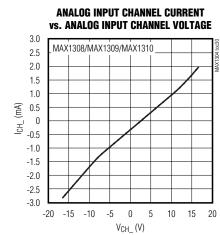
 $AV_{DD}(V)$ 

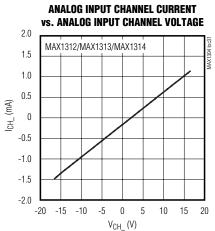












# **Pin Description**

	PIN			
MAX1304 MAX1308 MAX1312	MAX1305 MAX1309 MAX1313	MAX1306 MAX1310 MAX1314	NAME	FUNCTION
1, 15, 17	1, 15, 17	1, 15, 17	AV <sub>DD</sub>	Analog Power Input. AV <sub>DD</sub> is the power input for the analog section of the converter. Apply +5V to AV <sub>DD</sub> . Connect all AV <sub>DD</sub> pins together. See the <i>Layout, Grounding, and Bypassing</i> section for additional information.
2, 3, 14, 16, 23	2, 3, 14, 16, 23	2, 3, 14, 16, 23	AGND	Analog Ground. AGND is the power return for AVDD. Connect all AGND pins together.
4	4	4	CH0	Channel 0 Analog Input
5	5	5	CH1	Channel 1 Analog Input
6	6	6	MSV	Midscale Voltage Bypass. For the unipolar MAX1304/MAX1305/MAX1306, connect a 2.2µF and a 0.1µF capacitor from MSV to AGND. For the bipolar MAX1308/MAX1309/MAX1310/MAX1312/MAX1313/MAX1314, connect MSV to AGND.
7	7	_	CH2	Channel 2 Analog Input
8	8	_	СНЗ	Channel 3 Analog Input
9	_	_	CH4	Channel 4 Analog Input
10	_	_	CH5	Channel 5 Analog Input
11	_	_	CH6	Channel 6 Analog Input
12	_	_	CH7	Channel 7 Analog Input
13	13	13	INTCLK/ EXTCLK	Clock-Mode Select Input. Connect INTCLK/EXTCLK to AV <sub>DD</sub> to select the internal clock. Connect INTCLK/EXTCLK to AGND to use an external clock connected to CLK.
18	18	18	REFMS	Midscale Reference Bypass or Input. REF <sub>MS</sub> connects through a $5k\Omega$ resistor to the internal +2.5V bandgap reference buffer. For the MAX1304/MAX1305/MAX1306 unipolar devices, V <sub>REFMS</sub> is the input to the unity-gain buffer that drives MSV. MSV sets the midpoint of the input voltage range. For internal reference operation, bypass REF <sub>MS</sub> with a $\geq$ 0.01μF capacitor to AGND. For external reference operation, drive REF <sub>MS</sub> with an external voltage from +2V to +3V. For the MAX1308/MAX1309/MAX1310/MAX1312/MAX1313/MAX1314 bipolar devices, connect REF <sub>MS</sub> to REF. For internal reference operation, bypass the REF <sub>MS</sub> /REF node with a $\geq$ 0.01μF capacitor to AGND. For external reference operation, drive the REF <sub>MS</sub> /REF node with an external voltage from +2V to +3V.
19	19	19	REF	ADC Reference Bypass or Input. REF connects through a 5kΩ resistor to the internal +2.5V bandgap reference buffer. For internal reference operation, bypass REF with a ≥0.01μF capacitor. For external reference operation with the MAX1304/MAX1305/MAX1306 unipolar devices, drive REF with an external voltage from +2V to +3V. For external reference operation with the MAX1308/MAX1309/MAX1310/MAX1312/MAX1313/MAX1314 bipolar devices, connect REF <sub>MS</sub> to REF and drive the REF <sub>MS</sub> /REF node with an external voltage from +2V to +3V.

Pin Description (continued)

PIN		PIN		PIN		
MAX1304 MAX1308 MAX1312	MAX1305 MAX1309 MAX1313	MAX1306 MAX1310 MAX1314	NAME	FUNCTION		
20	20	20	REF+	Positive Reference Bypass. Bypass REF+ with a 0.1µF capacitor to AGND. Also bypass REF+ to REF- with a 2.2µF and a 0.1µF capacitor. VREF+ = VCOM + VREF / 2.		
21	21	21	COM	Reference Common Bypass. Bypass COM to AGND with a 2.2µF and a 0.1µF capacitor. V <sub>COM</sub> = 13 / 25 x AV <sub>DD</sub> .		
22	22	22	REF-	Negative Reference Bypass. Bypass REF- with a 0.1µF capacitor to AGND. Also bypass REF- to REF+ with a 2.2µF and a 0.1µF capacitor. VREF- = VCOM - VREF / 2.		
24, 39	24, 39	24, 39	DGND	Digital Ground. DGND is the power return for DV <sub>DD</sub> . Connect all DGND pins together.		
25, 38	25, 38	25, 38	DV <sub>DD</sub>	Digital Power Input. DV <sub>DD</sub> powers the digital section of the converter, including the parallel interface. Apply +2.7V to +5.25V to DV <sub>DD</sub> . Bypass DV <sub>DD</sub> to DGND with a 0.1µF capacitor. Connect all DV <sub>DD</sub> pins together.		
26	26	26	D0	Digital I/O 0 of 12-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
27	27	27	D1	Digital I/O 1 of 12-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
28	28	28	D2	Digital I/O 2 of 12-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
29	29	29	D3	Digital I/O 3 of 12-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
30	30	30	D4	Digital I/O 4 of 12-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
31	31	31	D5	Digital I/O 5 of 12-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
32	32	32	D6	Digital I/O 6 of 12-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
33	33	33	D7	Digital I/O 7 of 12-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
34	34	34	D8	Digital Output 8 of 12-Bit Parallel Data Bus. High impedance when $\overline{RD}$ = 1 or $\overline{CS}$ = 1.		
35	35	35	D9	Digital Output 9 of 12-Bit Parallel Data Bus. High impedance when $\overline{RD}$ = 1 or $\overline{CS}$ = 1.		
36	36	36	D10	Digital Output 10 of 12-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
37	37	37	D11	Digital Output 11 of 12-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
40	40	40	EOC	End-of-Conversion Output. EOC goes low to indicate the end of a conversion. It returns high on the next rising CLK edge or the falling CONVST edge.		
41	41	41	EOLC	End-of-Last-Conversion Output. FOLC goes low to indicate the end of the last conversion. It returns high when CONVST goes low for the next conversion sequence.		
42	42	42	RD	Read Input. Pulling RD low initiates a read command of the parallel data bus.		
43	43	43	WR	Write Input. Pulling WR low initiates a write command for configuring the device with D0–D7.		

# Pin Description (continued)

	PIN			
MAX1304 MAX1308 MAX1312	MAX1305 MAX1309 MAX1313	MAX1306 MAX1310 MAX1314	NAME	FUNCTION
44	44	44	CS	Chip-Select Input. Pulling $\overline{\text{CS}}$ low activates the digital interface. Forcing $\overline{\text{CS}}$ high places D0-D11 in high-impedance mode.
45	45	45	CONVST	Conversion Start Input. Driving CONVST high initiates the conversion process. The analog inputs are sampled on the rising edge of CONVST.
46	46	46	CLK	External Clock Input. For external clock operation, connect INTCLK/EXTCLK to AGND and drive CLK with an external clock signal from 100kHz to 20MHz. For internal clock operation, connect INTCLK/EXTCLK to AVDD and connect CLK to DGND.
47	47	47	SHDN	Shutdown Input. Driving SHDN high initiates device shutdown. Connect SHDN to DGND for normal operation.
48	48	48	CHSHDN	Active-Low Analog-Input Channel-Shutdown Input. Drive CHSHDN low to power down analog inputs that are not selected for conversion in the configuration register. Drive CHSHDN high to power up all analog input channels regardless of whether they are selected for conversion in the configuration register. See the <i>Channel Shutdown (CHSHDN)</i> section for more information.
_	9, 10, 11, 12	7, 8, 9, 10, 11, 12	I.C.	Internally connected. Connect I.C. to AGND.

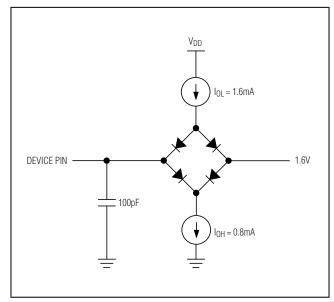


Figure 1. Digital Load Test Circuit

# **Detailed Description**

The MAX1304-MAX1306/MAX1308-MAX1310/MAX1312-MAX1314 are 12-bit ADCs. The devices offer 8, 4, or 2 independently selectable input channels, each with dedicated T/H circuitry. Simultaneous sampling of all active channels preserves relative phase information making these devices ideal for motor control and power monitoring. Three input ranges are available, 0 to +5V, ±5V and ±10V. The 0 to +5V devices provide ±6V faulttolerant inputs. The ±5V and ±10V devices provide ±16.5V fault-tolerant inputs. Two-channel conversion results are available in 0.9µs. Conversion results from all eight channels are available in 1.98µs. The 8-channel throughput is 456ksps per channel. Internal or external reference and clock capability offer great flexibility, and ease of use. A write-only configuration register can mask out unused channels and a shutdown feature reduces power. A 20MHz, 12-bit, parallel data bus outputs the conversion results. Figure 2 shows the functional diagram of these ADCs.

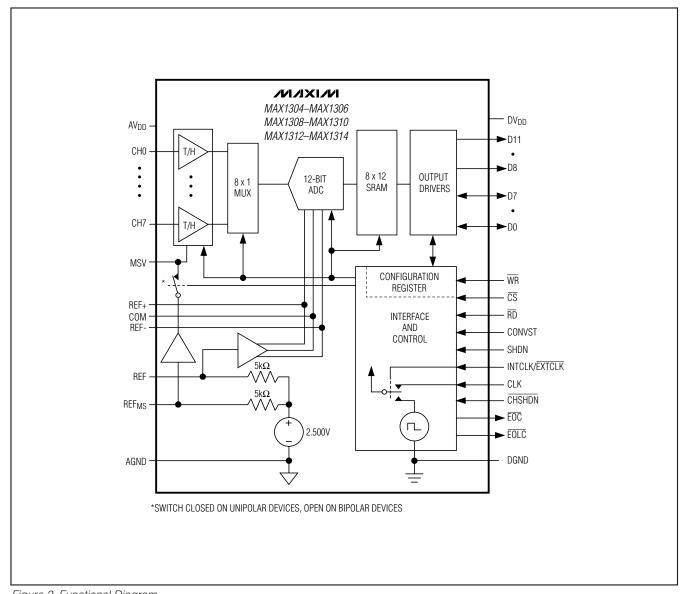


Figure 2. Functional Diagram

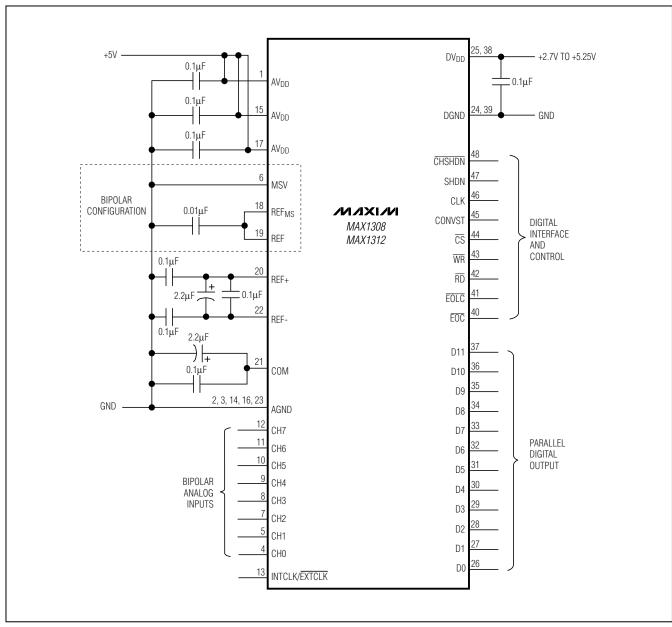


Figure 3. Typical Bipolar Operating Circuit

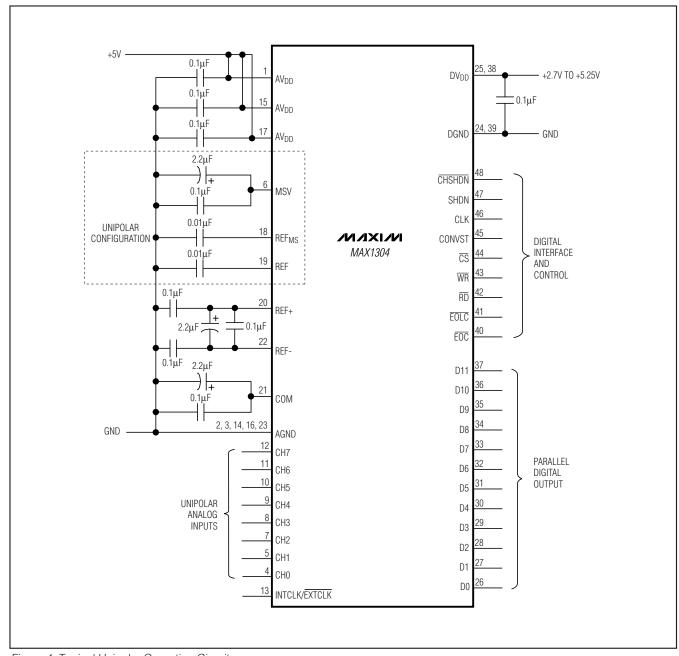


Figure 4. Typical Unipolar Operating Circuit

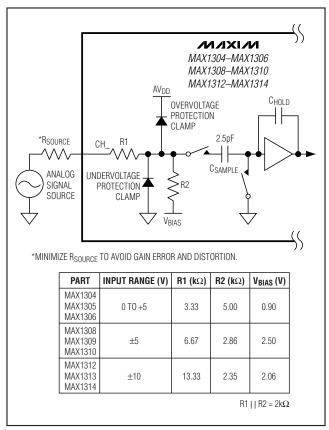


Figure 5. Single-Channel, Equivalent Analog Input T/H Circuit

# **Analog Inputs**

### Track and Hold (T/H)

To preserve phase information across the multichannel MAX1304–MAX1306/MAX1308–MAX1310/MAX1312–MAX1314, all input channels have dedicated T/H amplifiers. Figure 5 shows the equivalent analog input T/H circuit for one channel.

The input T/H circuit is controlled by the CONVST input. When CONVST is low, the T/H circuit tracks the analog input. When CONVST is high the T/H circuit holds the analog input. The rising edge of CONVST is the analog input sampling instant. There is an aperture delay (t<sub>AD</sub>) of 8ns and a 50ps<sub>RMS</sub> aperture jitter (t<sub>AJ</sub>). The aperture delay of each dedicated T/H input is matched within 100ps of each other.

To settle the charge on CSAMPLE to 12-bit accuracy, use a minimum acquisition time (tACQ) of 100ns. Therefore, CONVST must be low for at least 100ns. Although longer acquisition times allow the analog input to settle to its final value more accurately, the maximum

acquisition time must be limited to 1ms. Accuracy with conversion times longer than 1ms cannot be guaranteed due to capacitor droop in the input circuitry.

Due to the analog input resistive divider formed by R1 and R2 in Figure 5, any significant analog input source resistance (RSOURCE) results in gain error. Furthermore, RSOURCE causes distortion due to nonlinear analog input currents. Limit RSOURCE to a maximum of  $100\Omega$ .

# Selecting an Input Buffer

To improve the input signal bandwidth under AC conditions, drive the input with a wideband buffer (>50MHz) that can drive the ADC's input capacitance (15pF) and settle quickly. For example, the MAX4431 or the MAX4265 can be used for the 0 to +5V unipolar devices, or the MAX4350 can be used for ±5V bipolar inputs.

Most applications require an input buffer to achieve 12-bit accuracy. Although slew rate and bandwidth are important, the most critical input buffer specification is settling time. The simultaneous sampling of multiple channels requires an acquisition time of 100ns. At the beginning of the acquisition, the ADC internal sampling capacitor array connects to the analog inputs, causing some disturbance. Ensure the amplifier is capable of settling to at least 12-bit accuracy during this interval. Use a low-noise, low-distortion, wideband amplifier that settles quickly and is stable with the ADC's 15pF input capacitance.

See the Maxim website at <u>www.maxim-ic.com</u> for application notes on how to choose the optimum buffer amplifier for your ADC application.

# Input Bandwidth

The input-tracking circuitry has a 20MHz small-signal bandwidth, making it possible to digitize high-speed transient events and measure periodic signals with bandwidths exceeding the ADC's sampling rate by using undersampling techniques. To avoid high-frequency signals being aliased into the frequency band of interest, anti-alias filtering is recommended.

### Input Range and Protection

The MAX1304/MAX1305/MAX1306 provide a 0 to +5V input voltage range with fault protection of ±6V. The MAX1308/MAX1309/MAX1310 provide a ±5V input voltage range with fault protection of ±16.5V. The MAX1312/MAX1313/MAX1314 provide a ±10V input voltage range with fault protection of ±16.5V. Figure 5 shows the single-channel equivalent input circuit.

# **Data Throughput**

The data throughput (f<sub>TH</sub>) of the MAX1304–MAX1306/MAX1308–MAX1310/MAX1312–MAX1314 is a function of the clock speed (f<sub>CLK</sub>). In internal clock mode, f<sub>CLK</sub> = 15MHz (typ). In external clock mode, 100kHz  $\leq$  f<sub>CLK</sub>  $\leq$  20MHz. When reading during conversion (Figures 7 and 8), calculate f<sub>TH</sub> as follows:

$$f_{TH} = \frac{1}{t_{ACQ} + t_{QUIET} + \frac{12 + 3 \times (N-1) + 1}{f_{CLK}}}$$

where N is the number of active channels and tQUIET is the period of bus inactivity before the rising edge of CONVST. See the *Starting a Conversion* section for more information.

Table 1 uses the above equation and shows the total throughput as a function of the number of channels selected for conversion.

### **Clock Modes**

The MAX1304–MAX1306/MAX1308–MAX1310/MAX1312–MAX1314 provide a 15MHz internal conversion clock. Alternatively, an external clock can be used.

### Internal Clock

Internal clock mode frees the microprocessor from the burden of running the ADC conversion clock. For internal clock operation, connect INTCLK/EXTCLK to AVDD and connect CLK to DGND. Note that INTCLK/EXTCLK is referenced to AVDD, not DVDD.

### External Clock

For external clock operation, connect INTCLK/EXTCLK to AGND and connect an external clock source to CLK. Note that INTCLK/EXTCLK is referenced to AVDD, not DVDD. The external clock frequency can be up to 20MHz. Linearity is not guaranteed with clock frequencies below 100kHz due to droop in the T/H circuits.

Table 1. Throughput vs. Channels Sampled:  $f_{CLK} = 15MHz$ ,  $t_{ACQ} = 100ns$ ,  $t_{QUIET} = 50ns$ 

CHANNELS SAMPLED (N)	CLOCK CYCLES UNTIL LAST RESULT	CLOCK CYCLE FOR READING LAST CONVERSION	TOTAL CONVERSION TIME (ns)	TOTAL THROUGHPUT (ksps)	THROUGHPUT PER CHANNEL (fth)
1	12	1	800	983	983
2	15	1	1000	1643	821
3	18	1	1200	2117	705
4	21	1	1400	2474	618
5	24	1	1600	2752	550
6	27	1	1800	2975	495
7	30	1	2000	3157	451
8	33	1	2200	3310	413

# **Applications Information**

# **Digital Interface**

The bidirectional parallel digital interface allows for setting the 8-bit configuration register (see the *Configuration Register* section) and reading the 12-bit conversion result. The interface includes the following control signals: chip select  $(\overline{CS})$ , read  $(\overline{RD})$ , write  $(\overline{WR})$ , end of conversion  $(\overline{EOC})$ , end of last conversion  $(\overline{EOC})$ , conversion start  $(\overline{CONVST})$ , shutdown  $(\overline{SHDN})$ , channel shutdown  $(\overline{CHSHDN})$ , internal clock select  $(\overline{INTCLK/EXTCLK})$ , and external clock input  $(\overline{CLK})$ . Figures 6, 7, 8, 9, Table 2, and the *Timing Characteristics* show the operation of the interface. D0–D7 are bidirectional, and D8–D11 are output only. D0–D11 go high impedance when  $\overline{RD} = 1$  or  $\overline{CS} = 1$ .

# **Configuration Register**

Enable channels as active by writing to the configuration register through I/O lines D0–D7 (Table 2). The bits in the configuration register map directly to the channels, with D0 controlling channel zero, and D7 controlling channel seven. Setting any bit high activates the corresponding input channel, while resetting any bit low deactivates the corresponding channel. On the devices with less than eight channels, some of the bits have no function (Table 2).

To write to the configuration register, pull  $\overline{CS}$  and  $\overline{WR}$  low, load bits D0 through D7 onto the parallel bus, and force  $\overline{WR}$  high. The data are latched on the rising edge of  $\overline{WR}$  (Figure 6). Write to the configuration register at any point during the conversion sequence. At powerup, write to the configuration register to select the active channels before beginning a conversion.

However, the new configuration does not take effect until the next CONVST falling edge. At power-up all channels default active. Shutdown does not change the configuration register. The configuration register may be written to in shutdown. See the *Channel Shutdown* (CHSHDN) section for information about using the configuration register for power saving.

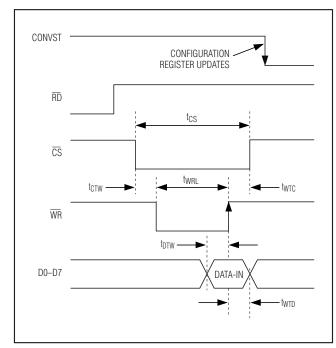


Figure 6. Write Timing

**Table 2. Configuration Register** 

PART	STATE	BIT/CHANNEL							
NUMBER	SIAIE	D0/CH0	D1/CH1	D2/CH2	D3/CH3	D4/CH4	D5/CH5	D6/CH6	D7/CH7
MAX1304 MAX1308	ON	1	1	1	1	1	1	1	1
MAX1312	OFF	0	0	0	0	0	0	0	0
MAX1305	ON	1	1	1	1	Х	Х	X	Х
MAX1309 MAX1313	OFF	0	0	0	0	Χ	Χ	Χ	Х
MAX1306	ON	1	1	Х	Х	Х	Х	X	Х
MAX1310 MAX1314	OFF	0	0	Х	Х	Х	Х	Х	Х

X = Don't care (must be 1 or 0).

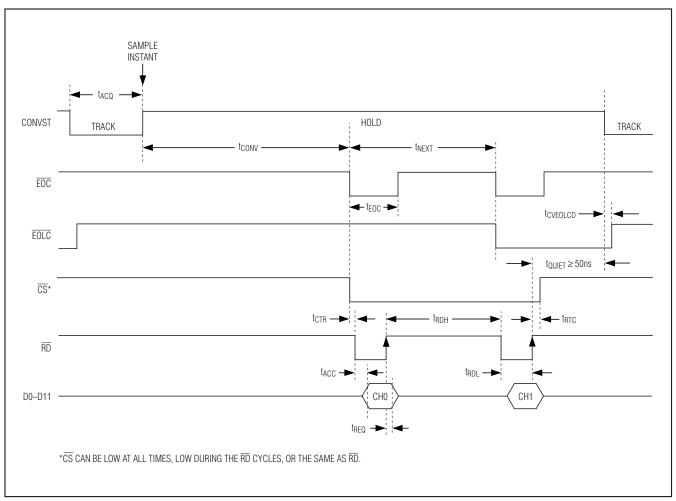


Figure 7. Read During Conversion—Channel 0 and Channel 1 Selected, Internal Clock

### Starting a Conversion

To start a conversion using internal clock mode, pull CONVST low for the acquisition time ( $t_{ACQ}$ ). The T/H acquires the signal while CONVST is low, and conversion begins on the rising edge of CONVST. The end-of-conversion signal ( $\overline{EOC}$ ) pulses low whenever a conversion result becomes available for read. The end-of-last-conversion signal ( $\overline{EOLC}$ ) goes low when the last conversion result is available (Figure 7).

To start a conversion using external clock mode, pull CONVST low for the acquisition time (tACQ). The T/H acquires the signal while CONVST is low. The rising edge of CONVST is the sampling instant. Apply an external clock to CLK to start the conversion. To avoid T/H droop degrading the sampled analog input signals,

the first CLK pulse must occur within 10µs from the rising edge of CONVST. Additionally, the external clock frequency must be greater than 100kHz to avoid T/H droop-degrading accuracy. The first conversion result is available for read when EOC goes low on the rising edge of the 13th clock cycle. Subsequent conversion results are available after every third clock cycle thereafter (Figures 8 and 9).

In both internal and external clock modes, hold CONVST high until the last conversion result is read. If CONVST goes low in the middle of a conversion, the current conversion is aborted and a new conversion is initiated. Furthermore, there must be a period of bus inactivity (tquiet) for 50ns or longer before the falling edge of CONVST for the specified ADC performance.

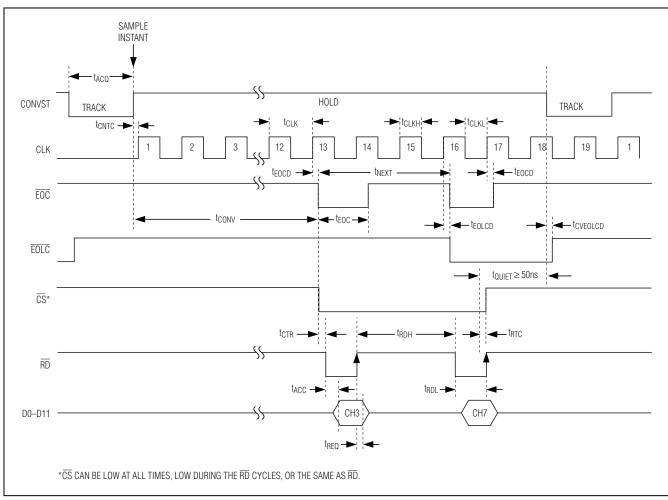


Figure 8. Read During Conversion—Channel 3 and Channel 7 Selected, External Clock

# **Reading a Conversion Result**Reading During a Conversion

Figures 7 and 8 show the interface signals to initiate a read operation during a conversion cycle. These figures show two channels selected for conversion. If more channels are selected, the results are available successively at every EOC falling edge. CS can be low at all times, low during the RD cycles, or the same as RD.

After initiating a conversion by bringing CONVST high, wait for  $\overline{EOC}$  to go low. In internal clock mode,  $\overline{EOC}$  goes low within 900ns. In external clock mode,  $\overline{EOC}$  goes low on the rising edge of the 13th CLK cycle. To read the conversion result, drive  $\overline{CS}$  and  $\overline{RD}$  low to latch data to the parallel digital output bus. Bring  $\overline{RD}$ 

high to release the digital bus. In internal clock mode, the next  $\overline{EOC}$  falling edge occurs within 225ns. In external clock mode, the next  $\overline{EOC}$  falling edge occurs in three CLK cycles. When the last result is available  $\overline{EOLC}$  goes low.

### Reading After Conversion

Figure 9 shows the interface signals for a read operation after a conversion with all eight channels enabled. At the falling of  $\overline{EOLC}$ , driving  $\overline{CS}$  and  $\overline{RD}$  low places the first conversion result onto the parallel bus. Successive low pulses of  $\overline{RD}$  place the successive conversion results onto the bus. When the last conversion results in the sequence are read, additional read pulses wrap the pointer back to the first converted result.

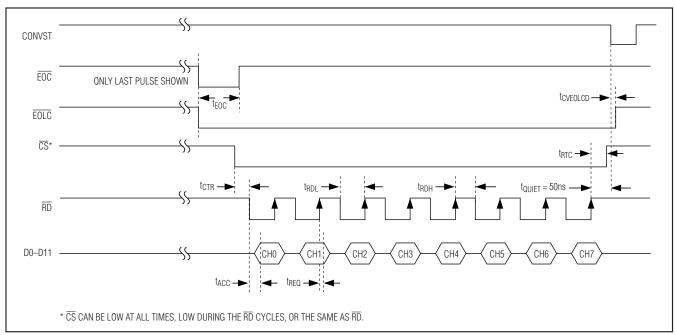


Figure 9. Read After Conversion—Eight Channels Selected, External Clock

### **Power-Up Reset**

At power-up, all channels are selected for conversion (see the *Configuration Register* section). After applying power, allow the 1ms wake-up time to elapse and then initiate a dummy conversion and discard the results. After the dummy conversion is complete, accurate conversions can be obtained.

# **Power-Saving Modes**Shutdown Mode

During shutdown the internal reference and analog circuits in the device shutdown and the analog supply current drops to 0.6µA (typ). Select shutdown mode using the SHDN input. Set SHDN high to enter shutdown mode. SHDN takes precedence over CHSHDN.

Entering and exiting shutdown mode does not change the configuration byte. However, a new configuration byte can be written while in shutdown mode by following the standard write procedure shown in Figure 6.

EOC and EOLC are high when the MAX1304–MAX1306/MAX1308–MAX1310/MAX1312–MAX1314 are shut down.

The state of the digital outputs D0–D11 is independent of the state of SHDN. If  $\overline{CS}$  and  $\overline{RD}$  are low, the digital outputs D0–D11 are active regardless of SHDN. The digital outputs only go high impedance when  $\overline{CS}$  or  $\overline{RD}$  is high. When the digital outputs are powered down, the digital supply current drops to 20nA.

Exiting shutdown (falling edge of SHDN) starts a conversion in the same way as the rising edge of CONVST. After coming out of shutdown, initiate a dummy conversion and discard the results. After the dummy conversion, allow the 1ms wake-up time to expire before initiating the first accurate conversion.

### Channel Shutdown (CHSHDN)

The channel-shutdown feature allows analog input channels to be powered down when they are not selected for conversion. Powering down channels that are not selected for conversion reduces the analog supply current by 2.9mA per channel. To power down channels that are not selected for conversion, pull CHSHDN low. See the *Configuration Register* section for information on selecting and deselecting channels for conversion.

The drawback of powering down analog inputs that are not selected for conversion is that it takes time to power them up. Figure 10 shows how a dummy conversion is used to power up an analog input in external clock mode. After selecting a new channel in the configuration register, initiate a dummy conversion and discard the results. After the dummy conversion, allow the 1ms wake-up time (twake) to expire before initiating the first accurate conversion.

\_\_ /VI/XI/VI

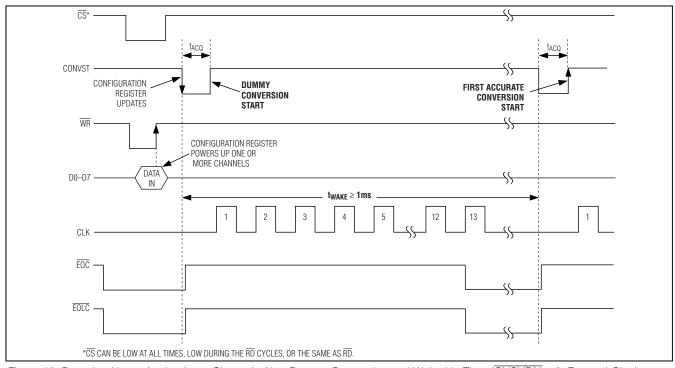


Figure 10. Powering Up an Analog Input Channel with a Dummy Conversion and Wake-Up Time (CHSHDN = 0, External-Clock Mode, One Channel Selected)

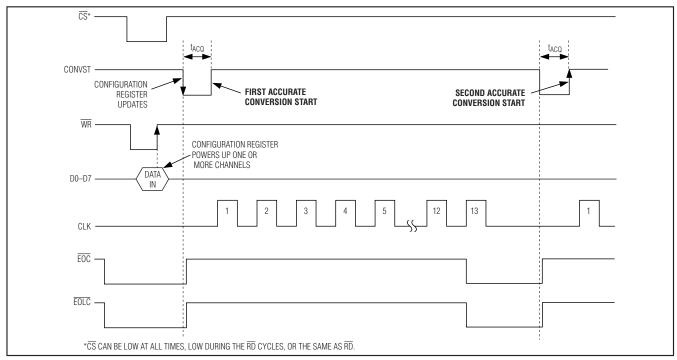


Figure 11. Powering Up an Analog Input Channel Directly (CHSHDN = 1, External-Clock Mode, One Channel Selected)

To avoid the timing requirements associated with powering up an analog channel, force CHSHDN high. With CHSHDN high, each analog input is powered up regardless of whether it is selected for conversion in the configuration register. Note that shutdown mode takes precedence over the CHSHDN mode.

### Reference

### Internal Reference

The internal reference circuits provide for analog input voltages of 0 to  $\pm 5V$  for the unipolar MAX1304/MAX1305/MAX1306,  $\pm 5V$  for the bipolar MAX1308/MAX1309/MAX1310 or  $\pm 10V$  for the bipolar MAX1312/MAX1313/MAX1314. Install external capacitors for reference stability, as indicated in Table 3 and shown in Figures 3 and 4.

As illustrated in Figure 2, the internal reference voltage is 2.5V (VREF). This 2.5V is internally buffered to create the voltages at REF+ and REF-. Table 4 shows the voltages at COM, REF+, and REF-.

### External Reference

External reference operation is achieved by overriding the internal reference voltage. Override the internal reference voltage by driving REF with a +2.0V to +3.0V external reference. As shown in Figure 2, the REF input impedance is  $5k\Omega$ . For more information about using external references see the *Transfer Functions* section.

# Midscale Voltage (MSV)

The voltage at MSV (V<sub>MSV</sub>) sets the midpoint of the ADC transfer functions. For the 0 to  $\pm$ 5V input range (unipolar devices), the midpoint of the transfer function is  $\pm$ 2.5V. For the  $\pm$ 5V and  $\pm$ 10V input range devices, the midpoint of the transfer function is zero.

As shown in Figure 2, there is a unity-gain buffer between REF<sub>MS</sub> and MSV in the unipolar MAX1304/MAX1305/MAX1306. This midscale buffer sets the midpoint of the unipolar transfer functions to either the internal +2.5V reference or an externally applied voltage at REF<sub>MS</sub>. V<sub>MSV</sub> follows V<sub>REFMS</sub> within ±3mV.

The midscale buffer is not active for the bipolar devices. For these devices, MSV must be connected to AGND or externally driven. REF<sub>MS</sub> must be bypassed with a 0.01µF capacitor to AGND.

See the *Transfer Functions* section for more information about MSV.

**Table 3. Reference Bypass Capacitors** 

LOCATION	INPUT VOLTAGE RANGE			
LOCATION	UNIPOLAR (μF)	BIPOLAR (μF)		
MSV Bypass Capacitor to AGND	2.2    0.1	N/A		
REF <sub>MS</sub> Bypass Capacitor to AGND	0.01	0.01		
REF Bypass Capacitor to AGND	0.01	0.01		
REF+ Bypass Capacitor to AGND	0.1	0.1		
REF+ to REF- Capacitor	2.2    0.1	2.2    0.1		
REF- Bypass Capacitor to AGND	0.1	0.1		
COM Bypass Capacitor to AGND	2.2    0.1	2.2    0.1		

N/A = Not applicable. Connect MSV directly to AGND.

# **Table 4. Reference Voltages**

PARAMETER	EQUATION	CALCULATED VALUE (V) $\begin{pmatrix} V_{REF} = 2.000V, \\ AV_{DD} = 5.0V \end{pmatrix}$	CALCULATED VALUE (V) $\begin{pmatrix} V_{REF} = 2.500V, \\ AV_{DD} = 5.0V \end{pmatrix}$	CALCULATED VALUE (V) $\begin{pmatrix} V_{REF} = 3.000V, \\ AV_{DD} = 5.0V \end{pmatrix}$
Vcom	$V_{COM} = 13 / 25 \times AV_{DD}$	2.600	2.600	2.600
V <sub>REF+</sub>	$V_{REF+} = V_{COM} + V_{REF} / 2$	3.600	3.850	4.100
V <sub>REF</sub> -	V <sub>REF-</sub> = V <sub>COM</sub> - V <sub>REF</sub> / 2	1.600	1.350	1.100
V <sub>REF+</sub> - V <sub>REF-</sub>	V <sub>REF+</sub> - V <sub>REF-</sub> = V <sub>REF</sub>	2.000	2.500	3.000

### **Transfer Functions**

### Unipolar 0 to +5V Devices

Table 5 and Figure 12 show the offset binary transfer function for the MAX1304/MAX1305/MAX1306 with a 0 to +5V input range. The full-scale input range (FSR) is two times the voltage at REF. The internal +2.5V reference gives a +5V FSR, while an external +2V to +3V reference allows an FSR of +4V to +6V, respectively. Calculate the LSB size using:

$$1 LSB = \frac{2 \times V_{REF}}{212}$$

which equals 1.22mV when using a 2.5V reference.

The input range is centered about V<sub>MSV</sub>, internally set to +2.5V. For a custom midscale voltage, drive REF<sub>MS</sub> with an external voltage source and MSV will follow REF<sub>MS</sub>. Noise present on MSV or REF<sub>MS</sub> directly couples into the ADC result. Use a precision, low-drift voltage reference with adequate bypassing to prevent MSV from degrading ADC performance. For maximum FSR, do not violate the absolute maximum voltage ratings of the analog inputs when choosing MSV.

Determine the input voltage as a function of VREF, VMSV, and the output code in decimal using:

V<sub>CH</sub><sub>\_</sub> = LSB x CODE<sub>10</sub> + V<sub>MSV</sub> - 2.500V

Table 5. 0 to +5V Unipolar Code Table

BINARY DIGITAL OUTPUT CODE	DECIMAL EQUIVALENT DIGITAL OUTPUT CODE (CODE <sub>10</sub> )	INPUT VOLTAGE (V) (VREF = +2.5V VREFMS = +2.5V)
1111 1111 1111 = 0xFFF	4095	+4.9994 ± 0.5 LSB
1111 1111 1110 = 0xFFE	4094	+4.9982 ± 0.5 LSB
1000 0000 0001 = 0x801	2049	+2.5018 ± 0.5 LSB
1000 0000 0000 = 0x800	2048	+2.5006 ± 0.5 LSB
0111 1111 1111 = 0x7FF	2047	+2.4994 ± 0.5 LSB
0000 0000 0001 = 0x001	1	+0.0018 ± 0.5 LSB
0000 0000 0000 = 0x000	0	+0.0006 ± 0.5 LSB

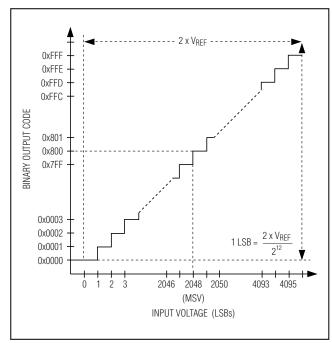


Figure 12. 0 to +5V Unipolar Transfer Function

# Bipolar ±5V Devices

Table 6 and Figure 13 show the two's complement transfer function for the ±5V input range MAX1308/MAX1309/MAX1310. The FSR is four times the voltage at REF. The internal +2.5V reference gives a +10V FSR, while an external +2V to +3V reference allows an FSR of +8V to +12V respectively. Calculate the LSB size using:

$$1 LSB = \frac{4 \times V_{REF}}{2^{12}}$$

which equals 2.44mV when using a 2.5V reference.

The input range is centered about V<sub>MSV</sub>. Normally, MSV = AGND, and the input is symmetrical about zero. For a custom midscale voltage, drive MSV with an external voltage source. Noise present on MSV directly couples into the ADC result. Use a precision, low-drift voltage reference with adequate bypassing to prevent MSV from degrading ADC performance. For maximum FSR, do not violate the absolute maximum voltage ratings of the analog inputs when choosing MSV.

Determine the input voltage as a function of  $V_{\text{REF}}$ ,  $V_{\text{MSV}}$ , and the output code in decimal using:

# Table 6. ±5V Bipolar Code Table

TWO'S COMPLEMENT DIGITAL OUTPUT CODE	DECIMAL EQUIVALENT DIGITAL OUTPUT CODE (CODE <sub>10</sub> )	INPUT VOLTAGE (V) (VREF = +2.5V VMSV = 0
0111 1111 1111 = 0x7FF	+2047	+4.9988 ± 0.5 LSB
0111 1111 1110 = 0x7FE	+2046	+4.9963 ± 0.5 LSB
0000 0000 0001 = 0x001	+1	+0.0037 ± 0.5 LSB
0000 0000 0000 = 0x000	0	+0.0012 ± 0.5 LSB
1111 1111 1111 = 0xFFF	-1	-0.0012 ± 0.5 LSB
1000 0000 0001 = 0x801	-2047	-4.9963 ± 0.5 LSB
1000 0000 0000 = 0x800	-2048	-4.9988 ± 0.5 LSB

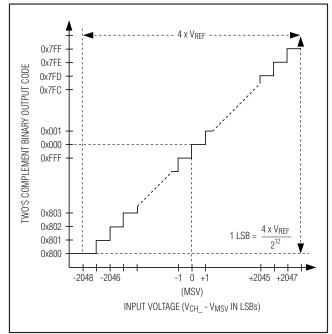


Figure 13. ±5V Bipolar Transfer Function

### Bipolar ±10V Devices

Table 7 and Figure 14 show the two's complement transfer function for the ±10V input range MAX1312/MAX1313/MAX1314. The FSR is eight times the voltage at REF. The internal +2.5V reference gives a +20V FSR, while an external +2V to +3V reference allows an FSR of +16V to +24V, respectively. Calculate the LSB size using:

$$1 LSB = \frac{8 \times V_{REF}}{2^{12}}$$

which equals 4.88mV with a +2.5V reference.

The input range is centered about  $V_{MSV}$ . Normally, MSV = AGND, and the input is symmetrical about zero. For a custom midscale voltage, drive MSV with an external voltage source. Noise present on MSV directly couples into the ADC result. Use a precision, low-drift voltage reference with adequate bypassing to prevent MSV from degrading ADC performance. For maximum FSR, do not violate the absolute maximum voltage ratings of the analog inputs when choosing MSV.

Determine the input voltage as a function of  $V_{REF}$ ,  $V_{MSV}$ , and the output code in decimal using:

# Table 7. ±10V Bipolar Code Table

TWO'S COMPLEMENT DIGITAL OUTPUT CODE	DECIMAL EQUIVALENT DIGITAL OUTPUT CODE (CODE <sub>10</sub> )	INPUT VOLTAGE (V) (VREF = +2.5V VMSV = 0
0111 1111 1111 = 0x7FF	+2047	+9.9976 ± 0.5 LSB
0111 1111 1110 = 0x7FE	+2046	+9.9927 ± 0.5 LSB
0000 0000 0001 = 0x001	+1	+0.0073 ± 0.5 LSB
0000 0000 0000 = 0x000	0	0.0024 ± 0.5 LSB
1111 1111 1111 = 0xFFF	-1	-0.0024 ± 0.5 LSB
1000 0000 0001 = 0x801	-2047	-9.9927 ± 0.5 LSB
1000 0000 0000 = 0x800	-2048	-9.9976 ± 0.5 LSB

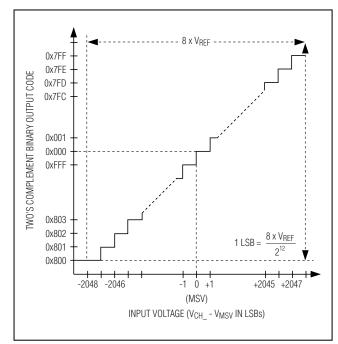


Figure 14. ±10V Bipolar Transfer Function

### **3-Phase Motor Controller**

The MAX1304–MAX1306/MAX1308–MAX1310/MAX1312–MAX1314 are ideally suited for motor-control systems (Figure 15). The devices' simultaneously sampled inputs eliminate the need for complicated DSP algo-

rithms that realign sequentially sampled data into a simultaneous sample set. Additionally, the variety of input voltage ranges allows for flexibility when choosing current sensors and position encoders.

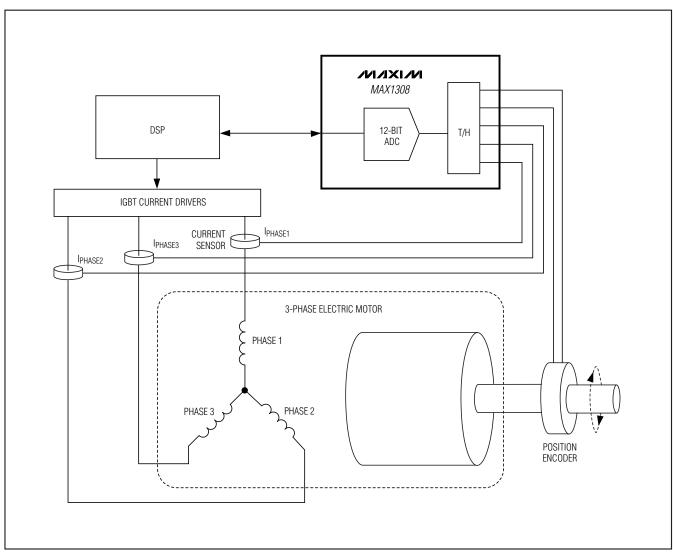


Figure 15. 3-Phase Motor Control

# 3-Phase Power-Monitoring System

The 8-channel devices are well suited for use in 3-phase power monitoring (Figure 16). The simultane-

ously sampled eight channels eliminate the need for complicated DSP algorithms that realign sequentially sampled data into a simultaneous sample set.

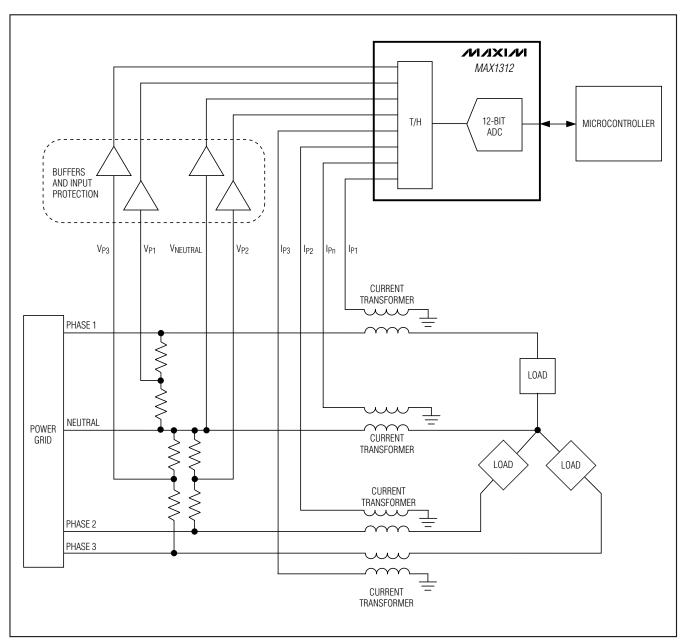


Figure 16. 3-Phase Power Monitoring

# Layout, Grounding, and Bypassing

For best performance use PC boards. Board layout must ensure that digital and analog signal lines are separated from each other. Do not run analog and digital lines parallel to one another (especially clock lines), and do not run digital lines underneath the ADC package.

Figure 17 shows the recommended system ground connections. Establish an analog ground point at AGND and a digital ground point at DGND. Connect all analog grounds to the analog ground point. Connect all digital grounds to the digital ground point. For lowest noise operation, make the power-supply ground returns as low impedance and as short as possible. Connect the analog ground point to the digital ground point at one location.

High-frequency noise in the power supplies degrades the ADC's performance. Bypass the analog power plane to the analog ground plane with a 2.2µF capacitor within one inch of the device. Bypass each AVDD to AGND pair of pins with a 0.1µF capacitor as close to the device as possible. AVDD to AGND pairs are pin 1 to pin 2, pin 14 to pin 15, and pin 16 to pin 17. Likewise, bypass the digital power plane to the digital ground plane with a 2.2µF capacitor within one inch of the device. Bypass each DVDD to DGND pair of pins with a 0.1µF capacitor as close to the device as possible. DVDD to DGND pairs are pin 24 to pin 25, and pin 38 to pin 39. If a supply is very noisy use a ferrite bead as a lowpass filter as shown in Figure 17.

### **Definitions**

### Integral Nonlinearity (INL)

INL is the deviation of the values on an actual transfer function from a straight line. For these devices, this straight line is drawn between the endpoints of the transfer function, once offset and gain errors have been nullified.

### **Differential Nonlinearity (DNL)**

DNL is the difference between an actual step width and the ideal value of 1 LSB. For these devices, the DNL of each digital output code is measured and the worst-case value is reported in the *Electrical Characteristics* table. A DNL error specification of less than  $\pm 1$  LSB guarantees no missing codes and a monotonic transfer function.

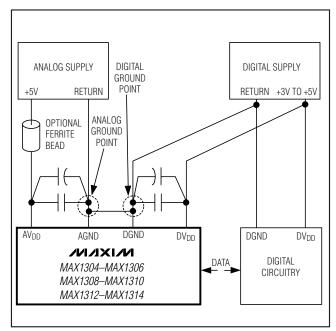


Figure 17. Power-Supply Grounding and Bypassing

### Offset Error

Offset error is a figure of merit that indicates how well the actual transfer function matches the ideal transfer function at a single point. Typically the point at which offset error is specified is either at or near the zero-scale point of the transfer function or at or near the midscale point of the transfer function.

For the unipolar devices (MAX1304/MAX1305/MAX1306), the ideal zero-scale transition from 0x000 to 0x001 occurs at 1 LSB above AGND (Figure 12, Table 5). Unipolar offset error is the amount of deviation between the measured zero-scale transition point and the ideal zero-scale transition point.

For the bipolar devices (MAX1308/MAX1309/MAX1310/MAX1312/MAX1313/MAX1314), the ideal midscale transition from 0xFFF to 0x000 occurs at MSV (Figures 14 and 13, Tables 7 and 6). The bipolar offset error is the amount of deviation between the measured midscale transition point and the ideal midscale transition point.

### **Gain Error**

Gain error is a figure of merit that indicates how well the slope of the actual transfer function matches the slope of the ideal transfer function. For the MAX1304–MAX1306/MAX1308–MAX1310/MAX1312–MAX1314, the gain error is the difference of the measured full-scale and zero-scale transition points minus the difference of the ideal full-scale and zero-scale transition points.

For the unipolar devices (MAX1304/MAX1305/MAX1306), the full-scale transition point is from 0xFFE to 0xFFF and the zero-scale transition point is from 0x000 to 0x001.

For the bipolar devices (MAX1308/MAX1309/MAX1310/MAX1312/MAX1313/MAX1314), the full-scale transition point is from 0x7FE to 0x7FF and the zero-scale transition point is from 0x800 to 0x801.

# Signal-to-Noise Ratio (SNR)

For a waveform perfectly reconstructed from digital samples, the theoretical maximum SNR is the ratio of the full-scale analog input (RMS value) to the RMS quantization error (residual error). The ideal, theoretical minimum analog-to-digital noise is caused by quantization error only and results directly from the ADC's resolution (N bits):

$$SNR_{dB[max]} = 6.02_{dB} \times N + 1.76_{dB}$$

In reality, there are other noise sources such as thermal noise, reference noise, and clock jitter.

For these devices, SNR is computed by taking the ratio of the RMS signal to the RMS noise. RMS noise includes all spectral components to the Nyquist frequency excluding the fundamental, the first five harmonics, and the DC offset.

### Signal-to-Noise Plus Distortion (SINAD)

SINAD is computed by taking the ratio of the RMS signal to the RMS noise plus distortion. RMS noise plus distortion includes all spectral components to the Nyquist frequency excluding the fundamental and the DC offset.

$$SINAD(dB) = 20 \times log \left( \frac{SIGNAL_{RMS}}{(NOISE + DISTORTION)_{RMS}} \right)$$

# **Effective Number of Bits (ENOB)**

ENOB specifies the dynamic performance of an ADC at a specific input frequency and sampling rate. An ideal ADC's error consists of quantization noise only. ENOB for a full-scale sinusoidal input waveform is computed as:

$$ENOB = \frac{SINAD - 1.76}{6.02}$$

# **Total Harmonic Distortion (THD)**

THD is the ratio of the RMS sum of the first five harmonics to the fundamental itself. This is expressed as:

THD = 20 x log 
$$\left( \frac{\sqrt{V_2^2 + V_3^2 + V_4^2 + V_5^2 + V_6^2}}{V_1} \right)$$

where  $V_1$  is the fundamental amplitude, and  $V_2$  through  $V_6$  are the amplitudes of the 2nd- through 6th-order harmonics.

# Spurious-Free Dynamic Range (SFDR)

SFDR is the ratio of the RMS amplitude of the fundamental (maximum signal component) to the RMS value of the next largest spurious component, excluding DC offset. SFDR is specified in decibels relative to the carrier (dBc).

### **Channel-to-Channel Isolation**

Channel-to-channel isolation indicates how well each analog input is isolated from the others. The channel-to-channel isolation for these devices is measured by applying DC to channel 1 through channel 7 while an AC 500kHz, -0.4dBFS sine wave is applied to channel 0. An FFT is taken for channel 0 and channel 1 and the difference (in dB) of the 500kHz magnitudes is reported as the channel-to-channel isolation.

### **Aperature Delay**

Aperture delay (t<sub>AD</sub>) is the time delay from the CONVST rising edge to the instant when an actual sample is taken.

### **Aperture Jitter**

Aperture Jitter (t<sub>AJ</sub>) is the sample-to-sample variation in aperture delay.

Jitter is a concern when considering an ADC's dynamic performance, e.g., SNR. To reconstruct an analog input from the ADC digital outputs, it is critical to know the time at which each sample was taken. Typical applications use an accurate sampling clock signal that has low jitter from sampling edge to sampling edge. For a system with a perfect sampling clock signal, with no clock jitter, the SNR performance of an ADC is limited by the ADC's internal aperture jitter as follows:

$$SNR = 20 \times log \left( \frac{1}{2 \times \pi \times f_{IN} \times t_{AJ}} \right)$$

where  $f_{\mbox{\scriptsize IN}}$  represents the analog input frequency and  $t_{\mbox{\scriptsize AJ}}$  is the time of the aperture jitter.

# **Small-Signal Bandwidth**

A small -20dBFS analog input signal is applied to an ADC so that the signal's slew rate does not limit the ADC's performance. The input frequency is then swept up to the point where the amplitude of the digitized conversion result has decreased by -3dB.

### **Full-Power Bandwidth**

A large, -0.5dBFS analog input signal is applied to an ADC, and the input frequency is swept up to the point where the amplitude of the digitized conversion result has decreased by -3dB. This point is defined as full-power input bandwidth frequency.

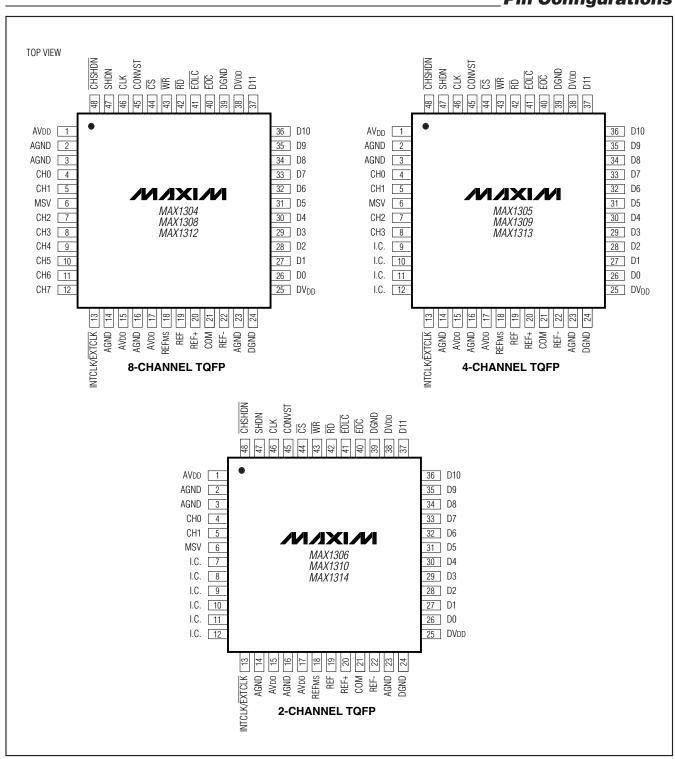
# **DC Power-Supply Rejection (PSRR)**

DC PSRR is defined as the change in the positive full-scale transfer function point caused by a  $\pm 5\%$  variation in the analog power-supply voltage (AVDD).

# WAX1304-MAX1306/MAX1308-MAX1310/MAX1312-MAX1314

# 8-/4-/2-Channel, 12-Bit, Simultaneous-Sampling ADCs with ±10V, ±5V, and 0 to +5V Analog Input Ranges

**Pin Configurations** 



**Chip Information** 

TRANSISTOR COUNT: 50,000 PROCESS: 0.6µm BiCMOS

# Package Information

For the latest package outline information and land patterns, go to **www.maxim-ic.com/packages**.

PACKAGE TYPE	PACKAGE CODE	DOCUMENT NO.
48 TQFP	C48+6	21-0054

**Revision History** 

REVISION NUMBER	REVISION DATE	DESCRIPTION	
4	8/09	Added automotive part numbers	1

Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time.