Recitation 2: Fast Fourier Transform

1 The Fast Fourier Transform

Recall the Fast Fourier Transform from lecture this week as an algorithm for multiplying two polynomials as follows. Let A and B be two degree bound n (degree $\leq n$) polynomials expressed as follows.

$$A(x) = a_0 + a_1 x + a_2 x^2 + \ldots + a_{n-1} x^{n-1}$$
(1)

$$B(x) = b_0 + b_1 x + b_2 x^2 + \ldots + b_{n-1} x^{n-1}$$
(2)

We call the length n vector $(a_0, a_1, \ldots, a_{n-1})$ the coefficient vector representation for A and similarly, $(b_0, b_1, \ldots, b_{n-1})$ is the coefficient vector representation for B. Equivalently, since any polynomial P is uniquely determined by its evaluations on $\geq degree(P) + 1$ points, A and B can also be represented by n points evaluated on the polynomial. We call this the point-value representation.

The product polynomial $C(x) = A(x) \cdot B(x)$ has degree $2 \cdot (n-1) < 2n$. Note that the first coefficient of C(x) is $c_0 = a_0b_0$, the second coefficient is $c_1 = a_0b_1 + a_1b_0$, ..., and the last coefficient is $c_{2n-2} = a_{n-1}b_{n-1}$. In general the coefficient c_k is given as follows.

$$c_k = \sum_{i=0}^k a_i b_{k-i} \tag{3}$$

Equation (3) is also known as the *convolution* of the coefficient vectors of A and B. Multiplying polynomials A and B, can now be expressed more mathematically as convolving their coefficient vectors. Note that trivially, it would take $O(n^2)$ time to compute this convolution. However, if A and B were evaluated at the same 2n points i.e. they were in point-value representation, multiplying them is easy. Simply do a point-wise multiplication in O(n) time. Using this trick, as we saw in lecture, the Fast Fourier Transform allows us to compute this convolution in time $O(n \log n)$.

$$A(x), B(x) \text{ coefficient representation} \xrightarrow{\qquad \qquad O(n^2) \qquad \qquad C(x) \text{ coefficient representation}} \\ FFT \downarrow O(n \log n) \qquad \qquad O(n \log n) \qquad \qquad O(n \log n) \qquad \text{Inverse FFT} \\ A(x), B(x) \text{ point-value representation} \xrightarrow{\qquad C(x) = A(x) \cdot B(x) \qquad } C(x) \text{ point-value representation}$$

Recall our algorithm for polynomial multiplication:

- 1. Evaluate polynomials A(x) and B(x) on the same 2n locations $\{x_0, x_1, \dots, x_{2n-1}\}$. $(O(n \log n)$ time using FFT)
- 2. Point-wise multiply the polynomials to obtain a point-value representation of $C(x) = A(x) \cdot B(x)$. (O(n) time)
- 3. Compute the coefficient vector for C from the point-value representation. This is called *interpolation*. $(O(n \log n)$ time using Inverse FFT)

For step (1), we will choose the N-th roots of unity, where $N=2^k$ is a power of 2 so that 2n <= N < 4n (Note that N=O(n) and we could also have more than 2n points). The N-th roots of unity are given as $\{w^0, w^1, \ldots, w^{N-1}\}$ where $w=e^{\frac{2\pi i}{N}}$. Note that $(w^k)^N=1$ for $k \in \{0\ldots N-1\}$.

Let y_k be value of A at $x_k = w^k$, we wish to evaluate A at all the roots of unity and find y_0, y_1, \dots, y_{N-1} as follows:

$$y_k = \sum_{j=0}^{n-1} a_j e^{\frac{2\pi i k j}{N}} \tag{4}$$

Equation (4) is called the Discrete Fourier Transform (DFT) of A. The Fast Fourier Transform computes the DFT in $O(n \log n)$ time. The FFT to evaluate A at all the N-th roots of unity (also called DFT) is a divide and conquer algorithm given as follows:

1. Define

$$A_{even}(x) = a_0 + a_2 x + a_4 x^2 + \ldots + a_{n-1} x^{(n-1)/2}$$
(5)

$$A_{odd}(x) = a_1 + a_3 x + a_5 x^2 + \ldots + a_{n-2} x^{(n-3)/2}$$
(6)

Hence

$$A(x) = A_{even}(x^2) + xA_{odd}(x^2)$$

$$\tag{7}$$

Note that this is simply algebraic manipulation. Nothing special going on here. However, note that A_{even} and A_{odd} are degree bound $\frac{n}{2}$ polynomials.

2. Recursively evaluate $A_{even}(x)$ and $A_{odd}(x)$ on the squares of the N-th roots of unity.

$$\{(w^0)^2, (w^1)^2, \dots, (w_{N-1})^2\}$$

But note that this set is the $\frac{N}{2}$ -th roots of unity and has size $\frac{N}{2}$ (all the values in the second half of the set are a repeat of the first half, you can verify this easily). Hence, only $\frac{N}{2}$ evaluations need to be performed on $A_{even}(x)$ and $A_{odd}(x)$.

3. Evaluate A(x) on all the N-th roots of unity using (7) and the recursively computed values for $A_{even}(x)$ and $A_{odd}(x)$.

We are now ready to compute the runtime for the FFT. Step (1) divides the problem into 2 problems of half the size (both in the degree of the polynomials and the number of evaluations). And it takes O(N) time to perform the necessary additions in step (3). Hence, we have $T(N) = 2T(\frac{N}{2}) + O(N)$ which evaluates to $T(N) = \Theta(N \log N) = \Theta(n \log N)$ since $N = \Theta(n)$.

Hence, going back to our polynomial multiplication algorithm, we have performed step (1) in $O(n \log n)$ time. Step (2) is trivially O(n) time to perform the point-wise multiplication. For step (3), we need to interpolate the evaluations of C to find the coefficient vector for C. The coefficient c_k can be obtained from the evaluations of C, y_t 's, as follows:

$$c_k = \frac{1}{N} \sum_{t=0}^{N-1} y_t e^{\frac{-2\pi i t k}{N}}$$
 (8)

This can easily be proven by plugging in the value of $y_t = \sum_{j=0}^{N-1} c_j e^{\frac{2\pi i j t}{N}}$ since we know the y_t 's are the evaluations of C at the N-th roots of unity.

$$c_k = \frac{1}{N} \sum_{t=0}^{N-1} y_t e^{\frac{-2\pi i t k}{N}}$$
 (9)

$$= \frac{1}{N} \sum_{t=0}^{N-1} \left(\sum_{j=0}^{N-1} c_j e^{\frac{2\pi i j t}{N}} \right) e^{\frac{-2\pi i t k}{N}}$$
 (10)

$$= \frac{1}{N} \sum_{j=0}^{N-1} \left(c_j \sum_{t=0}^{N-1} e^{\frac{2\pi i t (j-k)}{N}} \right)$$
 (11)

$$=\frac{1}{N}c_kN=c_k\tag{12}$$

Note that in (11), $\sum_{t=0}^{N-1} e^{\frac{2\pi i t (j-k)}{N}} = N \cdot \delta_{j-k}$ is N if j=k and 0 otherwise.

Hence, (8) is known as the Inverse DFT, which is the same as the DFT but with a scaling factor and a minus sign. This can also be used with the Fast Fourier Transform using as evaluation points $\{w^0, w^{-1}, \cdots, w^{-(N-1)}\}$ which is also a collapsing set of the roots of unity.

Hence, in step (3) of our polynomial multiplication algorithm, the interpolation takes $O(n \log n)$ to obtain the polynomial C(x) in coefficient form using the Fast Fourier Transform. Hence overall, we can multiply the two polynomials in $O(n \log n)$ time.

1.1 Minkowski Sum using FFT

Let X and Y be length n sets of integers in the range $\{0, ..., m-1\}$. The Minkowski Sum X+Y is defined as the set:

$$X + Y = \{x + y \mid x \in X, y \in Y\}$$
(13)

We want to compute the size |X + Y|.

Naively, we can look through all n^2 pairs $(x,y)|x\in X,y\in Y$ and sum them up. We can then maintain a binary search tree of the values in order to avoid duplicate entries. Initialize a counter i=0. Each time we insert a new value into the BST, increment i by 1. At the end of the process, i will be the size of X+Y. This process takes $O(n^2\log n)$. If we use a different, perhaps randomized (Hash Table) method of avoiding duplicates, we could get a better runtime, but even this will take $\Omega(n^2)$ time.

We will now use the Fast Fourier Transform to solve this in $O(m \log m)$ time instead. The algorithm is as follows:

- 1. Construct a degree bound m polynomial $P_X(x)$ that has coefficient 1 for term x^k if $k \in X$, 0 otherwise.
- 2. Similarly, construct a degree bound m polynomial $P_Y(x)$ that has coefficient 1 for term x^k if $k \in Y$, 0 otherwise.
- 3. Multiply polynomials $P_{X+Y} = P_X(x) \cdot P_Y(x)$ using FFT.
- 4. Return the number of terms in P_{X+Y} that have a non-zero coefficient.

Note that by our construction, the coefficient of term $a_k x^k$ in P_{X+Y} is exactly the number of ways that numbers in X and Y can sum to k. If a_k is greater than 0, that means there exists values $x \in X$ and $y \in Y$ such that x + y = k. Hence, |X + Y| is equal to the number of non-zero coefficients in P_{X+Y} .

Steps (1), (2) and (4) take O(m) time and step (2) takes $O(m \log m)$ time. Hence, the overall cost of this algorithm is $O(m \log m)$. Note that if m = O(n), this is $O(n \log n)$.

Note: One common mistake is to try to use FFT when the integers in X and Y are not bounded. If so, the integers in X and Y can get arbitrarily large, so the polynomials corresponding to X and Y will also be very large. Using FFT on those high degree polynomials could then take a lot of time.