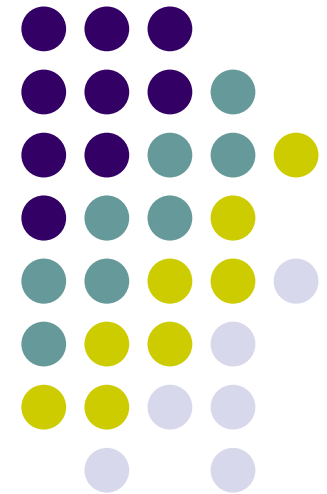


Evaluation Methodology

J. Savoy
Université de Neuchâtel

Ian H. Witten, Eibe Frank, M. A. Hall: Data Mining.
Practical Machine Learning Tools and Techniques. Morgan
Kaufmann.





Overview

- Issues: training, testing, tuning
- Predicting performance: confidence limits
- Holdout, cross-validation, bootstrap
- Comparing schemes: the t -test
- Predicting probabilities: loss functions
- Cost-sensitive measures
- Evaluating numeric prediction
- The Minimum Description Length (MDL) principle



Evaluation: the Key to Success

- How predictive is the model we learned?
- Error on the training data is *not* a very good indicator of performance on future data
 - Otherwise 1-NN (or table look-up) would be the optimum classifier!
- Simple evaluation approaches that can be used if a lot of (labeled) data is available (e.g., simulation)
 - Usually split data into training and test sets
- However: (labeled) data is usually limited
 - More sophisticated techniques need to be used
 - What is the cost to obtain more labeled data?



Issues in Evaluation

- Statistical reliability of estimated differences in performance (→ significance tests)
Is a performance difference between 45.8 vs. 45.6 really significant (or due to random factors)?
- Choice of performance measure:
 - Number of correct classifications
 - Accuracy of probability estimates (e.g., naïve Bayes)
 - Error in numeric predictions (e.g., regression)
- Costs assigned to different types of errors
 - Many practical applications involve costs
- The Italian seismologists in 2012 (6 years in jail!)



Training and Testing

- Natural performance measure for classification problems: *error rate*
 - *Success*: instance's class is predicted correctly
 - *Error*: instance's class is predicted incorrectly
 - Error rate: proportion of errors made over the whole set of instances
- *Resubstitution error (apparent error)*: error rate obtained from training data
- Resubstitution error is (hopelessly) optimistic!



Training and Testing

- *Test set*: independent instances that have played no part in formation of classifier
 - Assumption: both training data and test data are representative samples of the underlying problem
- Test and training data may differ in nature
 - Example: classifiers built using customer data from two different towns *A* and *B*

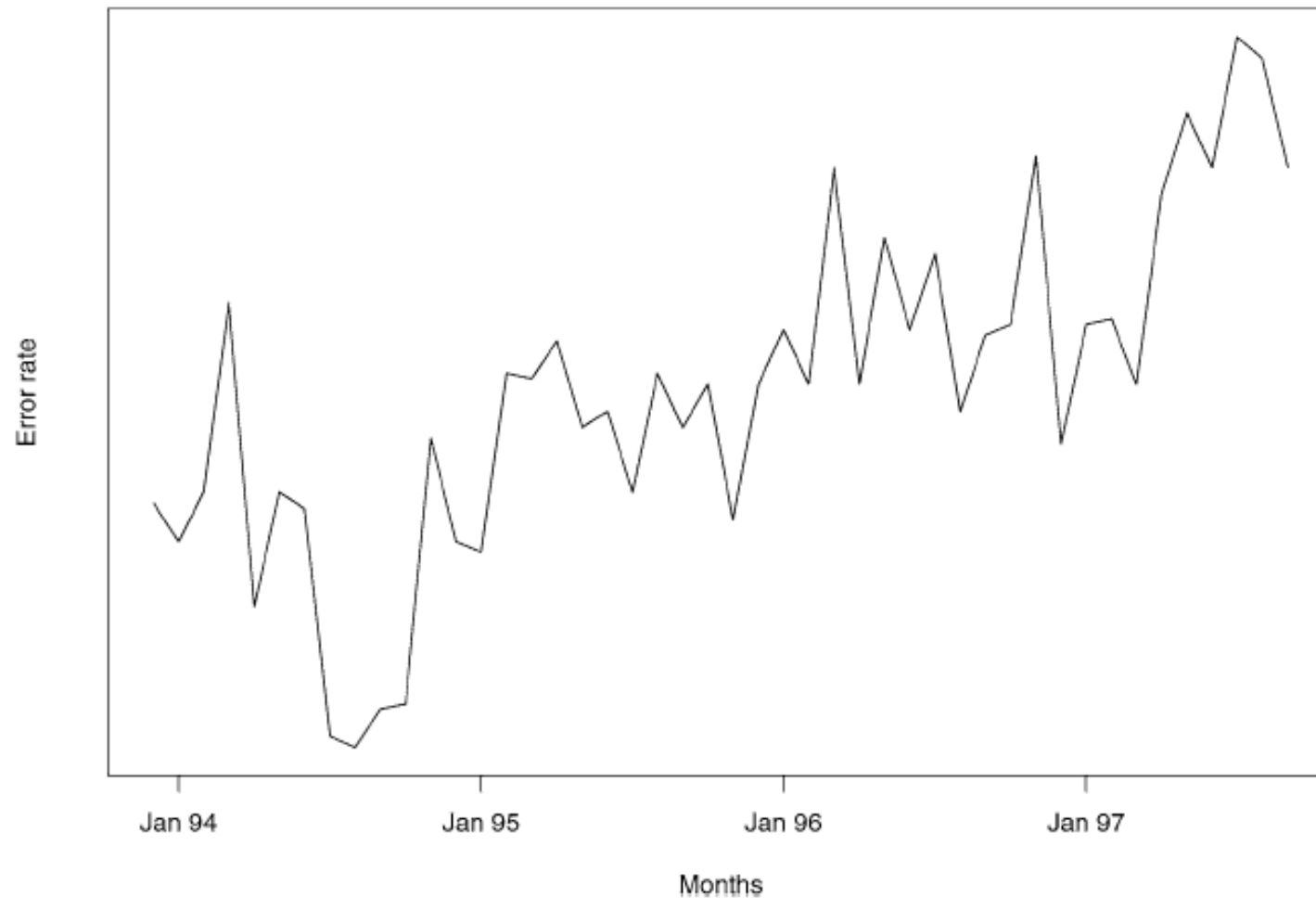
To estimate performance of classifier from town *A* in completely new town *B*

Thus both samples must *representative*

But the evolution may change this factor!



The evolution (of the error rate)



Hand, D.J.. (2006). Classifier Technology and the Illusion of Progress. *Statistical Science*, 21(1), 1-14.



Parameter Tuning

- It is important that the test data is not used *in any way* to create the classifier
- Some learning schemes operate in two stages:
 - Stage 1: build the basic structure (training set)
 - Stage 2: optimize parameter settings / do some selections (validation set)
- The test data can't be used for parameter tuning!
Trump's philosophy: build walls
- In this case, proper procedure uses *three* sets: *training data*, *validation data*, and *test data*
- How much in each case?



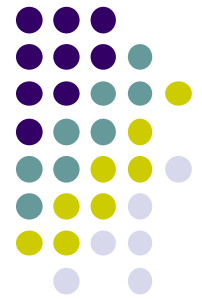
Making the Most of the Data

- Once evaluation is complete, *all the data* can be used to build the final classifier
- Generally, the larger the training data the better the classifier (but returns diminish, at some point the gain is minimal)
- The larger the test data the more accurate the error estimate
- *Holdout* procedure: method of splitting original data into training and test set
 - Dilemma: ideally both training set *and* test set should be large!



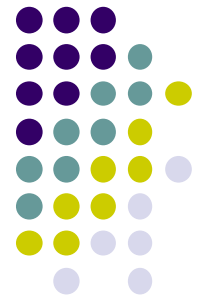
Predicting Performance

- Assume the estimated error rate is 25%.
How close is this to the true error rate?
 - Depends on the amount of test data
- Prediction is just like tossing a (biased!) coin
 - head is a *success*, tail is an *error*
- In statistics, a succession of independent events like this is called a *Bernoulli process*
 - Statistical theory provides us with confidence intervals for the true underlying proportion



Confidence Intervals

- We can say: p (*true proportion*) lies within a certain specified interval with a certain specified confidence
- Example: $S = 750$ successes in $N = \mathbf{1,000}$ trials
 - Estimated success rate: 75%
 - How close is this to true success rate p ?
 - Answer: with 80% confidence p in $[73.2, 76.7]$
- Another example: $S = 75$ and $N = \mathbf{100}$
 - Estimated success rate: 75%
 - With 80% confidence p in $[69.1, 80.1]$
- Increasing N reduces the uncertainty



Mean and Variance

- Mean and variance for a Bernoulli trial: p and $p \cdot (1-p)$
- Expected success rate (estimation) $f = S/N$
- Mean and variance for f : p and $p \cdot (1-p)/N$
- For large enough N , f follows a Normal distribution
- $c\%$ confidence interval $[-z \leq X \leq z]$ for a normal random variable is given by:

$$Prob[-z \leq X \leq z] = c$$

- With a symmetric distribution:

$$Prob[-z \leq X \leq z] = 1 - 2 \cdot Prob[X \geq z]$$



Confidence Limits

- Confidence limits for the normal distribution
 $N(\mu = 0, \sigma = 1)$

Prob [$X \geq z$]	0.1%	0.5%	1%	2.5%	5%	10%
z	3.09	2.58	2.33	1.96	1.65	1.28

- Thus: $Prob[-1.96 \leq X \leq +1.96] = 95\%$ (or 0.95)
 $Prob[-2.58 \leq X \leq +2.58] = 99\%$ (or 0.99)
- To use this we have to reduce our random variable f to have 0 mean and unit variance



Transform f

- Transformed value for f :
(i.e. subtract the mean
and divide by its
standard deviation)

$$\frac{f - p}{\sqrt{\frac{p \cdot (1-p)}{N}}}$$

- Resulting equation:

$$Prob\left[-z \leq \left(\frac{f - p}{\sqrt{\frac{p \cdot (1-p)}{N}}}\right) \leq +z\right] = c$$

- Solving for p :

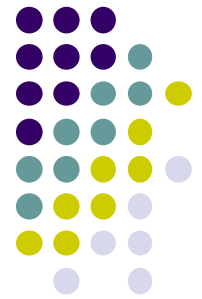
$$p = \frac{\left(f + \frac{z^2}{2 \cdot N} \pm z \cdot \sqrt{\frac{f}{N} - \frac{f^2}{N} + \frac{z^2}{4 \cdot N^2}}\right)}{1 + \frac{z^2}{N}}$$

you have two values for p
because you have a \pm sign



Examples

- $f = 75\%$, $N = \mathbf{1,000}$, $c = 80\%$ (so that $z = 1.28$):
 $p \in [0.732, 0.767]$
- $f = 75\%$, $N = \mathbf{100}$, $c = 80\%$ (so that $z = 1.28$):
 $p \in [0.691, 0.801]$
- Note that Normal distribution assumption is only valid for large N (i.e. $N > 100$)
- $f = 75\%$, $N = \mathbf{10}$, $c = 80\%$ (so that $z = 1.28$):
 $p \in [0.560, 0.870]$
(should be taken with a grain of salt)



Better confidence intervals

- Expected success rate (estimation) $f' = (S+2) / (N+4)$
for $c = 95\%$
Otherwise:

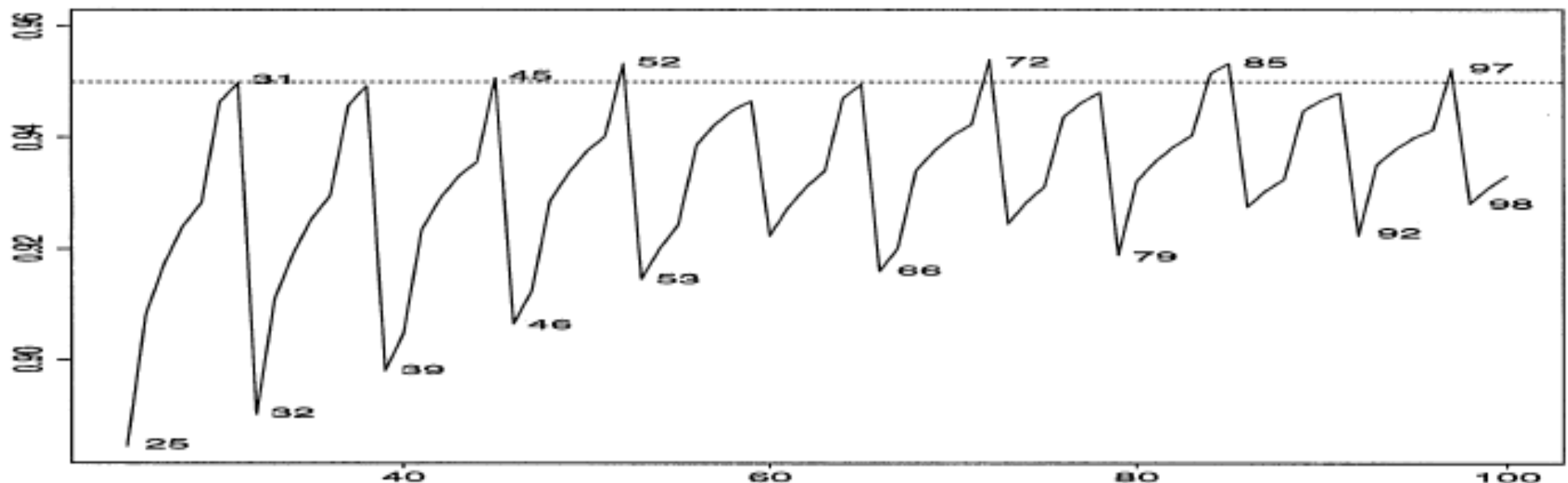


FIG. 1. *Standard interval; oscillation phenomenon for fixed $p = 0.2$ and variable $n = 25$ to 100.*

Brown, L.D., Cai, T.T, DasGupta, A. (2001). Interval estimation for a binomial proportion.
Statistical Science, 16(2), 101-133



Holdout Estimation

- What to do if the amount of data is limited?
- The *holdout* method reserves a certain amount for testing and uses the remainder for training
 - Usually: one third for testing, the rest for training
- Problem: the samples might not be representative
 - Example: class might be missing in the test data
- Advanced version uses *stratification* (e.g. vote prediction)
 - Ensures that each class is represented with approximately equal proportions in both subsets
- Better solution?



Repeated Holdout Method

- Holdout estimate can be made more reliable by repeating the process with different subsamples
 - In each iteration, a certain proportion is randomly selected for training (possibly with stratification)
 - The error rates on the different iterations (err_i) are averaged to yield an overall error rate

$$\widehat{err} = \frac{1}{k} \cdot \sum_{i=1}^k err_i$$

- This is called the *repeated holdout* method (or random subsampling)
- Still not optimum: the different test sets overlap
 - Can we prevent overlapping?



Repeated Holdout Method

- Comparison of the holdout and repeated holdout method

	Holdout	Random subsampling
Training instances	j	j
Testing instances	$n-j$	$n-j$
Iterations	1	$k \ll n$



Cross-Validation

- *Cross-validation* avoids overlapping test sets
 - First step: split data into k subsets of (roughly) equal size
 - Second step: use each subset in turn for testing, the remainder for training
- Called *k-fold cross-validation*



K-fold Cross-Validation

Example: 5-fold CV

4 parts for the training, one for the test
iterate five times

1	1	1	1	1
2	2	2	2	2
3	3	3	3	3
4	4	4	4	4
5	5	5	5	5

err₁

err₂

err₃

err₄

err₅



Cross-Validation

- *Cross-validation* avoids overlapping test sets
- Called *k-fold cross-validation*
- Often the subsets are stratified before the cross-validation is performed
- The error estimates are averaged to yield an overall error estimate

$$\hat{err} = \frac{1}{k} \cdot \sum_{i=1}^k err_i$$



Cross-Validation

- Standard method for evaluation:
stratified ten-fold cross-validation
- Why ten?
 - Extensive experiments have shown that this is the best choice to get an accurate estimate
 - There is also some theoretical evidence for this
- Stratification reduces the estimate's variance
- Even better: repeated stratified cross-validation
 - E.g. ten-fold cross-validation is repeated ten times and results are averaged (reduces the variance)



Leaving-One-Out

- Leaving-One-Out: a particular form of cross-validation:
 - Set number of folds to number of training instances
 - i.e., for n training instances, build classifier n times
train on $n-1$ instances, evaluate on the n th
- Makes best use of the data
- Involves no random subsampling
- Very computationally expensive
 - (exception: NN)



Leaving-One-Out & CV

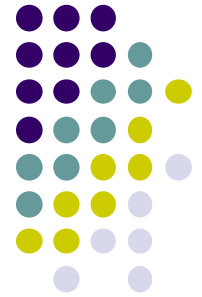
- Comparison of the leaving-one-out and 10-fold CV

	Leave-one-out	10-fold CV
Training instances	$n-1$	90%
Testing instances	1	10%
Iterations	n	10



Leaving-One-Out

- Disadvantage of Leave-One-Out: stratification is not possible
 - It *guarantees* a nonstratified sample because there is only one instance in the test set!
- Time needed to compute / learn
- Extreme example: random dataset split equally into two classes
 - Best inducer predicts majority class
 - 50% accuracy on fresh data
 - Leave-One-Out-CV estimate is 100% error!
(because if we have 50% in one case, and 50% in the other, the majority in the training set will always be in the wrong class)



The Bootstrap

- CV uses sampling *without replacement*
 - The same instance, once selected, cannot be select again for a particular training/test set
- The general idea behind the *bootstrap* can be used to estimate the standard error of *various statistics* (e.g., median, correlation coef.)
- If we have a sample $X = \{x_1, x_2, \dots, x_i, \dots, x_n\}$, we can use it to generate *with replacement* other sample (with the same size n) and putting the probability $1/n$ on each observed value x_i (non-parametric bootstrap).

$$\hat{F} \rightarrow \mathbf{x}^* = (x_1^*, x_2^*, \dots, x_n^*)$$



The Bootstrap

Procedure

1. Select B independent bootstrap samples $\mathbf{x}^{*1}, \mathbf{x}^{*2}, \dots, \mathbf{x}^{*B}$ each consisting of n data values drawn *with replacement* from \mathbf{X} (B is in the range 25 - 2,000)

$$\hat{F} \rightarrow \mathbf{x}^{*i} = (x_1^*, x_2^*, \dots, x_n^*)$$

2. Evaluate the bootstrap replication corresponding to each bootstrap sample

$$\hat{\theta}^*(b) = s(\mathbf{x}^{*b}) \text{ with } b = 1, 2, \dots, B$$

where θ is the statistics of interest computed using the appropriate function $s()$ (e.g., the median)



The Bootstrap

Procedure

3. Estimate the standard error $se_F(\hat{\theta})$
by the sample standard deviation of the B replications

$$\hat{se}_B = \sqrt{\sum_{b=1}^B [\hat{\theta}^*(b) - \hat{\theta}^*(.)]^2 / (B - 1)}$$

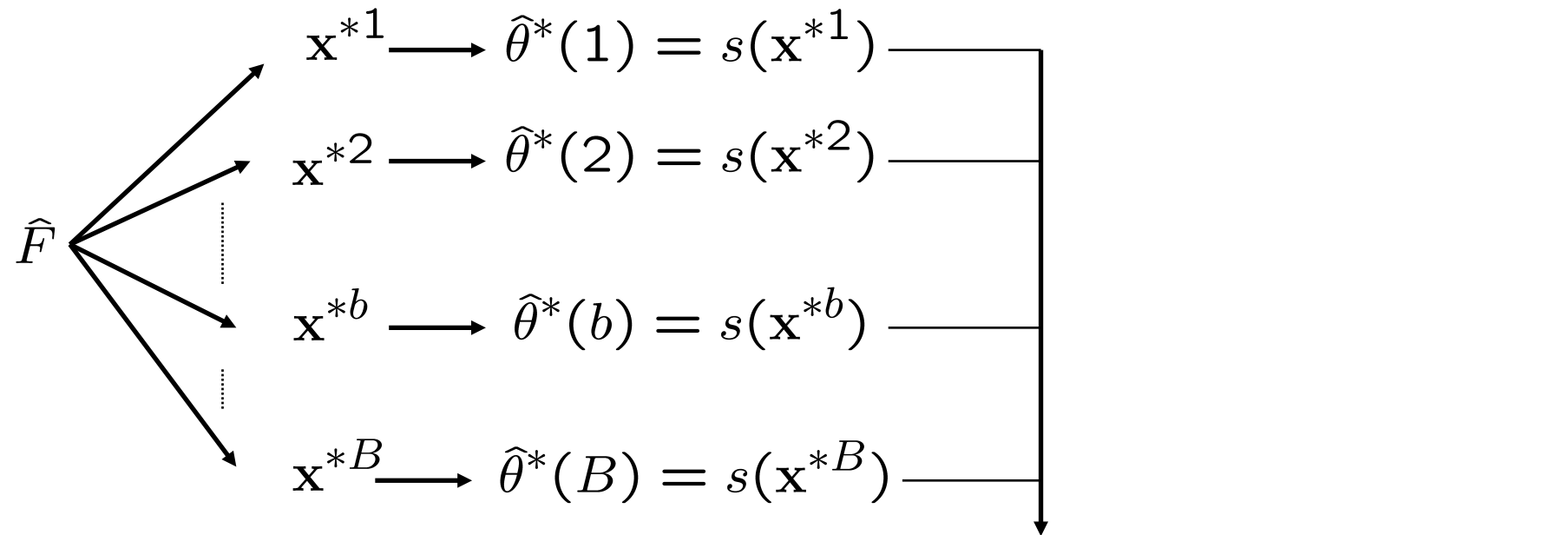
$$\text{with } \hat{\theta}^*(.) = 1/B \cdot \sum_{b=1}^B \hat{\theta}^*(b)$$

and knowing that $\lim_{B \rightarrow \infty} \hat{se}_B = se_{\hat{F}} = se_{\hat{F}}(\hat{\theta}^*)$



The Bootstrap

Example



$$\hat{se}_B = \sqrt{\sum_{b=1}^B [\hat{\theta}^{*}(b) - \hat{\theta}^{*}(.)]^2 / (B - 1)}$$

$$\text{with } \hat{\theta}^{*}(.) = 1/B \cdot \sum_{b=1}^B \hat{\theta}^{*}(b)$$



The Bootstrap

- In our context, the *bootstrap* uses sampling *with replacement* to form the training set
 - Sample a dataset of n instances n times *with replacement* to form a new dataset of n instances
 - Use this data as the training set
 - Use the instances from the original dataset that don't occur in the new training set for testing



The Bootstrap

- Also called the *0.632 bootstrap*
- A particular instance has a probability $1/n$ of being picked
- Thus an instance has a probability of $1-(1/n)$ of *not* being picked
- Thus its probability of ending up in the test data is:

$$\left[1 - \frac{1}{n}\right]^n \approx e^{-1} \approx 0.368$$

- This means that the training data will contain approximately 63.2% of the instances



The Bootstrap

- The error estimate on the test data will be very pessimistic
 - Trained on just ~63% of the instances
- Therefore, combine it with the resubstitution error:

$$err = 0.632 \cdot e_{test\ instances} + 0.368 \cdot e_{training\ instances}$$

- The resubstitution error gets less weight than the error on the test data
- Repeat process several times with different replacement samples; average the results



The Bootstrap

- Bootstrap estimators

	Bootstrap
Training instances	n (with j unique)
Testing instances	$n-j$
Iterations	200

Efron b., & Tibshirani R.J.: An Introduction to the Bootstrap, Chapman & Hall, New York, 1993

Comparing Data Mining Schemes



- Frequent question: which of two learning schemes performs better?
- Note: this is domain dependent!
- Obvious way: compare 10-fold CV estimates
- Generally sufficient in applications
- However, what about machine learning research?
 - Need to show convincingly that a particular method works better

Comparing Data Mining Schemes



- Want to show that scheme A is better than scheme B in a particular domain
 - For a given amount of training data
 - On average, across all possible training sets
- Let's assume we have an infinite amount of data from the domain:
 - Sample infinitely many dataset of specified size
 - Obtain cross-validation estimate on each dataset for each scheme
 - Check if mean accuracy for scheme A is better than mean accuracy for scheme B



A Practical Example

Which one is the best?

Why?

$n = 10$

By intuition?

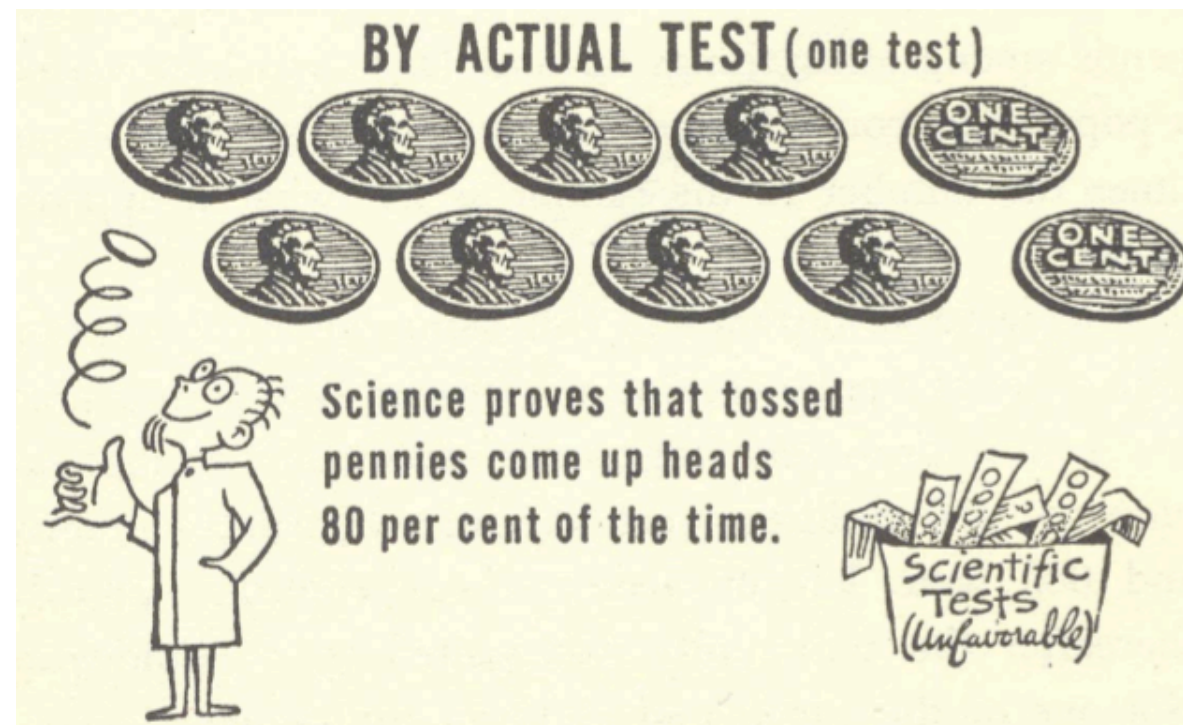
(toy-sided
for demo only!)

obs.	X_i	Y_i
1	0.84	0.88
2	0.78	0.97
3	0.67	0.74
4	0.87	0.80
5	0.80	0.87
6	0.78	0.90
7	0.78	0.90
8	0.79	0.86
9	0.82	0.84
10	0.81	0.78
sum	7.94	8.54

Formal (scientific) procedure



A scientific methodology





Paired t -Test

- In practice we have limited data and a limited number of estimates for computing the mean
- *Student's t -test* tells whether the means of two samples are significantly different
- In our case the samples are cross-validation estimates for different datasets from the domain
- Use a *paired t -test* because the individual samples are paired
- The same splitting for the two CV

William Gosset (1876 - 1937)
(working for Guinness)



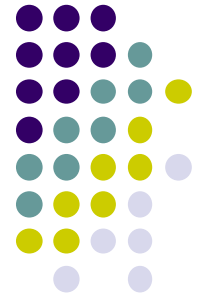
Comparing Data Mining Schemes



- If we have x_1, x_2, \dots, x_k and y_1, y_2, \dots, y_k are the $2k$ samples for the k -different datasets
- and the means \bar{x}_x and \bar{x}_y
- With enough samples, the mean of a set of independent samples is normally distributed
- Estimated variances of the means are σ_x^2/k and σ_y^2/k
- If μ_x and μ_y are the true means then

$$\frac{\bar{x}_x - \mu_x}{\sigma_x / \sqrt{k}} \text{ and } \frac{\bar{x}_y - \mu_y}{\sigma_y / \sqrt{k}} \text{ with } \hat{\sigma}_x^2 = \frac{\sum_{i=1}^k (x_i - \bar{x}_x)^2}{k - 1}$$

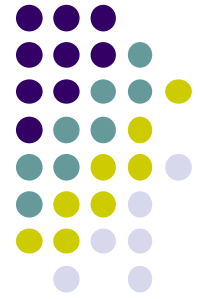
are *approximately* normally distributed with mean 0, standard deviation 1



Student's Distribution

- With small samples ($k < 100$) the mean follows *Student's distribution with $k-1$ degrees of freedom*
- Confidence limits:

Prob [$X \geq \text{lim}$]	t (9 dof)	t (10 dof)	t (20 dof)	Normal
0.05%	4.781	4.587	3.850	3.29
0.5%	3.250	3.169	2.845	2.58
1%	2.821	2.764	2.528	2.33
2.5%	2.262	2.228	2.086	1.96
5%	1.833	1.812	1.725	1.65
10%	1.383	1.3372	1.325	1.28

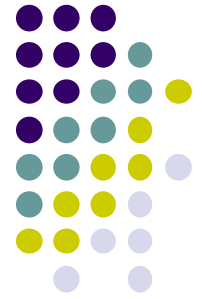


Student's Distribution

- Let $\bar{x}_d = \bar{x}_x - \bar{x}_y$ with $d_i = x_i - y_i$
- The difference of the means (\bar{x}_d) also has a Student's distribution with $k-1$ degrees of freedom
- Let σ_d^2 be the variance of the difference
- The standardized version of \bar{x}_d is called the t -statistic:

$$t_{obs} = \frac{\bar{x}_d}{\hat{\sigma}_d / \sqrt{k}} \quad \text{with} \quad \hat{\sigma}_d = \sqrt{\frac{\sum_{i=1}^k d_i^2 - \frac{\left(\sum_{i=1}^k d_i\right)^2}{k}}{k-1}}$$

- We use t_{obs} to perform the t -test ($k-1$ dof)



Student's Distribution

- Fix a significance level
 - If a difference is significant at the $\alpha\%$ level, there is a $(100-\alpha)\%$ chance that the true means differ
- Divide the significance level by two because the test is two-tailed
 - i.e. the true difference can be $+v$ or $-v$
- Look up the value for z that corresponds to $\alpha/2$
- If $t_{obs} \leq -z$ or $t_{obs} \geq z$ then the difference is significant
 - i.e. the *null hypothesis* (that the difference is zero) can be rejected

Student's Distribution

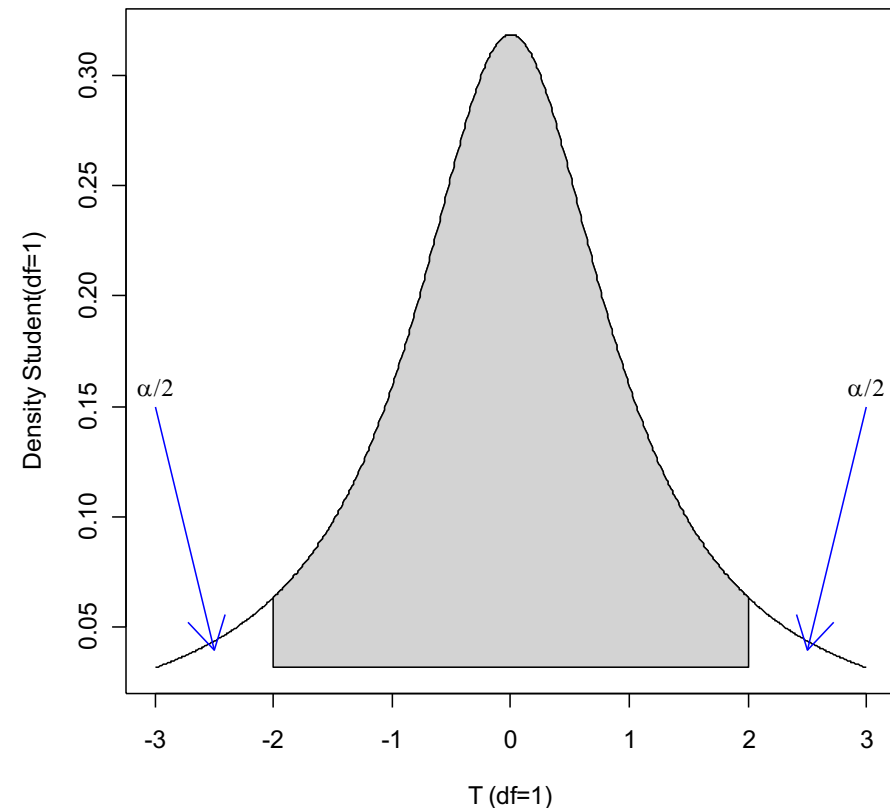


The Student distribution is symmetric.

Example with $\alpha = 5\%$

- 1) $\text{Prob}[-t_{\text{lim}} < T_{\text{df}=1} < t_{\text{lim}}] = 0.05$
- 2) $\text{Prob}[-t_{\text{lim}} < T_{\text{df}=7} < t_{\text{lim}}] = 0.05$
- 3) $\text{Prob}[-t_{\text{lim}} < T_{\text{df}=50} < t_{\text{lim}}] = 0.05$

$$\begin{aligned} \rightarrow t_{\text{lim df}=1} &= 12.71 \\ \rightarrow t_{\text{lim df}=7} &= 2.365 \\ \rightarrow t_{\text{lim df}=50} &= 2.009 \end{aligned}$$





Example

$n = 10$
(or $k = 10$)

obs.	X_i	Y_i	$X_i - Y_i$	$(X_i - Y_i)^2$
1	0.84	0.88	-0.04	0.0016
2	0.78	0.97	-0.19	0.0361
3	0.67	0.74	-0.07	0.0049
4	0.87	0.80	0.07	0.0049
5	0.80	0.87	-0.07	0.0049
6	0.78	0.90	-0.12	0.0144
7	0.78	0.90	-0.12	0.0144
8	0.79	0.86	-0.07	0.0049
9	0.82	0.84	-0.02	0.0004
10	0.81	0.78	0.03	0.0009
sum	7.94	8.54	-0.60	0.0874



Example

When need to compute the value t_{obs} according to your data

$$t_{obs} = \frac{\bar{x}_d}{\sigma_d / \sqrt{k}}$$

And then the estimated standard deviation

$$\hat{\sigma}_d = \sqrt{\frac{\sum_{i=1}^k d_i^2 - \frac{\left(\sum_{i=1}^k d_i\right)^2}{k}}{k - 1}}$$



Example

$$k = 10$$

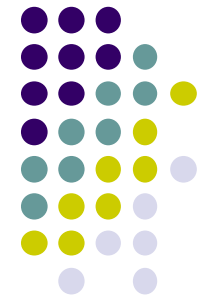
$$\hat{\sigma}_d = \sqrt{\frac{\sum_{i=1}^k d_i^2 - \frac{\left(\sum_{i=1}^k d_i\right)^2}{k}}{k-1}} = 0.07557$$

$$t_{obs} = \frac{\bar{x}_d}{\sigma_d / \sqrt{k}} = -0.06 / (0.07557 / \sqrt{10}) = -2.51$$

Theoretical limit Student 9 dof, $\alpha = 5\%$ $t_{lim} = 2.262$

Decision: Reject H_0

Another test: (unpaired) t -test $t_{obs} = -2.231$



Another View: Excel

A	B	C
1	X	Y
2	0.84	0.88
3	0.78	0.97
4	0.67	0.74
5	0.87	0.8
6	0.8	0.87
7	0.78	0.9
8	0.78	0.9
9	0.79	0.86
10	0.82	0.84
11	0.81	0.78

Data row

Two-tailed or
on-tailed?

Paired=1
Normal=2

In cell E2

= TTEST(B2:B11, C2:C11, 2, 1)

In cell E3

= TTEST(B2:B11, C2:C11, 2, 2)

A	D	E
1		
2	paired	3.33%
3	normal	3.86%
4		

Return the p-value, probability of having the
corresponding t_{obs} value or larger

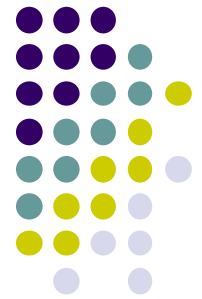


Predicting Probabilities

- Performance measure so far: success rate
- Also called *0-1 loss function*:

$$\sigma_i = \begin{cases} 0 & \text{if prediction is correct} \\ 1 & \text{if prediction is incorrect} \end{cases}$$

- Most classifiers produces class probabilities
- Depending on the application, we might want to check the accuracy of the probability estimates
- 0-1 loss is not the right thing to use in those cases



Quadratic Loss Function

- p_1, p_2, \dots, p_k are probability estimates for an instance (e.g., naïve Bayes)
- c is the index of the instance's actual class
- The actual class a_i
 $a_1, \dots, a_k = 0$, except for a_c which is 1
- Quadratic loss is:
$$\sum_{j=1}^k (p_j - a_j)^2 = \sum_{j \neq c} p_j^2 + (a - p_c)^2$$
- We want to minimize
$$E \left[\sum_{j=1}^k (p_j - a_j)^2 \right]$$
- Can show that this is minimized when $p_j = p_j^*$, the true probabilities



Informational Loss Function

- The informational loss function is $-\log_2(p_c)$
where c is the index of the instance's actual class
- Number of bits required to communicate the actual class
- Let $p_1^*, p_2^*, \dots, p_k^*$
be the true class probabilities
- Then the expected value for the loss function is:
$$-p_1^* \cdot \log_2(p_1^*) - p_2^* \cdot \log_2(p_2^*) \dots - p_k^* \cdot \log_2(p_k^*)$$
- Justification: minimized when $p_j = p_j^*$
- Difficulty: *zero-frequency problem*



Discussion

- Which loss function to choose?
 - Both encourage honesty
 - Quadratic loss function takes into account all class probability estimates for an instance
 - Informational loss focuses only on the probability estimate for the actual class
 - Quadratic loss is bounded:
it can never exceed 2
$$1 + \sum_{j=1}^k p_j$$
 - Informational loss can be infinite
- Informational loss is related to *MDL principle*



Counting the Cost

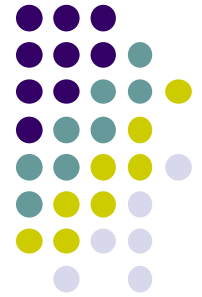
- In practice, different types of classification errors often incur different costs
- Examples:
 - Terrorist profiling
“Not a terrorist” correct 99.99% of the time
 - Loan decisions
 - Oil-slick detection
 - Fault diagnosis
 - Promotional mailing



Counting the Cost

- The *confusion matrix*

		Predicted class	
		Yes (R+)	No (R-)
True state of nature	Yes (C+)	True Positive (TP)	False Negative (FN)
	No (C-)	False Positive (FP)	True Negative (TN)



Counting the Cost

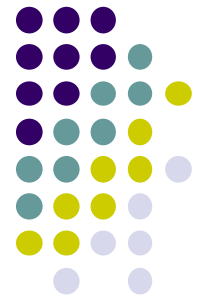
- The lie detector (US)
“Do you tell the true?”

		Person	
		Truth (R+)	Lier (R-)
State of nature	True (C+)	True Positive (TP)	False Negative (FN)
	Lie (C-)	False Positive (FP)	True Negative (TN)



Counting the Cost

- Different measures can be used
- Accuracy = $(TP + TN) / ((C+) + (C-))$
- Sensitivity = $TP / C+$
(the ability to correctly classify patients that actually have the disease, e.g. AIDS)
- Specificity = $TN / C-$
(the ability to correctly classify patients that actually do not have the disease)
- Predictive value (+) = $TP / R+$
- Predictive value (-) = $TN / R-$
- There are many other types of cost!
 - e.g.: cost of collecting training data



Precision, Recall, F_1 , ...

- Percentage of detected examples as positive that are really positive: $Precision = TP / (TP + FP)$
- Percentage of positive examples that are detected as positive: $Recall = TP / (TP + FN)$
- Precision/recall curves have hyperbolic shape (If one increases, the other decreases)
- Trivial acceptor (always “yes”) ($FN = TN = 0$)
 $Recall = TP / (TP + 0) = 100\%$
- Need both high recall and high precision!



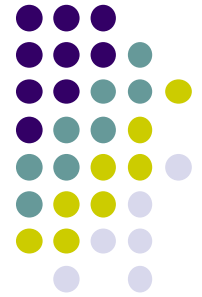
Precision, Recall, F_1 , ...

- Percentage of detected examples as positive that are really positive: $Precision = TP / (TP+FP)$
- Percentage of positive examples that are detected as positive: $Recall = TP / (TP+FN)$
- Mix the two measures as:
- Measure the performance using one single value, the F-measure
- $F\text{-measure} =$
$$F_1 = (2 \times recall \times precision) / (recall + precision)$$



Example

- Example: The lie detector (polygraph) can detect lies by considering biological measurements (blood pressure, respiration rhythm, heart frequency, ...)
- Hypothesis: stress indicates a lie
- Performance: 83% to 89% lies are detected!
- But: 53% to 75% innocents correctly detected??
- Error: 12% to 47% (Vrij, 2008)
- Are you convince by the lie detector?



Example

- The lie detector (US)
“Do you tell the true?”

		Person	
		Truth (R+)	Lier (R-)
State of nature	True (C+)	53% 75%	17% 11%
	Lie (C-)	47% 25%	83% 89%



More than Two Classes

- When with have more than two classes

		Predicted class	
		Yes	No
True state of nature	Class k Yes	True Positive (TP_k)	False Negative (FN_k)
	No	False Positive (FP_k)	True Negative (TN_k)



More than Two Classes

- Precision, Recall and F_1 measures must be given for each of the m classes
- For a single overall performance measure?
- Macro-averaging:
one category = one vote

$$Prec = \sum_{k=1}^m \frac{Prec_k}{m}$$

$$Recall = \sum_{k=1}^m \frac{Recall_k}{m}$$

- Micro-averaging:
one decision = one vote

$$Prec = \frac{TP}{TP + FP} = \frac{\sum_{k=1}^m TP_k}{\sum_{k=1}^m (TP_k + FP_k)}$$

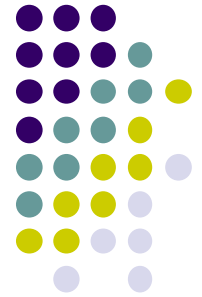
$$Recall = \frac{TP}{TP + FN} = \frac{\sum_{k=1}^m TP_k}{\sum_{k=1}^m (TP_k + FN_k)}$$



Example

Evaluation of a given learning scheme with four different datasets (macro-averaging)

Dataset	Precision	Recall	F_1
Iris	0.7	0.5	0.6
cars	0.5	0.6	0.55
TC 1	0.9	0.3	0.6
TC 2	0.7	0.5	0.6



Classification with Costs

- Two cost matrices:

		Predicted class						Predicted class		
			<i>yes</i>	<i>no</i>				<i>a</i>	<i>b</i>	<i>c</i>
Actual class	<i>yes</i>	0	1			<i>a</i>	0	1	1	
	<i>no</i>	1	0		Actual class	<i>b</i>	1	0	1	
						<i>c</i>	1	1	0	

- Success rate is replaced by average cost per prediction
 - Cost is given by appropriate entry in the cost matrix



Classification with Costs

- Can take costs into account when making predictions
 - Basic idea: only predict high-cost class when very confident about prediction
- Given: predicted class probabilities
 - Normally we just predict the most likely class
 - Here, we should make the prediction that minimizes the expected cost
 - Expected cost: dot product of vector of class probabilities and appropriate column in cost matrix
 - Choose column (class) that minimizes expected cost



Cost-Sensitive Learning

- So far we haven't taken costs into account at training time
- Most learning schemes do not perform cost-sensitive learning
 - They generate the same classifier no matter what costs are assigned to the different classes
 - Example: standard decision tree learner
- Simple methods for cost-sensitive learning:
 - Resampling of instances according to costs
 - Weighting of instances according to costs
- Some schemes can take costs into account by varying a parameter, e.g. naïve Bayes



Evaluating Numeric Prediction

- Same strategies: independent test set, cross-validation, significance tests, etc.
- Difference: error measures
- Actual target values: a_1, a_2, \dots, a_n
- Predicted target values: p_1, p_2, \dots, p_n
- Most popular measure: *mean-squared error*

$$\frac{(p_1 - a_1)^2 + (p_2 - a_2)^2 + \dots + (p_n - a_n)^2}{n}$$

- Easy to manipulate mathematically



Other Measures ...

- The *root mean-squared error* :

$$\sqrt{\frac{(p_1 - a_1)^2 + (p_2 - a_2)^2 + \dots + (p_n - a_n)^2}{n}}$$

- The *mean absolute error* is less sensitive to outliers than the mean squared error:

$$\frac{|p_1 - a_1| + |p_2 - a_2| + \dots + |p_n - a_n|}{n}$$

- Sometimes *relative* error values are more appropriate (e.g. 10% for an error of 50 when predicting 500)



Other Measures ...

- How much does the scheme improve on simply predicting the average?
- The *relative squared error* is:

$$\frac{(p_1 - a_1)^2 + (p_2 - a_2)^2 + \dots + (p_n - a_n)^2}{(\bar{a} - a_1)^2 + (\bar{a} - a_2)^2 + \dots + (\bar{a} - a_n)^2}$$

- The *relative absolute error* is:

$$\frac{|p_1 - a_1| + |p_2 - a_2| + \dots + |p_n - a_n|}{|\bar{a} - a_1| + |\bar{a} - a_2| + \dots + |\bar{a} - a_n|}$$



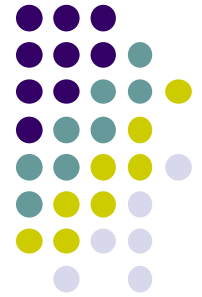
Correlation Coefficient

- Measures the *statistical correlation* between the predicted values and the actual values

$$\hat{\rho} = \frac{\hat{\sigma}_{pa}}{\sqrt{\hat{\sigma}_p \hat{\sigma}_a}} \quad \hat{\sigma}_{pa} = \frac{\sum_{i=1}^n (p_i - \bar{p}) \cdot (a_i - \bar{a})}{n - 1}$$

$$\hat{\sigma}_p = \frac{\sum_{i=1}^n (p_i - \bar{p})^2}{n - 1} \quad \text{and} \quad \hat{\sigma}_a = \frac{\sum_{i=1}^n (a_i - \bar{a})^2}{n - 1}$$

- Scale independent, between -1 and $+1$
- Good performance leads to large values!



Which Measure?

- Best to look at all of them
 - Often it doesn't matter
 - Example:
- D the best
 - C the second-best

Error	A	B	C	D
Root mean-squared	67.8	91.7	63.3	57.4
Mean absolute	41.3	38.5	33.4	29.2
Root rel squared	42.2%	57.2%	39.4%	35.8%
Relative absolute	43.1%	40.1%	34.8%	30.4%
Correlation coefficient	0.88	0.88	0.89	0.91



The MDL Principle

- MDL stands for *minimum description length*
- The description length is defined as:
 - space required to describe a theory*
 - + *space required to describe the theory's mistakes*
- In our case the theory is the classifier and the mistakes are the errors on the training data
- Aim: we seek a classifier with minimal DL
- MDL principle is a *model selection criterion*



Model Selection Criteria

- Model selection criteria attempt to find a good compromise between:
 - The complexity of a model
 - Its prediction accuracy on the training data
- Reasoning: a good model is a simple model that achieves high accuracy on the given data
- Also known as *Occam's Razor* :
- the best theory is the smallest one that describes all the facts

William of Ockham (about 1285-1348), the most influential philosopher of the 14th century





Elegance vs. Errors

- Theory 1: very simple, elegant theory that explains the data almost perfectly
- Theory 2: significantly more complex theory that reproduces the data without mistakes
- Theory 1 is probably preferable
- Classical example: Kepler's three laws on planetary motion



Conclusion

- Have two sets, a training and a test set
- Holdout, a first solution, 10-fold Cross-validation is better
- Give a confidence interval
- Use the t -test or better the paired t -test
- Take account of the error cost (if needed)
- Other measures: Precision, Recall, F_1
- Many measures for numerical prediction
- Take the complexity of the model into account (Occam's razor)