

Development of a ROS Node for Mitsubishi RV-2F-D

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Project Plan Presentation

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Outline

Problem Statement

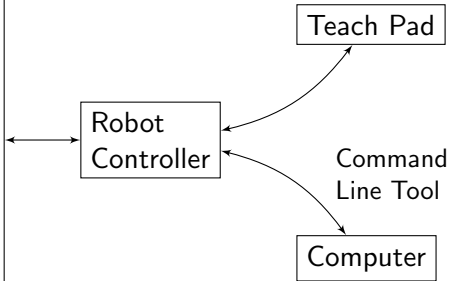
Robot Operating System

Project Plan



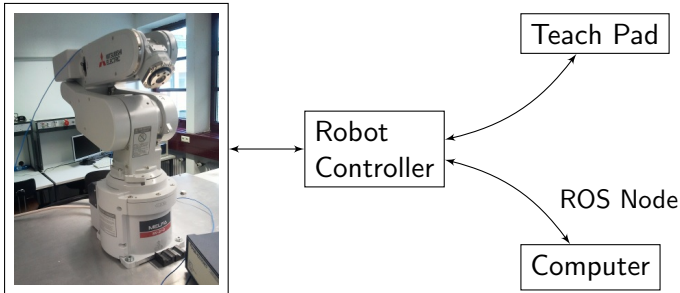
Problem Statement

Mitsubishi
RV-2F-D



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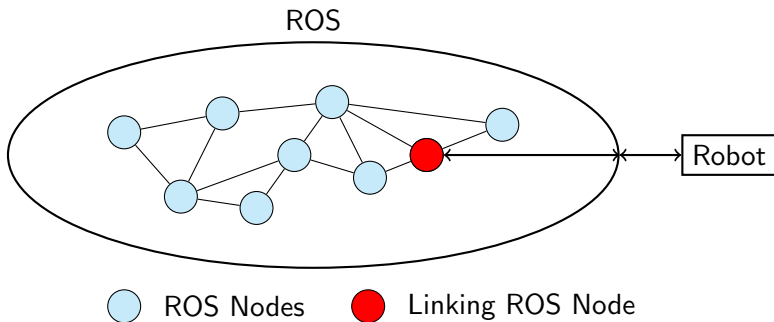


Objective

Control robot with Robot Operating System (ROS)

Robot Operating System

- Open source software collection to develop robot applications
- Organizes executables (nodes) via network



Project Plan

