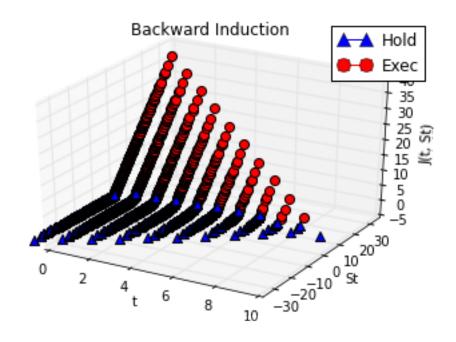
## question6

## January 15, 2016

```
In [1]: %pylab inline
Populating the interactive namespace from numpy and matplotlib
In [2]: import pandas as pd
        import numpy as np
        import matplotlib.pyplot as plt
In [3]: # Load microsoft data
        msft = pd.read_csv('microsoft.csv')
        trajectories = np.diff(msft['MSFT.Adjusted'])
        length_short_path = 30 # days
        length = len(trajectories)
        num_paths = int(length / length_short_path)
        trajectories = trajectories[:length_short_path * num_paths]
        trajectories.shape = (length_short_path, num_paths)
        for i in range(3):
            plt.plot(trajectories[i, :])
        plt.show()
        K = 0.
        T = 5
           2.5
           2.0
           1.5
           1.0
           0.5
           0.0
          -0.5
          -1.0
                      10
                               20
                                                                        70
                                       30
                                               40
                                                       50
                                                               60
                                                                                80
```

```
In [4]: outcomes = np.sort(np.sum(trajectories[:5,:], axis=1))
        print(outcomes)
        num_outcomes = len(outcomes)
[-4.404346 -0.829189 -0.79187 1.067787 3.531883]
In [5]: def generate_slates(n):
            St = np.array([0])
            S = [St]
            for i in range(n):
                Stnext = np.array([])
                for ds in outcomes:
                    Stnext = np.concatenate([Stnext, (St + ds)])
                St = unique(Stnext)
                St = np.sort(St)
                S.append(St)
            return S[::-1]
        def backward_induction(St, Jnext):
            expected_J = np.zeros_like(St)
            offset = len(Jnext) - len(St)
            p = 1. / offset
            for i in range(offset):
                expected_J += p* (Jnext[i:-(offset - i)] if offset != i else Jnext[i:])
            buffer = np.array([expected_J, St-K])
            control = np.argmax(buffer, axis=0)
            J = np.maximum(St-K, expected_J)
            return (J, control)
        def price_tree(n):
            slates = generate_slates(n)
            J = np.zeros(len(slates[0])+num_outcomes-1)
            for t, St in enumerate(slates):
                J, control = backward_induction(St, J)
                yield np.array([t*np.ones_like(St), St, J, control])
In [7]: from mpl_toolkits.mplot3d import Axes3D
        import matplotlib.pyplot as plt
        import matplotlib.lines as mlines
        T = 10
        def plot(pricing_method, name, img):
            fig = plt.figure()
            ax = fig.add_subplot(111, projection='3d')
            c = np.array(('b', 'r'))
            m = np.array(('^', 'o'))
            for points in pricing_method(T):
                for u in (0, 1):
                    xs, ys, z_tree, _ = points[:,abs(points[3] - u) <= 0.01]</pre>
                    ax.scatter(xs,
                           ys, z_{tree}, s=50,
                           c=c[u], marker=m[u],
```

## depthshade=False)



## In [0]: #LP

```
# Get the relevent matrices
def get_A():
    row = np.zeros(T*T)
    for i in range(num_outcomes):
        row[T+i] = 1./num_oucomes
A = [row]
    for _ in range(T*(T-1)-1):
        row = np.roll(row, 1)
        A.append(row)
    row = 0 * row
    for _ in range(T): A.append(row)
    return np.array(A)
```

```
def get_B():
    B = np.zeros( shape=(T*(T-1)/2, T*T) )
    i, j = 0, 0
    for St in generate_slates(T)[::-1]:
        Nt = len(St)
        j += Nt + 1
        for b in range(T-(Nt+1)):
            B[i, j] = 1
            i, j = i+1, j+1
    return B

def get_U():
    return np.array(itertools.chain(*generate_slate(T))) - K
```