Problem 1

1. Let's consider $g: u \to \log(1+e^u)$. g is non-decreasing and convexe because $g'(u) = \frac{e^u}{1+e^u} = \frac{1}{1+e^{-u}}$ is increasing.

We notice that $f(x_1, x_2) = g(x_1 - x_2) + x_2$.

- $x_2 \to x_2$ is linear
- $x_2 \to x_1 x_2$ is linear, g convexe and non-decreasing, so $g(x_1 x_2)$ is convexe

c/c: f is convexe.

2. The following transformation is a bijection from $(2,3)\times(0,\infty)\times(0,\infty)$ to $(\frac{\log 2}{2},\frac{\log 3}{2})\times\mathbb{R}\times\mathbb{R}$

$$x_1 = 2 \log x$$

$$x_2 = \log y - \log z$$

$$x_3 = \log y$$

 $\frac{x}{y} = z^2 = e^{2\log z} = e^{2\log y - 2x_2} = e^{2x_3 - 2x_2}$ Minimizing $\frac{x}{y}$ is the same as minimizing $a(x_1, x_2, x_3) := e^{2x_3 - 2x_2}$ which is convexe as the composition of a linear function and a convexe and increasing one exp.

- $\frac{x}{y} = z \iff \log x \log y = \log z \iff \frac{1}{2}x_1 x_3 = x_3 x_2 \iff \frac{1}{2}x_1 + x_2 2x_3 = 0$ and $b(x_1, x_2, x_3) := \frac{1}{2}x_1 + x_2 2x_3$ is linear.
- $x^2 + \frac{y}{z} \le \sqrt{y} \iff e^{x_1} + e^{x_2} \le \sqrt{e^{x_3}} \iff \log(e^{x_1} + e^{x_2}) \le \frac{1}{2}x_3 \iff f(x_1, x_2) \frac{1}{2}x_3 \le 0$ and $c(x_1, x_2, x_2) := f(x_1, x_2) \frac{1}{2}x_3$ is convexe as the sum of two convexe functions

c/c: the optimization problem is equivalent to:

$$\max a(x_1, x_2, x_2) \text{ s.t. } b(x_1, x_2, x_2) = 0, c(x_1, x_2, x_2) \le 0, (x_1, x_2, x_2) \in (\frac{\log 2}{2}, \frac{\log 3}{2}) \times \mathbb{R} \times \mathbb{R}$$

which is a convexe problem.

Problem 2

 \Rightarrow) Let's suppose f convexe.

$$\nabla f^{T}(x)(y-x) = \lim_{\alpha 0} \frac{f(x+\alpha(y-x)) - f(x)}{\alpha}$$

$$= \lim_{\alpha 0} \frac{f((1-\alpha)x + \alpha y) - f(x)}{\alpha}$$

$$\leq \lim_{\alpha 0} \frac{(1-\alpha)f(x) + \alpha f(y) - f(x)}{\alpha}$$

$$\leq f(x) - f(y)$$
 (because f convexe)

 \Leftarrow) Let's suppose $\forall x, y \nabla f^T(y-x) \leq f(y) - f(x)$ Let $\alpha \in (0,1)$, and $u = (1-\alpha)x + \alpha y$

$$f(x) - f(u) \ge \nabla f(u)(x - u)$$

$$f(y) - f(u) \ge \nabla f(u)(y - u)$$

By multiplying the first inequality by $1-\alpha$ and the second one by α and summing, we get: $(1-\alpha)f(x) + \alpha f(y) - f(u) \ge 0$

Which proves that f convexe.

Problem 3

Problem 4

- 1. For $y \in \mathbb{R}^n \sup_y L(x,y) \ge L(x,u)$ By taking the \inf_x : $\inf_x \sup_y L(x,y) \ge \inf_x L(x,u)$ By taking the \sup_u : $\inf_x \sup_y L(x,y) \ge \sup_u \inf_x L(x,u)$
- 2. Let $f(x) := \max_y L(x, y)$ We know that $x^* \in \arg\min f$ and f is convexe, so $\partial f(x^*) = 0$. L is continuous the Danskin's theorem, we have that: $0 \in \{\nabla_x L(x^*, y) | y \in \arg\min L(x^*, y^*)\} = \{\nabla_x L(x^*, y^*)\}$, which means that $\nabla_x L(x^*, y^*) = 0$, and symmetrically, $\nabla_y L(x^*, y^*) = 0$.

$$x^* = x^* - \alpha \nabla_x L(x^*, y^*)$$
$$y^* = y^* - \alpha \nabla_y L(x^*, y^*)$$

Problem 4

1. By taylor equality, there exist $y \in X$ such that:

$$f(x^k) - f(x^*) = \nabla f(x^*)(x^k - x^*) + \nabla^2 f(x^*)$$

Problem 5

- 1. Let's call S_t the price of the stock at time t, and $C_t(S_t)$ the price of the corresponding american action (with strike K)
 - State $x_t = S_t, t = 1..T$
 - Action:

$$u_t = \begin{cases} 1 & \text{meaning we exercise the option} \\ 0 & \text{meaning we don't} \end{cases}$$

- Randomness: The change in the stock price $w_t = \frac{S_{t+1}}{S_t}$ s.t $x_{t+1} = w_t x_t$, $P(w_t = u) = 1 P(w_t = d) = p$
- Transitional cost:

 $g(x_k, u_k = 0, w_t) = 0$ $g(x_k, u_k = 1, w_t) = (x_t - K)^+ - C_{t+1}(x_t + w_t)$ Explication: If we exercise the option, we gain $(x_t - K)^+$ but we lose the right to the option $(-C_{t+1})$. $g(x_T) = (x_T - K)^+$: We are forced to exercise the option at time T

The price problem:

$$C_k(x) = \max_{\mu} E[g(x_T) + \sum_{t=k}^{T-1} g(x_k, \mu_k(x_k), w_t) | x_k = x]$$

2. Bellman equation:

$$C_k(x) = \max_{\mu_k} E[g_k(x, \mu_k(x), w_k) + C_{k+1}(w_k x_{k+1}) | x_k = x] = \max\{(x - K)^+, pC_{k+1}(ux) + (1 - p)C_{k+1}(dx)\}$$

$$C_T(x) = (x - K)^+$$

3. LP: Let J(t, S) be the price of the option at time t is $S_t = S$, and we decide to adopt the strategy J verifies: $J(t, S) = \max\{E[J(t+1, S_{t+1})|S_t = S], S-K\} = [\max_{\mu}(P_{\mu}J + g_{\mu})](t, S)$ where $\mu(t, S) \in \{\text{HOLD}, \text{EXEC}\},$

$$(P_{\mu}J)(t,S) = \left\{ \begin{array}{cc} pJ(t+1,uS) + (1-p)J(t+1,dS) & \text{if } \mu(t,S) = \text{HOLD} \\ 0 & \text{otherwise} \end{array} \right\}$$

$$g_{\mu}(t,S) = \left\{ \begin{array}{cc} 0 & \text{if } \mu(t,S) = \text{HOLD} \\ S-K & \text{otherwise} \end{array} \right\}$$