# Problem set 5, ORF523

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## 1 Problem 1

Notation  $E_{ij} = (\delta_{ik}\delta_{jl} + \delta_{il}\delta_{jk})_{k,l}$  the matrix with all 0 except in (i,j) and (j,i)

$$-\nu(G) = \min_{X} \qquad Tr(X(-J))$$
 subject to 
$$X \ge 0$$
 
$$Tr(XI_n) = 1 \qquad (:\alpha)$$
 
$$Tr(E_{ij}X) = 0 \ \forall (i,j) \in E, i < j \qquad (:\lambda_{ij})$$

has for dual:

$$\max_{\alpha, \lambda_{ij} \in \mathbb{R}} \qquad \qquad \alpha$$
 subject to 
$$\alpha I + \sum_{(i,j) \in E, i < j} \lambda_{ij} E_{ij} \leq -J$$

Both are strictly feasible:

- for the primal, take  $X = \frac{I_n}{n}$
- For the dual, take  $\alpha = -2$ ,  $\lambda_{ij} = 0$

Which proves that the dual and primal are equal. Taking  $\beta = -\alpha$ , we can write that as:

$$\nu(G) = \min_{\alpha, \lambda_{ij} \in \mathbb{R}} \beta$$
subject to
$$-\beta I + \sum_{(i,j) \in E, i < j} \lambda_{ij} E_{ij} \le -J$$

Note that the (1,1) entry of  $-\beta I + \sum_{(i,j)\in E} \lambda_{ij} E_{ij} + J$ :  $1-\beta$  should be negative, so we can ammend to the constraints that  $\beta \geq 1$ 

$$-\beta I + \sum_{(i,j)\in E, i < j} \lambda_{ij} E_{ij} \le -J \iff \beta (I - \sum_{(i,j)\in E}, i < j \frac{\lambda_{ij}}{\beta} E_{ij}) \succeq J$$

$$\iff I - \sum_{(i,j)\in E, i < j} \frac{\lambda_{ij}}{\beta} E_{ij} \succeq \frac{1}{\beta} 11^{T}$$

$$\iff \begin{pmatrix} I - \sum_{(i,j)\in E, i < j} \frac{\lambda_{ij}}{\beta} E_{ij} & \vdots \\ 1 & \dots & 1 & \beta \end{pmatrix} \succeq 0 \quad \text{(By Schur Lemma bc } \beta > 0 \text{)}$$

Let's note this big matrix Z. It is clear that a matrix  $Z \in S^{(n+1)}$  is of this form iff it verifies the constraints of the following optimization problem:

min 
$$Z_{n+1,n+1}$$
 subject to 
$$Z\succeq 0$$
 
$$Z_{i,n+1}=Z_{ii}=1$$
 
$$Z_{i,j}=0 \forall \{i,j\}\in \bar{E}$$

And this quantity is then equal to  $\vartheta(G)$ .

Let's now prove the inequality (2).

Let  $C = \chi(\bar{G})$ .

By definition, there exist a partition of  $V: \{V_1, \ldots, V_C\}$  such that  $V_i$  is a clique for all  $i \leq C$ 

- Define  $1_{V_i} \in \mathbb{R}^n$  to be the indicator function of the set  $V_i$ , and note that  $1 = \sum_{i \leq C} V_i$
- Define  $z_i = \begin{pmatrix} 1_{V_i} \\ 1 \end{pmatrix} \in \mathbb{R}^{n+1}$ . Note that:

$$z_i z_i^T = \begin{pmatrix} 1_{V_i} 1_{V_i}^T & 1_{V_i} \\ 1_{V_i}^T & 1 \end{pmatrix}$$

• Define

$$Z = \sum_{i} z_i z_i^T = egin{pmatrix} \sum_{i=1}^{T} 1_{V_i} 1_{V_i}^T & 1 \ 1^T & C \end{pmatrix}$$

Z is positive semidefinite because it is a sum of psd terms  $z_i z_i^T$ 

- $(1_{V_i}1_{V_i}^T)_{kl} = (e_k^T1_{V_i})(e_l^T1_{V_i}) = 1_{V_i}(k)1_{V_i}(l)$ . If  $(k,l) \in \bar{E}$ , then the  $k^{th}$  node and the  $j^{th}$  node cannot be in the same  $V_i$ , and therfore  $(1_{V_i}1_{V_i}^T)_{kl} = 0$
- If k = l, all the terms in  $\sum_{i} (1_{V_i} 1_{V_i}^T)_{kl}$  are zero except for the *i* for which the  $k^{th}$  node is in  $V_i$ , in which case it is equal to one.

As a conclusion, Z verifies all constraints of the dual, and  $Z_{n+1,n+1} = C = \chi(\bar{G})$ , so

$$\chi(\bar{G}) \ge \vartheta(G)$$

 $\mathbf{2}$ 

Consider  $G = C_5$ .

Using CVX to calculate  $\vartheta(G)$ 

2.2361

$$2 < \vartheta(G) < 3$$

- $\vartheta(G) \notin \mathbb{N}$
- $\alpha(G), \chi(\bar{G}) \in \mathbb{N}$ No inequality can thus be tight.

## 2 Q2

1

Consider

min 
$$Z_{n+1,n+1}$$
 (P(G)) subject to  $Z \succeq 0$   $Z_{i,n+1} = Z_{ii} = 1$   $Z_{i,j} = 0 \forall \{i,j\} \in \bar{E}$ 

Write the lagrangian:

$$\mathcal{L}(Z,Y) = Z_{n+1,n+1} + \sum_{i=1}^{n} 2Y_{i,n+1}(Z_{i,n+1} - 1) + Y_{ii}(Z_{ii} - 1) + \sum_{ij \in \bar{E}, i < j} Y_{ij}Z_{ij}$$

$$= -\sum_{i} Y_{ii} + 2Y_{i,n+1} + \langle E_{n+1,n+1} + Y_{i,n+1}E_{i,n+1} + Y_{ii}E_{ii} + \sum_{ij \in \bar{E}, i < j} Y_{ij}E_{ij}, Z \rangle$$

Dual:

$$\sum_{i \leq n} -Y_{ii} - 2Y_{i,n+1} \tag{D_1(G)}$$
 subject to 
$$Y \succeq 0$$
 
$$Y_{n+1,n+1} = 1$$
 
$$Y_{i,j} = 0 \forall \{i,j\} \in E$$

P(G) and D(G) are both strictly feasible (Consider  $I_{n+1}$  and  $E_{n+1,n+1}$  respectively). So their optimal values are attained and are equal.

Let Y be a feasible solution, write:

$$Y = \begin{pmatrix} & Y' & & y \\ & & & \\ & y^T & & 1 \end{pmatrix}$$

Note that by Schur's lemma:

$$Y \succeq 0 \iff Y' \succeq yy^T \iff Y' \succeq (-y)(-y)^T$$

So we can replace  $Y_{i,n+1}$  by  $-Y_{i,n+1}$  without affecting the optimal value:

$$\sum_{i \leq n} -Y_{ii} + 2Y_{i,n+1} \qquad (D_2(G))$$
 subject to 
$$Y \succeq 0$$
 
$$Y_{n+1,n+1} = 1$$
 
$$Y_{i,j} = 0 \forall \{i,j\} \in E$$

Let's now prove that this is equivalent to the following problem:

$$\sum_{i \leq n} Y_{ii} \qquad (D_3(G))$$
 subject to 
$$Y \succeq 0$$
 
$$Y_{n+1,i} = Y_{ii}$$
 
$$Y_{n+1,n+1} = 1$$
 
$$Y_{i,j} = 0 \forall \{i,j\} \in E$$

- If Y is feasible to  $D_3(G)$ , then it is also feasible to  $D_2(G)$ . Moreover in that case,  $\sum_i -Y_{ii} + 2Y_{i,n+1} = \sum_i Y_{ii}$ , so  $D_2(G) \geq D_3(G)$
- Let Y be an optimal solution to  $D_2(G)$  (we proved that it exists), note  $\gamma = \sum_{i \leq n} -Y_{ii} + 2Y_{i,n+1} = D_2(G)$ . Argue by contradiction that that  $Y_{n+1,j} Y_{jj} \neq 0$ .
  - Note  $a = \sum_{i} Y_{ii} 2Y_{i,n+1}$ .
  - Note by Y' the matrix obtained from Y by multiplying the  $j^{th}$  row/column of Y by  $s \in \mathbb{R}$ .
  - $-Y' = \operatorname{diag}(1 \dots \underbrace{s}_{i} \dots 1)Y \operatorname{diag}(1 \dots \underbrace{s}_{i} \dots 1) \succeq 0$ , and we can see that Y' is feasible in  $D_{2}(G)$ .
  - Noting that  $Y'_{jj} = s^2 Y_{jj}, Y'_{j,n+1} = s Y_{j,n+1}$ , the objective value of Y' in  $D_2(G)$  is:

$$\sum_{i \le n} -Y'_{ii} + 2Y'_{i,n+1} - \gamma = -(s^2 - 1)Y_{jj} + 2(s - 1)Y_{j,n+1} = -s^2Y_{jj} + 2sY_{j,n+1} + Y_{jj} - 2Y_{j,n+1}$$

The descriminant of the last equation in s is  $\Delta = 4[Y_{j,n+1}^2 + Y_{jj}(Y_{jj} - 2Y_{j,n+1})] = 8Y_{j,n+1}(Y_{j,n+1} - Y_{j,n+1})$  Note that by looking at a  $2 \times 2$  leading minor,  $Y_{jj} \geq Y_{n+1,j}^2$ , and since  $Y_{jj} \neq Y_{n+1,j}$  they cannot be both equal to 0, so  $Y_{jj} > 0$ . As a result,  $\Delta > 0$ , meaning there exist an s that makes the objective value increase. Absurd.

We have that showed that Y verifies the satisfiability conditions of  $D_3(G)$ , and therefore  $D_3(G) = \sum_i -Y_{ii} + 2Y_{i,n+1} = \sum_i Y_{ii} \leq D_2(G)$  Which completes the proof of the hint. Let  $Y \in S^{n+1 \times n+1}$  be a feasible solution to this problem. Let  $x := (Y_{ii})_{i \leq n}$ .

By consider the  $1 \times 1$  and  $2 \times 2$  minors:

$$Y \succeq 0 \implies \begin{vmatrix} Y_{ii} & Y_{ii} \\ Y_{ii} & 1 \end{vmatrix} \ge 0, Y_{ii} \ge 0$$
$$\implies Y_{ii} - Y_{ii}^2 \ge 0, Y_{ii} \ge 0$$
$$\implies 0 \le Y_{ii} \le 1$$

We have just proved that  $0 \le x \le 1$ 

Let  $\{i_1,\ldots,i_k\}$  a clique in the graph. Let  $I=\{i_1,\ldots,i_k,n+1\}$ , and consider the principal minor:

$$\det Y_{I,I} = \det \begin{vmatrix} Y_{i_1i_1} & \dots & 0 & Y_{i_1i_1} \\ 0 & \ddots & \vdots & \vdots \\ \vdots & & Y_{i_ki_k} & Y_{i_ki_k} \\ Y_{i_1i_1} & \dots & Y_{i_ki_k} & 1 \end{vmatrix} = \det \begin{vmatrix} x_{i_1} & \dots & 0 & x_{i_1} \\ 0 & \ddots & \vdots & \vdots \\ \vdots & & x_{i_k} & x_{i_k} \\ x_{i_1} & \dots & x_{i_k} & 1 \end{vmatrix} \ge 0$$

To calculate this determinant, substract the sum of the first n rows from the last one to get a triangular matrix:

$$\det Y_{I,I} = \det \begin{vmatrix} x_{i_1} & \dots & 0 & x_{i_1} \\ 0 & \ddots & \vdots & & \vdots \\ \vdots & & x_{i_k} & & x_{i_k} \\ 0 & \dots & 0 & 1 - x_{i_1} - \dots x_{i_k} \end{vmatrix} = x_{i_1} \dots x_{i_k} (1 - x_{i_1} - \dots - x_{i_k})$$

Which means that  $x_{i_1} + \ldots + x_{i_k} \leq 1$ , eg x respects all the clique inequalities.

As a result:

$$\sum_{i=1}^{n} Y_{ii} = \sum_{i=1}^{n} x_i \le \eta_{LP}^{(k)}$$

Taking the sup over feasible  $Y: \vartheta(G) \leq \eta_{LP}^{(k)}$ 

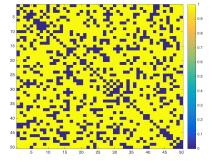


Figure 1: G Adjacency matrix

## **2.1** $\vartheta(G)$

```
n = 50
   J = ones(n, n);
   cvx_begin sdp
   variable X(n, n) symmetric;
   maximize(trace(X*J))
   X >= 0
   for i=1:n
        for j=1:i
            if G(i, j) == 1
10
                X(i, j) == 0
11
            end
12
        end
13
   end
```

```
15  trace(X) == 1
16  cvx_end
17
18  ans=cvx_optval
```

5

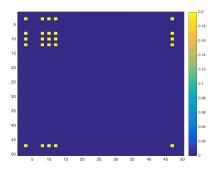


Figure 2: X optimal solution

Note that the resulting X is of rank 1, so it can be decomposed into  $X = xx^T$ . We check that  $V_x = \{i, x_i \neq 0\}$  represents indeed a stable set.

```
[v,e] = eigs(full(X),1);
stableset = find(abs(v) > 0.01)
ans=stableset'
```

 $3 \quad 8 \quad 10 \quad 12 \quad 47$ 

#### G(stableset, stableset)

Table 1: Subgraph of the nodes in the stableset

Let's assume that there exist another stable set of size 5.

This would mean that there exist  $v \in V_x$  such that imposing  $x_j = 0$  (eg  $X_{jj} = 0$ ) would not change  $\alpha$ . Let's check:

```
n = 50

J = ones(n, n);

opt = [stableset, zeros(5, 1)]

for vi=1:5

v = stableset(vi)

cvx_begin sdp

variable Y(n, n) symmetric;
```

```
variable optvalue;
          maximize(trace(Y*J))
9
          Y >= 0
10
          for i=1:n
11
               for j=1:i
12
                   if G(i, j) == 1
13
                        Y(i, j) == 0
14
                   end
               end
          end
          Y(v,v) == 0
18
          trace(Y) == 1
19
          optvalue == trace(Y*J)
20
          cvx_end
21
          opt(vi, 2) = optvalue
22
      end
23
   ans=opt
24
```

 Table 2: Lovazs

 Node removed
 Lovasz of the subgraph

 3
 4.4463

 8
 4.5191

 10
 4.512

12

47

Since Lovasz number  $\vartheta$  is an upper bound on  $\alpha$ , This proves that any stable set not containing one of the nodes in  $V_x$  is of size less than 5.

4.5586

4.4771

We have just proved uniqueness of the stable set.

```
\mathbf{2.2} \quad \mu^{LP} \mathbf{k} = 2
```

```
cvx_begin
   variable x(n)
   maximize(sum(x))
   for i=2:n
        for j=1:(i-1)
            if G(i, j) == 1
6
                 x(i) + x(j) \setminus langle = 1
            end
        end
   end
   0 <= x <= 1
11
   cvx_end
12
13
   ans=cvx_optval
14
```

```
k = 3
```

end

23

```
cvx_begin
   variable x(n)
   maximize(sum(x))
    for i=2:n
        for j=1:(i-1)
             if G(i, j) == 1
                 x(i) + x(j) <= 1
             end
             for r=1:(j-1)
9
                 if G(i, j) + G(j, r) + G(r, i) == 3
10
                      x(i) + x(j) + x(r) <= 1
11
                  end
12
             end
13
        end
    end
15
    0 <= x <= 1
16
    cvx_end
17
18
    ans=cvx_optval
19
    16.667
       k = 4
   M = 50
    cvx_begin
      variable x(n)
      maximize(sum(x))
      for i=2:M
          for j=1:(i-1)
6
               if G(i, j) == 0
                    continue
               \quad \text{end} \quad
9
               x(i) + x(j) \le 1
10
               for r=1:(j-1)
11
                    if G(j, r) == 0 \mid \mid G(r, i) == 0
12
                        continue
13
                    end
14
                    x(i) + x(j) + x(r) \le 1
15
                    for p = 1:(r-1)
16
                        if G(i, p) == 0 \mid \mid G(j, p) == 0 \mid \mid G(r, p) == 0
                             continue
19
                        x(i) + x(j) + x(r) + x(p) \le 1
20
                    end
21
               end
22
```

```
24     end
25     0 <= x <= 1
26     cvx_end
27
28     ans=cvx_optval</pre>
```

12.5

## 3 Problem 3

1. Let (a,b),(u,v) be two nodes in  $G_A\otimes G_B$  The two nodes are connected if and only if:

• 
$$A_{au} = 1, A_{bv} = 1$$

• 
$$a = u, A_{bv} = 1$$

• 
$$A_{au} = 1, b = v$$

This can be summerised as  $(A_{au} + \delta_{au})(A_{bv} + \delta_{bv}) - \delta_{au}\delta_{bv} = 1$ So the adjacency matrix of  $G_A \otimes G_B$  is  $(A + I_n) \otimes (B + I_m) - I_{nm}$ . Where  $\otimes$  denote the Kronecker product:  $(A \otimes B)_{p(r-1)+v,q(s-1)+w} = A_{rs}B_{vw}$ 2.

$$5 = \alpha(G) \le \Theta(G) \le \vartheta(G) = 5$$

so  $\Theta(G) = 5$ 

## 4 Problem 4

1. (1) is equivalent to

$$\begin{cases} x^T A y = \max_{\tilde{x} \in \Delta_m} \tilde{x}^T A y \\ x^T B y = \max_{\tilde{y} \in \Delta_n} x^T B \tilde{y} \end{cases}$$

Consider the first problem:

$$\max_{\tilde{x} \in \Delta_m} \tilde{x}^T A y$$

This is an LP whose feasible region  $\Delta_m = conv(e_i, i = 1...m)$  is compact, so the maximum is attained in one of the extreme points  $e_{i_0}$ . Therefore

$$x^TAy = \max_{\tilde{x} \in \Delta_m} \tilde{x}^TAy \iff x^TAy = e_{i_0}^TAy = \max_i e_i^TAy \iff x^TAy \ge e_i^TAy \forall i$$

Same argument applies for y so that:

$$x^T B y = \max_{\tilde{y} \in \Delta_n} x^T B \tilde{y} \iff x^T A y \ge x^T B e_i \forall i$$

So:

$$(1) \iff \begin{cases} x^T A y & \geq e_i^T A y \ \forall i = 1 \dots m \\ x^T B y & \geq x^T A e_i \ \forall i = 1 \dots n \end{cases}$$

 $x \in \Delta_m, y \in \Delta_n$ 

Note 
$$z = \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$
,  $u = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ ,  $v = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ ,

$$M = zz^T = \begin{pmatrix} xx^T & xy^T & x \\ yx^T & yy^T & y \\ x^T & y^T & 1 \end{pmatrix}$$

Note that

- *M* ≥ 0
- rank(M) = 1
- $M_{n+m:n+m+1,1:n} = x \in \Delta_n$
- $M_{n+m:n+m+1,n+1:n+m} = y \in \Delta_m$
- $M_{n+m+1,n+m+1} = 1$

Now to express the fact that (x, y) is a Nash equilibrium (\*):

- $tr(M_{n+1:n+m,1:n}A) = tr(yx^TA) = tr(x^TAy) \ge tr(e_i^TAy) \ge tr(e_i^TAM_{n+m:n+m+1,n+1:n+m})$
- $tr(M_{n+1:n+m,1:n}B) \ge tr(M_{n+m:n+m+1,1:n}Ae_i)$

Now let  $M \in S^{n+m}$ , verifying all the previous conditions. Then by cholesky, there exist a vector  $z \in \mathbb{R}^{n+m+1}$ , such that:  $M = zz^T$ 

- Let's decompose  $z := \begin{pmatrix} x \\ y \\ \alpha \end{pmatrix} \in \mathbb{R}^{n+m+1}$ , so that  $M = zz^T = \begin{pmatrix} xx^T & xy^T & \alpha x \\ yx^T & yy^T & \alpha y \\ \alpha x^T & \alpha y^T & \alpha^2 \end{pmatrix}$
- $1 = M_{n+m+1,n+m+1} = \alpha^2 \implies \alpha = \pm 1$
- $M_{n+m:n+m+1,1:n} = \alpha x \in \Delta_n$
- Similarly:  $\alpha y \in \Delta_m$
- If  $\alpha = -1$ , we can always change z to -z without loss of generality to make  $x, y \geq 0$  and therefore  $x \in \Delta_m, y \in \Delta_n$
- (x, y) naturally represent a Nash equilibrium due to (\*).

PSD relaxation:

- $M \succeq 0$
- $\bullet \ M_{n+m:n+m+1,1:n} \in \Delta_n$
- $M_{n+m:n+m+1,n+1:n+m} \in \Delta_m$
- $M_{n+m+1,n+m+1} = 1$

Moreover, we can add the following constraints:

- The sum of the columns of  $M_{1:n,1:n} = xx^T = (x_ix_j)_{ij}$  is equal to x. (This is true because  $x \in \Delta_n$ )
- Similarly the sum of the columns of  $M_{n+1:n+m,n+1:n+m}$  is equal to y.

- The sum of the columns of  $M_{n+1:2n,1:n} = yx^T$  is equal to y, and the sum of the rows is equal to x.
- $M \ge 0$

```
A = [345 78 97 355 264 528;
         310 52 483 385 541 276;
2
         236 248 445 243 7 80;
         64 23 290 226 157 426;
         292 129 300 116 628 580;
         477 317 342 58 152 106]
6
   B = [404 183 215 531 232 31;
        79 624 442 145 277 182;
9
         421 619 1 271 477 456;
10
         561 364 423 539 96 147;
11
         632 546 528 580 388 229;
12
         279 112 198 97 172 94]
13
14
   n = length(A)
15
   In = eye(n, n);
16
   cvx_begin sdp
18
   variable M(2*n+1, 2*n+1) symmetric;
19
   variables x(n) y(n);
20
   variables yx(n, n) xx(n, n) yy(n, n);
21
22
   maximize(trace(yx * A))
23
24
   M >= 0
   M(2*n+1, 2*n+1) == 1
26
   for i=1:(2*n+1)
27
       for j=1:(2*n+1)
28
            M(i, j) >= 0
29
       end
30
   end
31
32
   % sub-blocks of M
33
   x == M(1:n, 2*n+1)
34
   y == M(n + (1:n), 2*n+1)
35
   xx == M(1:n, 1:n)
36
   yy == M(n + (1:n), n + (1:n))
37
   yx == M(n + (1:n), 1:n)
39
   % x  and y  in the simplex
40
   sum(x) == 1
41
   sum(y) == 1
42
43
   % Additional constraints
44
   x == sum(xx)
45
   y == sum(yy)
```

```
x == sum(yx)
   y == sum(yx)
49
   % Nash equilibrium constraint
50
   for i=1:n
51
        ei = In(1:n, i);
52
        trace(yx * A) >= trace(ei' * A * y)
53
        trace(yx * B) >= trace(x' * B * ei)
    \quad \text{end} \quad
56
   cvx\_end
57
58
   ans=cvx_optval;
59
```

## 443.13

Which proves that the score of the first player cannot exceed 434