ORF523 - Problem Set 1

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Problem 1

- 1. Let λ be an eigen value of A^TA corresponding to an eigen vector $u \neq 0$, then $0 \leq ||Au||^2 = u^TA^TAu = \lambda ||u||^2$, therefore $\lambda > 0$.
- 2. Let λ be an eigen value of A corresponding to an eigen vector u, the $A^TAu = A(Au) = \lambda^2 u$, so λ^2 is an eigen value of A^TA . Since A has n eigen values (accounting for multiplicity), the eigen values of A^TA are exactly the squares of the eigen values of A, and therefore the singular values of A are the absolute values of the eigen values of A.

3.

$$u_i^T u_j = u_i^T \frac{A^T A u_j}{\lambda_i} = \frac{u_i^T A^T A}{\lambda_i} u_j$$

Since $\lambda_i \neq \lambda_j$, $u_i^T u_j = 0$

- The L_2 norm for vectors is unitarly invariant: Let O unitary matrix and X a vector, then $||OX||^2 = X^T O^T O X = X^T X = ||X||^2$.
- Since O is invertible, the application $S \to S, X \to OX$, where S is the L_2 sphere, is a bijection. So $\{x, ||x||_2 = 1\} = \{Ox, ||x||_2 = 1\}$
- The L_2 norm for matrices is unitarly invariant. If A a matrix, then $||AO|| = \max_{||x||_2=1} ||AOx|| = \max_{||Ox||_2=1} ||AOx|| = \max_{||y||_2=1} ||Ay|| = ||A||$ and $||OA|| = \max_{||x||_2=1} ||OAx|| = \max_{||x||_2=1} ||Ax|| = ||A||$.
- Let B be a matrix of rank at most k. $||A B|| = ||U(\Sigma U^T BV)V^T|| = ||\Sigma U^T BV||$ Let's do the change of variable $C = U^T BV$, and since U and V are invertible, that rank(B) = rank(C). $rank(B) \le k \Rightarrow null(C) \ge n-k$, therefore $\{e_1, \ldots, e_{k+1}\} \cap null(C) \ne \{0\}$ (otherwise the dimension of the sum will exceed n). Let $u = \sum_{i \le k+1} \alpha_i e_i$ in that intersection, and assume wihtout loss of generality that $|u| = \sum_{i \le k+1} \alpha_i^2 = 1$.

$$|(\Sigma - C)u|^2 = |\sum_{i \le k+1} \alpha_i e_i|^2 = \sum_{i \le k+1} \alpha_i^2 \sigma_i \ge \sigma_{k+1}, \text{ so } |\sigma - C|_2 \ge \sigma_{k+1}.$$

$$|\Sigma - \Sigma^{(k)}| = |diag(0, \dots, \sigma_{k+1}, \dots)| = \sigma_{k+1}$$

and since $rank(\Sigma^{(k)}) = k$, it is the argmin. Doing the inverse the change of variable $B = UCV^T = U\Sigma^{(k)}V^T$.

But $U\Sigma^{(k)}V^T = U^{(k)}\Sigma^{(k)}V^{(k)}^T$. To prove that we consider the column vectors of V: $(v_1, ..., v_n)$, and we have that:

$$U^{(k)}\Sigma^{(k)}V^{(k)}^{T}v_{i} = \left\{ \begin{array}{cc} U^{(k)}(\sigma_{i}e_{i}) = \sigma_{i}u_{i} & \text{if } i \leq k \\ 0 = U\Sigma^{(k)}e_{i} & \text{if } i > k \end{array} \right\} = U\Sigma^{(k)}Vv_{i}$$

Which proves the result.

 $1. \ 50.2409 \ 31.2567 \ 18.0737 \ 9.9583$

k	$ A - A_{(k)} _F$
25	50.24
50	31.25
100	18.07
200	9.96

2. To store $A^{(k)}$ we need only to store $\Sigma^{(k)}$ (k parameters), $U^{(k)}$, $V^{(k)}$ (each of them has only at most k column not set to zero, so they take nk + mk), while A takes nm numbers to store. In conclusion, we save (nm - k(n + m + 1)).



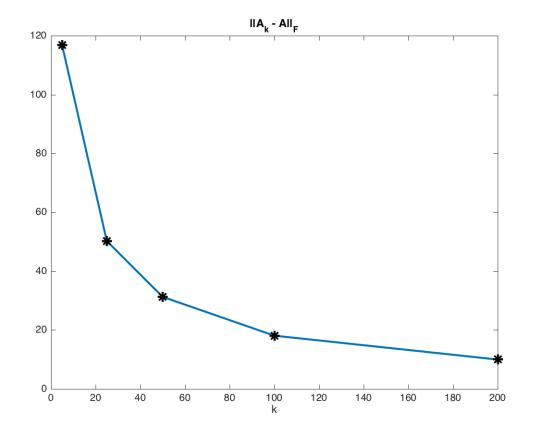


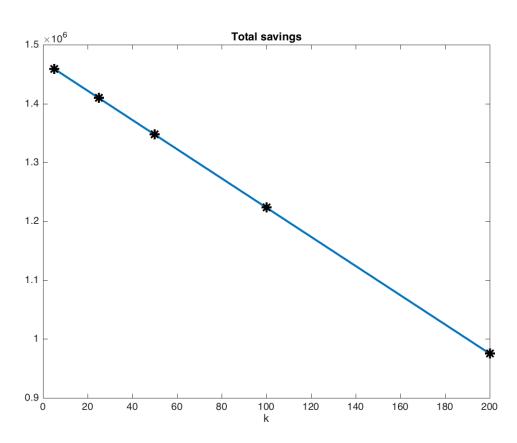






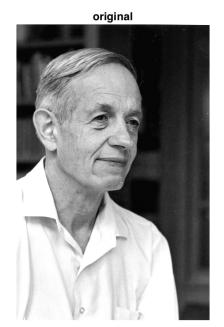






for k = 200, the total saving is 975100.

3. Comparing the original and the compressed image for k = 200. You can't tell the difference.





Code

```
%cd Documents/Princeton/ORF523/hw1/
2
3 | %% Load Image
  A=imread('nash.jpg');
   A=im2double (A);
6
  A=rgb2gray(A);
   [m,n] = size(A);
8
9
   %% SVD decomposition
  [U,S,V] = svd(A);
10
11
12
   %% arrays initialization
13
  k_{range} = [5 25 50 100 200];
  diff_norm = zeros('like', k_range);
14
  total_savings = zeros('like', k_range);
15
16
17 \mid \%\% Plot the original image
18
  subplot(1,length(k_range)+1, 1);
  imshow(A);
19
   title('original')
20
21
22
   for i = 1:length(k_range)
23
       k = k_range(i);
```

```
24
       Uk = U; Sk = S; Vk = V;
25
       Sk(k+1:end, k+1:end) = 0;
26
       Uk(:, k+1:end) = 0;
27
       Vk(:, k+1:end) = 0;
28
       Ak = Uk * Sk * Vk';
29
       diff_norm(i) = norm(A - Ak, 'fro');
30
       total_savings(i) = prod(size(A)) ... % size of A
31
       - k*m ...% size of Uk
32
       - k*n ... % size of Vk
33
       - k; % size of Sigma
34
35
       subplot(1,length(k_range)+1, i+1);
36
       imshow(Ak);
37
       title(['k = ' int2str(k)])
38
   end
   print('compressed','-dpng')
39
40
41
  42
   figure
43
  plot(k_range, diff_norm, ...
44
        '-*',...
45
        'LineWidth',2,...
        'MarkerEdgeColor','k',...
46
47
        'MarkerFaceColor',[.49 1 .63],...
48
        'MarkerSize',10)
49
   title(' | | A_k - A | | F')
   xlabel('k')
50
   print('diffnorm','-dpng')
51
52
53
  |\% Plot total savings
54
  figure
55
   plot(k_range, total_savings,...
56
        '-*',...
57
        'LineWidth',2,...
58
         'MarkerEdgeColor','k',...
59
        'MarkerFaceColor', [.49 1 .63], ...
60
        'MarkerSize',10)
61
62
  title('Total savings')
63
   xlabel('k')
   print('totalsavings','-dpng')
64
65
66 \mid \%\% Plot original and compressed for k = 200
67 | figure
68
  subplot(1,2, 1);
69
  imshow(A);
70 | title('original')
71
   subplot(1,2, 2);
72 \mid imshow(Ak);
```

```
73 | title('k = 200')
74 | print('compare','-dpng')
```

Problem 2

1. Let $u = x_1 + x_2$, it is easy to verify that $f(x_1, x_2) = \underbrace{\frac{u^2}{2} - 2u}_{g(u)} + \underbrace{-2x_2^2 + 3x_2 + \frac{1}{3}x_2^3}_{h(x_2)} = g(u) + h(x_2)$

Since this transformation is a diffeomorphisme, it preserves neighbourhoods, and therefore it preserves local minimizers/maximizers.

A point (u, x_2) is a local maximizer (resp. minimizer) of $g(u) + h(x_2)$ if and only if u is a local maximizer (resp. minimizer) of g and x_2 is local maximizer (resp. minimizer) of h.

- $g(u) = \frac{1}{2}(u-2)^2 2$ has one local(and global) minimum u=2
- $h'(x_2) = x_2^2 4x_2 + 3 = (x_2 1)(x_2 3), h''(x_2) = 2x_2 4$

The candidates are $x_2 = 1$ and $x_2 = 3$. Since h''(1) = -2 < 0, h''(3) = 2 > 0, 1 is local maximum and 3 is a local minimum. f canot have a local maximum because g doesn't have one.

In conclusion, $(u, x_2) = (2, 3)$ is the only local optimizer (it is a local min) of $g(u) + h(x_2)$, and $(x_1 = -5, x_2 = 3)$ is the only local optimizer (minimum) of f.

- 2. By Taylor expansion, since f is a polynomial of order 2: $f(x) f(\bar{x}) = \nabla f(\bar{x})(x \bar{x}) + \frac{1}{2}(x \bar{x})^T \nabla^2 f(x \bar{x})(x \bar{x})$
 - a)(\Rightarrow) Let \bar{x} be a local min, then $\nabla f(\bar{x}) = 0$. If $\nabla^2 f$ is not positive semi-definite, let $d \in \mathbb{R}^n d^T \nabla f(\bar{x}) =: -\lambda < 0$, therefore $f(x + \alpha d) f(x) = -\alpha^2 \lambda < 0$, and for any neighbourhood of \bar{x} , there exist α such that $\bar{x} + \alpha d$ is in that neighbourhood, and we have a contradiction.
 - (\Leftarrow) In this case: $f(x) f(\bar{x}) = \frac{1}{2}(x \bar{x})\nabla^2 f(x \bar{x}) \ge 0$, which proves that \bar{x} is local min.
 - b)(\Rightarrow) In this case: $f(x) f(\bar{x}) = \frac{1}{2}(x \bar{x})\nabla^2 f(x \bar{x}) > 0$, which proves that \bar{x} is strict local min.
 - (\Leftarrow) In this case: $f(x) f(\bar{x}) = \frac{1}{2}(x \bar{x})\nabla^2 f(x \bar{x}) > 0$, which proves that \bar{x} is strict local min.

Counterexamples: $f: \mathbb{R} \to \mathbb{R}, x \to x^3$, f'(0) = 0, f''(0) = 0, but 0 is not a local min. $f: \mathbb{R} \to \mathbb{R}, x \to x^4$, f'(0) = 0, f''(0) = 0, but 0 is a strict local min.

3. using the chain rule: $g'(\alpha) = \frac{d}{||d||} \nabla f(x + \alpha \frac{d}{||d||}), \ g'(0) = \frac{d}{||d||} \nabla f(x).$ Using Cauchy-Shwarz, $|\frac{d}{||d||} \nabla f(x)| \le ||\nabla f(x)||, \text{ so } \frac{-\nabla f(x)}{||\nabla f(x)||} \nabla f(x) \le \frac{d}{||d||} \nabla f(x) \le \frac{\nabla f(x)}{||\nabla f(x)||} \nabla f(x)$

Problem 3

Q > 0, so it admist an eigenvalue decomposition and all the eigen values are positive, let $Q = U\Sigma U^T$ be that decomposition, with $\Sigma = diag(\sigma_1, \ldots, \sigma_n)$, and Let $\sqrt{\Sigma} = diag(\sqrt{\sigma_1}, \ldots, \sqrt{\sigma_n})$, then $Q = U\sqrt{\Sigma}U^TU\sqrt{\Sigma}U^T = \sqrt{Q}^2$

$$f(x) = \sqrt{x^T \sqrt{Q} \sqrt{Q} x} = \sqrt{||\sqrt{Q} x||^2} = ||\sqrt{Q} x||$$

1. f is a norm because:

$$f(\lambda x) = \sqrt{(\lambda x)^T Q(\lambda x)} = \sqrt{\lambda^2} f(x) = |\lambda| f(x)$$

$$f(x+y) = ||\sqrt{Q}x + \sqrt{Q}y|| \le ||\sqrt{Q}x|| + ||\sqrt{Q}y|| \le f(x) + f(y)$$

$$f(x) = 0 \iff \sqrt{Q}x = 0 \iff x = 0$$

By Riesz Representation theorem, we indentify a vector x with the linear form $y \to x^T y$. Let g be the dual norm of f, then

$$g(x) = \sup_{y \neq 0} \frac{x^T y}{f(y)}$$

$$= \sup_{u \neq 0} \frac{x^T \sqrt{Q}^{-1} u}{||u||}$$

$$= \sup_{u \neq 0} x^T \sqrt{Q}^{-1} \frac{u}{||u||}$$

$$= x^T \sqrt{Q}^{-1} \frac{(\sqrt{Q}^{-1} x)}{||\sqrt{Q}^{-1} x||}$$

$$= \frac{x^T Q^{-1} x}{\sqrt{x^T Q^{-1} x}}$$

$$= \sqrt{x^T Q x^{-1}}$$
(Cauchy shwarz, like in Problem 2)

3. $A^T A \ge 0$, Let $U \Sigma U^T$ be an eigen value decomposition where $\Sigma = diag(\sigma_1, \ldots, \sigma_n)$, and $\sigma_1 \ge \ldots \ge \sigma_n \ge 0$.

$$||A||_{2} = \sup_{||x||=1} x^{T} (A^{T} A) x$$

$$= \sup_{||x||=1} ||\sqrt{A^{T} A} x||$$

$$= ||\sqrt{A^{T} A}||_{2}$$

$$= ||\Sigma||_{2}$$

$$= \sup_{||x||=1} x^{T} (\Sigma) x$$

$$= \sup_{||x||=1} \sum_{i} x_{i}^{2} \sigma_{i} \leq \sum_{i} x_{i}^{2} \sigma_{1}$$

$$= \sigma_{1}$$

$$= ||\Sigma e_{1}||$$

So
$$||A||_2 = \sigma_1 = \sqrt{\lambda_{\max}(A^T A)}$$