An ALE Finite Element Method for Vorticity-Streamfunction Formulation with Species Transport Equation

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GESAR

Outline

Introduction

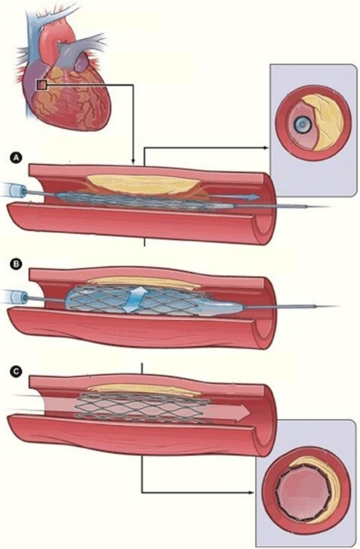
Motivation:

- Ischaemic heart disease and stroke have remained the leading death causes globally in the last 15 years [1]

Goals:

- To develop a ALE-FE code for the Vorticity-Streamfunction Formulation

- To create new drug-eluting stent design patent



[1] World Health Organization, 2018, "The top 10 causes of death". *www.who.int/news-room/fact-sheets/detail/the-top-10-causes-of-death* [Online accessed 06-04-20 08:27pm]

Arbitrary Lagrangian-Eulerian (ALE)

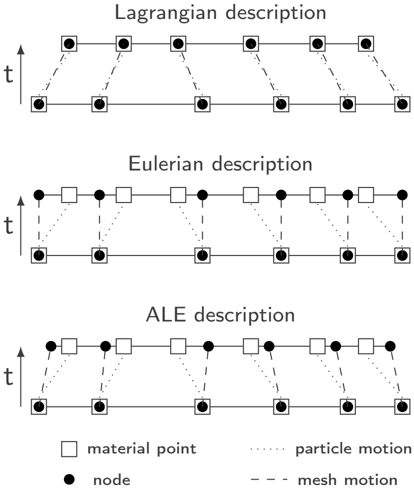
The Arbitrary Lagrangian-Eulerian combines the classical motion descriptions, while it provides [2]:

Advantages:

- Simulations in fluid-structure and moving boundary problems

Disadvantages:

- The computational mesh requires an extensive topological treatment



[2] Donea, J., Huerta, A., Ponthot, J.-P. and Rodríguez-Ferran, A. (2004). Arbitrary Lagrangian–Eulerian Methods. In Encyclopedia of Computational Mechanics *doi:10.1002/0470091355.ecm009*

Governing Equations

Assumptions [3]:

1. Continuum hypothesis
2. Homogeneous and Isotropic
3. Incompressible
4. Newtonian
5. Constant Mass Difusivity
6. Single-phase Flow
7. Two-dimensional flow

$$\frac{\partial \omega}{\partial t} + (\mathbf{v} - \hat{\mathbf{v}}) \cdot \nabla \omega = \frac{1}{Re} \nabla^2 \omega$$

$$\nabla^2 \psi = -\omega$$

$$\frac{\partial e}{\partial t} + (\mathbf{v} - \hat{\mathbf{v}}) \cdot \nabla e = \frac{1}{ReSc} \nabla^2 e$$

- If the mesh velocity field $\hat{\mathbf{v}} = \mathbf{v}$ (*Lagrangian*) or $\hat{\mathbf{v}} = 0$ (*Eulerian*)
- The material velocity field $\mathbf{v} = (v_x, v_y)$ is calculated by: $v_x = \partial\psi/\partial y$ and $v_y = -\partial\psi/\partial x$

[3] Panton, R. (2013). Incompressible Flow John Wiley & Sons, Ltd

Semi-Lagrangian Method

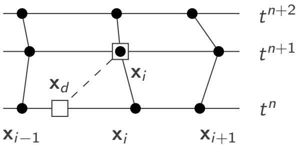
The convective term was replaced by material derivative in the direction of characteristic trajectory, that is: $\frac{D(\cdot)}{Dt} = \frac{\partial(\cdot)}{\partial t} + (\mathbf{v} - \hat{\mathbf{v}}) \cdot \nabla(\cdot)$

$$\frac{D\omega}{Dt} = \frac{1}{Re}\nabla^2\omega$$

$$\nabla^2\psi = -\omega$$

$$\frac{De}{Dt} = \frac{1}{ReSc}\nabla^2 e$$

The departure node is calculated by $x_d^n = x_i^{n+1} - (\mathbf{v} - \hat{\mathbf{v}})\,\Delta t$. Then, a searching procedure is required to find x_d^n using barycentric coordinates



Semi-Lagrangian Method

The implicit semi-Lagrangian time discretization provides [4]:

Advantages:

- Symmetric linear systems
- Unconditionnal stability

Disadvantages:

- Numerical Diffusion
- Searching procedure may lead to excessive computational cost if it is not well designed

$$\frac{\omega_i^{n+1} - \omega_d^n}{\Delta t} = \frac{1}{Re}\nabla^2 \omega^{n+1}$$

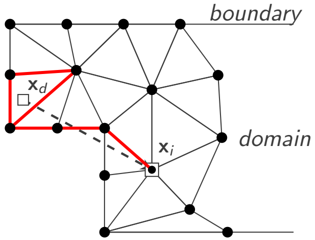
$$\nabla^2 \psi = -\omega$$

$$\frac{e_i^{n+1} - e_d^n}{\Delta t} = \frac{1}{ReSc}\nabla^2 e^{n+1}$$

[4] Pironneau, O. On the transport-diffusion algorithm and its applications to the Navier-Stokes equations. Numer. Math. 38, 309–332 (1982). *https://doi.org/10.1007/BF01396435*

Searching Procedure

The convective term was replaced by material derivative in the direction of characteristic trajectory, that is: $\frac{D(\cdot)}{Dt} = \frac{\partial(\cdot)}{\partial t} + (\mathbf{v} - \hat{\mathbf{v}}) \cdot \nabla(\cdot)$



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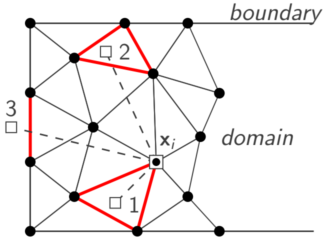
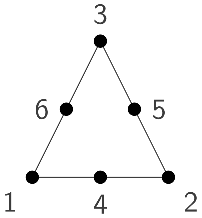
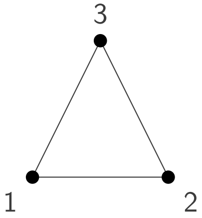


Galerkin FE Method



Quad Element



Linear Element

$$\left[\frac{\mathbf{M}}{\Delta t} + \frac{\mathbf{K}}{Re}\right]\omega_i^{n+1} = \frac{\mathbf{M}}{\Delta t}\omega_d^n$$

$$\mathbf{K}\psi = \mathbf{M}\omega$$

$$\left[\frac{\mathbf{M}}{\Delta t} + \frac{\mathbf{K}}{ReSc}\right]e_i^{n+1} = \frac{\mathbf{M}}{\Delta t}e_d^n$$

- The material velocity field is calculated by:
  $\mathbf{M}v_x = \mathbf{G_y}\psi$
  $\mathbf{M}v_y = -\mathbf{G_x}\psi$

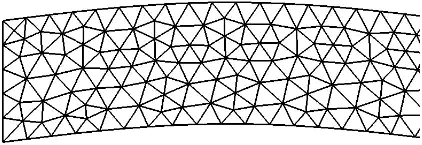
Laplacian Smoothing

To avoid the fast degradation of the computational elements due to ALE description, it was used the Laplacian Smoothing Method [5]

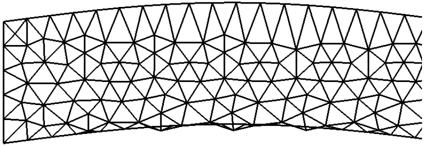
The new node position $\hat{\mathbf{x}}_\mathbf{i}$ can be approximated by:

$$\hat{\mathbf{x}}_\mathbf{i} = w_{ij} \sum_{j}^{N_1} (\mathbf{x}_j - \mathbf{x}_i)$$

where, N_1 is the 1-ring neighbors of the node, w_{ij} is the weight and was calculated by the inverse distance from neighbors vertices



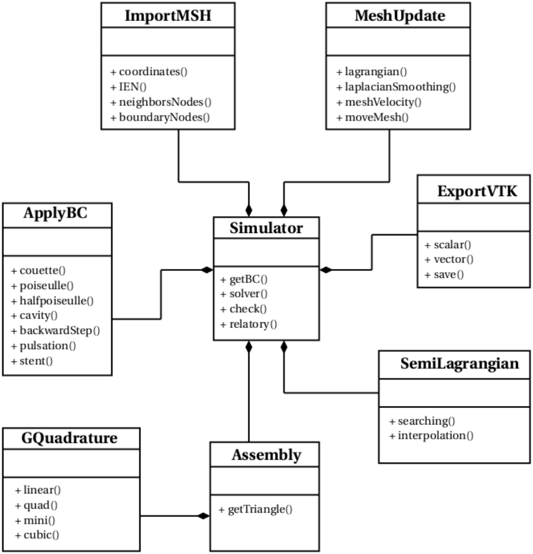
with Laplacian Smoothing



no Laplacian Smoothing

[5] Zheng, Y. Lewis, R. Gethin, D., Three-dimensional unstructured mesh generation: Part 2. surface meshes. Computer Methods in Applied Mechanics and Engineering, Amsterdam: North-Holland Pub. Co., c1972-, v. 134, n. 3, p. 269–284, 1996.

Code Framework



Simplified Class Diagram

Computational Cost

Process	AVG Computational Cost (%)
Mesh import	1.24
Assembly	73.87
BC Apply	6.70
Mesh update	10.05
Semi-Lagrangian	2.27
Vorticity Solver	5.51
VTK export	0.36

Average computational cost for the linear triangular element.

Solution Algorithm

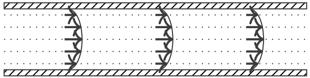
1. Import mesh
2. Calculate Gaussian Quadradure and Assemble Matrix
3. Apply Boundary Conditions
4. Calculate Laplacian smoothing and ALE velocity
5. Move Nodes
6. Calculate semi-Lagrangian Method
7. Calculate Gaussian Quadrature and Assemble Matrix
8. Apply Boundary Conditions
9. Calculate vorticity field
10. Calculate streamfunction field
11. Calculate velocity field
12. Calculate concentration field

Repeat the procedure for the next time step until the steady state

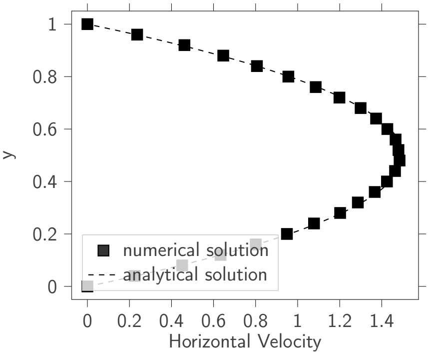
Validation - Poiseuille Flow

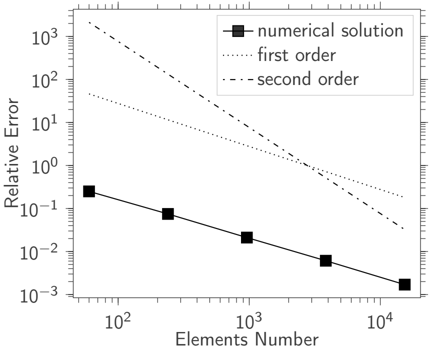
Boundaries Conditions:

Inflow condition: $u = u_{analytical}, \ v = 0$
Top plate: $u = 0, \ v = 0, \ \psi = 1$
Bottom plate: $u = 0, \ v = 0, \ \psi = 0$



Nodes: 1757
Elements: 3263
Relative Error: 1.2%





Validation - Lid Driven Cavity Flow

Boundaries Conditions:

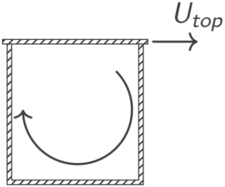
Bottom and side plates: $u = 0$, $v = 0$ e $\psi = 0$

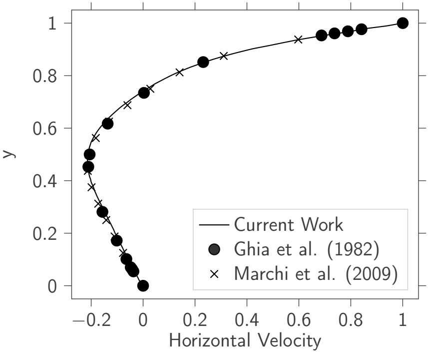
Top plate: $u = 1$, $v = 0$ e $\psi = 0$

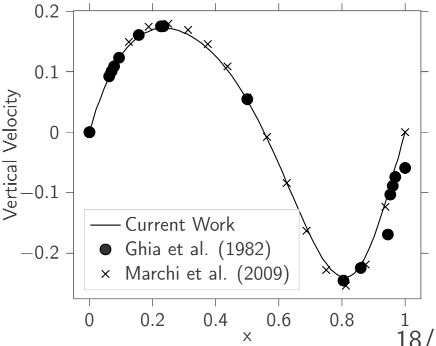
Nodes: 3798

Elements: 7382

Re: 100



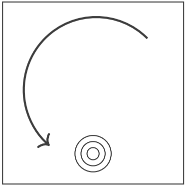




Validation - Pure Advection Flow

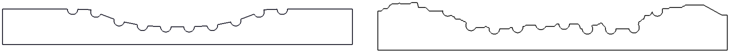
Hipóteses:

1. Fluido como um Meio Contínuo
2. Fluido incompressível
3. Fluido newtoniano
4. Escoamento monofásico
5. Escoamento bidimensional
6. Elevado número de Reynolds ($Re = \infty$)



$$\frac{\partial c}{\partial t} + \mathbf{v} \cdot \nabla c = 0$$

Results



(a)

(b)

Non-dimensional symmetric geometry for blood flow in coronary artery with drug-eluting stent placed by Wang et al. (2017): (a) Curved Channel with Stent (b) Real Channel with Stent.

Boundaries Conditions:

Inflow condition: $u = 1$, $v = 0$ e $\psi = y$;

Outflow condition: $\psi = y$;

Top plate: $u = 0$, $v = 0$, $\psi = 1$;

Symmetry condition: $v = 0$, $\psi = 0$;

Drug-eluting stent: $u = 0$, $v = 0$, $\psi = 1$ e $c = 1$

$R = 0.0015m$

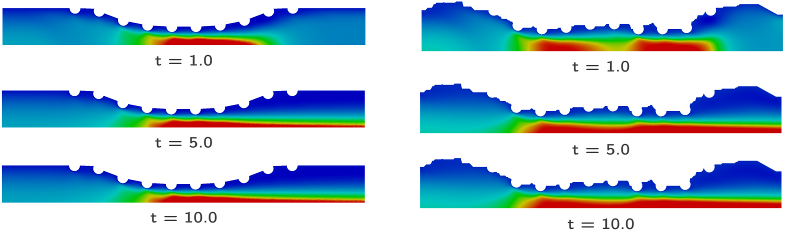
$\mu = 0.0035 Pa.s$

$\rho = 1060 kg/m^3$

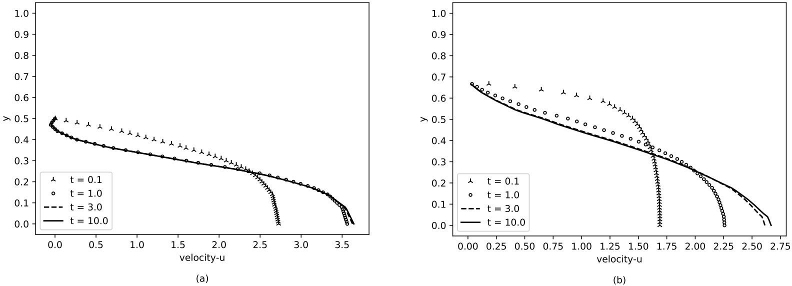
$u = 12 cm/s$

$Re = 54.5$

Results - Velocity Field

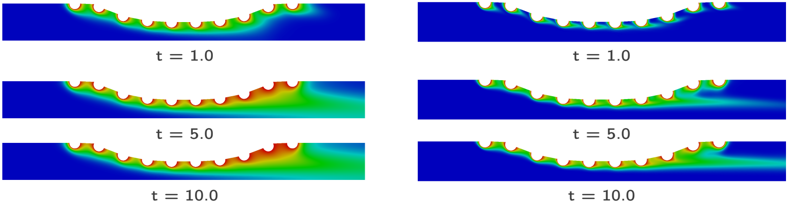


Evolution in time and space of velocity field:
Curved Channel (left column) and Real Channel (right column)

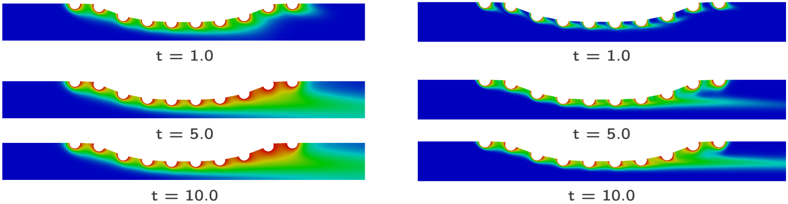


Evolution of velocity profile in centerline ($x = 0.5L$):
(a) Curved Channel and (b) Real Channel

Results - Concentration Field

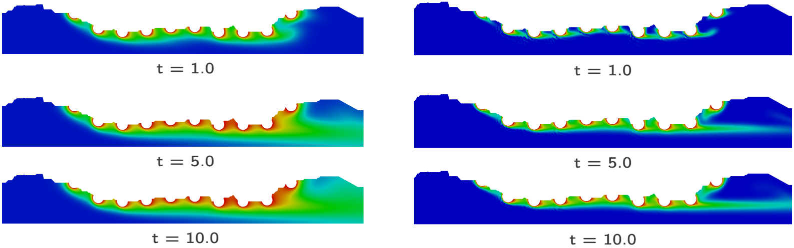


Evolution in time and space of concentration field in Curved Channel:
$Sc = 1$ (left column) and $Sc = 10$ (right column)

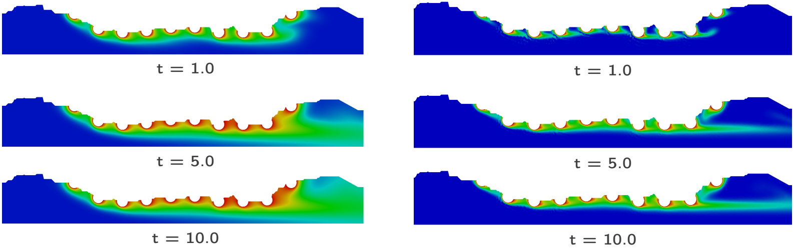


Evolution in time and space of concentration field in Real Channel:
$Sc = 1$ (left column) and $Sc = 10$ (right column)

Results - Concentration Field



Evolution in time and space of concentration field in Curved Channel:
$Sc = 1$ (left column) and $Sc = 10$ (right column)



Evolution in time and space of concentration field in Real Channel:
$Sc = 1$ (left column) and $Sc = 10$ (right column)

Conclusion

1. The streamfunction-vorticity formulation showed an useful approach for to calculate the velocity and concentration fields since the variables are scalars allowing a smooth implementation
2. Due to generalized construction of the code, the simulator is able to describe drug-eluting stent problem in coronary artery as well as flows of Newtonian fluids with scalar transport (concentration or temperature)
3. The ALE description allows moving boundary problems to be simulated

Thank you!

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