

An ALE Finite Element Method for Vorticity-Streamfunction Formulation with Species Transport Equation

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Outline

1. Introduction
2. Mathematical Model
3. Computational Code
4. Validation
5. Results
6. Conclusion

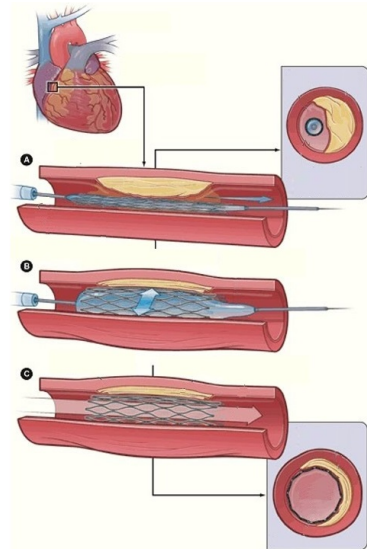
Introduction

Motivation:

- Ischaemic heart disease and stroke have remained the leading death causes globally in the last 15 years [1]

Goals:

- To develop a Finite Element code for the Vorticity-Streamfunction Formulation with species transport equation using the Arbitrary Lagrangian-Eulerian (ALE) approach and semi-Lagrangian Method
- To create new drug-eluting stent design patent



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Arbitrary Lagrangian-Eulerian (ALE)

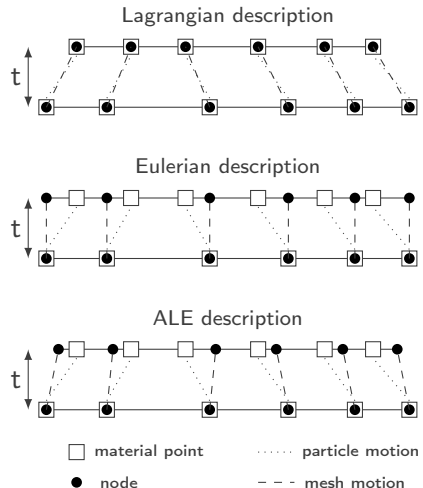
The Arbitrary Lagrangian-Eulerian combines the classical motion descriptions, while it provides [2]:

Advantages:

- Simulations in fluid-structure and moving boundary problems

Disadvantages:

- The computational mesh requires an extensive topological treatment



[2] Donea, J., Huerta, A., Ponthot, J.-P. and Rodríguez-Ferran, A. (2004). Arbitrary Lagrangian-Eulerian Methods. In Encyclopedia of Computational Mechanics *doi:10.1002/0470091355.ecm009*

Governing Equations

Assumptions [3]:

1. Continuum hypothesis
2. Homogeneous and Isotropic
3. Incompressible
4. Newtonian
5. Constant Mass Difusivity
6. Single-phase Flow
7. Two-dimensional flow

$$\frac{\partial \omega}{\partial t} + (\mathbf{v} - \hat{\mathbf{v}}) \cdot \nabla \omega = \frac{1}{Re} \nabla^2 \omega$$

$$\nabla^2 \psi = -\omega$$

$$\frac{\partial c}{\partial t} + (\mathbf{v} - \hat{\mathbf{v}}) \cdot \nabla c = \frac{1}{ReSc} \nabla^2 c$$

- If the mesh velocity field $\hat{\mathbf{v}} = \mathbf{v}$ (*Lagrangian*) or $\hat{\mathbf{v}} = 0$ (*Eulerian*)
- The material velocity field $\mathbf{v} = (v_x, v_y)$ is calculated by:
 $v_x = \partial \psi / \partial y$ and $v_y = -\partial \psi / \partial x$

Semi-Lagrangian Method

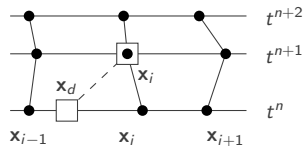
The convective term was replaced by material derivative in the direction of characteristic trajectory, that is: $\frac{D(\cdot)}{Dt} = \frac{\partial(\cdot)}{\partial t} + (\mathbf{v} - \hat{\mathbf{v}}) \cdot \nabla(\cdot)$

$$\frac{D\omega}{Dt} = \frac{1}{Re} \nabla^2 \omega$$

$$\nabla^2 \psi = -\omega$$

$$\frac{Dc}{Dt} = \frac{1}{ReSc} \nabla^2 c$$

The departure node is calculated by $x_d^n = x_i^{n+1} - (\mathbf{v} - \hat{\mathbf{v}}) \Delta t$. Then, a searching procedure is required to find x_d^n using barycentric coordinates



The implicit semi-Lagrangian time discretization provides [4]:

Advantages:

- ▶ Symmetric linear systems
- ▶ Unconditionnal stability

$$\frac{\omega_i^{n+1} - \omega_d^n}{\Delta t} = \frac{1}{Re} \nabla^2 \omega^{n+1}$$

$$\nabla^2 \psi = -\omega$$

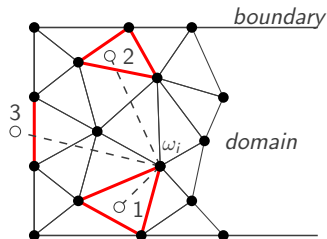
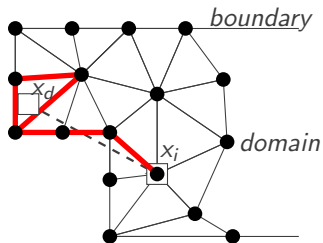
Disadvantages:

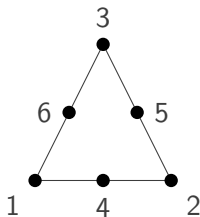
- ▶ Numerical Diffusion
- ▶ Searching procedure may lead to excessive computational cost if it is not well designed

$$\frac{c_i^{n+1} - c_d^n}{\Delta t} = \frac{1}{ReSc} \nabla^2 c^{n+1}$$

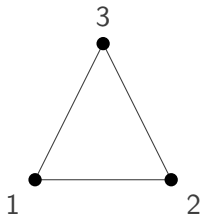
[4] Pironneau, O. On the transport-diffusion algorithm and its applications to the Navier-Stokes equations. Numer. Math. 38, 309–332 (1982). <https://doi.org/10.1007/BF01396435>

Searching Procedure





Quad Element



Linear Element

$$\left[\frac{\mathbf{M}}{\Delta t} + \frac{\mathbf{K}}{Re} \right] \omega_i^{n+1} = \frac{\mathbf{M}}{\Delta t} \omega_d^n$$

$$\mathbf{K}\psi = \mathbf{M}\omega$$

$$\left[\frac{\mathbf{M}}{\Delta t} + \frac{\mathbf{K}}{ReSc} \right] c_i^{n+1} = \frac{\mathbf{M}}{\Delta t} c_d^n$$

- The material velocity field is calculated by:

$$\mathbf{M}v_x = \mathbf{G}_y\psi$$

$$\mathbf{M}v_y = -\mathbf{G}_x\psi$$

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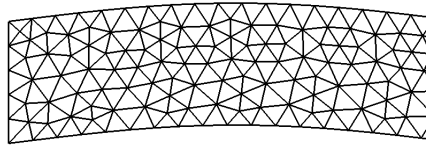
Laplacian Smoothing

To avoid the fast degradation of the computational elements due to ALE description, it was used the Laplacian Smoothing Method [5]

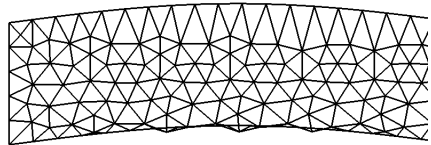
The new node position $\hat{\mathbf{x}}_i$ can be approximated by:

$$\hat{\mathbf{x}}_i = \sum_i^{np} \sum_j^{N_1} w_{ij} (\mathbf{x}_j - \mathbf{x}_i)$$

where, np is node number, N_1 is the 1-ring neighbors of a node, w_{ij} is the weight and was calculated by the inverse distance from neighbors vertices



with Laplacian Smoothing

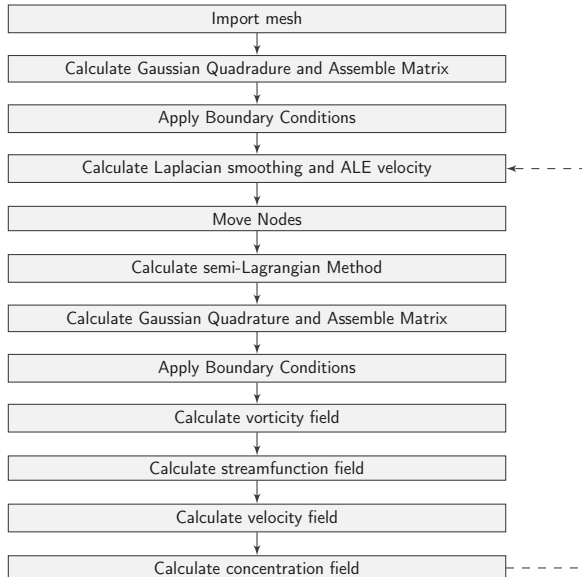


no Laplacian Smoothing

Process	AVG Computational Cost (%)
Mesh import	1.24
Assembly	73.87
BC Apply	6.70
Mesh update	10.05
Semi-Lagrangian	2.27
Vorticity Solver	5.51
VTK export	0.36

Tabela: Average computational cost for several linear triangular elements.

Solution Algorithm



Repeat the procedure
for the next time step
until the steady state

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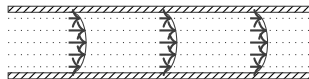
Validation - Poiseuille Flow

Boundaries Conditions:

Inflow condition: $u = u_{analytical}$, $v = 0$

Top plate: $u = 0$, $v = 0$, $\psi = 1$

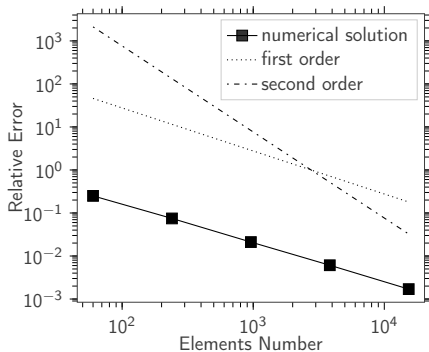
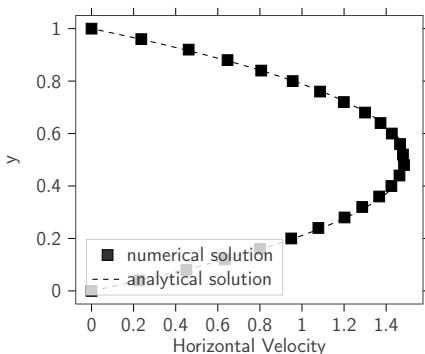
Bottom plate: $u = 0$, $v = 0$, $\psi = 0$



Nodes: 1757

Elements: 3263

Relative Error: 1.2%



Validation - Lid Driven Cavity Flow

Boundaries Conditions:

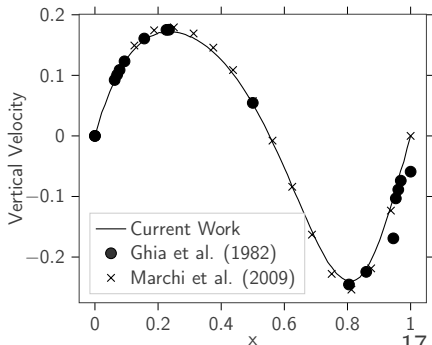
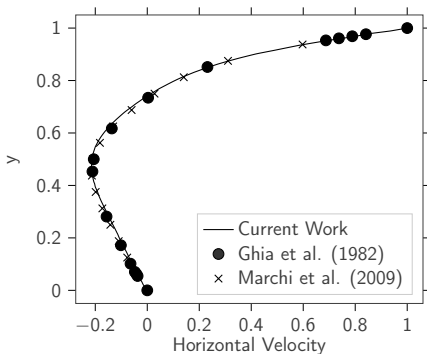
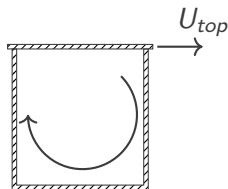
Bottom and side plates: $u = 0$, $v = 0$ e $\psi = 0$

Top plate: $u = 1$, $v = 0$ e $\psi = 0$

Nodes: 3798

Elements: 7382

Re: 100



Coming Soon

- ▶ Backward-Facing Step Validation
- ▶ Pulsation Flow Validation
- ▶ Drug-Eluting Stent Cases

Work Plan

	2018				2019												2020									
ACTIVITIES	9	10	11	12	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	4	5	6	7	8		
SUBJECTS																										
LITERATURE REVIEW																										
CODE IMPLEMENTATION																										
CODE VALIDATION																										
RESULTS SIMULATION																										
PRESENTATION																										

SUBJECTS:

- CONTINUUM MECHANICS I
- ADVANCED CALCULUS
- FLUID MECHANICS
- COMPUTATIONAL FLUID MECHANICS I
- COMPUTATIONAL FLUID MECHANICS II
- FINITE ELEMENT METHOD
- COMPUTATIONAL METHODS
- MULTIPHASE FLOWS

LITERATURE REVIEW:

- ARBITRARY LAGRANGIAN-EULERIAN (ALE)
- SEMI-LAGRANGIAN METHOD
- LAPLACIAN SMOOTHING

Expected Date for Final Presentation

August 2020 < >

	S	M	T	W	T	F	S
31	26	27	28	29	30	31	1
32	2	3	4	5	6	7	8
33	9	10	11	12	13	14	15
34	16	17	18	19	20	21	22
35	23	24	25	26	27	28	29
36	30	31	1	2	3	4	5

Thank you!

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