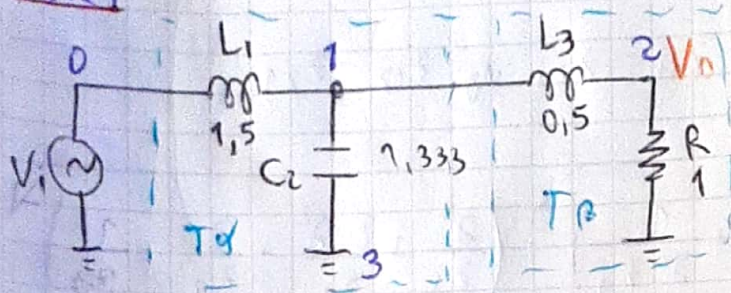


Exercice n° 8

Partie 1



Paramètres Z_L MV:

$$Z_{11} = \left. \frac{V_1}{I_1} \right|_{I_2=0} = L_1 + \frac{1}{sC_2}$$

$$Z_{12} = \left. \frac{V_1}{I_2} \right|_{I_1=0} = \frac{1}{sC_2}$$

$$Z_{21} = \left. \frac{V_2}{I_1} \right|_{I_2=0} = \frac{1}{sC_2}$$

$$Z_{22} = \left. \frac{V_2}{I_2} \right|_{I_1=0} = \frac{1}{sC_2}$$

$$Z_L = \begin{pmatrix} L_1 + \frac{1}{sC_2} & \frac{1}{sC_2} \\ \frac{1}{sC_2} & \frac{1}{sC_2} \end{pmatrix}$$

Paramètres Z_B :

$$Z_B = \begin{pmatrix} L_3 + 1 & 1 \\ 1 & 1 \end{pmatrix}$$

$$Z \begin{cases} V_1 = Z_{11} \cdot I_1 + Z_{12} \cdot I_2 \\ V_2 = Z_{21} \cdot I_1 + Z_{22} \cdot I_2 \end{cases}$$

$$T \begin{cases} V_1 = A \cdot V_2 + B \cdot (-I_2) \\ I_1 = C \cdot V_2 + D \cdot (-I_2) \end{cases}$$

$$A = \left. \frac{V_1}{V_2} \right|_{-I_2=0} = \frac{Z_{11}}{Z_{21}}$$

$$B = \left. \frac{V_1}{-I_2} \right|_{V_2=0} =$$

$$0 = Z_{21} \cdot I_1 + Z_{22} \cdot I_2 \rightarrow I_1 = -\frac{Z_{22} \cdot I_2}{Z_{21}} \rightarrow \text{Remplacer dans la 1^{re} équation}$$

$$V_1 = Z_{11} \cdot \left(-\frac{Z_{22} \cdot I_2}{Z_{21}} \right) + Z_{12} \cdot I_2$$

$$\frac{V_1}{-I_2} = \frac{Z_{11} \cdot Z_{22} - Z_{12} \cdot Z_{21}}{Z_{21}} = \frac{\det(Z)}{Z_{21}} = B$$

$$C = \left. \frac{I_1}{V_2} \right|_{-I_2=0} = \frac{1}{Z_{21}}$$

$$D = \left. \frac{I_1}{-I_2} \right|_{V_2=0} = \frac{Z_{22}}{Z_{21}}$$

T α :

$$A = \frac{z_{11}}{z_{21}} = \frac{L_1 + \frac{1}{sC_2}}{\frac{1}{sC_2}} = sL_1C_2 + 1 \quad C = sC_2$$

$$B = \frac{\left(L_1 + \frac{1}{sC_2}\right) - \frac{1}{s^2C_2}}{\frac{1}{sC_2}} = L_1 - \frac{1}{sC_2}$$

$$D = \frac{\frac{1}{sC_2}}{\frac{1}{sC_2}} = 1$$

$$T_\alpha = \begin{pmatrix} sL_1C_2 + 1 & L_1 - \frac{1}{sC_2} \\ sC_2 & 1 \end{pmatrix}$$

T β :

$$A = \frac{z_{11}}{z_{21}} = L_3 + 1 \quad C = 1$$

$$B = L_3 + 1 - 1 = L_3 \quad D = 1$$

$$T_\beta = \begin{pmatrix} L_3 + 1 & L_3 \\ 1 & 1 \end{pmatrix}$$

$$T_T = T_\alpha \cdot T_\beta$$

$$T_T = \begin{pmatrix} sL_1C_2 + 1 & L_1 - \frac{1}{sC_2} \\ sC_2 & 1 \end{pmatrix} \cdot \begin{pmatrix} L_3 + 1 & L_3 \\ 1 & 1 \end{pmatrix}$$

$$T_T = \begin{pmatrix} (L_3 + 1)(sL_1C_2 + 1) + (L_1 - \frac{1}{sC_2}) & L_3(sL_1C_2 + 1) + L_1 - \frac{1}{sC_2} \\ sC_2L_3 + sC_2 + 1 & sC_2L_3 + 1 \end{pmatrix}$$

$$A = \frac{V_1}{V_2} = (L_3 + 1)(sL_1C_2 + 1) + L_1 - \frac{1}{sC_2}$$

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$$A = sL_1L_3C_2 + sL_1C_2 + \cancel{sL_1C_2}L_3 + 1 + L_1 - \frac{1}{sC_2}$$

$$A = \frac{s^2(L_1L_3C_2^2 + L_1C_2^2) + s(C_2L_3 + C_2L_1 + C_2) - 1}{sC_2}$$

$$\frac{V_Q}{V_i} = A^{-1} = \frac{sC_2}{s^2(L_1L_3C_2^2 + L_1C_2^2) + s(C_2L_3 + C_2L_1 + C_2) - 1}$$

$$Y_{MAI} = \begin{pmatrix} Y_1 & -Y_1 & 0 & 0 \\ -Y_1 & Y_1 + Y_2 + Y_3 & -Y_3 & -Y_2 \\ 0 & -Y_3 & Y_3 + Y_1 & -Y_1 \\ 0 & -Y_2 & -Y_1 & Y_2 + Y_1 \end{pmatrix}$$

$$Y_{MAI} = \begin{pmatrix} \frac{1}{sL_1} & -\frac{1}{sL_1} & 0 & 0 \\ -\frac{1}{sL_1} & \frac{1}{sL_1} + sC_2 + \frac{1}{sL_3} & -\frac{1}{sL_3} & -sC_2 \\ 0 & -\frac{1}{sL_3} & \frac{1}{sL_3} + 1 & -1 \\ 0 & -sC_2 & -1 & sC_2 + 1 \end{pmatrix}$$

$$A_{03}^{23} = \frac{V_{23}}{V_{03}} = \text{signos}(0-3) \cdot \text{signos}(2-3) \cdot \frac{Y_{23}^{03}}{Y_{03}^{03}}$$

$$\frac{V_0}{V_i} = (-1) \cdot (-1) \cdot \frac{Y_{23}^{03}}{Y_{03}^{03}}$$

$$Y_{23}^{03} = \frac{1}{s^2 L_1 L_3}$$

$$\begin{aligned} Y_{03}^{03} &= \left(\frac{1}{sL_1} + sC_2 + \frac{1}{sL_3} \right) \cdot \left(\frac{1}{sL_3} + 1 \right) - \frac{1}{s^2 L_3^2} \\ &= \frac{1}{s^2 L_1 L_3} + \frac{1}{sL_1} + \frac{C_2}{L_3} + sC_2 + \frac{1}{s^2 L_3^2} + \frac{1}{sL_3} - \frac{1}{s^2 L_3^2} \\ &= \frac{1 + sL_3 + s^2 L_1 C_2 + s^3 L_1 C_2 L_3 + sL_1}{s^2 L_1 L_3} \end{aligned}$$

$$\frac{V_0}{V_i} = \frac{\frac{1}{s^2 L_1 L_3}}{\frac{1 + sL_3 + s^2 L_1 C_2 + s^3 L_1 C_2 L_3 + sL_1}{s^2 L_1 L_3}}$$

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$$\frac{V_0}{V_i} = \frac{1}{s^3 L_1 L_3 C_2 + s^2 L_1 C_2 + s(L_1 + L_3) + 1}$$