# **MEHRAN ZAMANI**

### MASc. | Al Engineer | Software Developer | MERN Stack

@ m\_zamani@live.com
 martellato \$ Go

.com **J** (647) 913-7236 **S** Google Scholar **D** 0000

Blvd. Waterloo, Ont in mehran-zamani-abnili

Portfolio

# SUMMARY OF SKILLS AND QUALIFICATION

- 4 years of experience in developing AI/ML platforms for a variety of applications
- Expert in Python and fluent in machine learning platforms such as PyTorch and TensorFlow
- Expert in systems programming with 8+ years of C++ experience and working knowledge of Rust
- Experienced in data manipulation and preprocessing techniques and strategies
- Experienced in post-processing, filtering, and statistical analysis techniques
- Published in AI with three published papers, two accepted papers, and one under review
- Multi-disciplinary generalist with production level applied AI experience
- Devotee of software development best practices and Agile methodologies

## **EXPERIENCE**

# Graduate Research Associate University of Waterloo/Toyota

苗 Jan. 2021 - Ongoing

Waterloo, Ontario

- Implemented epoch-split and data-split continual strategies for the short-term microscopic traffic participants' behaviour prediction strategy enabling the agents to train during the vehicle's downtime as new data becomes available. Converging over time the accuracy of predictions with an overall average accuracy of 1.5% MAPE
- Submitted two manuscripts from the results of the work done at Columbiad Launch Services Inc. and the project with Toyota
- Working on publishing the work done at the scaled autonomous vehicle test platform

## Intern AI Engineer

### **Columbiad Launch Services Inc.**

- **Sept.** 2020 Dec. 2020
- Kitchener, Ontario
- Created an orbital dynamics Python module with functions for space object dynamics, orbital element computations and space data stream processing as the toolbox for this project to be used by future researchers
- Designed and developed a space domain awareness infrastructure, a universal model for resident space object tracking and motion prediction using a recurrent neural network
- Statistical analysis on the results show a significant improvement in the accuracy of forecasts compared to the industry standard SGP-4 framework with  $\approx\!2\%$  MAPE for 10-day horizon compared to  $\approx\!50\%$
- Improved the efficiency of training by incorporating distributed data-split continual-learning strategy
- Used Amazon Elastic Cloud Computing, Google Cloud Compute Engine and Compute Canada GPU node resources to expedite the training
- Worked directly with the client and consulted Columbiad Launch Services Inc. for the decision-making in hardware and software implementation choices

## **ACHEIVEMENTS**

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**Champion of Footballer Robot League** 

Achieved 1<sup>st</sup> place in a simulation footballer robot tournament for competing controller designs



**President of Robotics Club** 

Was the president of Robotics Club under Student Scientific Association of University of Isfahan for three consecutive terms.



**Best Paper Award** 

Recieved the best paper award in the 7<sup>th</sup> International Conference of Controls, Dynamic Systems, and Robotics (CDSR'20)

# **SKILLS**

### **Languages and Tools**

Python
C++
Matlab
Haskell
JavaScript
Rust
Linux

Git
Docker
Apache Spark
Apache Hive
SQL
MongoDB
Apache Hadoop

Glavel Dreatife

**Amazon Web Services** 

**Cloud Practitioner** 

## **PROJECTS**

Short-Term Microscopic Traffic Participants Behaviour Prediction for Automated Vehicles

### University of Waterloo/Toyota

- **Sept.** 2018 Sept. 2020
- Proposed and established a novel hybrid deep-learning PGM strategy for microscopic, short-term, multi-agent, and contextaware traffic participant behaviour prediction
- Deployed the method for different traffic scenarios including highway merging, urban, intersection, and roundabout driving, and achieved accurate forecast results with great performance and real-world implementation considerations
- Inspired and impressed Toyota, the strategy is being investigated for implementation in next-gen Toyota vehicles

# Scaled Autonomous Vehicle Test Platform University of Waterloo/SHEVS Lab

- 苗 Jan. 2019 Sept. 2020
- Recruited, mentored, and supervised two final year design project teams and one undergraduate research assistant
- Designed and incorporated a scaled-down city layout in a 900 sqft. space, with a control network containing 14 nodes (6 computers and 8 Vicon<sup>®</sup> global positioning system cameras)
- Designed and built two fully-instrumented scaled-down robot cars with Encoders, LiDARs, and Cameras, controlled by NVIDIA<sup>®</sup> Jetson™TX2 running Ubuntu<sup>®</sup> and Arduino<sup>®</sup> actuator controller
- Incorporated human-in-the-loop system and control scheme
- Developed and deployed an ML-based roundabout controller

## **PUBLICATIONS**

- 1. M. Zamani Abnili, and Nasser L. Azad, "Universal Forecasting Model for Context-Aware Perception in Autonomous Highway Merging," *IEEE transactions on Intelligent Vehicles*. (Under review)
- 2. M. Zamani Abnili, Nasser L. Azad, H. B. Oqab, and G. B. Dietrich "Space Domain Awareness Using Deep Continual Learning Sequence Predictors," 19th IAA Symposium on Space Debris. (Accepted/to be published)
- 3. M. Zamani Abnili, and Nasser L. Azad, "On-line Situational Awareness for Autonomous Driving at Roundabouts using Artificial Intelligence," *Journal of Machine Intelligence and Data Science* (*JMIDS*), 2021, pp. 17–24, doi: TBA
- M. Zamani Abnili, and Nasser L. Azad, "Roundabout Situational Awareness for Automated Vehicles with Hybrid Machine Learning Approach," In Proc. 7<sup>th</sup> International Conference of Control, Dynamic Systems, and Robotics (CDSR'20), 2020, pp. CDSR 155-1 – 155-8, doi: 10.11159/cdsr20.155. (Best paper award)
- M. Zamani Abnili, and Nasser L. Azad, "A New Data-Driven Approach For On-line Traffic Participant Behaviour Prediction at Intersections for Automated Driving," *Progress in Canadian Mechanical Engineering*. V.3, Jun. 2020, doi: 10.32393/csme.2020.110
- M. Zamani Abnili, and Nasser L. Azad, "Short Term Predictions of Preceding Vehicle Speeds for Connected and Automated Vehicles," In Proc. 6<sup>th</sup> International Conference of Control, Dynamic Systems, and Robotics (CDSR'19), 2019, pp. CDSR 132-1 – CDSR 132-8, doi: 10.11159/cdsr19.132.

#### Libraries



### **ML Experience**

- Deep Neural Network
- Recurrent Neural Network
- Long Short-Term Memory
- Gated Recurrent Unit
- Dynamic Bayesian Network
- Learning Probabilistic Graphical Model
- Reinforcement Learning | Q-Learning
- Genetic Algorithm
- Fuzzy Logic Systems

### Misc.

- Filtering | Smoothing
- Data Analysis | Statistical Methods
- Data Cleaning | Parsing | Processing
- Graph Algorithms | Network Systems
- Distributed Computation Techniques
- Embedded Systems

## **EDUCATION**

MASc. Mechanical and Mechatronics Engineering

#### **University of Waterloo**

 **J**an. 2018 - Dec. 2020

- Project: Short-Term Microscopic Traffic Participants Behaviour Prediction for Automated Vehicles
- Advisor: Nasser L. Azad
- Sponsors: Toyota | NSERC | OCE

# B.Sc. Mechanical Engineering University of Isfahan

**Sept.** 2013 - May. 2017

- Project: Thermodynamic modelling of internal combustion engines
- Advisor: H. Ahmadikia
- **Special Achievements:** Early Graduation in 7 terms | Contribution to the book "Internal Combustion Engines" by H. Ahmadikia, University of Isfahan Press, 2018

### **REFERENCES**

#### **Upon request**