## 1 The Model

There are two players, a sender and a receiver, and a state of nature  $q \in [0,1]$  that is known to the sender but not the receiver. Let g denote the density of q. The sender sends an *intended* message  $m(q) \in [0,1]$ . The receiver receives a noisy version of the intended message, which we call the *received* message,  $\widetilde{m} = m + \epsilon$ .  $\epsilon$  is distributed according to a continuous density f with support  $[-\overline{\epsilon}, \overline{\epsilon}]$ , where  $\overline{\epsilon} = \frac{1}{2N} > 0$ . The receiver then takes an action  $A(\widetilde{m}) \in [0,1]$ .

Both sender and receiver have utility over the state, q, and the receiver's action, A, of

$$U(q, A) = -\frac{1}{2}(q - A)^{2}I(q)$$
(1)

Prior to the start of the game, the sender can specify an intended message function m(q) that she will use. The receiver chooses an action based upon the function m(q) and the received message  $\widetilde{m}$ , and we denote this function  $A(\widetilde{m})$ . We work backward and start with the optimal action, given m(q) and  $\widetilde{m}$ .

Fix a message function m. Let  $Q(\widetilde{m})$  denote the set of all states  $q \in [0,1]$  such that for some noise  $e \in [-\bar{\epsilon}, \bar{\epsilon}], \ \widetilde{m} = m(q) + e$ . Put differently,

$$Q(\widetilde{m}) = \{ q \in [0, 1] | m(q) - \overline{\epsilon} \le \widetilde{m} \le m(q) + \overline{\epsilon} \}. \tag{2}$$

Finally, let  $q_+(\widetilde{m}) \equiv \sup Q(\widetilde{m}), q_-(\widetilde{m}) \equiv \inf Q(\widetilde{m}),$  and  $w(\widetilde{m}) \equiv q_+(\widetilde{m}) - q_-(\widetilde{m}).$   $q_+(\widetilde{m})$  and  $q_-(\widetilde{m})$  are the highest and lowest states that could possibly be associated with the received message  $\widetilde{m}$ .  $w(\widetilde{m}) \equiv q_+(\widetilde{m}) - q_-(\widetilde{m})$  is the distance between these two bounds. Except near the boundaries of the message space,  $w(\widetilde{m})$  is equal to  $2\overline{\epsilon}$ .

Suppose that the receiver receives the message  $\widetilde{m} \in [-\overline{\epsilon}, 1 + \overline{\epsilon}]$ .  $q | \widetilde{m}$  has support  $[q_{-}(\widetilde{m}), q_{+}(\widetilde{m})]$ , and

$$g(q|\widetilde{m}) = \frac{f(\widetilde{m} - m(q))g(q)}{\int_0^1 f(\widetilde{m} - m(t))g(t)dt}$$
(3)

The receiver's problem is to choose an action that maximizes her expected utility:

$$\max_{a(\widetilde{m})} \int_{q_{-}(\widetilde{m})}^{q_{+}(\widetilde{m})} U(q, a) g(q | \widetilde{m}) dq. \tag{4}$$

Because of Assumptions A1 to A3, the receiver's optimal action is simply the expected value of the state, q, given the received message  $\tilde{m}$ :

$$A(\widetilde{m}) = \int_{q_{-}(\widetilde{m})}^{q_{+}(\widetilde{m})} qg(q|\widetilde{m})dq. \tag{5}$$

It will be helpful to refer to the cost of a message function. Let the cost functional C be given by

$$C[m] \equiv \int_0^1 \int_{-\bar{\epsilon}}^{\bar{\epsilon}} (q - A(m(q) + e))^2 f(e) de dq, \tag{6}$$

where A is the receiver's optimal action from Equation (5). C[m] is the expected loss for a given message function m. The integrand is the loss for a given state q and action  $A(\tilde{m})$ . The interior integral integrates over the possible exogenous errors, to generate the expected loss given the state. The exterior integral integrates over possible states. Therefore, the sender's problem is to choose a message function m that minimizes C[m]:

$$\min_{m \in M} C[m] \tag{7}$$

where M is the space of weakly increasing piece-wise continuous functions on [0,1]. The change of variables  $\widetilde{m}=m(q)+e$  and an application of Fubini's Theorem yield

$$C[m] = \int_0^1 \int_{m(q)-\bar{\epsilon}}^{m(q)+\bar{\epsilon}} (q - A(\tilde{m}))^2 f(\tilde{m} - m(q)) g(q) d\tilde{m} dq$$
 (8)

$$= \int_{-\bar{\epsilon}}^{1+\bar{\epsilon}} \int_{q_{-}(\widetilde{m})}^{q_{+}(\widetilde{m})} (q - A(\widetilde{m}))^{2} f(\widetilde{m} - m(q)) g(q) dq d\widetilde{m}. \tag{9}$$

## 2 Identity Message

Define

$$I_{(\alpha,\beta,\gamma)}(\widetilde{m}) \equiv \int_{\alpha}^{\beta} q^{\gamma} f(\widetilde{m} - q) dq$$
 (10)

and

$$A(\widetilde{m}) = \begin{cases} \overline{a}(\widetilde{m}) & \text{if } 1 - \overline{e} < \widetilde{m} \le 1 + \overline{e} \\ a(\widetilde{m}) & \text{if } \overline{e} < \widetilde{m} \le 1 - \overline{e} \\ \underline{a}(\widetilde{m}) & \text{if } - \overline{e} \le \widetilde{m} \le \overline{e} \end{cases}$$
(11)

where

$$\overline{a}(\widetilde{m}) = \frac{I_{(\widetilde{m} - \overline{e}, 1, 1)}(\widetilde{m})}{I_{(\widetilde{m} - \overline{e}, 1, 0)}(\widetilde{m})}$$
(12)

$$a(\widetilde{m}) = \frac{I_{(\widetilde{m} - \overline{e}, \widetilde{m} + \overline{e}, 1)}(\widetilde{m})}{I_{(\widetilde{m} - \overline{e}, \widetilde{m} + \overline{e}, 0)}(\widetilde{m})}$$
(13)

$$\underline{\underline{a}}(\widetilde{m}) = \frac{I_{(0,\widetilde{m}+\bar{e},1)}(\widetilde{m})}{I_{(0,\widetilde{m}+\bar{e},0)}(\widetilde{m})}$$
(14)

Note that the normalizing constant cancels out when computing the conditional expectation. We need three sets of weights and knots.

The cost of the identity message function is given by

$$C[m_i] = \int_{-\bar{e}}^{1+\bar{e}} \int_{q_-(\widetilde{m})}^{q_+(\widetilde{m})} (q - A(\widetilde{m}))^2 f(\widetilde{m} - q) dq d\widetilde{m}.$$
 (15)

where

$$q_{+}(\widetilde{m}) = \min\{\widetilde{m} + \bar{e}, 1\} \tag{16}$$

$$q_{-}(\widetilde{m}) = \max\{\widetilde{m} - \bar{e}, 0\} \tag{17}$$

Define

$$\overline{z} = \int_{1-\bar{e}}^{1+\bar{e}} \int_{\widetilde{m}-\bar{e}}^{1} (q - \overline{a}(\widetilde{m}))^2 f(\widetilde{m} - q) dq d\widetilde{m}$$
 (18)

$$z = \int_{\bar{e}}^{1-\bar{e}} \int_{\widetilde{m}-\bar{e}}^{\widetilde{m}+\bar{e}} (q - a(\widetilde{m}))^2 f(\widetilde{m} - q) dq d\widetilde{m}$$
 (19)

$$\underline{z} = \int_{-\bar{e}}^{\bar{e}} \int_{0}^{\tilde{m}+\bar{e}} (q - \underline{a}(\tilde{m}))^{2} f(\tilde{m} - q) dq d\tilde{m}$$
 (20)

Let  $x:[-\overline{e},\overline{e}] \to [0,1]$  be given by

$$x(e) = \frac{1}{2} \left[ 1 + \frac{e}{\overline{e}} \right] \tag{21}$$

Consider, as an example, the Beta PDF:

$$f(e) = x(e)^{a-1} (1 - x(e))^{b-1}$$
(22)

for constants a > 0 and b > 0.

## 3 Discrete Message

A discrete message with N+1 message is given by

$$m_d(q) = \sum_{n=0}^{N} \frac{n}{N} \mathbf{1}_{\frac{n}{N+1} \le q \frac{n+1}{N+1}}.$$
 (23)

where  $\bar{e} = 1/(2N)$ .

$$q_{+}(\widetilde{m}) = \min\{\widetilde{m} + \bar{e}, 1\} \tag{24}$$

$$q_{-}(\widetilde{m}) = \max\{\widetilde{m} - \bar{e}, 0\} \tag{25}$$

We have

$$I_{\gamma}(k) = \int_{q_k}^{q_{k+1}} q^{\gamma} f(\widetilde{m} - m(q)) dq$$
 (26)

The receiver knows which message was sent. The action function is

$$A(\widetilde{m}) = \tag{27}$$

The cost of the discrete message function is given by

$$C[m_d] = \frac{1}{3} \left( \frac{\bar{e}}{1 + 2\bar{e}} \right)^2 \tag{28}$$

## 4 Smooth Message

Suppose that for some  $N \geq 2, \; \bar{e} = 1/(2N).$  For  $i \in \{0,\dots,M\}$  and  $j \in \{0,\dots,N\},$  let

$$x_{i,j} = \frac{i + jM}{MN} \tag{29}$$

Unlike the case in which the receiver can perfectly infer the message sent. We have that

$$x$$
 (30)