I've done the math enough to know the dangers of our second guessing
Doomed to crumble unless we grow and strengthen our communication

$\sim$ Tool

1   The Model

There are two players, a sender and a receiver, and a state of nature $q \in [0, 1]$ that is known to the sender but not the receiver. Let g denote the density of q. The sender sends an *intended* message $m(q) \in [0, 1]$. The receiver receives a noisy version of the intended message, which we call the *received* message, $\widetilde{m} = m(q) + e$. e is distributed according to a continuous density f with support $[-\bar{e}, \bar{e}]$, where for some integer $N \geq 2$, $\bar{e} = \frac{1}{2N}$.

We specify f as follows. Let $x : [-\bar{e}, \bar{e}] \to [0, 1]$ be given by

$$x(e) = \frac{1}{2}\left[1 + \frac{e}{\bar{e}}\right] \tag{1}$$

Consider, as an example, the Beta PDF:

$$f(e) = x(e)^{a-1}(1 - x(e))^{b-1} \tag{2}$$

for constants $a > 0$ and $b > 0$. The receiver then takes an action $a(\widetilde{m}) \in [0, 1]$. Both sender and receiver have utility over the state, q, and the receiver's action, a, of

$$U(q, a) = -\frac{1}{2}(q - a)^2 \tag{3}$$

Prior to the start of the game, the sender can specify an intended message function $m(q)$ that she will use. The receiver chooses an action based upon the function $m(q)$ and the received message $\widetilde{m}$, and we denote this function $a(\widetilde{m})$. We work backward and start with the optimal action, given $m(q)$ and $\widetilde{m}$.

Fix a message function m. Let $Q(\widetilde{m})$ denote the set of all states $q \in [0, 1]$ such that for some noise $e \in [-\bar{e}, \bar{e}]$, $\widetilde{m} = m(q) + e$. In set builder notation,

$$Q(\widetilde{m}) = \{q \in [0, 1] \mid m(q) - \bar{e} \leq \widetilde{m} \leq m(q) + \bar{e}\}. \tag{4}$$

Finally, define

$$q_+(\widetilde{m}) \equiv \sup Q(\widetilde{m}) \tag{5}$$

$$q_-(\widetilde{m}) \equiv \inf Q(\widetilde{m}) \tag{6}$$

$q_+(\widetilde{m})$ and $q_-(\widetilde{m})$ are the highest and lowest states that could possibly be associated with the received message $\widetilde{m}$. Define

$$I(\widetilde{m}; \alpha, \beta, \gamma) \equiv \int_{\alpha}^{\beta} q^{\gamma} f(\widetilde{m} - m(q))dq \tag{7}$$

Suppose that the receiver receives the message $\widetilde{m} \in [-\bar{e}, 1+\bar{e}]$. $q|\widetilde{m}$ has support $[q_-(\widetilde{m}), q_+(\widetilde{m})]$ and density

$$g(q|\widetilde{m}) = \frac{f(\widetilde{m} - m(q))g(q)}{\int_0^1 f(\widetilde{m} - m(t))g(t)dt} \tag{8}$$

The receiver's problem is to

$$\max_{a(\widetilde{m})} \int_{q_-(\widetilde{m})}^{q_+(\widetilde{m})} U(q, a)g(q|\widetilde{m})dq. \tag{9}$$

The receiver's optimal action is simply the expected value of the state, q, given the received message $\widetilde{m}$:

$$a(\widetilde{m}) = \int_{q_-(\widetilde{m})}^{q_+(\widetilde{m})} qg(q|\widetilde{m})dq = \frac{I(\widetilde{m}; q_-(\widetilde{m}), q_+(\widetilde{m}), 1)}{I(\widetilde{m}; q_-(\widetilde{m}), q_+(\widetilde{m}), 0)} \tag{10}$$

It will be helpful to refer to the *cost* of a message function. Let the cost functional C be given by

$$C[m] \equiv \int_0^1 \int_{-\bar{e}}^{\bar{e}} (q - a(m(q) + e))^2 f(e)dedq, \tag{11}$$

where a is the receiver's optimal action from Equation (10). $C[m]$ is the expected loss for a given message function m. The integrand is the loss for a given state q and action $a(\widetilde{m})$. The interior integral integrates over the possible exogenous errors, to generate the expected loss given the state. The exterior integral integrates over possible states. Therefore, the *sender's problem* is to choose a message function m that minimizes $C[m]$:

$$\min_{m \in M} C[m] \tag{12}$$

where M is the space of weakly increasing piece-wise continuous functions on $[0, 1]$. The change of variables $\widetilde{m} = m(q) + e$ and an application of Fubini's Theorem yield

$$C[m] = \int_0^1 \int_{m(q)-\bar{e}}^{m(q)+\bar{e}} (q - a(\widetilde{m}))^2 f(\widetilde{m} - m(q))g(q)d\widetilde{m}dq \tag{13}$$

$$= \int_{-\bar{e}}^{1+\bar{e}} \int_{q_-(\widetilde{m})}^{q_+(\widetilde{m})} (q - a(\widetilde{m}))^2 f(\widetilde{m} - m(q))g(q)dqd\widetilde{m}. \tag{14}$$

We consider the costs of identity ("$\mathcal{I}$") and discrete ("$\mathcal{D}$") message functions.

2 Identity Message

We consider the identity message function, $m(q) = q$, only for the case in which q is uniformly distributed.

$$a(\widetilde{m}) = \begin{cases} \overline{a}(\widetilde{m}) & \text{if } 1 - \overline{e} < \widetilde{m} \le 1 + \overline{e} \\ a(\widetilde{m}) & \text{if } \overline{e} < \widetilde{m} \le 1 - \overline{e} \\ \underline{a}(\widetilde{m}) & \text{if } -\overline{e} \le \widetilde{m} \le \overline{e} \end{cases} \tag{15}$$

where

$$\overline{a}(\widetilde{m}) = \frac{I(\widetilde{m}; \widetilde{m} - \overline{e}, 1, 1)}{I(\widetilde{m}; \widetilde{m} - \overline{e}, 1, 0)} \tag{16}$$

$$a(\widetilde{m}) = \frac{I(\widetilde{m}; \widetilde{m} - \overline{e}, \widetilde{m} + \overline{e}, 1)}{I(\widetilde{m}; \widetilde{m} - \overline{e}, \widetilde{m} + \overline{e}, 0)} \tag{17}$$

$$\underline{a}(\widetilde{m}) = \frac{I(\widetilde{m}; 0, \widetilde{m} + \overline{e}, 1)}{I(\widetilde{m}; 0, \widetilde{m} + \overline{e}, 0)} \tag{18}$$

Note that the normalizing constant cancels out when computing the conditional expectation. The cost of the identity message function is given by

$$C[m_\mathcal{I}] = \int_{-\overline{e}}^{1+\overline{e}} \int_{q_-(\widetilde{m})}^{q_+(\widetilde{m})} (q - a(\widetilde{m}))^2 f(\widetilde{m} - q) dq \, d\widetilde{m}. \tag{19}$$

where $q_+(\widetilde{m}) = \min\{\widetilde{m} + \overline{e}, 1\}$ and $q_-(\widetilde{m}) = \max\{\widetilde{m} - \overline{e}, 0\}$. Define

$$\overline{z} = \int_{1-\overline{e}}^{1+\overline{e}} \int_{\widetilde{m}-\overline{e}}^{1} (q - \overline{a}(\widetilde{m}))^2 f(\widetilde{m} - q) dq \, d\widetilde{m} \tag{20}$$

$$z = \int_{\overline{e}}^{1-\overline{e}} \int_{\widetilde{m}-\overline{e}}^{\widetilde{m}+\overline{e}} (q - a(\widetilde{m}))^2 f(\widetilde{m} - q) dq \, d\widetilde{m} \tag{21}$$

$$\underline{z} = \int_{-\overline{e}}^{\overline{e}} \int_{0}^{\widetilde{m}+\overline{e}} (q - \underline{a}(\widetilde{m}))^2 f(\widetilde{m} - q) dq \, d\widetilde{m} \tag{22}$$

so that $C[m_\mathcal{I}] = \overline{z} + z + \underline{z}$.

3 Discrete Message

Fix an integer $M \ge 1$ and define $K = M \times N$. Consider the partition

$$0 = x_0 < x_1 < \cdots < x_K < x_{K+1} = 1 \tag{23}$$

of $[0, 1]$. For each $i \in \{0, \ldots, K\}$, define $X_i = [x_i, x_{i+1})$. A discrete message with $K + 1$ messages is given by

$$m_\mathcal{D}(q) = \frac{1}{K} \sum_{i=0}^{K} \chi_{X_i}(q). \tag{24}$$

3

Let $j_+, j_- : [-\bar{e}, 1 + \bar{e}] \to \{0, \ldots, K\}$ be given by

$$j_+(\widetilde{m}) = \min\{\lfloor \widetilde{m}K \rfloor + M, K\} \tag{25}$$
$$j_-(\widetilde{m}) = \max\{0, \lfloor \widetilde{m}K \rfloor - M\} \tag{26}$$

Note that

$$q_+(\widetilde{m}) = x_{j_+(\widetilde{m})} \tag{27}$$
$$q_-(\widetilde{m}) = x_{j_-(\widetilde{m})} \tag{28}$$

The action

$$a(\widetilde{m}) = \frac{I(\widetilde{m}; x_j, x_{j+1}, 1)}{I(\widetilde{m}; x_j, x_{j+1}, 0)} \tag{29}$$

The cost is given by

$$C[m_\mathcal{D}] = \int_{-\bar{e}}^{1+\bar{e}} \int_{x_{j_-(\widetilde{m})}}^{x_{j_+(\widetilde{m})}} (q - a(\widetilde{m}))^2 f(\widetilde{m} - m_\mathcal{D}(q))g(q)dqd\widetilde{m}. \tag{30}$$

$$= \sum_{j=0}^{K} \int_{x_j}^{x_j} (q - a(\widetilde{m}))^2 f(\widetilde{m} - j/K)g(q)dq. \tag{31}$$

$$\tag{32}$$

It is sufficient to choose the partition $x_0, \ldots, x_{K+1}$ in Equation 23. The first-order for x_j is

$$0 = \sum_{j=0}^{M} \frac{I(\widetilde{m}; x_j, x_{j+1}, 1)}{I(\widetilde{m}; x_j, x_{j+1}, 0)} \tag{33}$$