

MCV-M2: Image Inpainting and Completion

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Week 2: Poisson editing



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Task 1: Seamless cloning techniques from Patrick Perez paper

Patrick's paper describes a set of tools to achieve seamless importation of source image regions into a destination region.

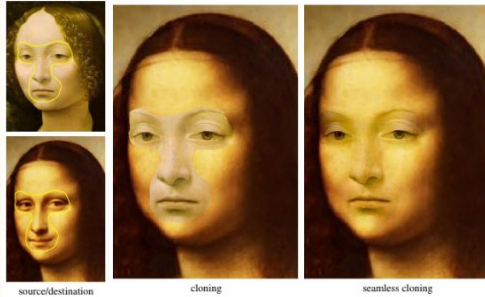


Image interpolation is used by means of a guidance vector field \mathbf{v}

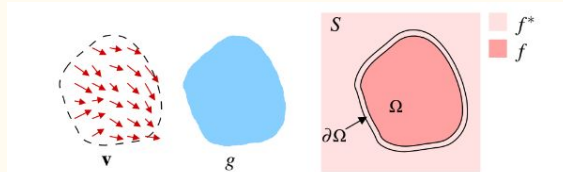


Figure 1: **Guided interpolation notations.** Unknown function f interpolates in domain Ω the destination function f^* , under guidance of vector field \mathbf{v} , which might be or not the gradient field of a source function g .

Criteria to define the problem:

1. Transition from src to dst images must be smooth
2. Details (gradient) of dst image must be kept

Mathematically, criteria can be expressed as the minimization problem

$$\min_f \iint_{\Omega} |\nabla f - \mathbf{v}|^2 \text{ with } f|_{\partial\Omega} = f^*|_{\partial\Omega},$$

Criteria 2

Criteria 1

which can be solved by the Poisson equation with Dirichlet boundary conditions

$$\Delta f = \text{div} \mathbf{v} \text{ over } \Omega, \text{ with } f|_{\partial\Omega} = f^*|_{\partial\Omega},$$

Task 1: Seamless cloning techniques from Patrick Perez paper

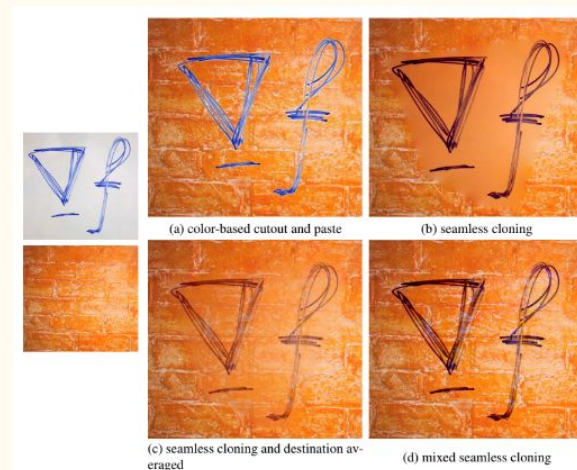
Two techniques are described to perform Seamless cloning:

Importing gradients: where the guidance field \mathbf{v} is the gradient field taken from the src image \mathbf{g}

$$\mathbf{v} = \nabla g, \quad \text{With the new problem solution} \quad \Delta f = \Delta g \text{ over } \Omega, \text{ with } f|_{\partial\Omega} = f^*|_{\partial\Omega}.$$


Mixing gradients: where we want to take texture from src image \mathbf{g} but we also want to keep some texture of the dst image \mathbf{f} and the guidance field \mathbf{v} is defined as

$$\text{for all } \mathbf{x} \in \Omega, \mathbf{v}(\mathbf{x}) = \begin{cases} \nabla f^*(\mathbf{x}) & \text{if } |\nabla f^*(\mathbf{x})| > |\nabla g(\mathbf{x})|, \\ \nabla g(\mathbf{x}) & \text{otherwise.} \end{cases}$$



Task 2: Implementation of importing gradients method

As we said, the solution to $\min_f \iint_{\Omega} |\nabla f - \mathbf{v}|^2$ with $f|_{\partial\Omega} = f^*|_{\partial\Omega}$, is $\Delta f = \operatorname{div} \mathbf{v}$ over Ω , with $f|_{\partial\Omega} = f^*|_{\partial\Omega}$,

Remember last week's inpainting problem was $\begin{cases} \arg \min_{u \in W^{1,2}(\Omega)} \int_D |\nabla u(x)|^2 dx \\ u|_{\partial D} = f \end{cases}$  **Last week's $u = f$ in Patrick's paper**

with solution $\begin{cases} \Delta u = 0 \text{ in } D & (1) \\ u = f \text{ in } \partial D & (2) \end{cases}$ and we proved that $\Delta u = u_{i+1,j} - u_{i-1,j} - u_{i,j+1} + u_{i,j-1} - 4u_{i,j} = 0$

If we do the same for the importing gradients problem, $\Delta f = \operatorname{div} \mathbf{v}$ over Ω , with $f|_{\partial\Omega} = f^*|_{\partial\Omega}$, becomes

$$\Delta f = f_{i+1,j} - f_{i-1,j} - f_{i,j+1} + f_{i,j-1} - 4f_{i,j} = \operatorname{div} (v) = \frac{\partial v}{\partial x} + \frac{\partial v}{\partial y} = \frac{\partial \nabla g}{\partial x} + \frac{\partial \nabla g}{\partial y}$$

The solution is then quite similar to what we implemented last week.

Task 2: Implementation of importing gradients method (Matlab code)

Our implementation in Matlab code consists in:

- In start.m file we compute $\frac{\partial \nabla g}{\partial x} + \frac{\partial \nabla g}{\partial y}$ of the masked src image and place it on the masked region of dst image

Computing $\frac{\partial \nabla g}{\partial x} + \frac{\partial \nabla g}{\partial y}$

```
drivingGrad_i = sol_DiFwd(src(:,:,nC),param.hi) - sol_DiBwd(src(:,:,nC), param.hi);  
drivingGrad_j = sol_DjFwd(src(:,:,nC),param.hj) - sol_DjBwd(src(:,:,nC), param.hj);  
driving_on_src = drivingGrad_i + drivingGrad_j;
```

Positioning values in the region of interest on dst image

```
driving_on_dst = zeros(size(src(:,:,1)));  
driving_on_dst(mask_dst(:)) = driving_on_src(mask_src(:));  
param.driving = driving_on_dst;
```


Task 2: Implementation of importing gradients method (Matlab code)

- Changed G7_Laplace_Equation_Axb.m to G7_Poisson_Equation_Axb.m by changing

G7_Laplace_Equation_Axb.m

```
idx_Ai(idx) = p; idx_Aj(idx) = p;      a_ij(idx) = -4; idx=idx+1;
idx_Ai(idx) = p; idx_Aj(idx) = p+1;    a_ij(idx) = 1;  idx=idx+1;
idx_Ai(idx) = p; idx_Aj(idx) = p-1;    a_ij(idx) = 1;  idx=idx+1;
idx_Ai(idx) = p; idx_Aj(idx) = p+(ni+2); a_ij(idx) = 1;  idx=idx+1;
idx_Ai(idx) = p; idx_Aj(idx) = p-(ni+2); a_ij(idx) = 1;  idx=idx+1;
```

```
b(p) = 0;
```



G7_Poisson_Equation_Axb.m

```
idx_Ai(idx) = p; idx_Aj(idx) = p;      a_ij(idx) = -4; idx=idx+1;
idx_Ai(idx) = p; idx_Aj(idx) = p+1;    a_ij(idx) = 1;  idx=idx+1;
idx_Ai(idx) = p; idx_Aj(idx) = p-1;    a_ij(idx) = 1;  idx=idx+1;
idx_Ai(idx) = p; idx_Aj(idx) = p+ni+2;  a_ij(idx) = 1;  idx=idx+1;
idx_Ai(idx) = p; idx_Aj(idx) = p-ni-2;  a_ij(idx) = 1;  idx=idx+1;
```

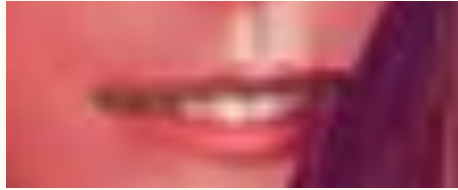
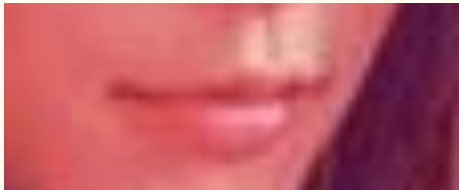
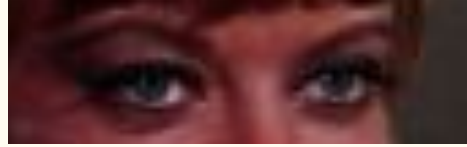
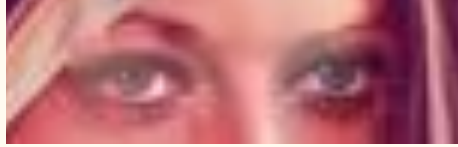
```
if (isfield(param, 'driving'))
    b(p) = driving_ext(i-1,j-1);
else
    b(p) = 0;
end
```



***i-1 and j-1 taking into account that
i and j variables iterate through
extended images with ghost
boundaries***

Task 3: Importing gradients method results

Gradient (shape and texture) is kept from right image but colors are adapted to the ones of the left image



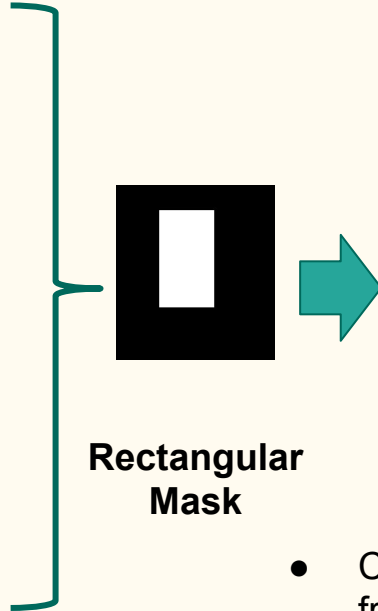
Task 4: Results on our own images

Test Image: Snowboarding on Mt.Everest

Destination image:
Mt.Everest



Source image: Team
Member Snowboarding



**Rectangular
Mask**



- Color is transferred, keeping gradient from source image.
- High frequency information on the background of destination image is lost.



Task 4: Results on our own images

Improving results by refining the mask:



**Refined
Mask**



Rectangular
mask result:



- Background information is saved with refined mask.
- Mask difficult to generate, not optimal solution

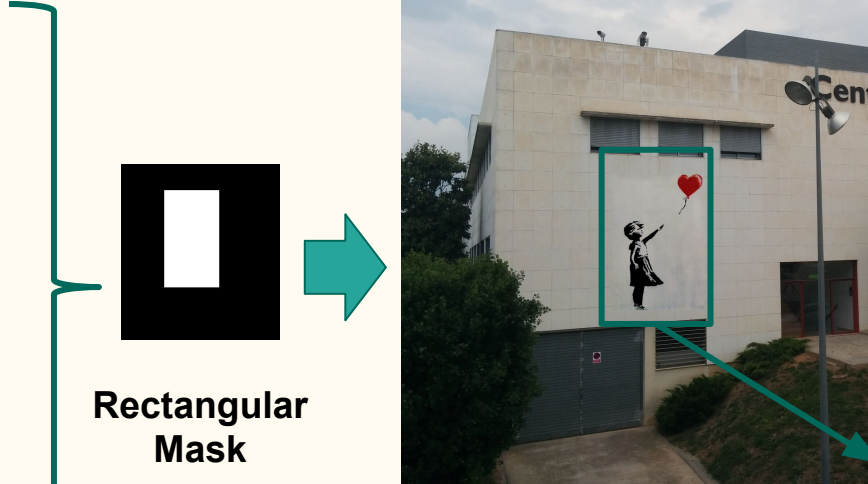
Task 4: Results on our own images

Test Image: Banksy at CVC

Destination image:
Banksy painting



Source image:
CVC building



**Rectangular
Mask**

- Color is transferred correctly.
- Building tiles from destination image are lost, image doesn't appear realistic. This issue will be solved with mixing gradients implementation



Task 5: Implementation of mixing gradients method

In order to implement the mixing technique for seamless cloning, the guidance field must be changed as follows:

$$\mathbf{v}(\mathbf{x}) = \begin{cases} \nabla f^*(\mathbf{x}) & \text{if } |\nabla f^*(\mathbf{x})| > |\nabla g(\mathbf{x})|, \\ \nabla g(\mathbf{x}) & \text{otherwise.} \end{cases} \quad \text{Where } f^* \text{ is the destination image.}$$

Once guidance field has been computed, the following equation must be solved as with importing gradients technique:

$$\Delta f = \operatorname{div} \mathbf{v} \text{ over } \Omega, \text{ with } f|_{\partial\Omega} = f^*|_{\partial\Omega},$$

$$\Delta f = f_{i+1,j} - f_{i-1,j} - f_{i,j+1} + f_{i,j-1} - 4f_{i,j} = \operatorname{div}(v) = \frac{\partial v}{\partial x} + \frac{\partial v}{\partial y}$$

Task 5: Implementation of mixing gradients method

Our implementation in Matlab code consists in:

- In `start_mixed_gradients.m` file guidance field is firstly computed as:

$$\mathbf{v}(\mathbf{x}) = \begin{cases} \nabla f^*(\mathbf{x}) & \text{if } |\nabla f^*(\mathbf{x})| > |\nabla g(\mathbf{x})|, \\ \nabla g(\mathbf{x}) & \text{otherwise.} \end{cases}$$

Source Gradient: `sourceGrad_i = sol_DiFwd(src(:,:,nC), param.hi);`
`sourceGrad_j = sol_DjFwd(src(:,:,nC), param.hj);`

Destination Gradient: `dstGrad_i = sol_DiFwd(dst(:,:,nC), param.hi);`
`dstGrad_j = sol_DjFwd(dst(:,:,nC), param.hj);`

Initialize driving vector as source gradient: `drivingGrad_i = zeros(size(dst(:,:,1)));`
`drivingGrad_i(mask_dst(:)) = sourceGrad_i(mask_src(:));`
`drivingGrad_j = zeros(size(dst(:,:,1)));`
`drivingGrad_j(mask_dst(:)) = sourceGrad_j(mask_src(:));`

`drivingDestGrad_i = zeros(size(dst(:,:,1)));`
`drivingDestGrad_j = zeros(size(dst(:,:,1)));`
`drivingDestGrad_i(mask_dst(:)) = dstGrad_i(mask_dst(:));`
`drivingDestGrad_j(mask_dst(:)) = dstGrad_j(mask_dst(:));`

Compute guidance field applying above condition: `drivingGrad_i (abs(drivingDestGrad_i)>abs(drivingGrad_i)) = drivingDestGrad_i(abs(drivingDestGrad_i)>abs(drivingGrad_i));`
`drivingGrad_j (abs(drivingDestGrad_j)>abs(drivingGrad_j)) = drivingDestGrad_j(abs(drivingDestGrad_j)>abs(drivingGrad_j));`

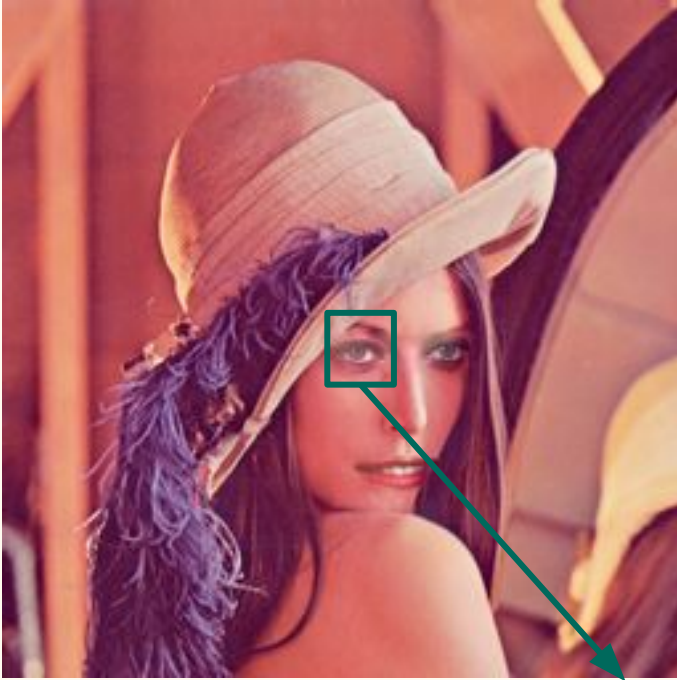
- Afterwards the divergence of the guidance field is computed:

$$\operatorname{div}(v) = \frac{\partial v}{\partial x} + \frac{\partial v}{\partial y}$$

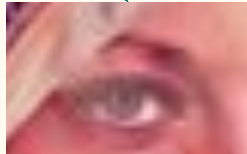
Compute divergence of guidance field: `driving_on_dst = +sol_DiBwd(drivingGrad_i(:,:,), param.hi) + sol_DjBwd(drivingGrad_j(:,:,), param.hj);`
`param.driving = driving_on_dst;`

Task 6: Mixing gradients results

Importing gradients:



Part of the hat is blurred with **Importing gradients** algorithm

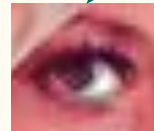


Mixing gradients:



Mixing gradient result:

- Image appear more realistic
- The hat region is preserved



Task 6: Mixing gradients results

Rectangular masks with mixing gradients algorithms:



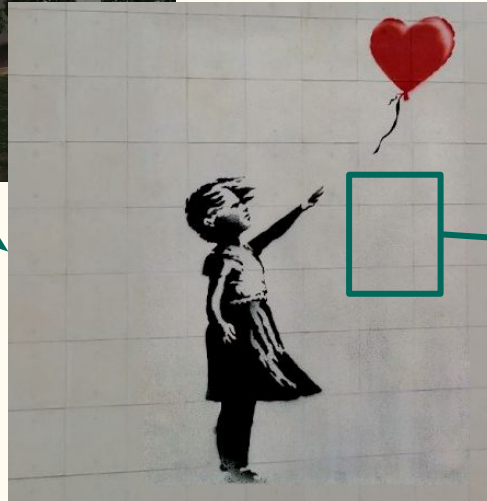
Refined mask with mixing gradients algorithms:



- Both masks produce similar results. The background is preserved with the rectangular mask
- Snowboarder from source image is mixed with the background (producing a ghostly appearance) due to the fact the gradient of the destination image is high compared to the source image
- This image set is not solved properly by the Poisson editing algorithm.

Task 6: Mixing gradients results

Mixing gradients result:



Importing gradients result:



- Building tiles from destination image have been preserved.
- Result image seems realistic with better results than importing gradients algorithm.

Conclusions

- Poisson editing problem implemented through optimization with great results. Both importing gradients and mixing gradients algorithms have been implemented. Test image has been edited successfully.
- Additional images have been tested. With the first one (Snowboarding on Mt.Everest) we did not obtain good results, the destination image has strong gradients which were either removed or produced a ghostly appearance on the snowboarder. Different mask shapes were tested with poor results.
- The second image (Banksy at CVC) was edited successfully with mixing gradients algorithm.
- Mixing gradients improves solution over the importing gradients algorithm as it preserves information from destination image. Result image appears more realistic