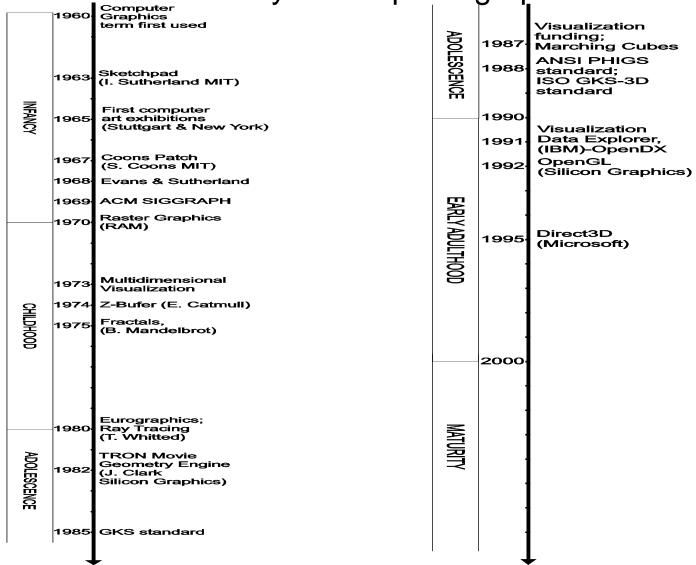
#### **Graphics & Visualization**

#### **Chapter 1**

#### Introduction

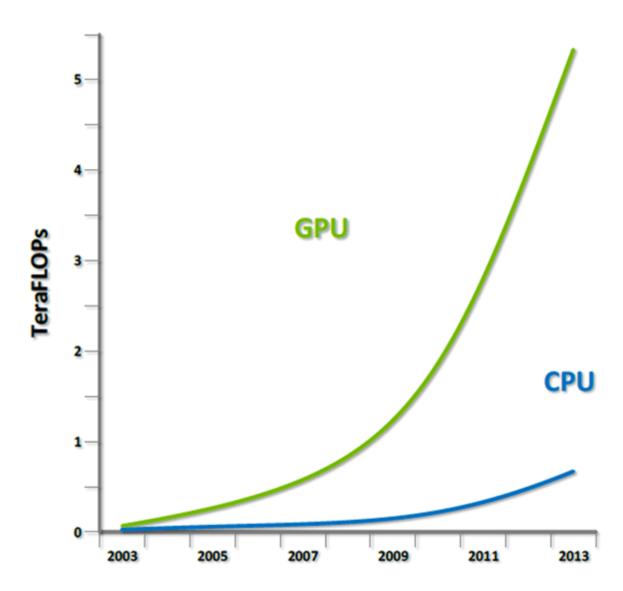
### **Brief History**

• Milestones in the history of computer graphics:



# Brief History (2)

CPU Vs GPU



#### **Applications**

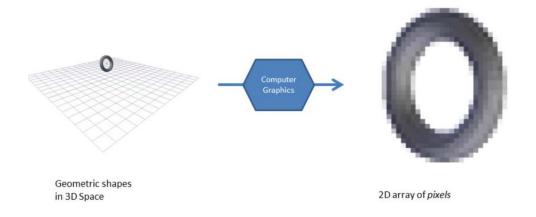
- Computer and mobile games the driving force
- Special effects films and advertisements
- Graphical user interfaces (GUIs)
- Data visualization enabling scientific exploration
- Interactive simulation Virtual reality, flight simulation etc
- Computer-aided design design and test before building
- Computer art

#### Concepts

- 3D or 2D scenes are composed of primitives (e.g. points, lines, curves, polygons, mathematical solids or functions)
- A raster image is a 2D array of pixels
- **Computer Graphics** use principles and algorithms to generate from a scene, a raster image that can be depicted on a display device
- Scene 

  Computer Graphics 

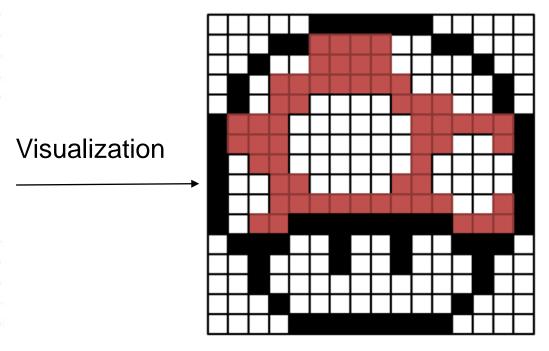
  Raster Image



## Concepts (2)

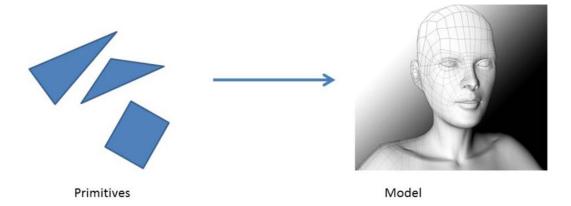
- Visualization exploits visual presentation of large data sets to increase understanding
- The result of visualization is a **visualization object**
- **Modeling** encompasses techniques for the representation of graphical objects
- Data Set ⇒ Visualization ⇒ Model
- Graphics Pipeline is a sequence of stages that create a digital image out of a model
- Model ⇒ Graphics Pipeline ⇒ Image

#### Concepts (3)



## Concepts (4)

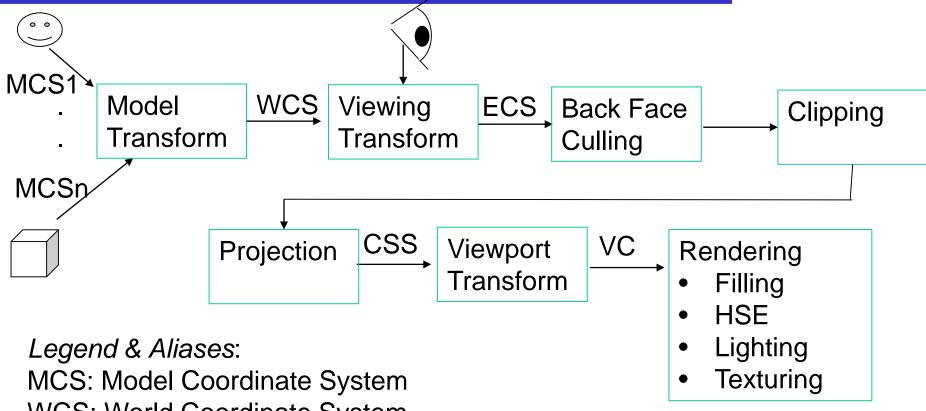
Boundary models: games, special effects...



Solid models: medical & engineering simulations, CAD, 3D

printers

# Graphics Pipeline: Conceptual



WCS: World Coordinate System

ECS: Eye Coordinate System = VCS: View Coordinate System

CSS: Canonical Screen Space=NDC: Normalised Device Coordinates

VC: Viewport Coordinates = DC: Device Coordinates = SC: Screen C.

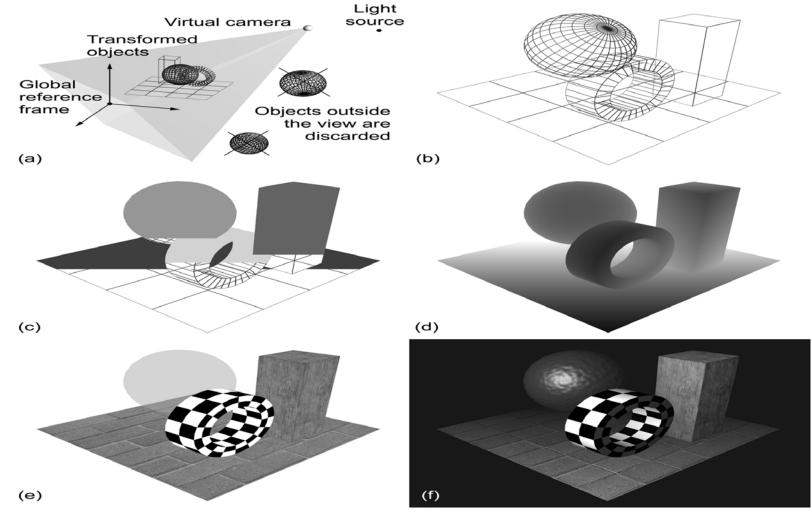
Projection=Perspective Division

Rendering=Rasterization

Lighting= Shading
Graphics & Visualization: Principles & Algorithms

## Graphics Pipeline (2)

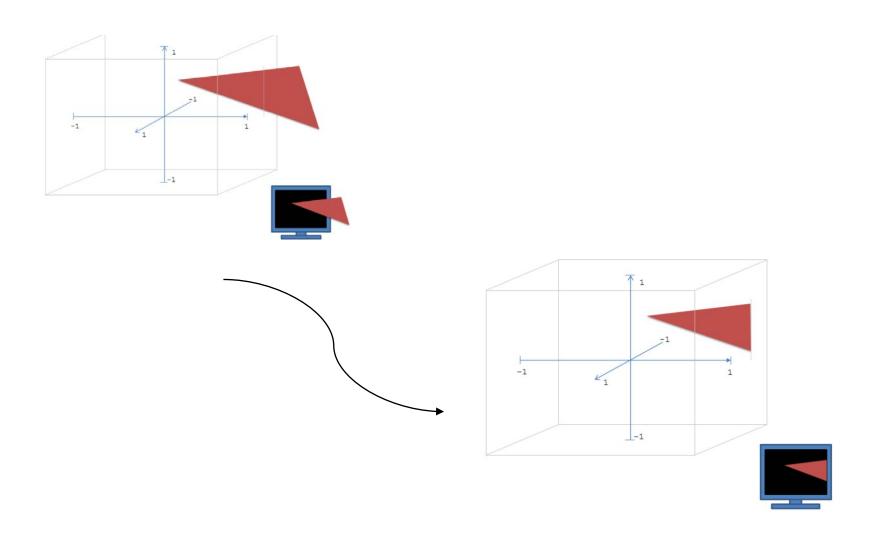
• Operations on primitives in the standard direct rendering graphics pipeline :



# Graphics Pipeline (3)

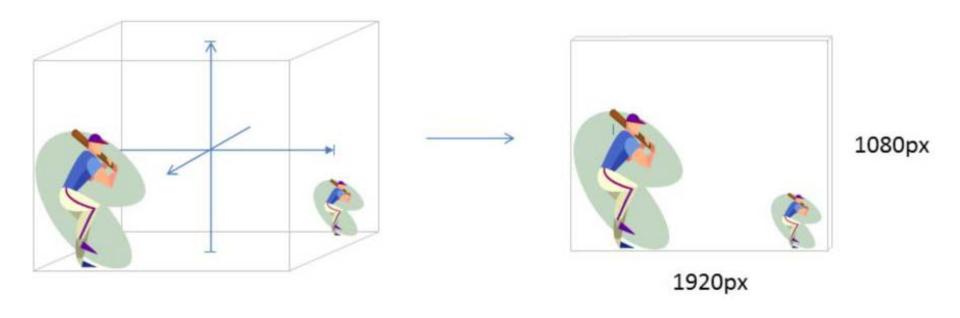
- For the above example:
- (a) Geometry transformation to a common reference frame and view frustum clipping.
- (b) Primitives after viewing transformation, projection, and backface culling.
- (c) Rasterization
- (d) fragment depth sorting: the darker a shade, the nearer the corresponding point is to the virtual camera.
- (e) Texturing.
- (f) Lighting and other fragment operations (such as fog).

# Clipping



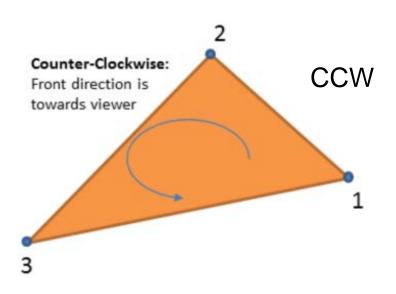
# Viewport Transform

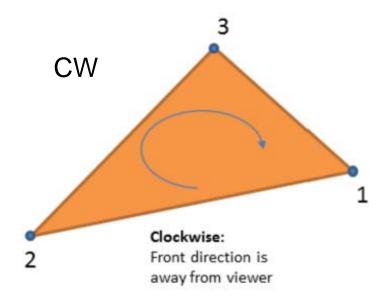
(Translate & Scale)



## Triangle Sides & Back Face Culling

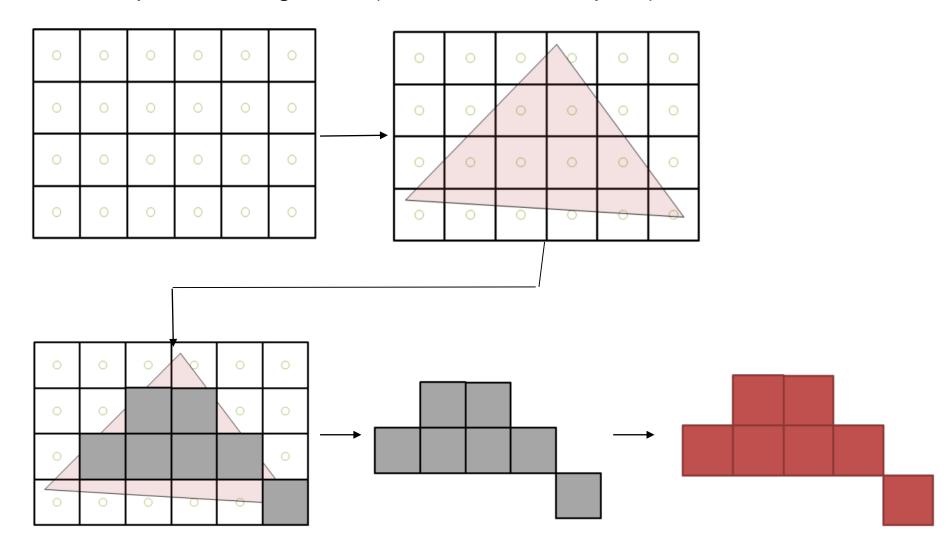
Triangle vertices must be taken in a *unique order* 



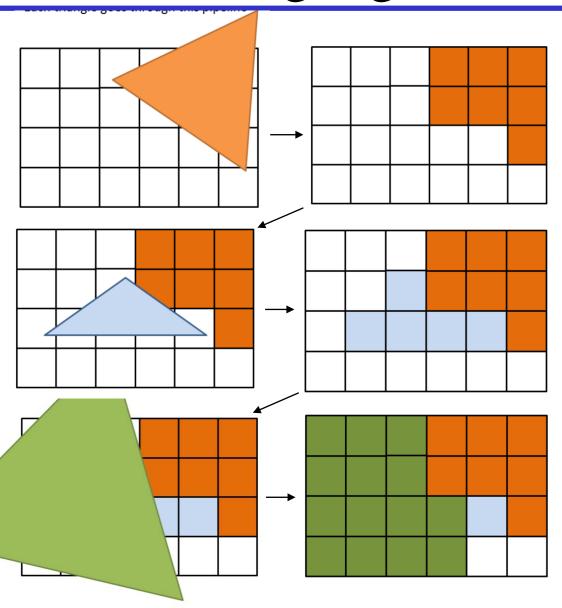


#### Rasterization

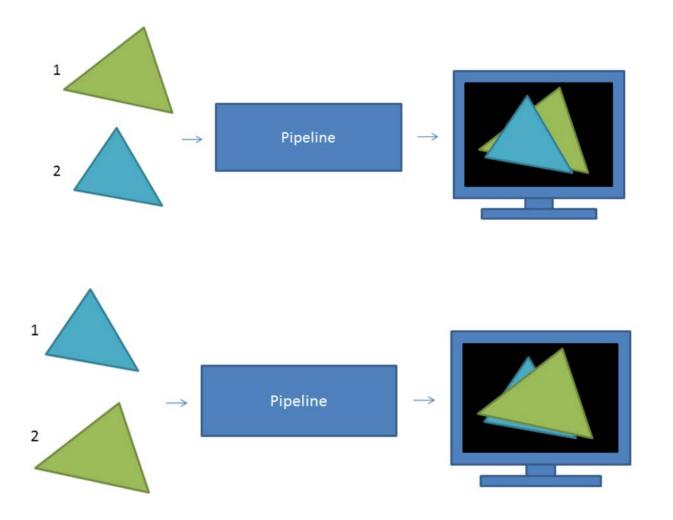
#### Turn Shapes into Fragments (elements within a pixel)



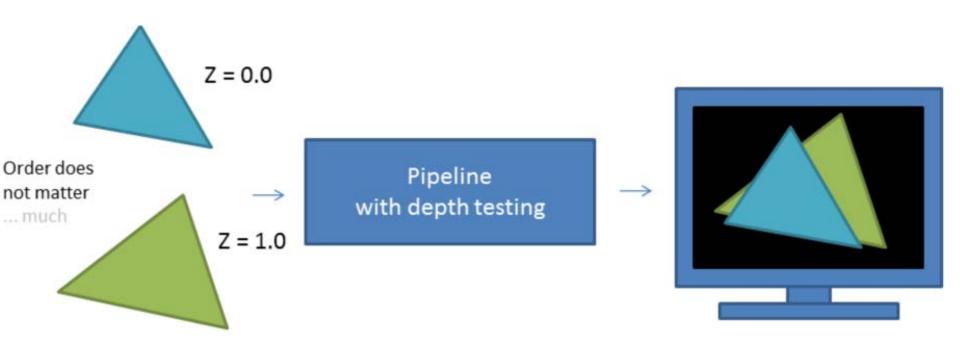
## Each Triangle goes through Pipeline



## **Drawing Order Matters**

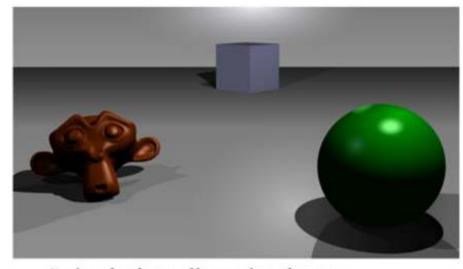


## Z-Testing Makes Order NOT Matter



# Depth (Z) Buffer

Typically 24bpp,
Same resolution as frame buffer
0.0 -> at near clip plane
1.0 -> at far clip plane



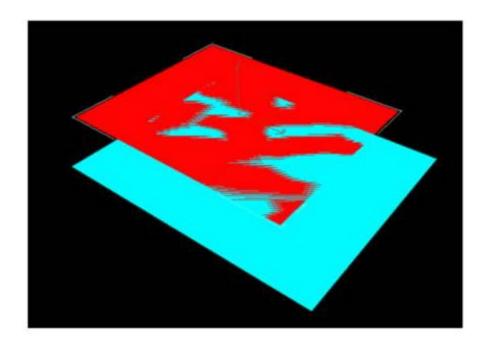
A simple three-dimensional scene



Z-buffer representation

# Z fighting

Sometimes appears during depth testing
Due to numerical accuracy
e.g. two overlapping planes



### Image Buffers

#### Storage and Encoding of Digital Images:

- **Image buffer** is a 2D array of dimensions w x h
- Size of the image buffer is at least (w x h x bpp) / 8 bytes
- Color depth (bpp): # bits used to store the color of each pixel
- Color representations:
  - Monochromatic (grayscale)
     True-color
  - Multi-channel (red/green/blue)
  - Palleted (CLUT)
- True-color: image buffer stores full color intensity information of each pixel
- Color look up table (CLUT):
  - bits per pixel do not affect the accuracy of the displayed color

## Image Buffers (2)

Image buffer with CLUT:

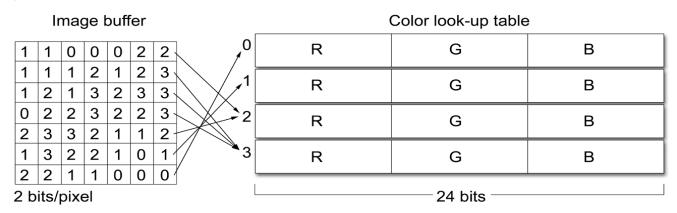
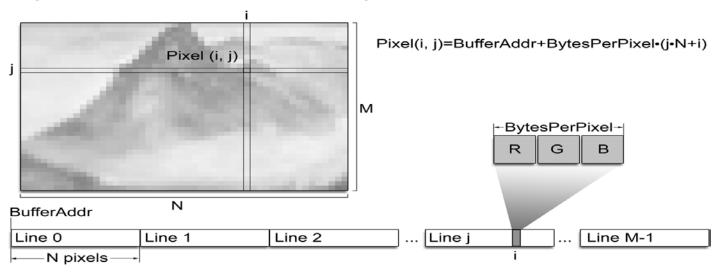


Image buffers occupy contiguous space of memory



# Image Buffers (3)

#### Frame Buffer:

- memory where all pixel color information from rasterization is accumulated before being driven to the graphics output
- double buffering

#### Depth Buffer or Z-buffer:

- stores distance values
- used for hidden surface elimination

#### Other Buffers:

- Stencil Buffer
- Accumulation Buffer

#### Framerates

- **Eye** perceives smooth motion at >= 30 fps
- Monitor needs refreshing at constant rate (typically 60 fps)
- Application produces frames as fast as it can
  - No point going beyond monitor refresh rate
- Display controller (typically on GPU)
  - Reads frame buffer and feeds monitor at 60 fps





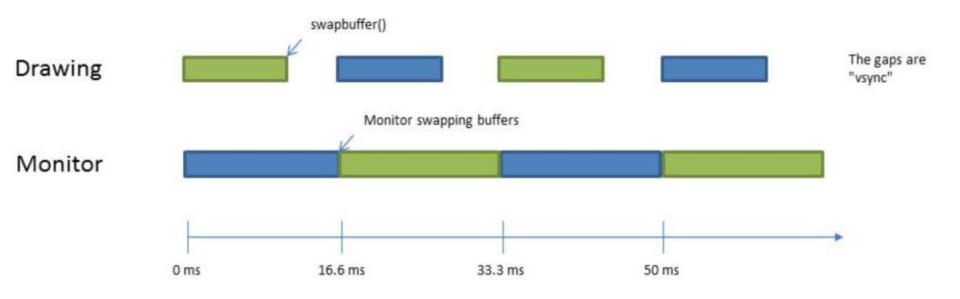
## Tearing

• **Tearing:** when application writes to frame buffer at the same time the display controller is reading



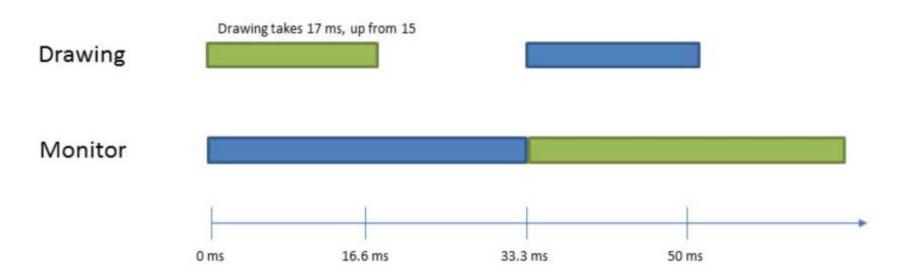
## Double Buffering

- Avoids tearing
  - Frame buffer 1 is read by display controller (every 16.6ms for 60fps)
  - Frame buffer 2 is written by application



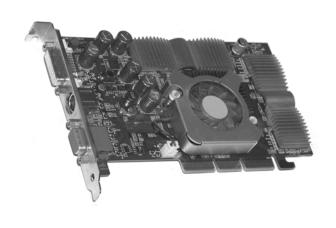
# Double Buffering (2)

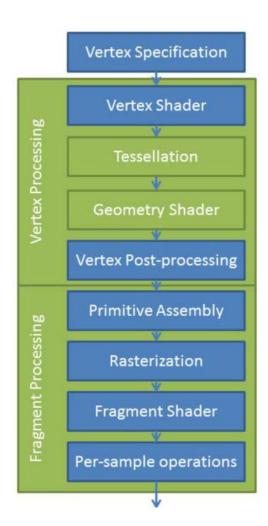
- Buffer swap rate is an integer multiple of monitor refresh rate
  - If Drawing takes 17ms, buffer swap every 33.3ms



## Graphics Hardware

- After a ~20 year development, we have
  - Programmable graphics hardware
  - 2 types of shaders-programs (vertex, fragment)





#### Conventions

- Scalars: x, y, z
- Vector quantities:
  - Points: a, b
  - Vectors:  $\vec{a}, \vec{b}, \overline{Oa}$
  - Unit vectors:  $\hat{\mathbf{e}}_1$ ,  $\hat{\mathbf{n}}$
- Matrices:  $M, R_x$ 
  - Column vectors:  $\vec{\mathbf{v}}^{\mathrm{T}} = [0,1,2]$
- Functions:
  - Standard mathematical functions and custom functions:  $sin(\theta)$
  - Functions follow the above conventions for scalar and vector quantities
- Norms:  $|\vec{v}|$
- Standard sets :  $\mathbb{R}$ ,  $\mathbb{C}$
- Algorithm descriptions are given in pseudocode based on standard C and C++
- Advanced sections are marked with an asterisk \*