

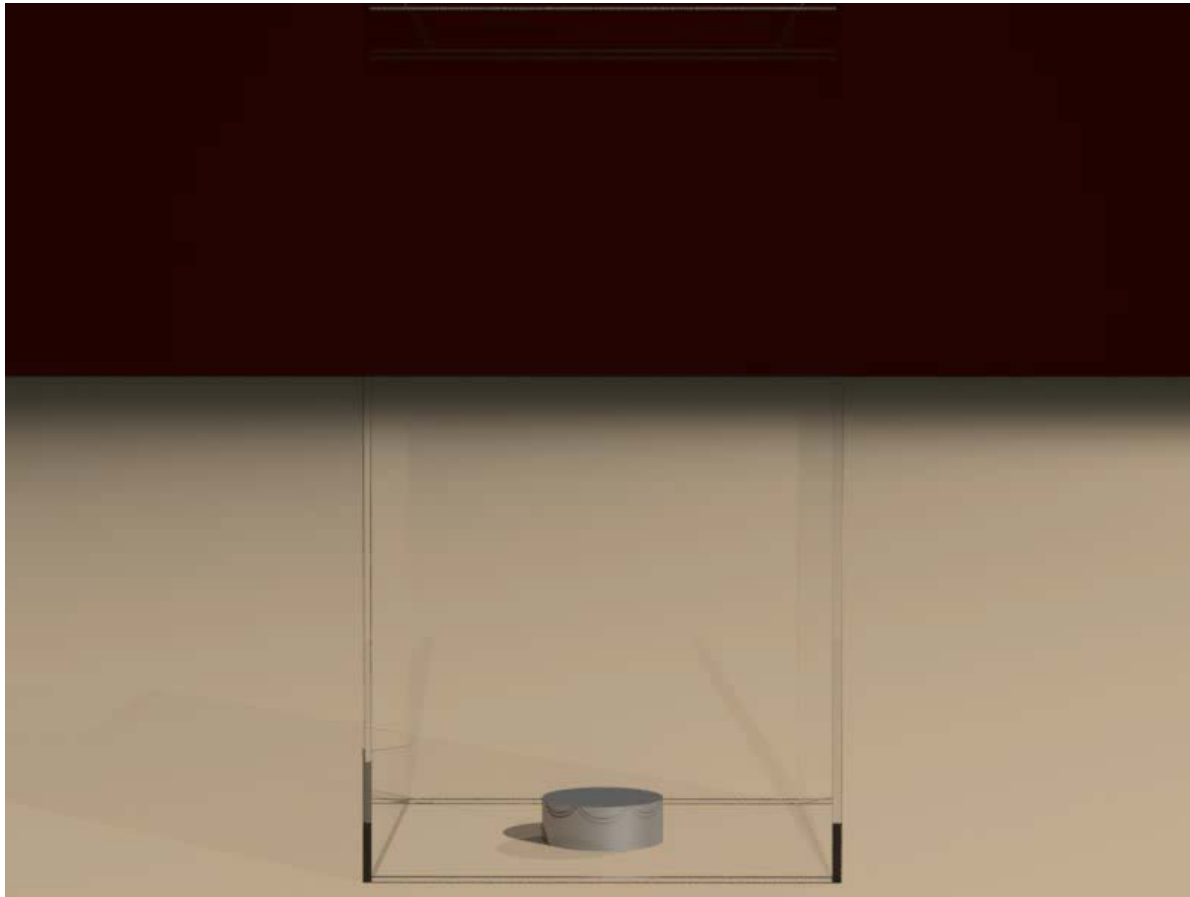
Lecture 24: Process modeling & balance laws

- Balance laws
 - Differential balances
 - Material derivative

Book: 10.4, 11.1-11.4

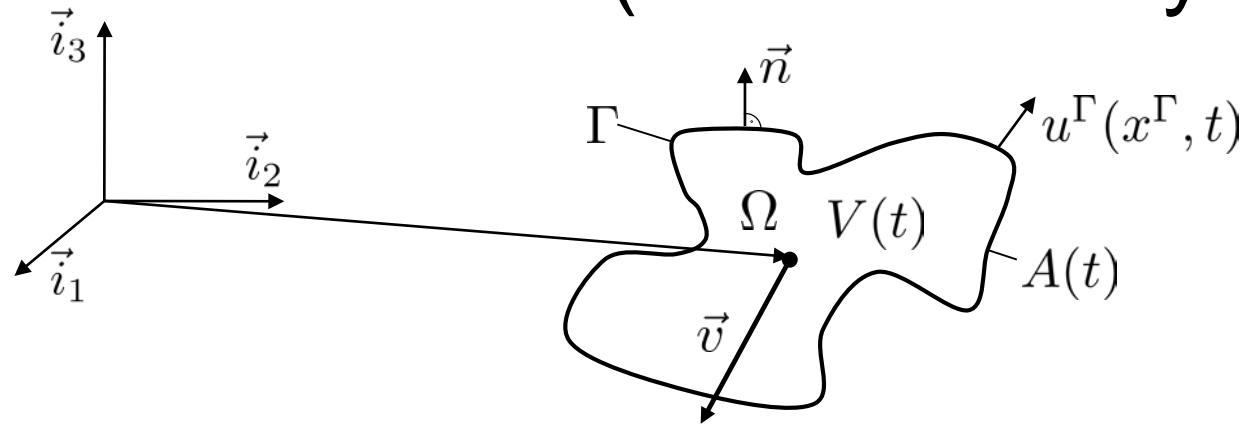
Computational fluid dynamics

- CFD = solving momentum + mass balances (that is, Navier-Stokes + continuity equation) for different setups



<http://physbam.stanford.edu/~fedkiw/>

Control volume (infinitesimally small)



- How can the extensive property Ψ change in the domain Ω ?

production rate : $\Sigma_\Psi \triangleq \frac{\text{produced/consumed } \Psi \text{ in } \Omega}{\text{time}}$

transport rate : $\bar{\Phi} = \frac{\text{over } \Gamma \text{ in/out of the domain } \Omega}{\text{time}}$

→ Integral balance: $\frac{d}{dt} \Psi = \bar{\Phi}_\Psi + \Sigma_\Psi$

Storage \rightarrow effort transport source

General integral balance

- Arbitrary size: In order to get a local character we have to introduce properties with local characteristics

$$\psi(x, t) = \lim_{V \rightarrow 0} \frac{\Psi}{V} |_{x, t} \quad [\text{intensive property}]$$

$$\Psi(t) = \int_{\Omega} \psi(x, t) dV$$

$$\Sigma_{\psi}(t) = \int_{\Omega} \sigma_{\psi}(x, t) dV$$

← source density

remote effects

$$\sigma_{\psi}(x, t) = \sigma_{\psi}^p(x, t) + \sigma_{\psi}^F(x, t)$$

$$\phi_{\psi}(x, t) = \lim_{V \rightarrow 0} \frac{\bar{\Phi}}{A} |_{x^p, t} \quad \leftarrow \text{physiochemical phenomena in } \Omega$$

$$\Rightarrow \bar{\Phi}_{\psi}(t) = - \int_{\Gamma} \langle \phi_{\psi}(x^p, t) \rangle dA$$

$$\frac{d}{dt} \int_{\Omega} \psi dV = - \int_{\Gamma} \phi_{\psi} \cdot \underline{n} dA + \int_{\Omega} \sigma_{\psi} dV$$

general
integral
balance

Derivation of differential balance I

- Goal: Find a derivative of the local density ψ instead of the total amount of extensive property Ψ

$$\frac{d}{dt} \int_{\Omega} \psi dV = - \int_{\Gamma} \phi_{\psi} \underline{n} dA + \int_{\Omega} \sigma_{\psi} dV$$

→ change differentiation and integration

- Use: Reynold's transport theorem:

$$\frac{d}{dt} \int_{\Omega} \psi dV = \int_{\Omega} \frac{\partial \psi}{\partial t} dV + \int_{\Gamma} \psi \underline{u}^{\Gamma} \underline{n} dA$$

← change of moving surface

$$\rightarrow \int_{\Omega} \frac{\partial \psi}{\partial t} dV = - \int_{\Gamma} \psi \underline{u}^{\Gamma} \underline{n} dA - \int_{\Gamma} \phi_{\psi} \cdot \underline{n} dA + \int_{\Omega} \sigma_{\psi} dV$$

Derivation of differential balance II

$$\int_{\Omega} \frac{\partial \psi}{\partial t} dV = - \int_{\Gamma} \psi \underline{u}^{\Gamma} \underline{n} dA - \int_{\Gamma} \phi_{\psi} \underline{n} dA + \int_{\Omega} \sigma_{\psi} dV$$

- Finally we have to transfer the surface integrals into volume integrals to get the same integration domain
- Use: Divergence theorem

$$\int_{\Gamma} \phi_{\psi} \underline{n} dA = \int_{\Omega} \nabla \cdot \phi_{\psi} dV$$

Nabla Operator: $\nabla = \left(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n} \right) = \sum_{i=1}^n \vec{e}_i \frac{\partial}{\partial x_i}$

Cartesian coordinates: $(\nabla \cdot \underline{v}) = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$

Cylindrical coordinates: $(\nabla \cdot \underline{v}) = \frac{1}{r} \frac{\partial}{\partial r} (r \cdot v_r) + \frac{1}{r} \frac{\partial v_{\theta}}{\partial \theta} + \frac{\partial v_z}{\partial z}$

Derivation of differential balance III

$$\int_{\Omega} \frac{\partial \psi}{\partial t} dV = - \int_{\Gamma} \psi \underline{u}^{\Gamma} \underline{n} dA - \int_{\Gamma} \phi_{\psi} \underline{n} dA + \int_{\Omega} \sigma_{\psi} dV$$

- Apply divergence theorem: *velocity of volume*

$$\int_{\Omega} \frac{\partial \psi}{\partial t} dV = - \int_{\Omega} \nabla \cdot \psi \underline{\omega} dV - \int_{\Omega} \nabla \cdot \phi_{\psi} dV + \int_{\Omega} \sigma_{\psi} dV$$

→ Ω is arbitrary since integration must be zero

$$\frac{\partial \psi}{\partial t} + \nabla \cdot \psi \underline{\omega} + \nabla \cdot \phi_{\psi} = \sigma_{\psi}$$

$\phi^t = \psi \underline{\omega} + \phi_{\psi}$ *→ general differential balance of density ψ*

$$\frac{\partial \psi}{\partial t} + \nabla \cdot \phi_{\psi}^t = \sigma_{\psi}$$

Mass balance

velocity of center of mass: $\underline{\omega} = \frac{1}{\rho} \sum_{i=1}^{n_c} \rho_i \underline{v}_i =: \underline{v}$

• diffusive flux: $\Phi_{\rho_i} = \rho_i (\underline{v}_i - \underline{v}) =: \underline{j}_i$

$$\rightarrow \frac{\partial \rho_i}{\partial t} + \nabla \cdot \rho_i \underline{v} + \nabla \cdot \underline{j}_i = r_i^v$$

Equation of continuity of substance i

→ sum over all substances

local rate of mass accumulation $\rightarrow \frac{\partial \rho}{\partial t} + \nabla \cdot \rho \underline{v} = 0$ [Equation of continuity]

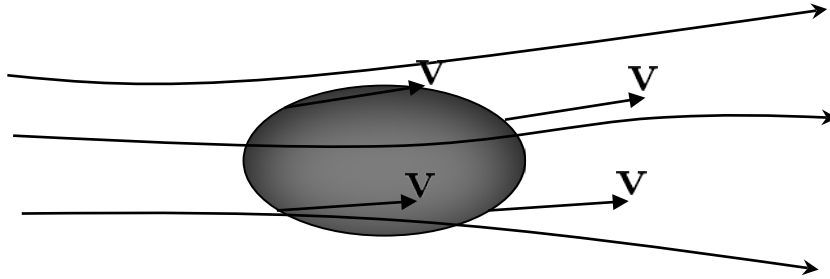
net rate of mass inflow

incompressible fluid

$$\nabla \cdot \underline{v} = 0$$

$$\underbrace{\frac{\partial \rho}{\partial t} + \underline{v} \cdot \nabla \rho}_{\frac{D\rho}{Dt}} + \rho \nabla \cdot \underline{v} = 0$$

“Moving with the flow”



- The boundary of the element moves with the bulk velocity

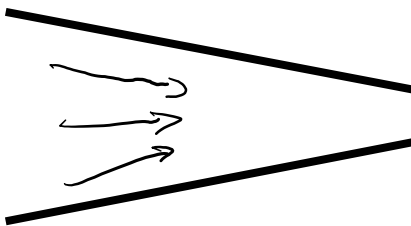
- Property change:

- Unsteady flow
- Motion through a gradient of the property

$$\frac{\partial V}{\partial t} + V \cdot \nabla V$$

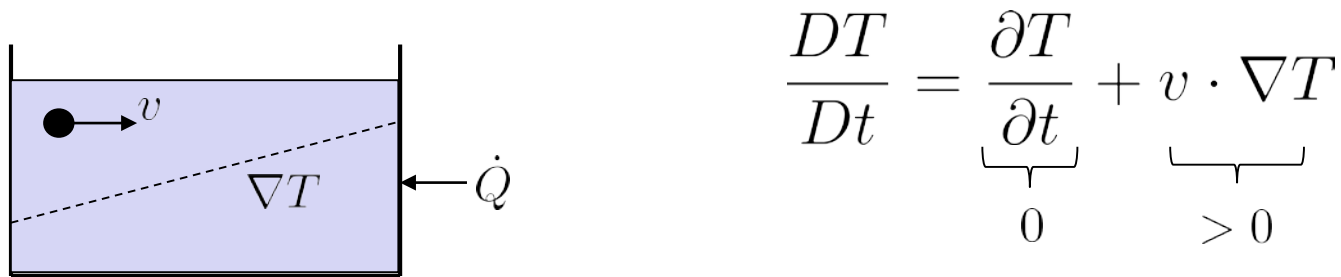
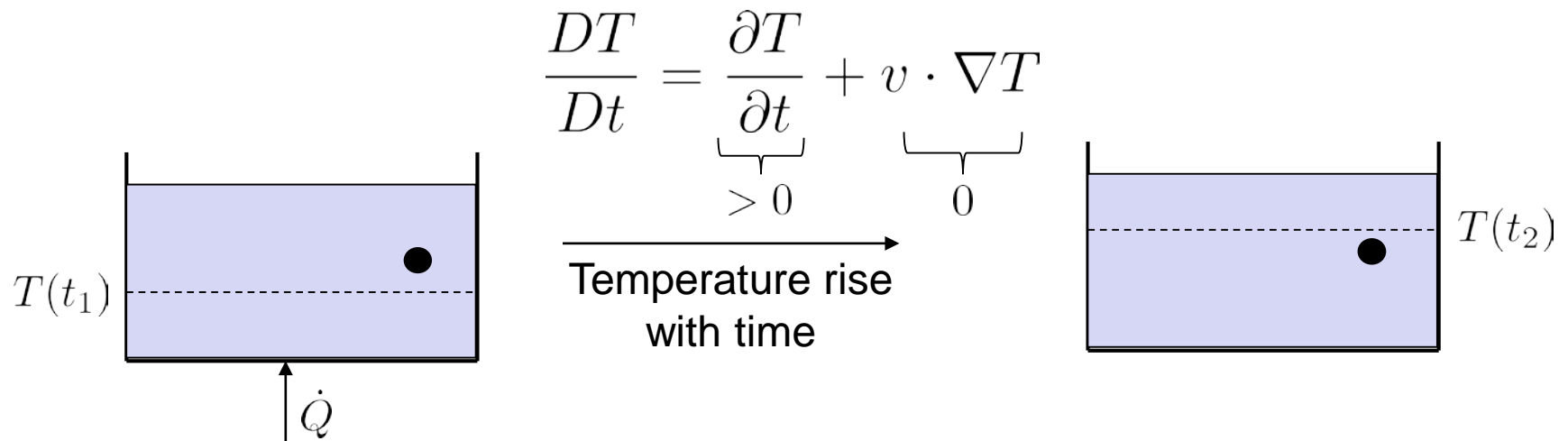
Handwritten arrows point from the text 'Unsteady flow' to the $\frac{\partial V}{\partial t}$ term and from 'Motion through a gradient of the property' to the $V \cdot \nabla V$ term.

- Example:

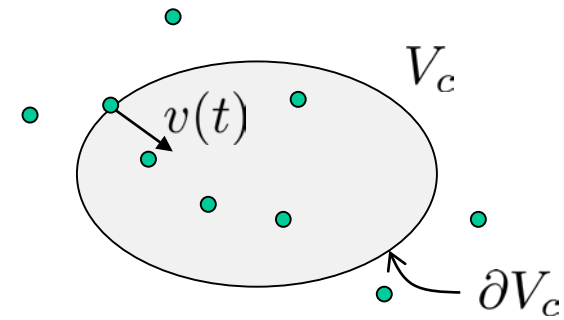


• velocity in creases
as pipe narrows
[Bernoulli's law]

Example: Material derivative $\frac{D}{Dt} = \frac{\partial}{\partial t} + v \cdot \nabla$



The momentum balance I



- In words

$$\frac{d}{dt}\mathbf{p} = \left\{ \begin{array}{c} \text{transfer of momentum into} \\ V_c \text{ by fluid flow} \\ \text{across surface } \partial V_c \end{array} \right\} + \left\{ \begin{array}{c} \text{generation of momentum} \\ \text{in } V_c \text{ due to forces} \\ \text{acting on } V_c \end{array} \right\}$$

- Mathematically

$$\frac{d}{dt}\vec{p} = \frac{d}{dt} \iiint_{V_c} \rho \vec{v} dV = - \iint_{\partial V_c} \rho \vec{v} \vec{v} \cdot \vec{n} dA + \vec{F}^{(r)}$$

where $\vec{F}^{(r)}$ is resultant force on fluid in control volume

(often: gravity (hydrostatic) and/or friction (hydrodynamic))

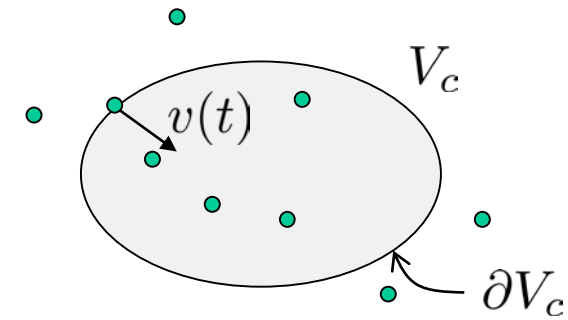
The momentum balance II

$$\frac{d}{dt} \int_{\Omega} \rho \underline{v} dV = - \int_{\Gamma} \rho \underline{v} \cdot \underline{v} \cdot \underline{n} dA + \int_{\Omega} B dV + \int_{\Gamma} \underline{n} \cdot \underline{\sigma} dA$$

$$\vdots$$

$$\frac{\partial \rho \underline{v}}{\partial t} + \nabla \cdot \underline{v} \rho \underline{v} - \nabla \underline{\sigma}$$

The energy balance I



- In words

$$\frac{d}{dt}E = \left\{ \begin{array}{c} \text{transfer of energy into} \\ V_c \text{ by fluid flow} \\ \text{across surface } \partial V_c \end{array} \right\} + \left\{ \begin{array}{c} \text{transfer of energy into} \\ V_c \text{ by heat transfer} \\ \text{and by work} \end{array} \right\}$$

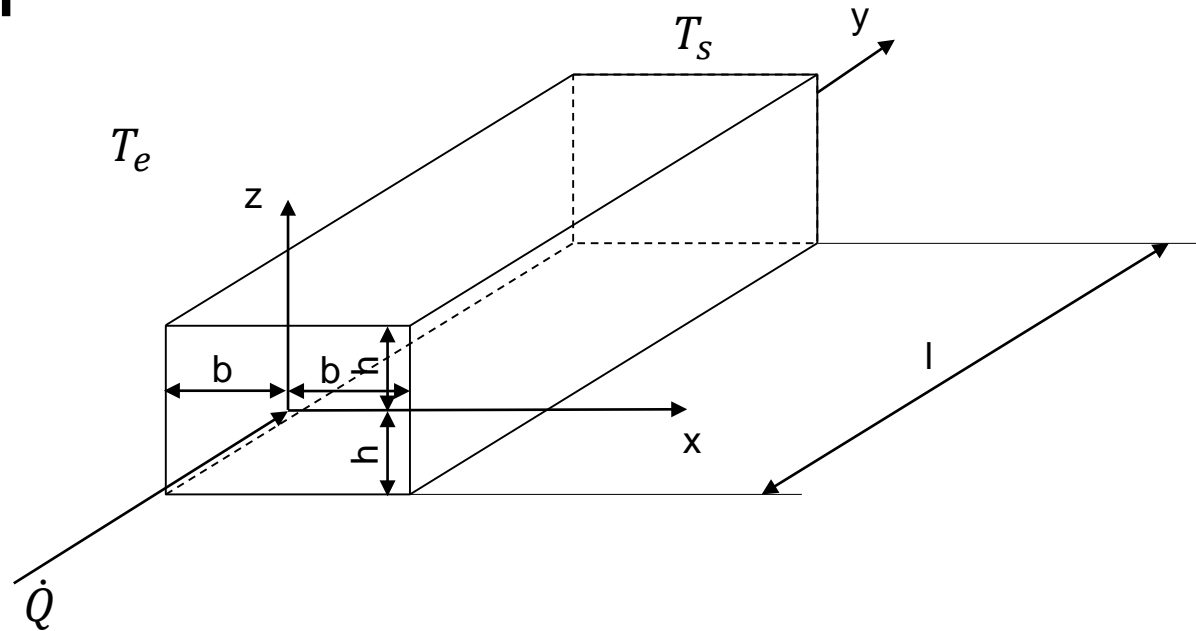
- Mathematically

$$\frac{d}{dt}E = \frac{d}{dt} \iiint_{V_c} \rho e dV = \underbrace{- \iint_{\partial V_c} \rho e \vec{v} \cdot \vec{n} dA}_{\text{Energy flow by convection}} + \dot{Q} - \dot{W}$$

The energy balance II

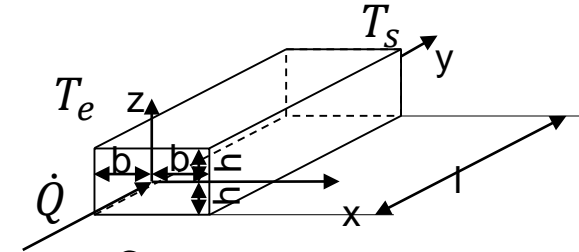
$$\frac{d}{dt} \int_{\Omega} \rho e dV = - \int_{\Gamma} \rho e \cdot \underline{v} \cdot \underline{n} dA + \frac{dQ}{dt} - \frac{dW}{dt}$$

Example – heated bar

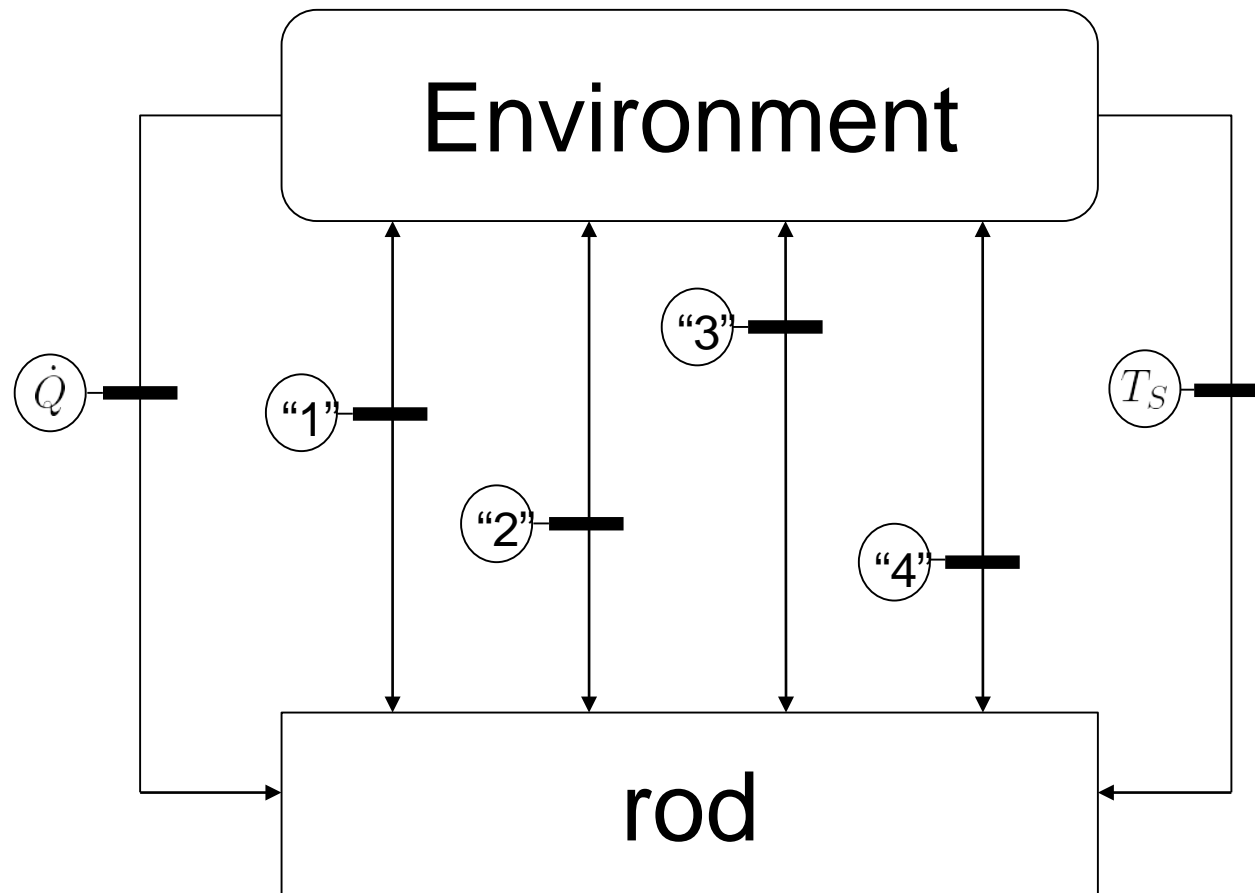


- At all sidewalls there is heat exchange with the environment (T_e , heat exchange coefficient α)
- At the front side there is a heat flux \dot{Q}
- At the back side there is a constant temperature T_s

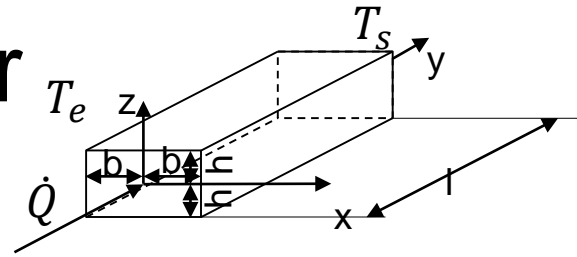
Abstraction of process



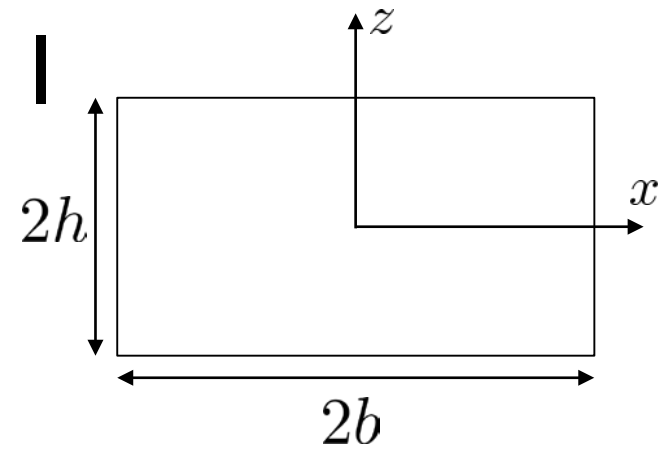
- How many interaction with the environment?



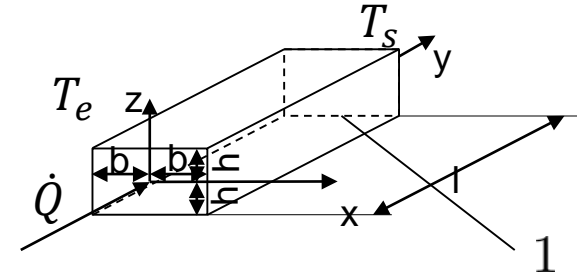
Energy balance – heated bar



Solve differential balance I



Boundary conditions



Solve differential balance II (pde)

