

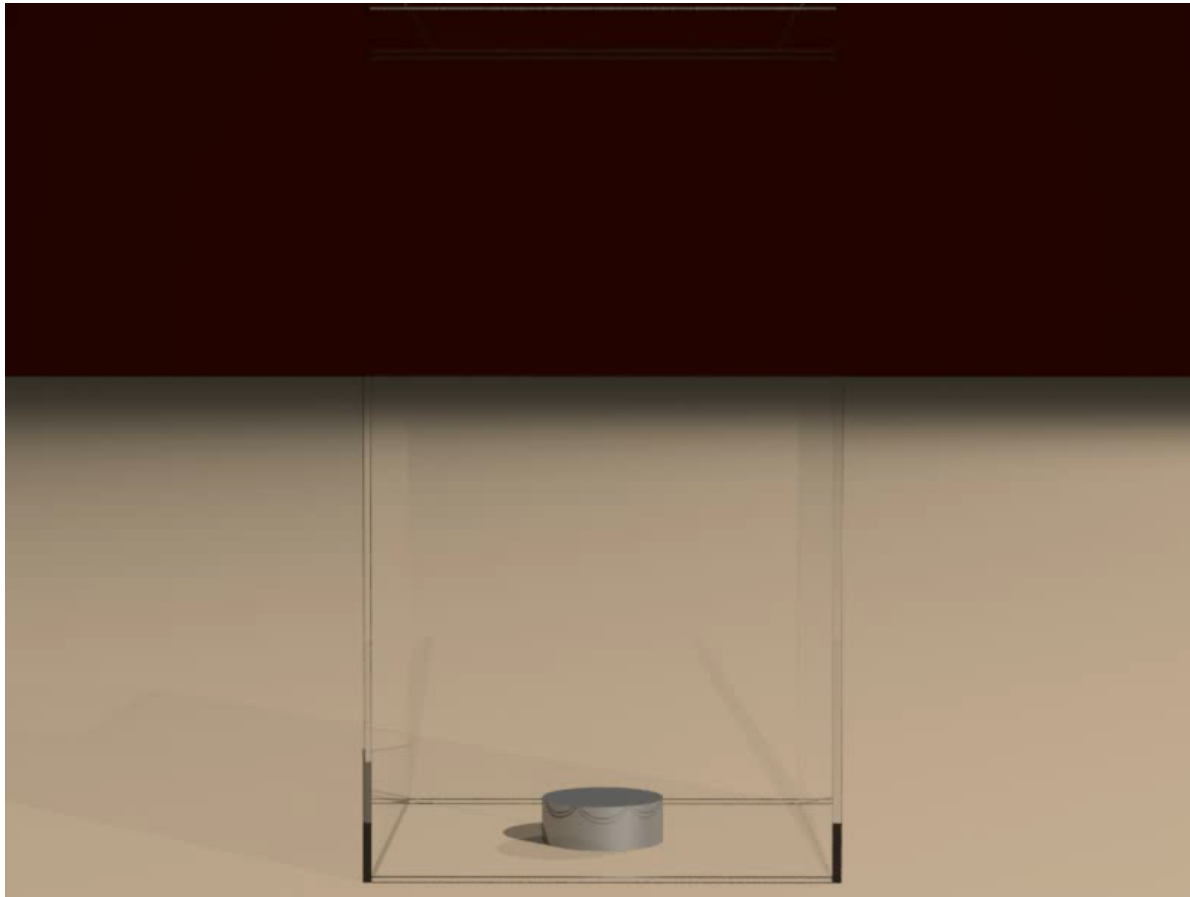
Lecture 24: Process modeling & balance laws

- Balance laws
 - Differential balances
 - Material derivative

Book: 10.4, 11.1-11.4

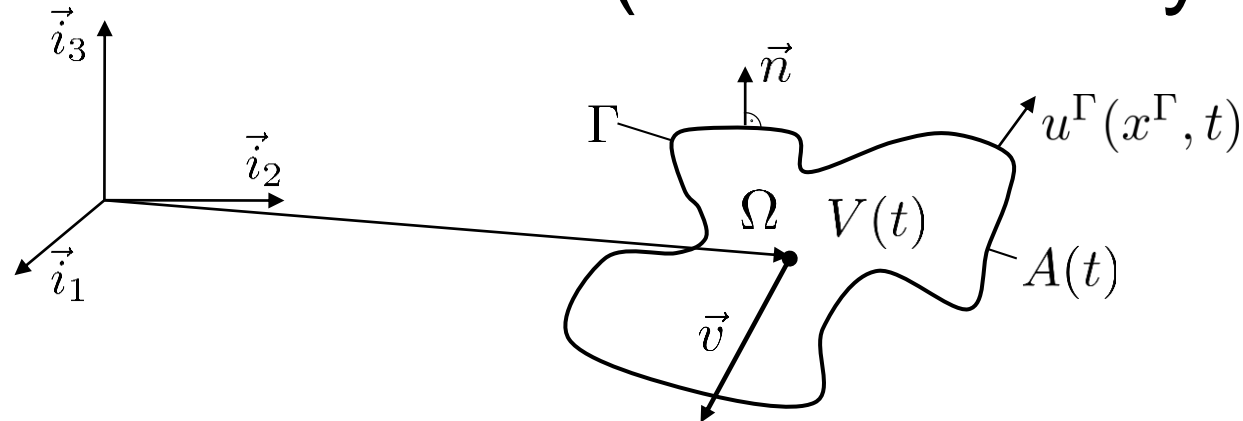
Computational fluid dynamics

- CFD = solving momentum + mass balances (that is, Navier-Stokes + continuity equation) for different setups



<http://physbam.stanford.edu/~fedkiw/>

Control volume (infinitesimally small)



- How can the extensive property Ψ change in the domain Ω ?

General integral balance

- Arbitrary size: In order to get a local character we have to introduce properties with local characteristics

Derivation of differential balance I

- Goal: Find a derivative of the local density ψ instead of the total amount of extensive property Ψ

$$\frac{d}{dt} \int_{\Omega} \psi dV = - \int_{\Gamma} \phi_{\psi} \underline{n} dA + \int_{\Omega} \sigma_{\psi} dV$$

→ change differentiation and integration

- Use: Reynold's transport theorem:

$$\frac{d}{dt} \int_{\Omega} \psi dV = \int_{\Omega} \frac{\partial \psi}{\partial t} dV + \int_{\Gamma} \psi \underline{u}^{\Gamma} \underline{n} dA$$

Derivation of differential balance II

$$\int_{\Omega} \frac{\partial \psi}{\partial t} dV = - \int_{\Gamma} \psi \underline{u}^{\Gamma} \underline{n} dA - \int_{\Gamma} \phi_{\psi} \underline{n} dA + \int_{\Omega} \sigma_{\psi} dV$$

- Finally we have to transfer the surface integrals into volume integrals to get the same integration domain
- Use: Divergence theorem

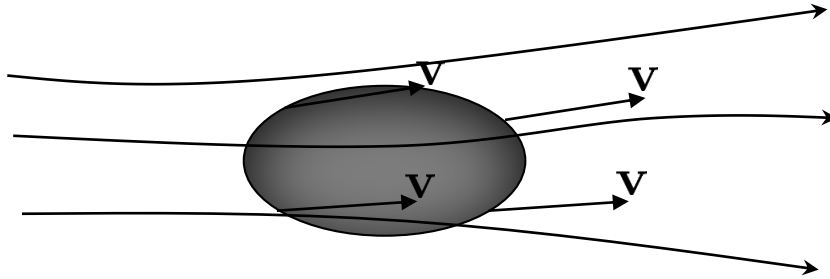
Derivation of differential balance III

$$\int_{\Omega} \frac{\partial \psi}{\partial t} dV = - \int_{\Gamma} \psi \underline{u}^{\Gamma} \underline{n} dA - \int_{\Gamma} \phi_{\psi} \underline{n} dA + \int_{\Omega} \sigma_{\psi} dV$$

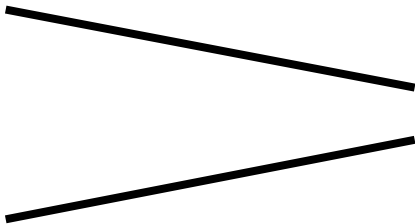
- Apply divergence theorem:

Mass balance

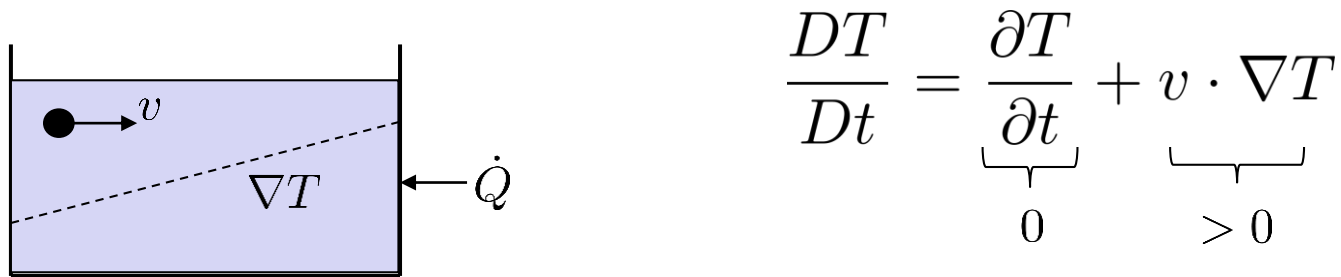
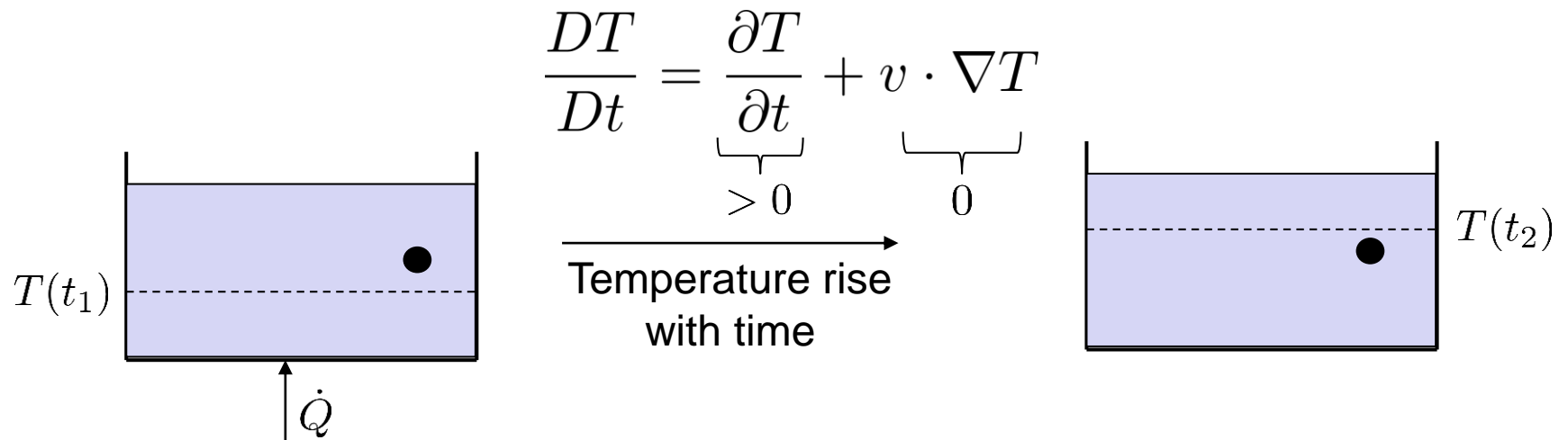
“Moving with the flow”



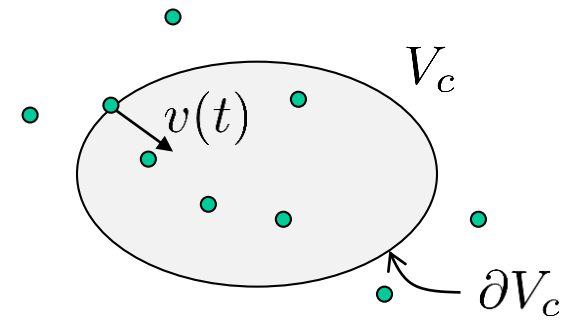
- The boundary of the element moves with the bulk velocity
- Property change:
 - Unsteady flow
 - Motion through a gradient of the property
- Example:



Example: Material derivative $\frac{D}{Dt} = \frac{\partial}{\partial t} + v \cdot \nabla$



The momentum balance I



- In words

$$\frac{d}{dt}\mathbf{p} = \left\{ \begin{array}{c} \text{transfer of momentum into} \\ V_c \text{ by fluid flow} \\ \text{across surface } \partial V_c \end{array} \right\} + \left\{ \begin{array}{c} \text{generation of momentum} \\ \text{in } V_c \text{ due to forces} \\ \text{acting on } V_c \end{array} \right\}$$

- Mathematically

$$\frac{d}{dt}\vec{p} = \frac{d}{dt} \iiint_{V_c} \rho \vec{v} dV = - \iint_{\partial V_c} \rho \vec{v} \vec{v} \cdot \vec{n} dA + \vec{F}^{(r)}$$

where $\vec{F}^{(r)}$ is resultant force on fluid in control volume

(often: gravity (hydrostatic) and/or friction (hydrodynamic))

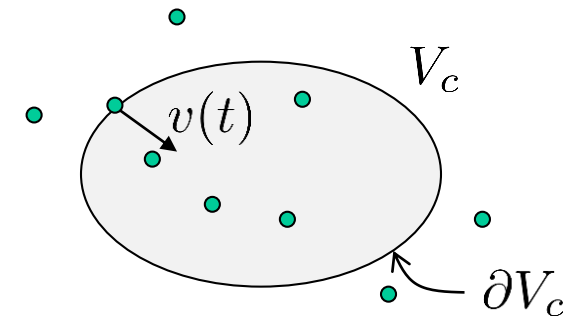
The momentum balance II

$$\frac{d}{dt} \int_{\Omega} \rho \underline{v} dV = - \int_{\Gamma} \rho \underline{v} \cdot \underline{v} \cdot \underline{n} dA + \int_{\Omega} B dV + \int_{\Gamma} \underline{n} \cdot \underline{\sigma} dA$$

$$\vdots$$

$$\frac{\partial \rho \underline{v}}{\partial t} + \nabla \cdot \underline{v} \rho \underline{v} - \nabla \underline{\sigma}$$

The energy balance I



- In words

$$\frac{d}{dt}E = \left\{ \begin{array}{c} \text{transfer of energy into} \\ V_c \text{ by fluid flow} \\ \text{across surface } \partial V_c \end{array} \right\} + \left\{ \begin{array}{c} \text{transfer of energy into} \\ V_c \text{ by heat transfer} \\ \text{and by work} \end{array} \right\}$$

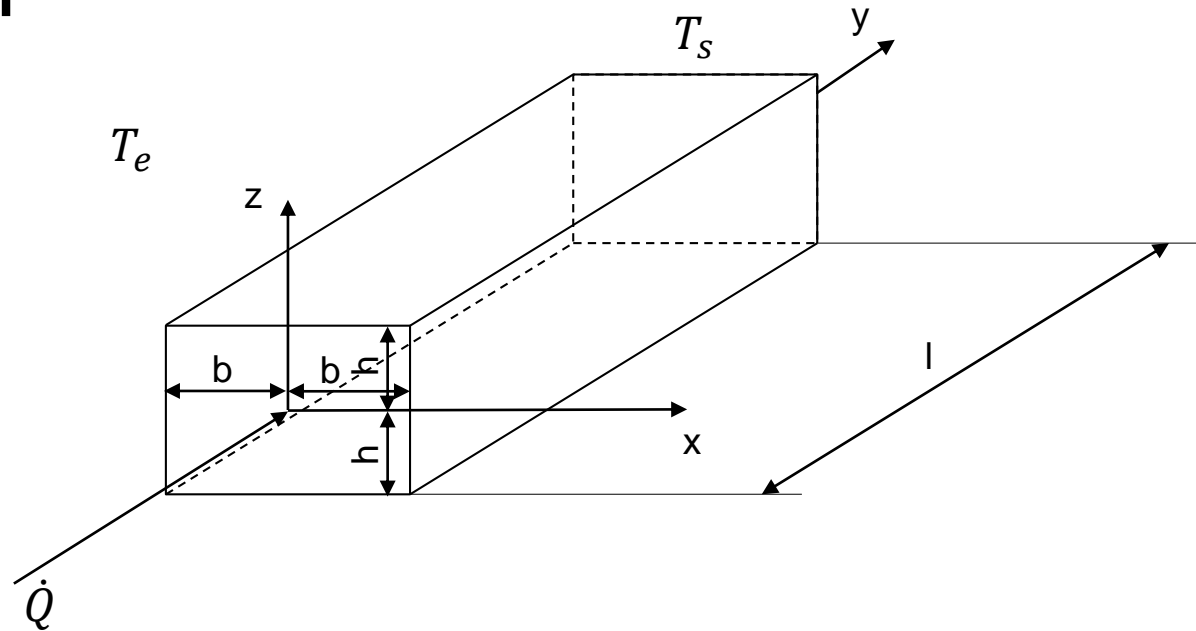
- Mathematically

$$\frac{d}{dt}E = \frac{d}{dt} \iiint_{V_c} \rho e dV = \underbrace{- \iint_{\partial V_c} \rho e \vec{v} \cdot \vec{n} dA}_{\text{Energy flow by convection}} + \dot{Q} - \dot{W}$$

The energy balance II

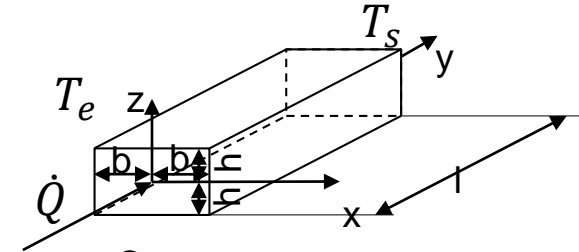
$$\frac{d}{dt} \int_{\Omega} \rho e dV = - \int_{\Gamma} \rho e \cdot \underline{v} \cdot \underline{n} dA + \frac{dQ}{dt} - \frac{dW}{dt}$$

Example – heated bar

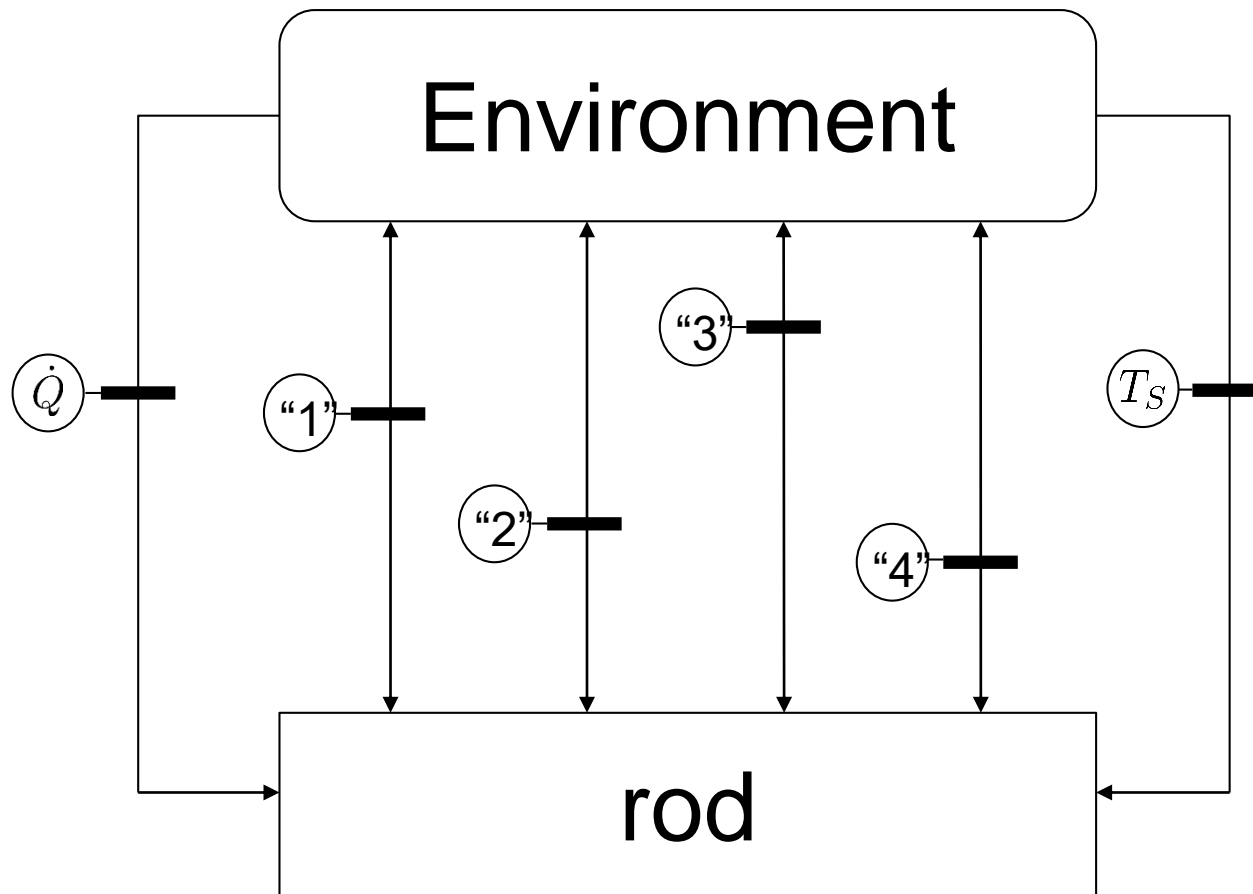


- At all sidewalls there is heat exchange with the environment (T_e , heat exchange coefficient α)
- At the front side there is a heat flux \dot{Q}
- At the back side there is a constant temperature T_s

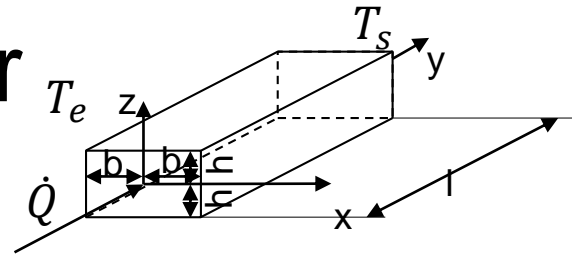
Abstraction of process



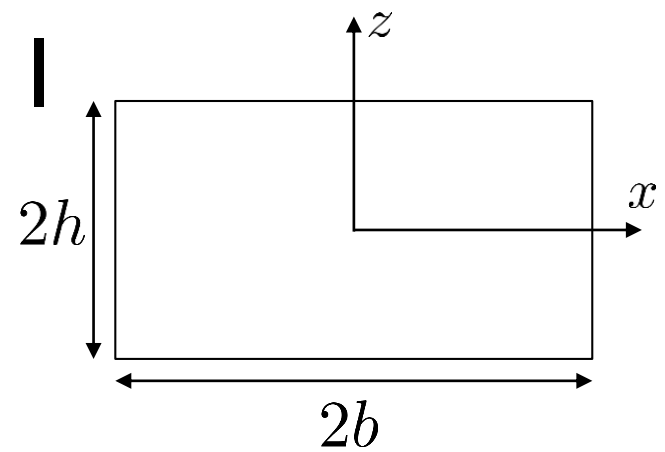
- How many interaction with the environment?



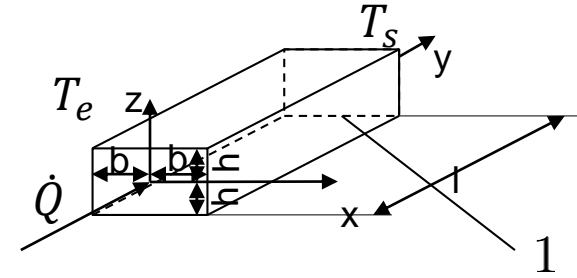
Energy balance – heated bar



Solve differential balance I



Boundary conditions



Solve differential balance II (pde)

