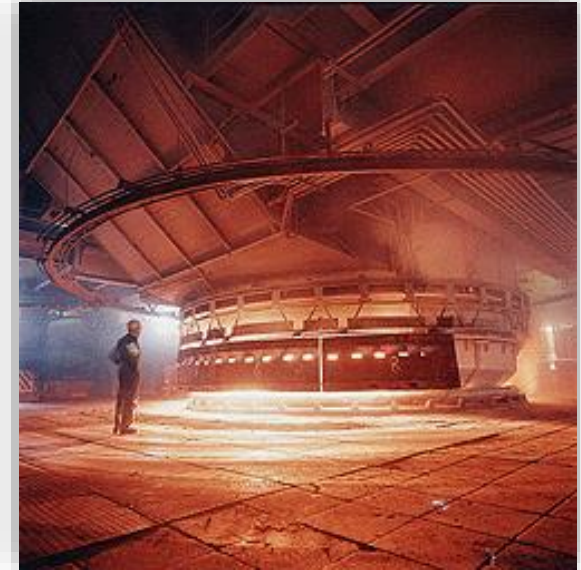


# Lecture 20: Process modeling & balance laws

- Process modeling, structure and methodology
- Balance laws
  - Mass balances
  - Mass balances for multi-component systems

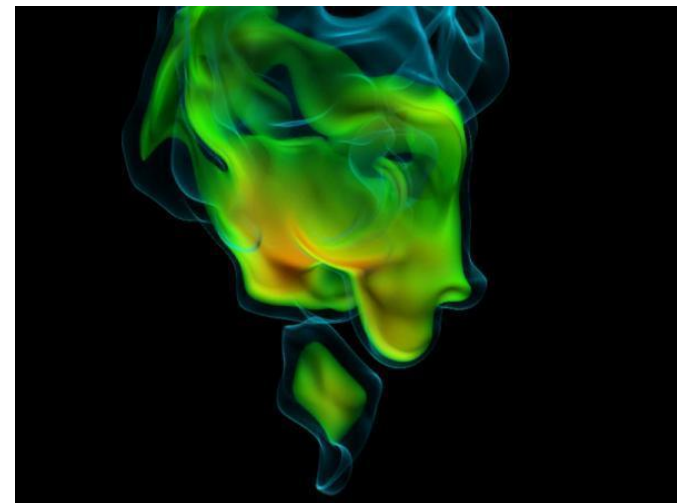
Book: 10.4, 11.1-11.4

# What are process modeling and balance laws used for?



## Process modeling & balance laws:

- Basically, modeling of anything that changes in the physical world.
- In this context, we will be concerned with **fluids** (liquids and gas) in (chemical) **process systems**

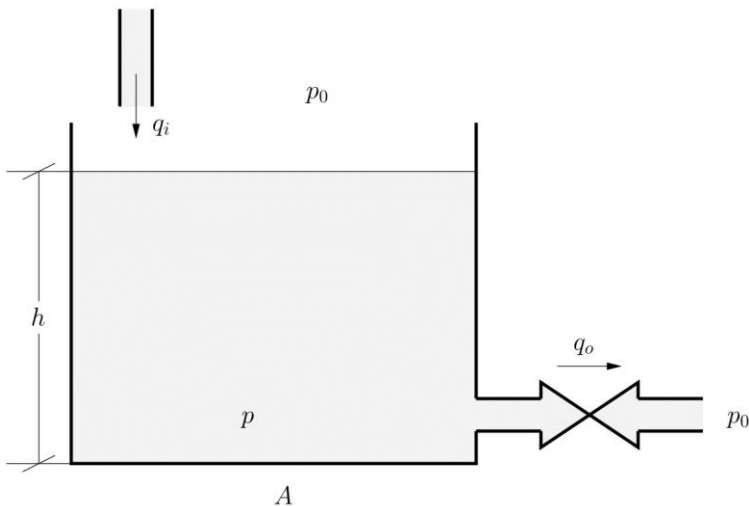


Autoignition of hydrogen in a turbulent hot air coflow

# Process modeling: Structure and methodology

- Goal of process modeling: **Construct mathematical models of the process under study.**
- These mathematical models consists of process variables (**variables** and **parameters**) and the **equations** that link these

## Process



## Process variables

(variables and parameters)

- Level
  - Variability: Variable
  - Symbol:  $h$
  - Value: 1.1
  - Unit: m
  - ...
- Area
  - Variability: Parameter
  - Symbol:  $A$
  - Value: 2.2
  - Unit:  $\text{m}^2$
  - ...
- ...

## Process equations

$$\frac{dh}{dt} = \frac{1}{A} (q_i - q_o)$$

$$q_o = C\sqrt{p - p_0}$$

$$p = p_0 + \rho gh$$

Number of equations must match number of (unknown) variables.

# Process equations

- Balance laws

- Mass
- Momentum
- Energy
- ...

- Constitutive equations

- For (generalized) flows
- Thermodynamic equations of state (e.g. ideal gas law)
- Phenomenological relationships (e.g. between friction force and flow in a pipe)
- ...

- Constraints

- Geometric relationships
- Equilibrium conditions
- ...

Also called «closure relations» as they «close» the balance laws (such that #equations = #variables)

Example Tank:

$$\frac{dh}{dt} = \frac{1}{A} (q_i - q_o)$$

$$q_o = C\sqrt{p - p_0}$$

$$p = p_0 + \rho gh$$

$$V = Ah$$

# Process variables

- Thermodynamic state variables
  - Mass, pressures, levels, ...
  - Velocities
  - Temperatures
  - ...

- (Generalized) flows
  - Transport (single phase)
  - Exchange (between phases)
  - Sources (reactions)
  - ...

- Phenomenological coefficients
  - Viscosity
  - Reaction rates
  - Valve constants
  - ...

- Geometric dimensions
  - Lengths, Areas, Volumes
  - ...

Example Tank:

$h, \rho, p, p_0$

$q_i, q_o$

$C, g$

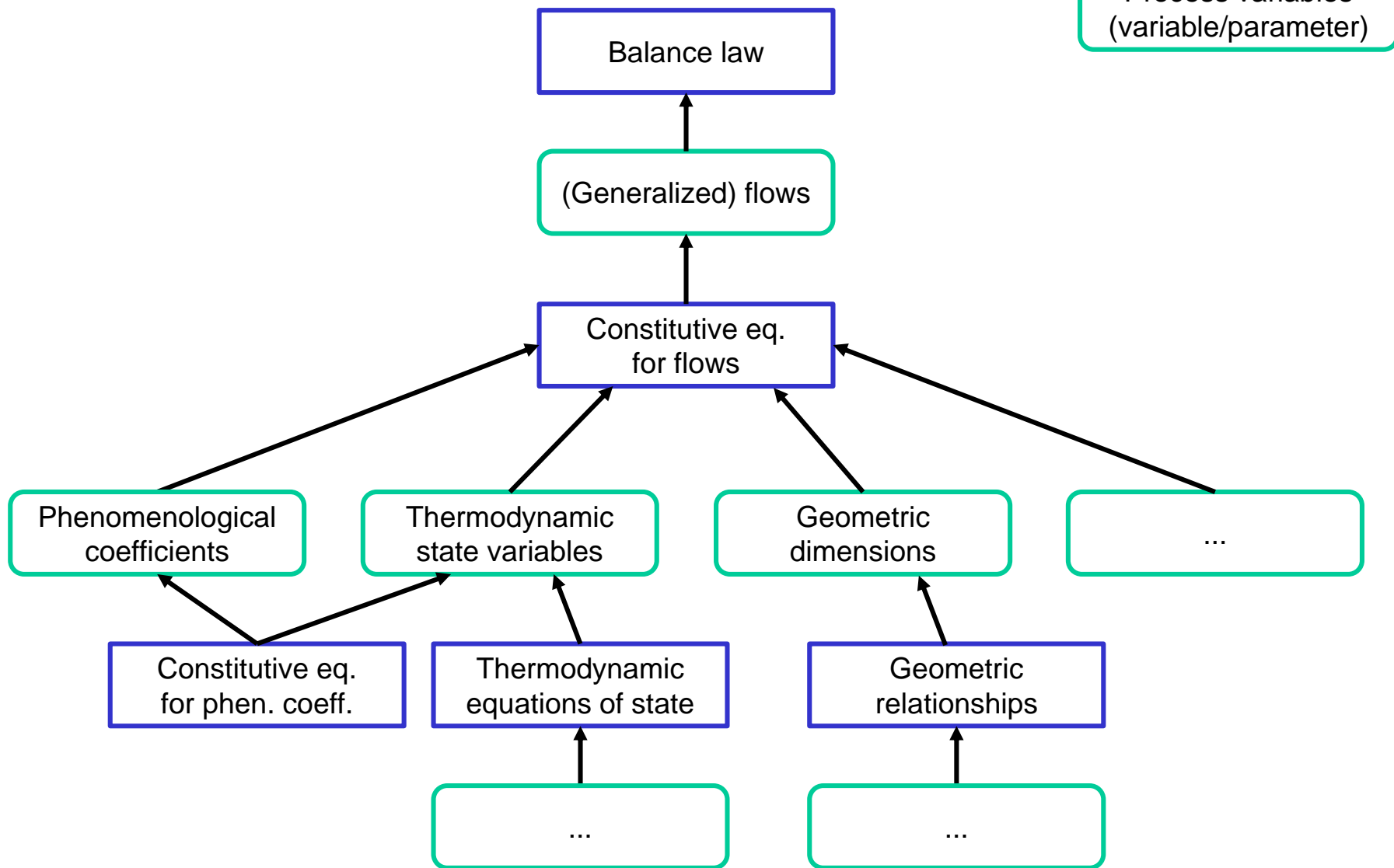
$A$

$$\frac{dh}{dt} = \frac{1}{A} (q_i - q_o)$$

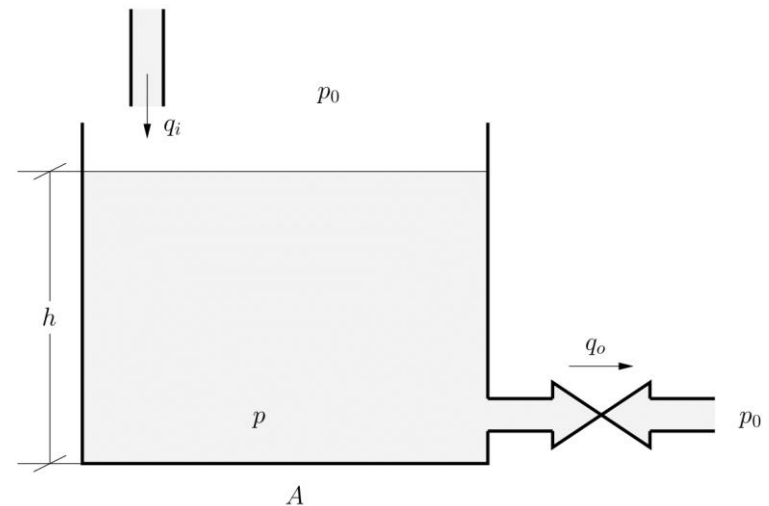
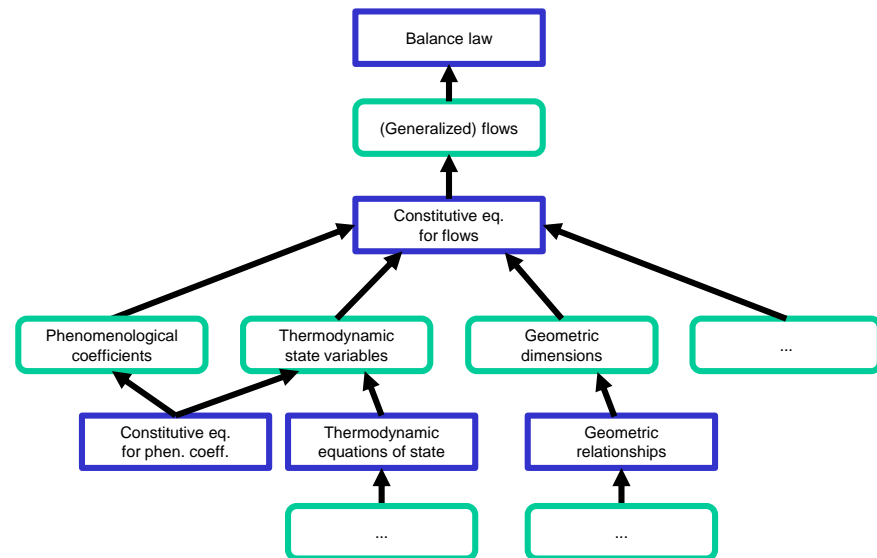
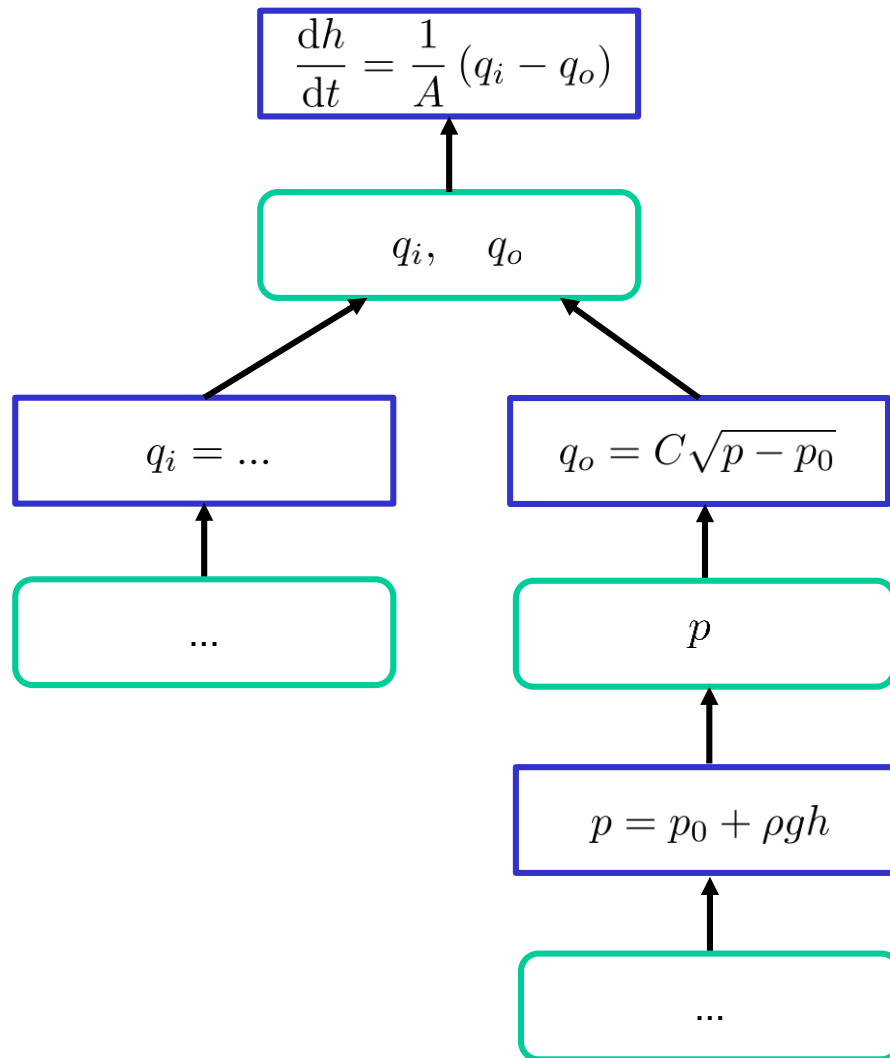
$$q_o = C\sqrt{p - p_0}$$

$$p = p_0 + \rho gh$$

# Structure of process models



# Example: Tank



# BALANCE LAWS



Physical balance principles are based on

# Conservation laws

That a physical property is *conserved*, means that it will remain constant in a closed system

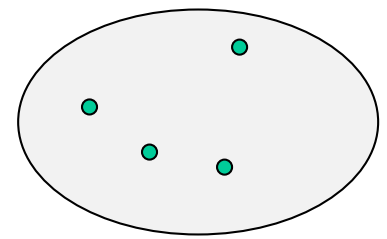
The following physical quantities are conserved:

- Mass
- Energy
- Momentum (norsk: impuls)
  - Linear and angular

No one has ever observed that conservation laws have been violated

- Conservation laws are exact laws

# The basic physical principles



Consider a volume consisting of a **fixed** number of fluid particles, with total mass  $m$ , total momentum  $\vec{p}$  and total energy  $E$ . From basic physics (conservation laws), we know the following principles hold:

- Conservation of mass (mass balance):

$$\frac{dm}{dt} = 0$$

- Newton's second law (momentum balance)

$$\frac{d\vec{p}}{dt} = \vec{F}$$

Also holds for angular momentum,  $\vec{h} = \vec{r} \times \vec{p}$ :

$$\frac{d\vec{h}}{dt} = \vec{r} \times \vec{F} = \vec{T}$$

- First law of thermodynamics (conservation of energy, energy balance):

$$\frac{dE}{dt} = \dot{Q} - \dot{W}$$

Rate of heat flowing into volume from surroundings  $\rightarrow \dot{Q}$   
 $\dot{W}$  Rate at which work is done by the body at surroundings

# State variables for process systems

- What variables are relevant as state variable(s) for balance laws based on conservation of mass (that is, mass balances)?
  - Mass
  - Density
  - Moles, and mole concentration
  - Derived quantities: Pressure, level, ...
  - (number of particles, etc.)
- For energy balances:
  - Internal energy
  - Temperature
- For momentum balances
  - Linear or angular momentum
  - Velocities

# Extensive and intensive properties

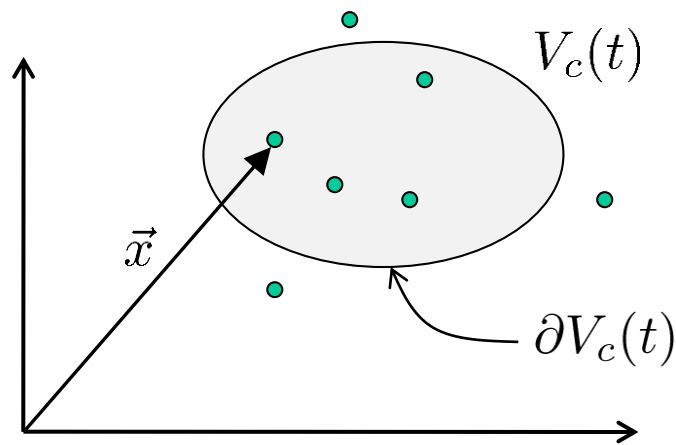
- We must choose properties (thermodynamic variables) to describe our process, and these are either *intensive* or *extensive*
- Intensive properties are scale invariant (does not change if we divide a volume in two), while extensive variables are proportional to amount of material
- In this course, we use mostly *mass-intensive* properties/variables (that is, we measure amount of material with mass):

Extensive properties	Symbol	Unit	Intensive properties	Symbol	Unit
mass	$m$	kg	1	-	-
volume	$V$	m <sup>3</sup>	specific volume	$v$	m <sup>3</sup> /kg
internal energy	$U$	J	specific internal energy	$u$	J/kg
enthalpy	$H$	J	specific enthalpy	$h$	J/kg
entropy	$S$	J/K	Specific entropy	$s$	J/K/kg

- What alternatives are there to mass-intensive?
- Is temperature an intensive or extensive property? Pressure? (yes and no...)

# The concept of control volume

- We use a control volume for separating what we are interested in from the rest of the world (surroundings)
- Generally, material flow into (or out of) the control volume, across the surface



Extensive Property  $B$  of one particle

$$dB = \rho(\mathbf{x})\beta(\mathbf{x}, t)dV$$

Summed over all particles in  $V_c(t)$

$$B = \iiint_{V_c(t)} \rho(\mathbf{x})\beta(\mathbf{x}, t)dV$$

- We are interested in
  - knowing how the extensive property  $B$  varies inside the control volume
  - **or** (equivalently?) how the intensive property  $\beta(\mathbf{x}, t)$  varies inside the volume
- Control volumes can move or change shape, but we will assume they are **fixed** (more on this in fluid mechanics)

# Lumped vs distributed modeling

- If we do *lumped modeling*, we assume that intensive properties are constant (or averaged) over the control volume

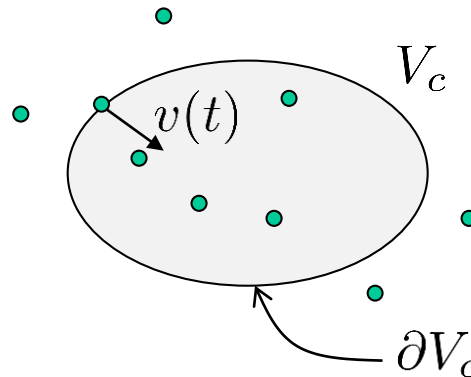
$$B = \iiint_{V_c} \rho \beta(\mathbf{x}) dV = \iiint_{V_c} \rho \bar{\beta} dV = \bar{\beta} \iiint_{V_c} \rho dV = m \bar{\beta}$$

- The balance laws used for lumped modeling are the *integral* (or *macroscopic*) balance laws
  - Formulated for extensive (e.g. mass), or averaged intensive (e.g. average temperature), variables
- The alternative to lumped modeling is *distributed* modeling, where we are interested in how  $\beta(\mathbf{x}, t)$  varies as a function of position  $\mathbf{x}$
- The balance laws for distributed modeling are the *differential* balance laws

(This course: Mainly lumped modeling and integral balance laws)

# The balance laws I

- Assume a **fixed** control volume (of arbitrary size and shape), where fluid flows across the control volume



$$B = \iiint_{V_c} \rho \beta(\mathbf{x}, t) dV$$

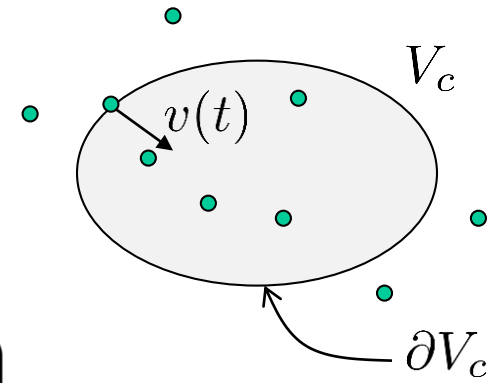
- The general integral (macroscopic) balance law for  $B$  is

$$\frac{d}{dt} B = \left\{ \begin{array}{l} \text{transfer of } B \text{ through} \\ \text{surface } \partial V_c \text{ by} \\ \text{fluid flow (convection)} \end{array} \right\} + \left\{ \begin{array}{l} \text{other effects that} \\ \text{transfer } B \text{ into } V_c \\ \text{(indep. of fluid flow)} \end{array} \right\}$$

# The balance laws II

- Mass balance (without reactions/phase transfer)

$$\frac{d}{dt}m = \left\{ \begin{array}{c} \text{transfer of mass into} \\ V_c \text{ by fluid flow} \\ \text{across surface } \partial V_c \end{array} \right\}$$



- Momentum (note: momentum is a vector)

$$\frac{d}{dt}\mathbf{p} = \left\{ \begin{array}{c} \text{transfer of momentum into} \\ V_c \text{ by fluid flow} \\ \text{across surface } \partial V_c \end{array} \right\} + \left\{ \begin{array}{c} \text{generation of momentum} \\ \text{in } V_c \text{ due to forces} \\ \text{acting on } V_c \end{array} \right\}$$

- Energy

$$\frac{d}{dt}E = \left\{ \begin{array}{c} \text{transfer of energy into} \\ V_c \text{ by fluid flow} \\ \text{across surface } \partial V_c \end{array} \right\} + \left\{ \begin{array}{c} \text{transfer of energy into} \\ V_c \text{ by heat transfer} \\ \text{and by work} \end{array} \right\}$$



# Mathematical formulation of convection

$$\frac{d}{dt}B = \underbrace{\left\{ \begin{array}{l} \text{transfer of } B \text{ through} \\ \text{surface } \partial V_c \text{ by} \\ \text{fluid flow (convection)} \end{array} \right\}}_{-\iint_{\partial V_c} \rho \beta \vec{v} \cdot \vec{n} dA} + \left\{ \begin{array}{l} \text{other effects that} \\ \text{transfer } B \text{ into } V_c \\ \text{(indep. of fluid flow)} \end{array} \right\}$$

# Mathematical formulation of mass balance

- For mass, the intensive variable is  $\beta(\mathbf{x}, t) = 1$

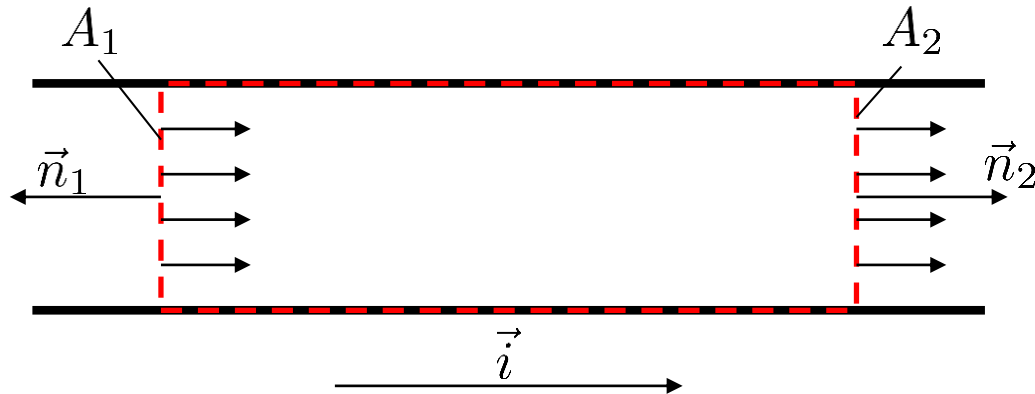
$$\frac{d}{dt}m = \underbrace{\left\{ \begin{array}{c} \text{transfer of mass into} \\ V_c \text{ by fluid flow} \\ \text{across surface } \partial V_c \end{array} \right\}}_{-\iint_{\partial V_c} \rho \beta \vec{v} \cdot \vec{n} dA}$$

$$\frac{d}{dt}m = \frac{d}{dt} \iiint_{V_c} \rho dV = - \iint_{\partial V_c} \rho \vec{v} \cdot \vec{n} dA$$

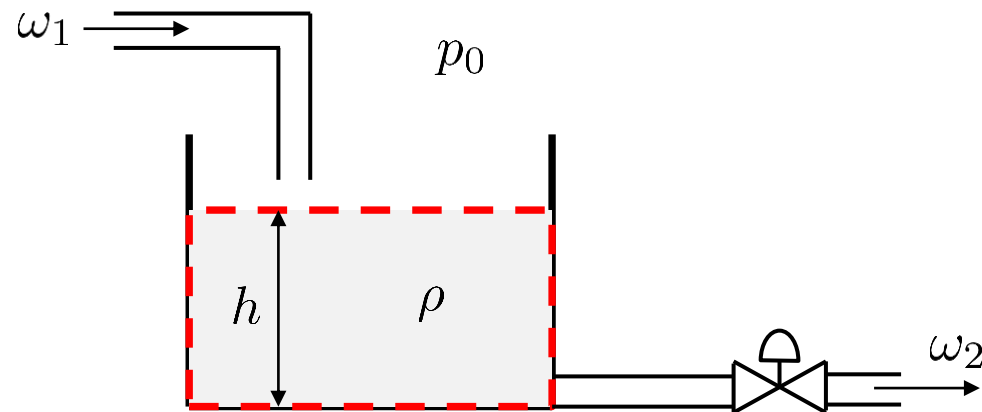
- Often, we have one (or more) «point inflows»  $\omega_{in,i}$ , and outflows  $\omega_{out,i}$ . Then mass balance can be formulated as

$$\frac{d}{dt}m = \sum_i w_{in,i} - \sum_i w_{out,i}$$

# Example: Flow in a pipe



# Example: Tank



# Mass-type balance laws with generation

- Assume  $B$  is an extensive variable «equivalent to» mass
  - that is, mass of a component in a volume, or number of molecules of a component, number of particles, etc.
- These types of mass balance laws can have *internal generation*:

$$\frac{d}{dt}B = \sum_i W_{\text{in},i} - \sum_i W_{\text{out},i} + W_{\text{generated}}$$

- More generally, if the local rate of generation of  $B$  is  $r_B$ :

$$\frac{d}{dt}B = \frac{d}{dt} \iiint_{V_c} \rho \beta dV = - \iint_{\partial V_c} \rho \beta \vec{v} \cdot \vec{n} dA + \iiint_{V_c} r_B dV$$

# Chemical reactions I

- Sometimes easier with amount of molecules than with masses
- Amount of molecules is measured in mol and the symbol  $n_k$

→ Moleculebalance instead of massbalance

# Molebalance

$$\frac{d}{dt} \iiint_{V_c} c_k dV = - \iint_{\partial V_c} c_k \vec{v} \cdot \vec{n} dA + \iiint_{V_c} \hat{r}_k dV$$

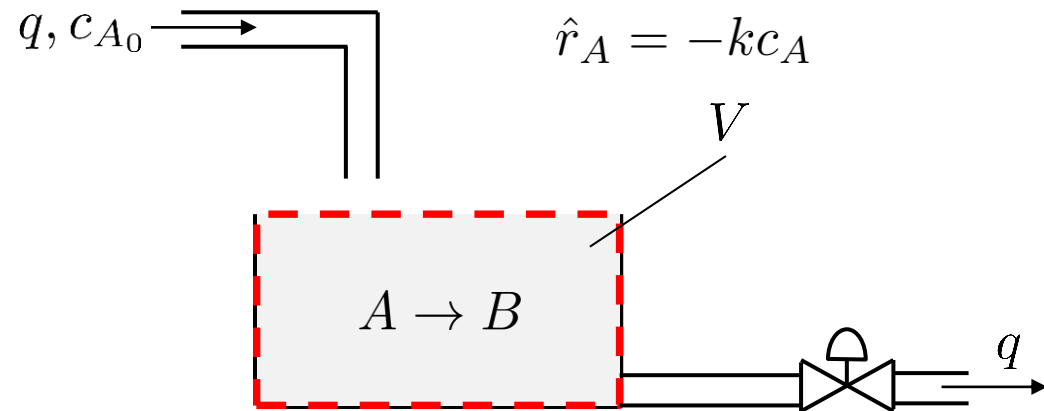
- Example:



# Chemical reactions II



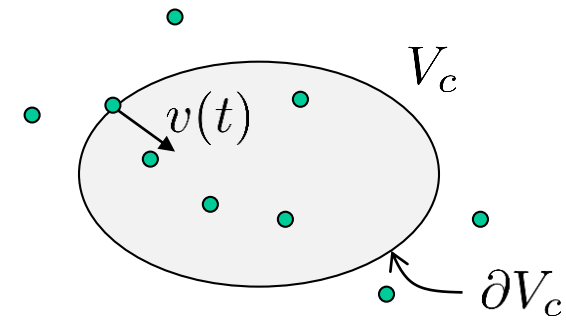
# Example: Reaction in tank



# Chemical reactions III

- Closed tank: 
$$\frac{d}{dt} \iiint_{V_c} c_k dV = - \iint_{\partial V_c} c_k \vec{v} \cdot \vec{n} dA + \iiint_{V_c} \hat{r}_k dV$$

# The momentum balance



- In words

$$\frac{d}{dt}\mathbf{p} = \left\{ \begin{array}{c} \text{transfer of momentum into} \\ V_c \text{ by fluid flow} \\ \text{across surface } \partial V_c \end{array} \right\} + \left\{ \begin{array}{c} \text{generation of momentum} \\ \text{in } V_c \text{ due to forces} \\ \text{acting on } V_c \end{array} \right\}$$

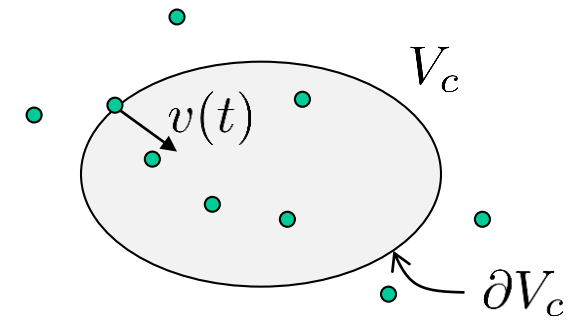
- Mathematically

$$\frac{d}{dt}\vec{p} = \frac{d}{dt} \iiint_{V_c} \rho \vec{v} dV = - \iint_{\partial V_c} \rho \vec{v} \vec{v} \cdot \vec{n} dA + \vec{F}^{(r)}$$

where  $\vec{F}^{(r)}$  is resultant force on fluid in control volume

(often: gravity (hydrostatic) and/or friction (hydrodynamic))

# The energy balance



- In words

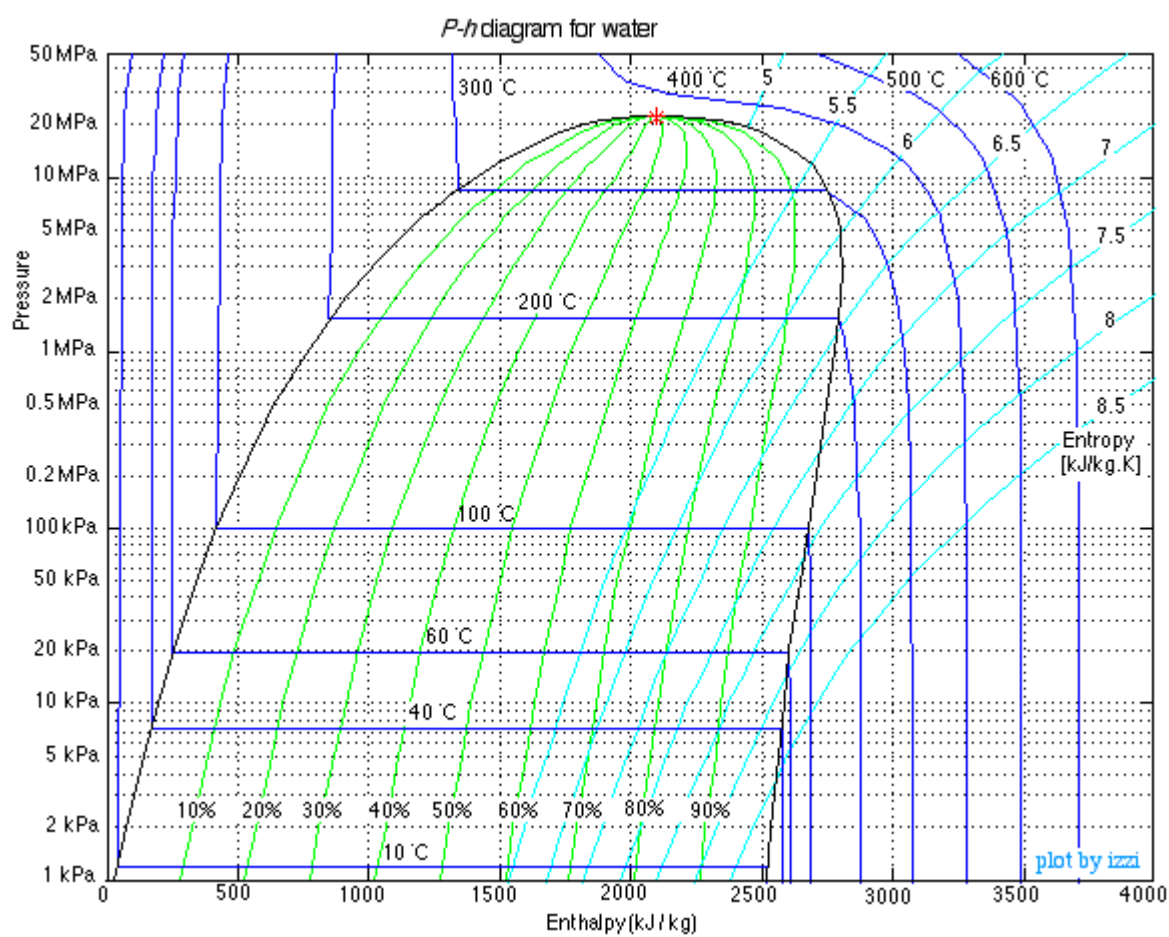
$$\frac{d}{dt}E = \left\{ \begin{array}{c} \text{transfer of energy into} \\ V_c \text{ by fluid flow} \\ \text{across surface } \partial V_c \end{array} \right\} + \left\{ \begin{array}{c} \text{transfer of energy into} \\ V_c \text{ by heat transfer} \\ \text{and by work} \end{array} \right\}$$

- Mathematically

$$\frac{d}{dt}E = \frac{d}{dt} \iiint_{V_c} \rho e dV = \underbrace{- \iint_{\partial V_c} \rho e \vec{v} \cdot \vec{n} dA}_{\text{Energy flow by convection}} + \dot{Q} - \dot{W}$$

- What is the energy of a fluid?

# P-h-diagram for water



# Homework

- Read 11.1-11.2
- Formulate a momentum balance for a pipeflow with friction

