

Lecture 24: Process modeling & balance laws

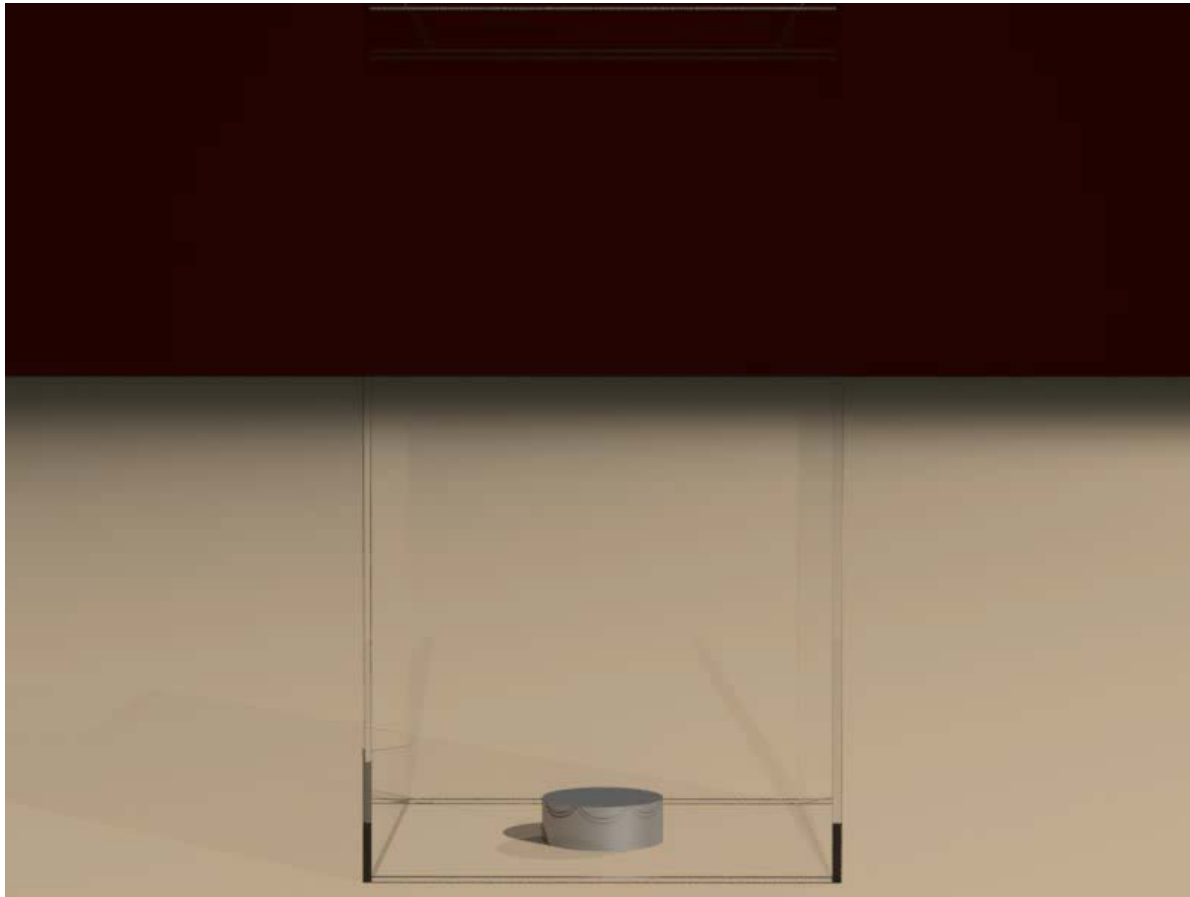
- Balance laws
 - Differential balances
 - Material derivative

Book: 10.4, 11.1-11.4

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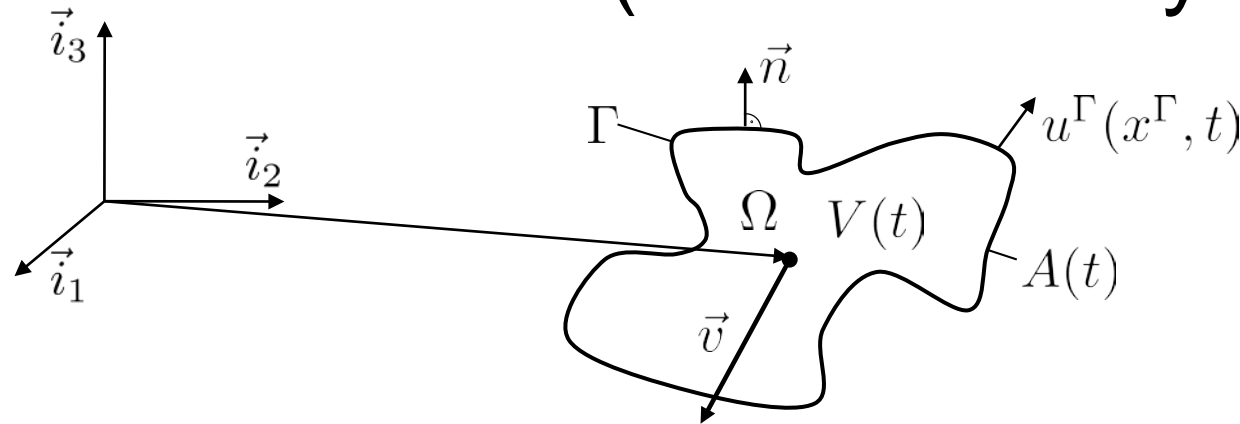
Computational fluid dynamics

- CFD = solving momentum + mass balances (that is, Navier-Stokes + continuity equation) for different setups



<http://physbam.stanford.edu/~fedkiw/>

Control volume (infinitesimally small)



- How can the extensive property Ψ change in the domain Ω ?

production rate : $\Sigma_\Psi \triangleq \frac{\text{produced/consumed } \Psi \text{ in } \Omega}{\text{time}}$

transport rate : $\bar{\Phi} = \frac{\text{over } \Gamma \text{ in/out of the domain } \Omega}{\text{time}}$

→ Integral balance: $\frac{d}{dt} \Psi = \bar{\Phi}_\Psi + \Sigma_\Psi$

Storage →
effort ↑
transport ↑
source

General integral balance

- Arbitrary size: In order to get a local character we have to introduce properties with local characteristics

$$\psi(x, t) = \lim_{V \rightarrow 0} \frac{\Psi}{V} |_{x, t} \quad [\text{intensive property}]$$

$$\Psi(t) = \int_{\Omega} \psi(x, t) dV$$

$$\Sigma_{\psi}(t) = \int_{\Omega} \sigma_{\psi}(x, t) dV$$

← source density

remote effects

$$\sigma_{\psi}(x, t) = \sigma_{\psi}^p(x, t) + \sigma_{\psi}^F(x, t)$$

$$\phi_{\psi}(x, t) = \lim_{V \rightarrow 0} \frac{\bar{\Phi}}{A} |_{x^p, t} \quad \leftarrow \text{physiochemical phenomena in } \Omega$$

$$\Rightarrow \bar{\Phi}_{\psi}(t) = - \int_{\Gamma} \langle \phi_{\psi}(x^p, t) \rangle dA$$

$$\frac{d}{dt} \int_{\Omega} \psi dV = - \int_{\Gamma} \phi_{\psi} \cdot \underline{n} dA + \int_{\Omega} \sigma_{\psi} dV$$

general
integral
balance

Derivation of differential balance I

- Goal: Find a derivative of the local density ψ instead of the total amount of extensive property Ψ

$$\frac{d}{dt} \int_{\Omega} \psi dV = - \int_{\Gamma} \phi_{\psi} \underline{n} dA + \int_{\Omega} \sigma_{\psi} dV$$

→ change differentiation and integration

- Use: Reynold's transport theorem:

$$\frac{d}{dt} \int_{\Omega} \psi dV = \int_{\Omega} \frac{\partial \psi}{\partial t} dV + \int_{\Gamma} \psi \underline{u}^{\Gamma} \underline{n} dA$$

← change of moving surface

$$\rightarrow \int_{\Omega} \frac{\partial \psi}{\partial t} dV = - \int_{\Gamma} \psi \underline{u}^{\Gamma} \underline{n} dA - \int_{\Gamma} \phi_{\psi} \cdot \underline{n} dA + \int_{\Omega} \sigma_{\psi} dV$$

Derivation of differential balance II

$$\int_{\Omega} \frac{\partial \psi}{\partial t} dV = - \int_{\Gamma} \psi \underline{u}^{\Gamma} \underline{n} dA - \int_{\Gamma} \phi_{\psi} \underline{n} dA + \int_{\Omega} \sigma_{\psi} dV$$

- Finally we have to transfer the surface integrals into volume integrals to get the same integration domain
- Use: Divergence theorem

$$\int_{\Gamma} \phi_{\psi} \underline{n} dA = \int_{\Omega} \nabla \cdot \phi_{\psi} dV$$

Nabla Operator: $\nabla = \left(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n} \right) = \sum_{i=1}^n \vec{e}_i \frac{\partial}{\partial x_i}$

Cartesian coordinates: $(\nabla \cdot \underline{v}) = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$

Cylindrical coordinates: $(\nabla \cdot \underline{v}) = \frac{1}{r} \frac{\partial}{\partial r} (r \cdot v_r) + \frac{1}{r} \frac{\partial v_{\theta}}{\partial \theta} + \frac{\partial v_z}{\partial z}$

Derivation of differential balance III

$$\int_{\Omega} \frac{\partial \psi}{\partial t} dV = - \int_{\Gamma} \psi \underline{u}^{\Gamma} \underline{n} dA - \int_{\Gamma} \phi_{\psi} \underline{n} dA + \int_{\Omega} \sigma_{\psi} dV$$

- Apply divergence theorem: *velocity of volume*

$$\int_{\Omega} \frac{\partial \psi}{\partial t} dV = - \int_{\Omega} \nabla \cdot \psi \underline{\omega} dV - \int_{\Omega} \nabla \cdot \phi_{\psi} dV + \int_{\Omega} \sigma_{\psi} dV$$

→ Ω is arbitrary since integration must be zero

$$\frac{\partial \psi}{\partial t} + \nabla \cdot \psi \underline{\omega} + \nabla \cdot \phi_{\psi} = \sigma_{\psi}$$

$\phi^t = \psi \underline{\omega} + \phi_{\psi}$ *→ general differential balance of density ψ*

$$\frac{\partial \psi}{\partial t} + \nabla \cdot \phi_{\psi}^t = \sigma_{\psi}$$

Mass balance

velocity of center of mass: $\underline{\omega} = \frac{1}{\rho} \sum_{i=1}^{n_c} \rho_i \underline{v}_i =: \underline{v}$

• diffusive flux: $\Phi_{\rho_i} = \rho_i (\underline{v}_i - \underline{v}) =: \underline{j}_i$

$$\rightarrow \frac{\partial \rho_i}{\partial t} + \nabla \cdot \rho_i \underline{v} + \nabla \cdot \underline{j}_i = r_i^v$$

Equation of continuity of substance i

→ sum over all substances

local rate of mass accumulation $\rightarrow \frac{\partial \rho}{\partial t} + \nabla \cdot \rho \underline{v} = 0$ [Equation of continuity]

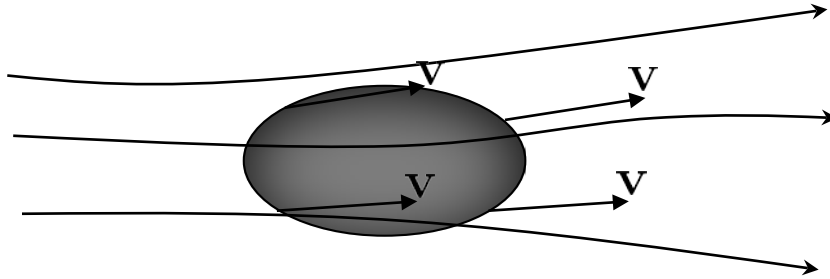
net rate of mass inflow

incompressible fluid

$$\nabla \cdot \underline{v} = 0$$

$$\underbrace{\frac{\partial \rho}{\partial t} + \underline{v} \cdot \nabla \rho}_{\frac{D\rho}{Dt}} + \rho \nabla \cdot \underline{v} = 0$$

“Moving with the flow”



- The boundary of the element moves with the bulk velocity

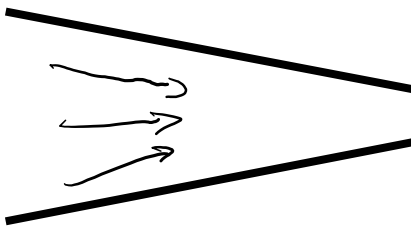
- Property change:

- Unsteady flow
- Motion through a gradient of the property

$$\frac{\partial V}{\partial t} + V \cdot \nabla V$$

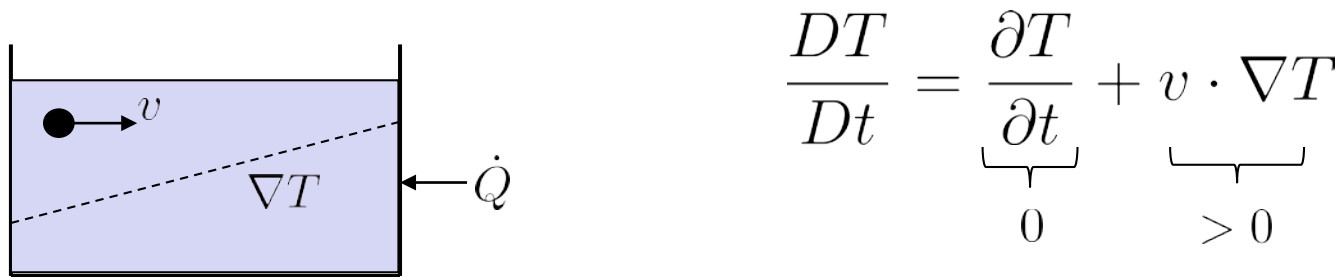
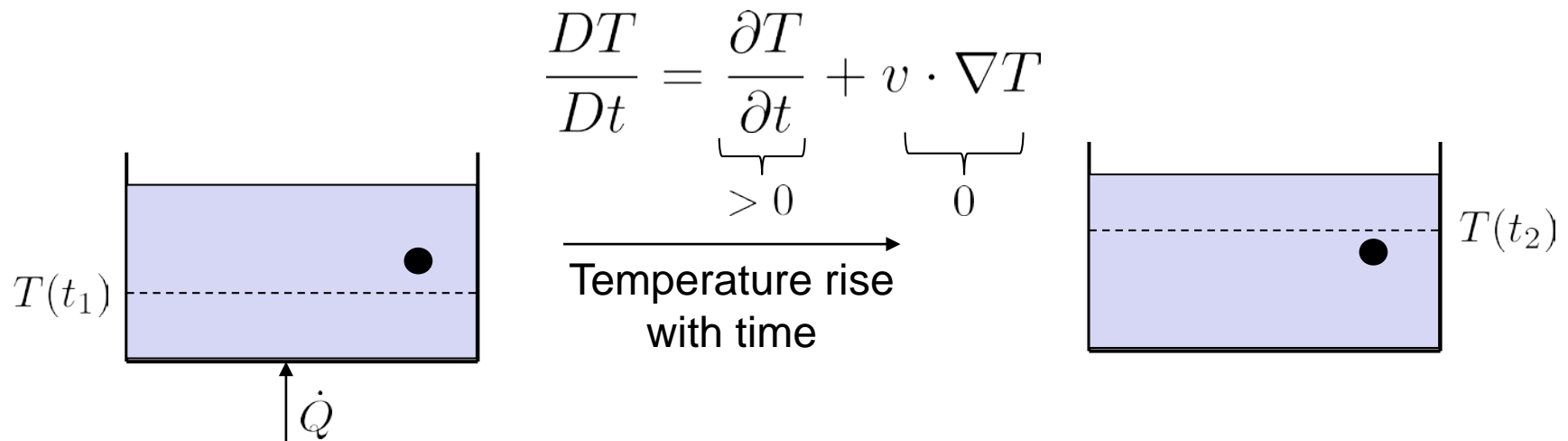
Handwritten arrows point from the text 'Unsteady flow' to the $\frac{\partial V}{\partial t}$ term and from 'Motion through a gradient of the property' to the $V \cdot \nabla V$ term.

- Example:

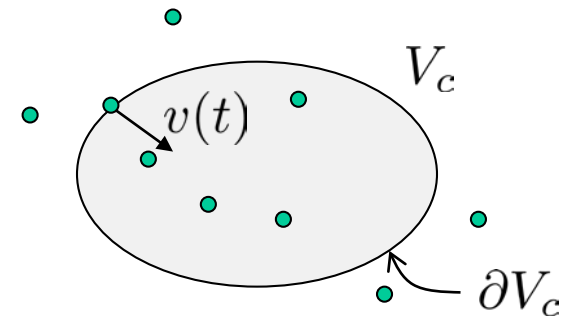


• velocity in creases
as pipe narrows
[Bernoulli's law]

Example: Material derivative $\frac{D}{Dt} = \frac{\partial}{\partial t} + v \cdot \nabla$



The momentum balance I



- In words

$$\frac{d}{dt}\mathbf{p} = \left\{ \begin{array}{c} \text{transfer of momentum into} \\ V_c \text{ by fluid flow} \\ \text{across surface } \partial V_c \end{array} \right\} + \left\{ \begin{array}{c} \text{generation of momentum} \\ \text{in } V_c \text{ due to forces} \\ \text{acting on } V_c \end{array} \right\}$$

- Mathematically

$$\frac{d}{dt}\vec{p} = \frac{d}{dt} \iiint_{V_c} \rho \vec{v} dV = - \iint_{\partial V_c} \rho \vec{v} \vec{v} \cdot \vec{n} dA + \vec{F}^{(r)}$$

where $\vec{F}^{(r)}$ is resultant force on fluid in control volume

(often: gravity (hydrostatic) and/or friction (hydrodynamic))

The momentum balance II

$$\frac{d}{dt} \int_{\Omega} \rho \underline{v} dV = - \int_{\Gamma} \rho \underline{v} \cdot \underline{v} \cdot \underline{n} dA + \int_{\Omega} B dV + \int_{\Gamma} \underline{n} \cdot \underline{\sigma} dA$$

⋮

$$\frac{\partial \rho \underline{v}}{\partial t} + \nabla \cdot \underline{v} \rho \underline{v} - \nabla \underline{\sigma} = B$$

product rule:

$$\int \frac{\partial \underline{v}}{\partial t} + \underbrace{\underline{v} \cdot \frac{\partial \rho \underline{v}}{\partial t} + \rho \underline{v} \cdot \nabla \underline{v}}_{=0 \text{ [Eq. of Cont.]}} - \nabla \underline{\sigma} = B$$

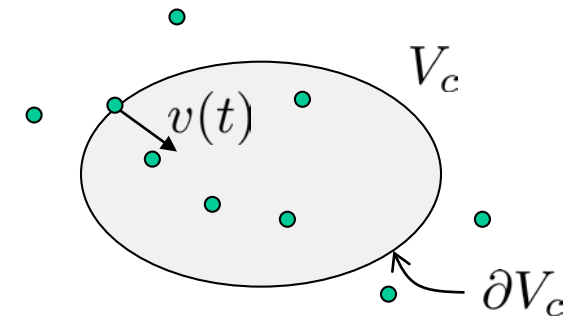
$$\int \left(\frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} \right) = B + \nabla \underline{\sigma}$$

local rate
of change of vel. over time

convective term

$$\rightarrow \int \frac{D \underline{v}}{Dt} = B + \nabla \underline{\sigma}$$

The energy balance I



- In words

$$\frac{d}{dt}E = \left\{ \begin{array}{c} \text{transfer of energy into} \\ V_c \text{ by fluid flow} \\ \text{across surface } \partial V_c \end{array} \right\} + \left\{ \begin{array}{c} \text{transfer of energy into} \\ V_c \text{ by heat transfer} \\ \text{and by work} \end{array} \right\}$$

- Mathematically

$$\frac{d}{dt}E = \frac{d}{dt} \iiint_{V_c} \rho e dV = \underbrace{- \iint_{\partial V_c} \rho e \vec{v} \cdot \vec{n} dA}_{\text{Energy flow by convection}} + \dot{Q} - \dot{W}$$

The energy balance II

$$\frac{d}{dt} \int_{\Omega} \rho e dV = - \int_{\Gamma} \rho e \cdot \underline{v} \cdot \underline{n} dA + \frac{dQ}{dt} - \frac{dW}{dt}$$

$$\frac{dQ}{dt} = - \int_{\Gamma} \underline{n} \cdot \underline{q} dA - \int_{\Omega} q''' dV$$

\nearrow heat flux vector

\nwarrow heat rate generation

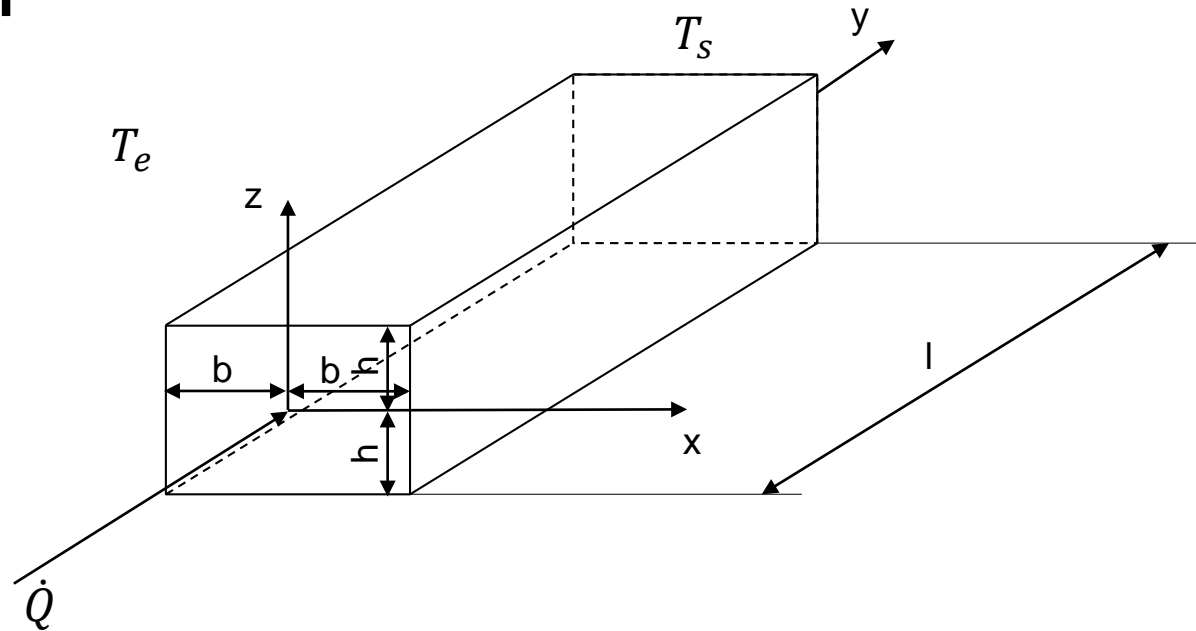
$$\frac{dW}{dt} = - \int_{\Gamma} \underline{n} \cdot (\underline{\sigma} \underline{v}) dA$$

$$\frac{\partial \rho e}{\partial t} + \nabla \cdot (\rho e \underline{v}) + \nabla \cdot \underline{q} - q''' - \nabla \cdot (\underline{\sigma} \cdot \underline{v}) = 0$$

product rule + Eq. of cont.

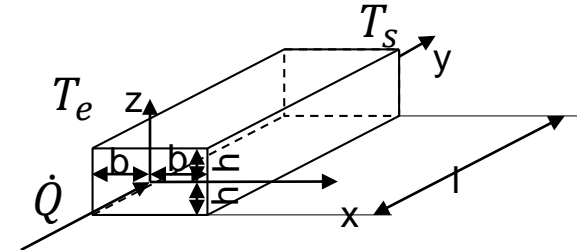
$$\rho \frac{De}{Dt} = - \nabla \cdot \underline{q} + q''' + \nabla \cdot (\underline{\sigma} \cdot \underline{v})$$

Example – heated bar

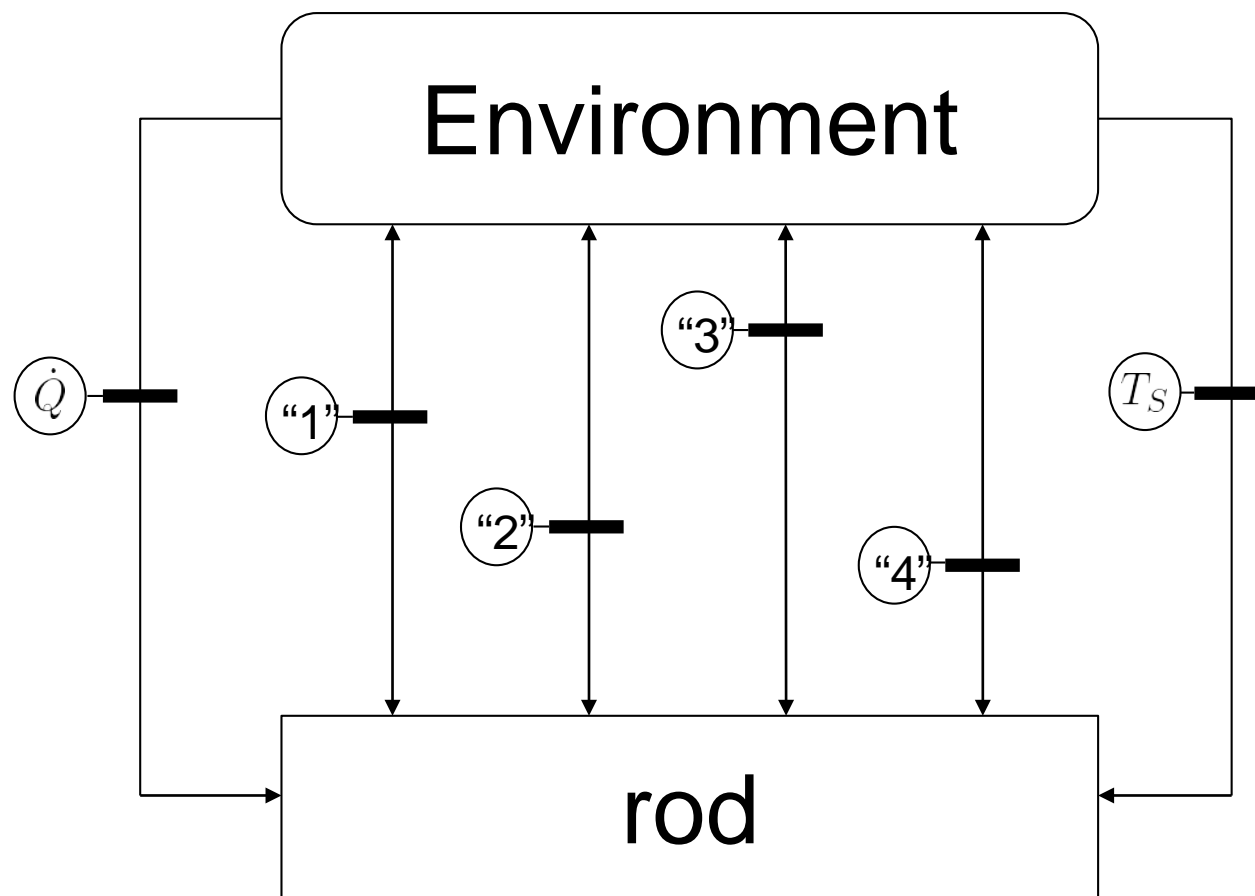


- At all sidewalls there is heat exchange with the environment (T_e , heat exchange coefficient α)
- At the front side there is a heat flux \dot{Q}
- At the back side there is a constant temperature T_s

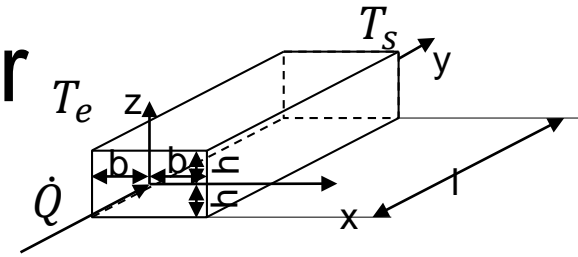
Abstraction of process



- How many interaction with the environment?



Energy balance – heated bar



1) Derive 3D energy balance

$$\frac{\partial \rho h}{\partial t} = - \nabla \cdot \underline{q}$$

Solve Nabla operator:

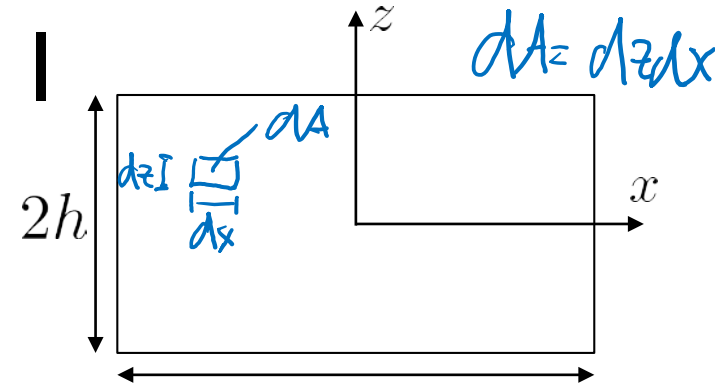
$$\frac{\partial \rho h}{\partial t} = - \frac{\partial}{\partial x} (q_x) - \frac{\partial}{\partial y} (q_y) - \frac{\partial}{\partial z} (q_z)$$

Fourier's law: $\underline{q} = -\lambda \nabla T$

heat capacities: $\frac{\partial h}{\partial t} = c_p \frac{\partial T}{\partial t}$

$$\rho \frac{\partial h}{\partial t} = \rho c_p \frac{\partial T}{\partial t} = \lambda \frac{\partial^2 T}{\partial x^2} + \lambda \frac{\partial^2 T}{\partial y^2} + \lambda \frac{\partial^2 T}{\partial z^2}$$

Solve differential balance I

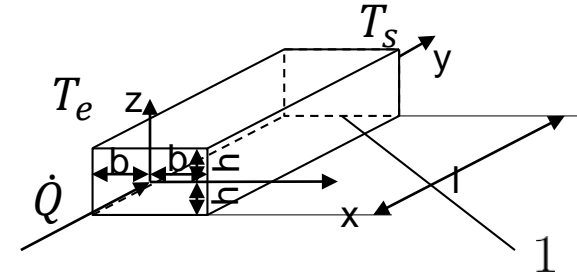


$$\int_{-b}^b \int_{-h}^h \rho c_p \frac{\partial T}{\partial t} dz dx$$

$$= \int_{-b}^b \int_{-h}^h \lambda \frac{\partial^2 T}{\partial x^2} dz dx + \int_{-b}^b \int_{-h}^h \lambda \frac{\partial^2 T}{\partial y^2} dz dx + \int_{-b}^b \int_{-h}^h \lambda \frac{\partial^2 T}{\partial z^2} dz dx$$

$$4hb \rho c_p \frac{\partial \bar{T}}{\partial t} = \int_{-h}^h \left(\left[\lambda \frac{\partial T}{\partial x} \right]_{x=b} - \left[\lambda \frac{\partial T}{\partial x} \right]_{x=-b} \right) dz + 4hb \lambda \frac{\partial^2 \bar{T}}{\partial y^2} + \int_{-b}^b \left(\left[\lambda \frac{\partial T}{\partial z} \right]_{z=h} - \left[\lambda \frac{\partial T}{\partial z} \right]_{z=-h} \right) dx$$

Boundary conditions



Energy balance boundary:

$$0 = q^- + q^+$$

$$q^+ = \alpha (T - T_e) \leftarrow \text{heat convection}$$

$$q^- = \left[\lambda \frac{\partial T}{\partial x} \right]_{x=b} \leftarrow \text{heat conduction}$$

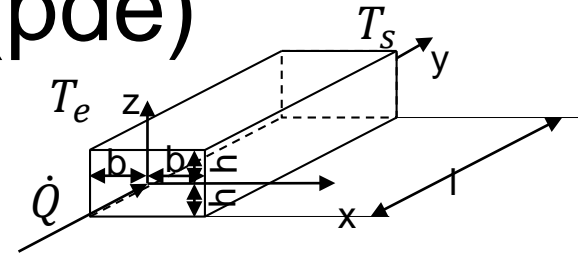
All surfaces:

$$\begin{aligned} 1: \quad & \lambda \left[\frac{\partial T}{\partial x} \right]_{x=b} = -\alpha (T - T_e) \\ 2: \quad & \lambda \left[\frac{\partial T}{\partial z} \right]_{z=h} = -\alpha (T - T_e) \\ 3: \quad & \lambda \left[\frac{\partial T}{\partial x} \right]_{x=-b} = \alpha (T - T_e) \\ 4: \quad & \lambda \left[\frac{\partial T}{\partial z} \right]_{z=-h} = \alpha (T - T_e) \end{aligned}$$

$$\rightarrow 4hb \rho c_p \frac{\partial \bar{T}}{\partial t} = 4hb\lambda \frac{\partial^2 \bar{T}}{\partial y^2} - 4(b+h)\alpha (T - T_e)$$

Solve differential balance II (pde)

- $\vartheta = T - T_e$
- steady-state



$$0 = \frac{\partial^2 \vartheta}{\partial y^2} - \underbrace{\frac{(b+h)h}{b\lambda}}_{\eta^2} \vartheta(y)$$

→ solution of 2nd order diff. eq.

$$\vartheta(y) = C_1 \sinh(\eta y) + C_2 \cosh(\eta y)$$

→ boundary conditions!

$$y=0 \quad \dot{Q} = -\lambda 4bh \left[\frac{\partial T}{\partial y} \right]_{y=0} = -4\lambda b h \eta [C_1 \cosh(0) + C_2 \sinh(0)]$$

$$y=l \quad T_s - T_e = T(y=l) - T_e = C_1 \sinh(\eta l) + C_2 \cosh(\eta l)$$

Homework

- Read Section 4.5 (Hydraulic transmission lines)
- Read Chapter 10