

Crowd  
counting using  
OpenCV and  
Python

Martí Gelabert  
Gómez

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Removal

CLAHE

Background Image  
Gaussian Blur

Subtraction

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Masking

Dilation

Find contours

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# Crowd counting using OpenCV and Python

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University of the Balearic Islands

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# Objective

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We need to generate an algorithm capable of **crowd counting**...

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We need to generate an algorithm capable of **crowd counting**...

So we need to :

- Have some kind of ground truth

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We need to generate an algorithm capable of **crowd counting**...

So we need to :

- Have some kind of ground truth
- An algorithm to Detect persons

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We need to generate an algorithm capable of **crowd counting**...

So we need to :

- Have some kind of ground truth
- An algorithm to Detect persons
- And be able to quantify our performance

# Labeling

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First, we need to **label** our images and establish some kind of **criteria** to decide which persons to label.

# Occlusions

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# Compact information

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# Masked areas

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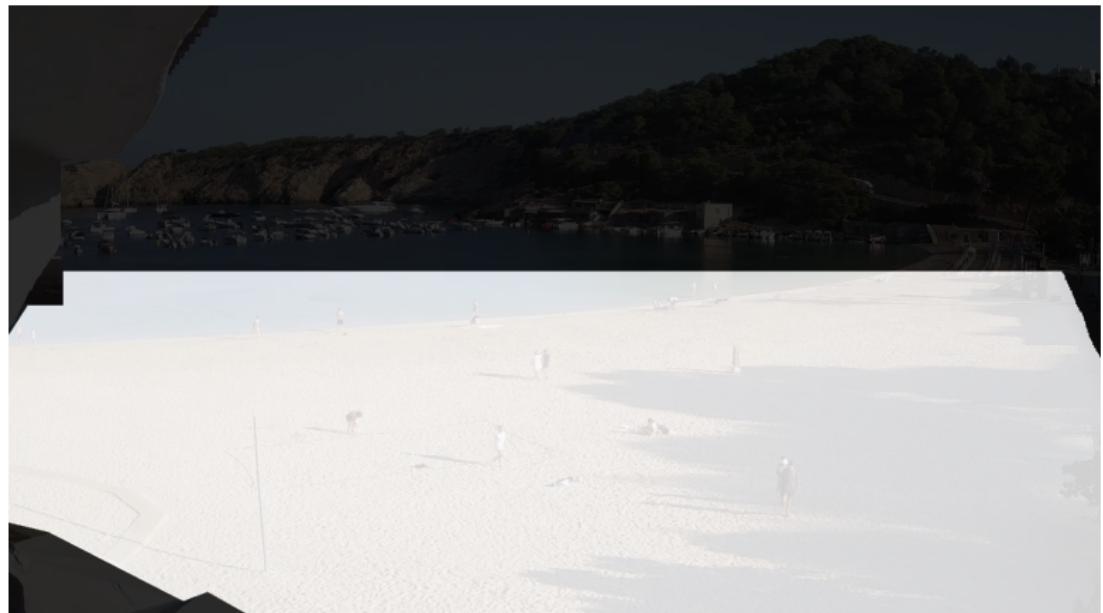
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# Person detection

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Now, we need a way for **detecting people**:

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Now, we need a way for **detecting people**:

- Gabor filtering 

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Now, we need a way for **detecting people**:

- Gabor filtering **X**
- Edge detector **X**

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Now, we need a way for **detecting people**:

- Gabor filtering **X**
- Edge detector **X**
- Applying derivatives **X**

# Person detection

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Now, we need a way for **detecting people**:

- Gabor filtering ✗
- Edge detector ✗
- Applying derivatives ✗
- Background removal ✓

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## Background Removal

# Background Removal

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## Remark

The operations will be done using **grey scale** images.

We need to do something with the **illumination** of the images and improve the **contrast**.

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# Background Image

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# Average image X

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# Gaussian Blur

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# Subtraction

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## Binarization

# Binarization

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`cv2.threshold(subtracted, 100, 255, cv2.THRESH_BINARY)`

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# Masking

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## Dilation

# Dilation

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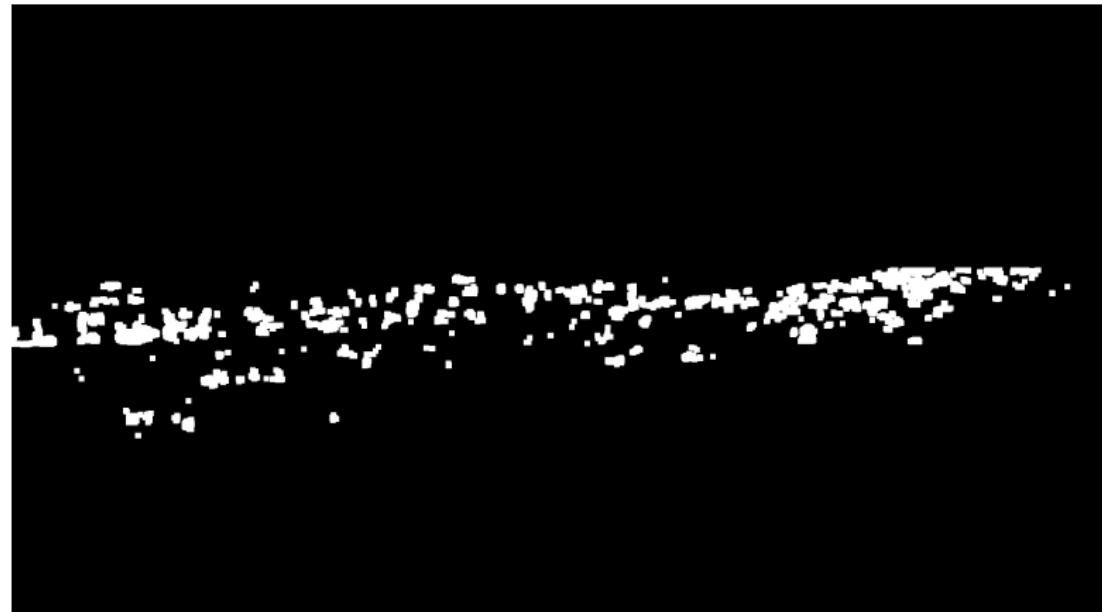
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# Find contours

# Output

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**Detected : 111**  
**Matched : 40**  
**GT : 101**



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- Only detections containing labels will be considered **TP**.
- If detection contains more than one person it will count as only one detection.
- Massive or tiny regions will be discarded.
- Some labels of the ground truth could be double checked.

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files	precision	recall	f1 score	gt	detected	matched
1660309200.jpg	0.336	0.444	0.383	90	119	40
1660302000.jpg	0.292	0.369	0.326	103	130	38
1660294800.jpg	0.333	0.458	0.386	72	99	33
1660320000.jpg	0.363	0.363	0.363	135	135	49
1660287600.jpg	0.200	0.471	0.281	17	40	8
1660298400.jpg	0.347	0.311	0.328	106	95	33
1660305600.jpg	0.360	0.396	0.377	101	111	40
1660316400.jpg	0.358	0.345	0.352	139	134	48
1660291200.jpg	0.353	0.346	0.350	52	51	18

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MSE	341.667
Macro-average precision	0.327
Macro-average recall	0.389
Macro-average F1	0.349

---

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Detected : 119  
Matched : 40  
GT : 90



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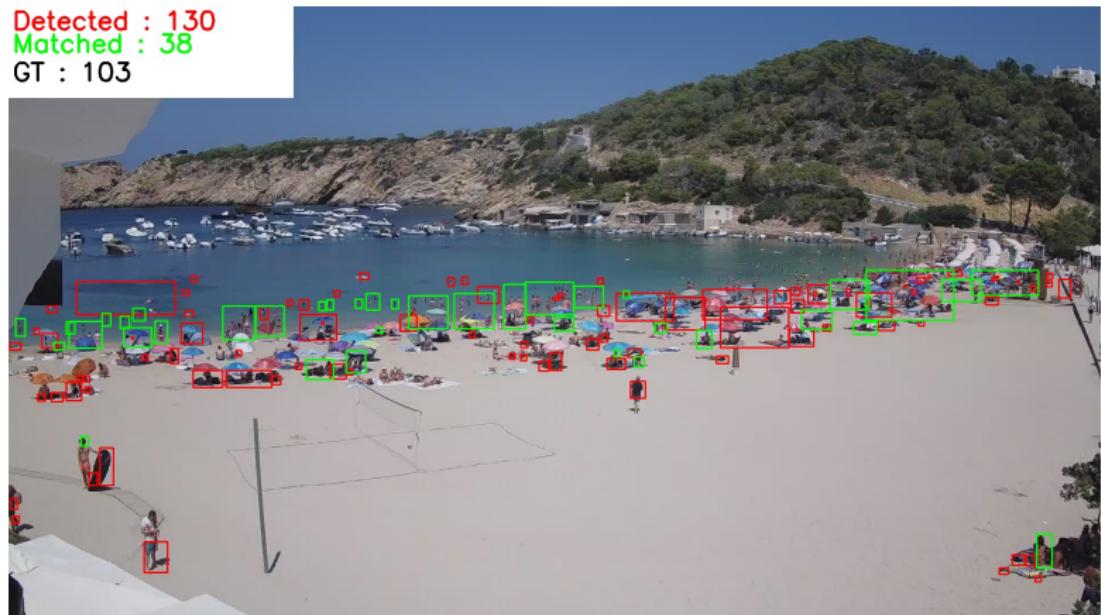
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**Detected : 130**  
**Matched : 38**  
**GT : 103**



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**Detected : 99**  
**Matched : 33**  
**GT : 72**



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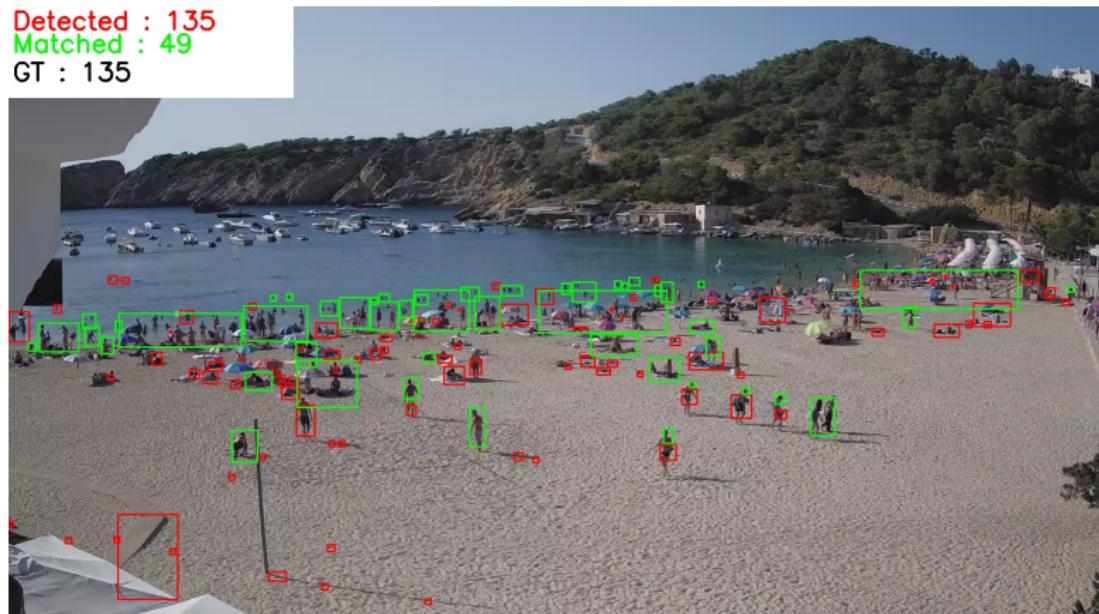
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**Detected : 135**  
**Matched : 49**  
**GT : 135**



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**Detected : 40**  
**Matched : 8**  
**GT : 17**



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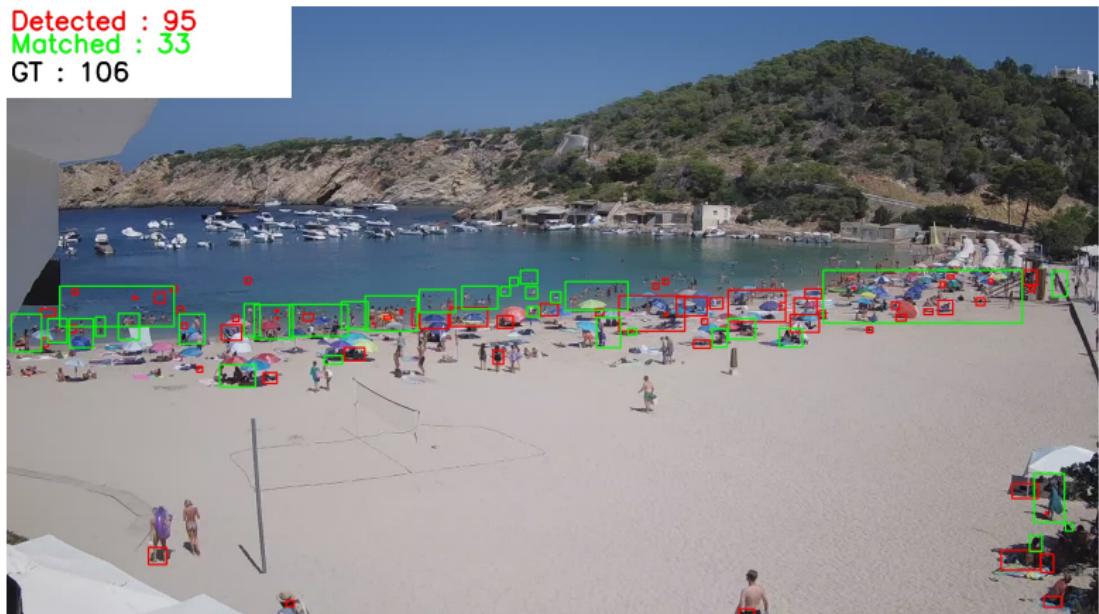
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**Detected : 95**  
**Matched : 33**  
**GT : 106**



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**Matched : 40**  
**GT : 101**



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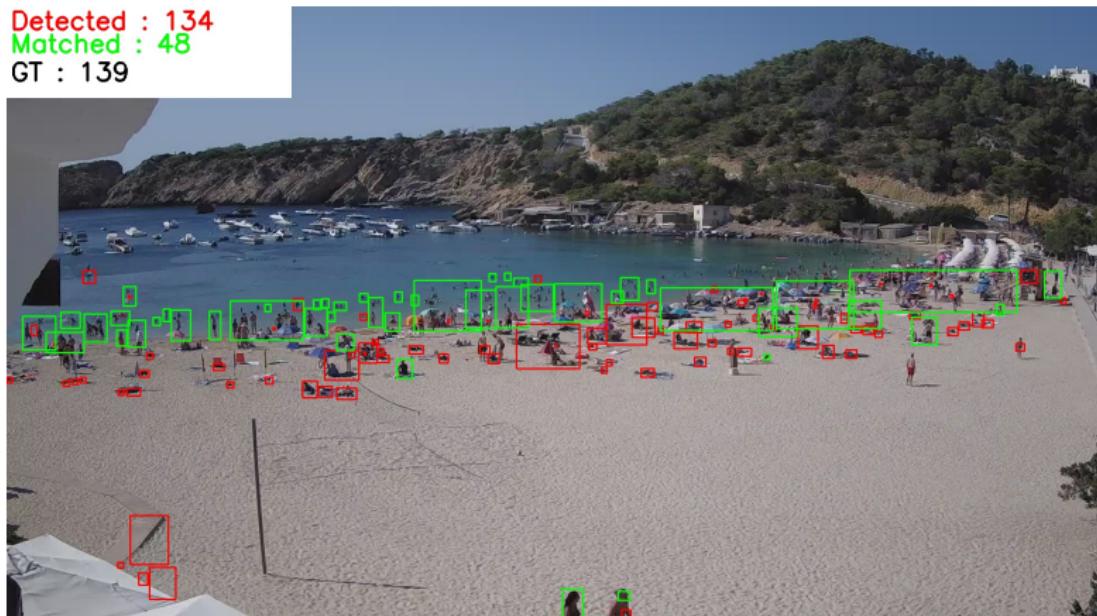
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**Detected : 134**  
**Matched : 48**  
**GT : 139**



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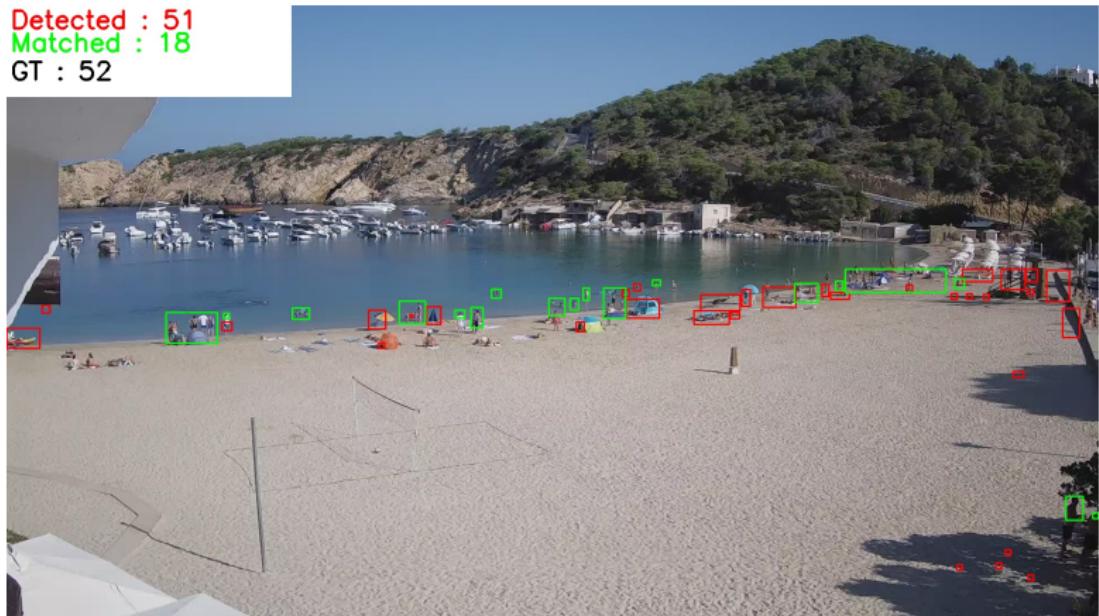
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**Detected : 51**  
**Matched : 18**  
**GT : 52**



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- Not seeking perfect detection.
- Brusque changes confuse our algorithm (i.e. cast shadows).
- Working in color could be not ideal.
- The results are really fragile.

# Thank you!

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Any Questions?