

1. a) $W = \alpha A_1 + \beta A_2 \Leftrightarrow$

$$\Leftrightarrow (5, 0, 0) = \alpha(4, 0, 0) + \beta(0, 4, -4)$$

$$\Leftrightarrow (5, 0, 0) = (4\alpha, 0, 0) + (0\beta, 4\beta, -4\beta)$$

$$\Leftrightarrow \begin{cases} 4\alpha + 0\beta = 5 \\ 0\alpha + 4\beta = 0 \\ 0\alpha - 4\beta = 0 \end{cases} \Leftrightarrow \begin{cases} 4\alpha + 0 = 5 \\ 0 + 4\beta = 0 \\ 0 - 4\beta = 0 \end{cases} \Leftrightarrow \begin{cases} \alpha = \frac{5}{4} \\ \beta = 0 \\ \beta = 0 \end{cases}$$

$\alpha = 1 \Leftrightarrow 1 = 1$ P.V.

R.: W é combinação linear das colunas de A

$$W = (4, 0, 0) + \frac{1}{4}(0, 4, -4)$$

b) $4AA^T + BC$

$$4A = 4 \begin{bmatrix} 4 & 0 \\ 0 & 4 \\ 0 & -4 \end{bmatrix} = \begin{bmatrix} 16 & 0 \\ 0 & 16 \\ 0 & -16 \end{bmatrix} \quad \left| \quad A^T = \begin{bmatrix} 4 & 0 & 0 \\ 0 & 4 & -4 \end{bmatrix} \right.$$

$$BC = \begin{bmatrix} 0 & 1 & 2 \\ 0 & 1 & 2 \\ -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 0 & 2 & -3 \\ 1 & -2 & 3 \end{bmatrix}$$

$$= \begin{bmatrix} 0+0+2 & 0+2+(-4) & 0+(-3)+6 \\ 4+0+2 & 2+2+(-4) & 0+(-3)+6 \\ -2+0+1 & -1+0+(-2) & 0+0+3 \end{bmatrix}$$

$$= \begin{bmatrix} 2 & -2 & 3 \\ 6 & 0 & 3 \\ -1 & -3 & 3 \end{bmatrix}$$

$$4AA^T = \begin{bmatrix} 16 & 0 \\ 0 & 16 \\ 0 & -16 \end{bmatrix} \begin{bmatrix} 4 & 0 & 0 \\ 0 & 4 & -4 \end{bmatrix} = \begin{bmatrix} 16 \times 4 + 0 \times 0 & 0 + 0 \times 4 & 0 \times 0 - 16 \times 4 \\ 0 + 16 \times 0 & 0 + 16 \times 4 & 0 + 16 \times (-4) \\ 0 \times 4 + (-16) \times 0 & 0 + (-16) \times 4 & 0 + (-16) \times (-4) \end{bmatrix}$$

$$= \begin{bmatrix} 64 & 0 & -64 \\ 0 & 64 & -64 \\ 0 & -64 & 64 \end{bmatrix}$$

$$4AA^T + BC = \begin{bmatrix} 80 & 30 & 0 \\ 30 & 64 & -64 \\ 64 & 64 & 80 \end{bmatrix} + \begin{bmatrix} 0 & -2 & 3 \\ 6 & 0 & 3 \\ -1 & -3 & 3 \end{bmatrix}$$

$$= \begin{bmatrix} 80 & 30 & 3 \\ 36 & 64 & -61 \\ 63 & 61 & 83 \end{bmatrix}$$

$$c) D = [A]z = \begin{bmatrix} 4 & 2 & 2 \\ 0 & 4 & 2 \\ 2 & -4 & 2 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \\ z_3 \end{bmatrix}$$

$$D^T = \begin{bmatrix} 4 & 0 & 2 \\ 2 & 4 & -4 \\ z_1 & z_2 & z_3 \end{bmatrix}$$

$$D^T D = \begin{bmatrix} 4 & 0 & 2 \\ 2 & 4 & -4 \\ z_1 & z_2 & z_3 \end{bmatrix} \begin{bmatrix} 4 & 2 & 2 \\ 0 & 4 & 2 \\ 2 & -4 & 2 \end{bmatrix}$$

$$= \begin{bmatrix} 20 & 0 & 4z_1 + 2z_3 \\ 0 & 36 & 2z_1 + 4z_2 + (-4z_3) \\ 4z_1 + 2z_3 & 2z_1 + 4z_2 - 4z_3 & (z_1^2 + z_2^2 + z_3^2) \end{bmatrix}$$

• para $D^T D$ ser matriz diagonal:

$$\begin{cases} 4z_1 + 2z_3 = 0 \\ 2z_1 + 4z_2 - 4z_3 = 0 \end{cases} \Leftrightarrow \begin{cases} z_1 = -\frac{z_3}{2} \\ -z_3 + 4z_2 - 4z_3 = 0 \end{cases}$$

$$\Leftrightarrow \begin{cases} - \\ -5z_3 = -4z_2 \end{cases} \Leftrightarrow \begin{cases} z_1 = -\frac{1}{2} z_3 \\ z_2 = \frac{5}{4} z_3 \end{cases}$$

$$z \left(-\frac{1}{2} z_3 ; \frac{5}{4} z_3 ; z_3 \right) \text{ seja } z=1 \Rightarrow z = \left(-\frac{1}{2} ; \frac{5}{4} ; 1 \right)$$

$$d) D = \begin{bmatrix} 4 & 2 & -1/2 \\ 0 & 4 & 5/4 \\ 2 & -4 & 1 \end{bmatrix}$$

\Rightarrow para ser conj. ortormal

$\| \|$ de todos os vetores = 1

$$\text{seja } x(4, 0, 2)$$

$$y(2, 4, -4)$$

$$z = \left(-\frac{1}{2} ; \frac{5}{4} ; 1 \right)$$

$$\|x\| = \sqrt{4^2 + 0^2 + 2^2} = \sqrt{16+4} = \sqrt{20} = 2\sqrt{5}$$

$$\|y\| = \sqrt{0^2 + 4^2 + (-4)^2} = \sqrt{4+32} = \sqrt{36} = 6$$

$$\begin{aligned}\|z\| &= \sqrt{\left(-\frac{1}{2}\right)^2 + \left(\frac{5}{4}\right)^2 + 1^2} = \sqrt{\frac{1}{4} + \frac{25}{16} + 1} \\ &= \sqrt{\frac{4+25+16}{16}} \\ &= \sqrt{\frac{45}{16}} = \frac{\sqrt{45}}{4}\end{aligned}$$

$$\begin{array}{r|l} 20 & 2 \\ 10 & 2 \\ 5 & 2 \\ 1 & 2 \\ \hline & 2\sqrt{5} \end{array}$$

$\left\{ \frac{x}{\|x\|}, \frac{y}{\|y\|}, \frac{z}{\|z\|} \right\}$ é um conj. ORTONORMAL de vetores

$$\frac{x}{\|x\|} = \left(\frac{4}{2\sqrt{5}}; \frac{0}{2\sqrt{5}}; \frac{2}{2\sqrt{5}} \right) = \left(\frac{2}{\sqrt{5}}; 0; \frac{1}{\sqrt{5}} \right)$$

$$\frac{y}{\|y\|} = \left(\frac{0}{6}; \frac{4}{6}; \frac{-4}{6} \right) = \left(\frac{1}{3}; \frac{2}{3}; -\frac{2}{3} \right)$$

$$\begin{aligned}\frac{z}{\|z\|} &= \left(\frac{-1/2}{\frac{\sqrt{45}}{4}}; \frac{5/4}{\frac{\sqrt{45}}{4}}; \frac{1}{\frac{\sqrt{45}}{4}} \right) = \left(\frac{-4}{2\sqrt{45}}; \frac{5}{\sqrt{45}}; \frac{4}{\sqrt{45}} \right) \\ &= \left(-\frac{2}{\sqrt{45}}; \frac{5}{\sqrt{45}}; \frac{4}{\sqrt{45}} \right)\end{aligned}$$

$\rightarrow \left\{ \left(\frac{2}{\sqrt{5}}, 0, \frac{1}{\sqrt{5}} \right); \left(\frac{1}{3}, \frac{2}{3}, -\frac{2}{3} \right); \left(-\frac{2}{\sqrt{45}}, \frac{5}{\sqrt{45}}, \frac{4}{\sqrt{45}} \right) \right\}$ é um conjunto ortonormal de vetores

$$e) \quad BC = \begin{bmatrix} 2 & -2 & 3 \\ 0 & 0 & 3 \\ -1 & -3 & 3 \end{bmatrix} \xrightarrow{\substack{l_2 = l_2 - 3l_1 \\ l_3 = l_3 + \frac{1}{2}l_1}} \begin{bmatrix} 2 & -2 & 3 \\ 0 & 6 & -6 \\ 0 & -4 & \frac{9}{2} \end{bmatrix} \xrightarrow{l_3 = l_3 + \frac{4}{6}l_2}$$

$$\rightarrow \begin{bmatrix} 2 & -2 & 3 \\ 0 & 6 & -6 \\ 0 & 0 & 1 \end{bmatrix} \quad \text{car}(BC) = 3$$

car(BC) \rightarrow é o nº de pivots $\neq 0$

0, logo há 3, 3 eles:

$$2; 6; \frac{1}{2}$$

$$\frac{9}{2} + \frac{4}{6} \times (-6)$$

$$\frac{9}{2} + \left(-\frac{24}{6}\right)$$

$$= \frac{9}{2} - 4$$

$$C^T = \begin{bmatrix} 2 & 0 & 1 \\ 1 & 2 & -2 \\ 0 & -3 & 3 \end{bmatrix}$$

$$B^T = \begin{bmatrix} 0 & 2 & -1 \\ 1 & 1 & 0 \\ 2 & 2 & 1 \end{bmatrix}$$

$$N^0(C^T B^T) = \{0, 0, 0\}$$

$C^T B^T x = 0$ ← é sempre possível e determinado pois o vetor $(0, 0, 0)$ é sempre solução do sist. homogêneo

f) $B = I_3 \Leftrightarrow \begin{bmatrix} 0 & 1 & 2 \\ 2 & 1 & 2 \\ -1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

$$\begin{bmatrix} 0 & 1 & 2 & 1 & 0 & 0 \\ 2 & 1 & 2 & 0 & 1 & 0 \\ -1 & 0 & 1 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{L_2/L_1} \begin{bmatrix} 0 & 1 & 2 & 1 & 0 & 0 \\ 0 & 1 & 2 & 1 & 1 & 0 \\ -1 & 0 & 1 & 0 & 0 & 1 \end{bmatrix}$$

$$\xrightarrow{L_2=L_2} \begin{bmatrix} 0 & 1 & 2 & 1 & 0 & 0 \\ 0 & 1 & 2 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \end{bmatrix} \xrightarrow{L_3=L_3-\frac{1}{2}L_2} \begin{bmatrix} 0 & 1 & 2 & 1 & 0 & 0 \\ 0 & 1 & 2 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \end{bmatrix}$$

$$\frac{1/2}{1} = \frac{1}{2}$$

R.: como o último pivot resultante da eliminação de Gauss é igual a 0, B não admite inversa

$$2 - \frac{1}{2}2 = 2 - 1 = 1$$

a) $\begin{cases} x + 2y + 3z = 1 \\ -3x - 5y + (\alpha^2 - 4)z = 0 \\ 2x + 3y - 5\alpha z = \alpha \end{cases} \Leftrightarrow$

$$\Leftrightarrow \begin{bmatrix} 1 & 2 & 3 \\ -3 & -5 & (\alpha^2 - 4) \\ 2 & 3 & -5\alpha \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ \alpha \end{bmatrix}$$

b) $\begin{bmatrix} 1 & 2 & 3 & 1 \\ -3 & -5 & (\alpha^2 - 4) & 0 \\ 2 & 3 & -5\alpha & \alpha \end{bmatrix} \xrightarrow{L_2=L_2+3L_1, L_3=L_3-2L_1} \begin{bmatrix} 1 & 2 & 3 & 1 \\ 0 & 1 & \alpha^2 & 3 \\ 0 & -1 & -5\alpha-6 & \alpha-2 \end{bmatrix}$

$$\xrightarrow{L_3=L_3-L_2} \begin{bmatrix} 1 & 2 & 3 & 1 \\ 0 & 1 & \alpha^2 & 3 \\ 0 & 0 & -\alpha^2-5\alpha-6 & \alpha-5 \end{bmatrix}$$

$$\underline{CA} \quad +\alpha^2 - 5\alpha - 6 = 0 \Leftrightarrow$$

$$\Leftrightarrow \alpha = \frac{+5 \pm \sqrt{25 - 4(1)(-6)}}{-2}$$

$$\Leftrightarrow \alpha = \frac{5 \pm 7}{-2} \Leftrightarrow \alpha = +6 \vee \alpha = -1$$

→ se $\alpha = 6$ \vee $\alpha = -1$:

$\text{cor}(A) = 2 < n = 4 \rightarrow$ sist. possível indeterminado

→ se $\alpha \in \mathbb{R} \setminus \{-1, 6\}$.

$\text{cor}(A) = 3 < n = 4 \rightarrow$ sist. possível indeterminado

c) $\alpha = -1$

$$\begin{cases} x + 2y + 3z = 1 \\ y + z = 3 \\ 0 = 0 \end{cases} \Leftrightarrow \begin{cases} x + 2(3-z) + 3z = 1 \\ y = 3-z \\ 0 = 0 \end{cases}$$

$$\Leftrightarrow \begin{cases} x + 6 - 2z + 3z = 1 \\ y = 3-z \\ 0 = 0 \end{cases} \Leftrightarrow \begin{cases} x = 1 - 6 + 2z - 3z \\ y = 3-z \\ 0 = 0 \end{cases}$$

$$\Leftrightarrow \begin{cases} x = -5 - z \\ y = 3-z \\ 0 = 0 \end{cases} \quad \text{CS} = \{(-5-z, 3-z, z), z \in \mathbb{R}\} \\ = \{z(-6, 2, 1), z \in \mathbb{R}\}$$

3. $M \rightarrow$ 4 linhas > 4 incógnitas 4 equações
5 colunas

$$Mx = b$$

$$\rightarrow \text{cor}(M) = 3 :$$

$$\rightarrow \text{cor}(M) = 4 :$$