Solution to the written exam

TECNICAL UNIVERSITY OF DENMARK

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Course name: Introduction to Numerical Algorithms

Course nr.: 02601

Aids and materials: All aids and materials permitted.

Question 1: Approximation of a function (20%)

The Matlab code:

```
Nvalue=9;
I=[1,2];
x=linspace(I(1),I(2),400);
f=@(x) log(x);
nodes=linspace(I(1),I(2),Nvalue+1);
ndata=f(nodes);
ydata=InterpolerLagrangeForm(nodes,ndata,x);
err =f(x)-ydata;
max_err=max(abs(err))
Theoreticalmaxerr=@(n)1/(4*(n+1))*factorial(n)*(1/n)^(n+1);
tbound=Theoreticalmaxerr(Nvalue)
```

- **1.1)** The solution is 3.63×10^{-8} .
- 1.2) Based on the second interpolation error theorem, we have

$$|f(x) - p_9(x)| \le \frac{1}{4(n+1)} M h^{n+1} = \frac{1}{4 \times 10} \cdot 9! \cdot \left(\frac{2-1}{9}\right)^{10} \approx 2.60 \times 10^{-6}$$

with M as the upper bound of $|f^{n+1}(x)|$.

- 1.3) Same as in 1.1) except setting Nvalue=25 in the code. The solution is 1.83×10^{-11} .
- 1.4) Based on the second interpolation error theorem, we have

$$|f(x) - p_{25}(x)| \le \frac{1}{4(n+1)} M h^{n+1} \approx 6.72 \times 10^{-14},$$

which is smaller than the one we got in 1.4). The reason is loss of significant in subtraction.

Question 2. Data fitting (20%)

The Matlab code:

norm(yk-A*c)

$$ub = cond(At*A)*0.01$$

2.1) The system matrix A^TA and the right-hand side A^Ty of the normal equation are

$$\begin{bmatrix} 5 & 0 & 5 \\ 0 & 10 & 0 \\ 5 & 0 & 19 \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} 200 \\ 255 \\ 305 \end{bmatrix}.$$

2.2) The solution is obtained by $c = (At'*A) \setminus (At'*yk)$:

$$a = 32.5, \quad b = 25.5, \quad c = 7.50$$
.

- 2.3) The absolute errors is obtained by e = norm(A*c-yk): 12.65.
- **2.4)** According to the sensitivity analysis, the upper bound of the relative error in the solution is

$$\kappa(\boldsymbol{A}^T\boldsymbol{A})\frac{\|\boldsymbol{A}^T\tilde{\boldsymbol{y}}-\boldsymbol{A}^T\boldsymbol{y}\|_2}{\|\boldsymbol{A}^T\boldsymbol{y}\|_2}=0.061.$$

Question 3: Newton's method for a system of nonlinear equations (15%)

3.1)

function [F,dF] = funFdF(X)

$$F = [X(1)^2+2*X(2)-2;...$$

$$X(1)+4*X(2)^2-4];$$

$$dF = [2*X(1) 2; ...$$

1 8*X(2)];

3.2) Newton iteration is

$$\mathbf{X}^{(k+1)} = \mathbf{X}^{(k)} - (F'(\mathbf{X}^{(k)}))^{-1}F(\mathbf{X}^{(k)}).$$

3.3) The final solution is $[-5.93 \times 10^{-17}, 1]^T$. The Matlab code:

$$X0=[1;2];$$

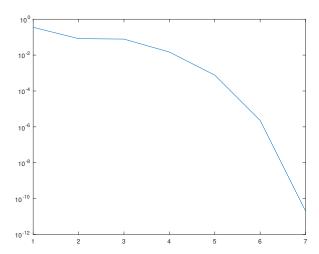
Xiterations = Newtonsys(@funFdF,X0,8);

Xiterations(:,end)

Xexa=Xiterations(:,end);

err=sqrt((Xiterations(1,1:end-1)-Xexa(1)).^2+(Xiterations(2,1:end-1)-Xexa(2)).^2)
figure, semilogy(err)

3.3)



Question 4: Integration (10%)

4.1) Set $f(x) = \frac{1}{x}$, then we have $f^{(4)}(x) = 24x^{-5}$ and $|f^{(4)}| \le 24$ in the interval [1, 2]. According to the error term for the composite Simpson's rule, we need

$$\left| \frac{1}{180} \cdot h^4 \cdot 24 \right| \le 10^{-4},$$

that is h < 0.16549. Then, use h = 1/n and we obtain n > 6.04.

4.2) Since n need be an even integer, we set n = 8. Run MySimpson(@(x)1/x, 1, 2, 8) and we will get 0.69315.

Question 5: LU factorization with pivoting (10%)

The Matlab code:

5.1) The matrix P is

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

It shows that we need interchange row 2 and row 4.

- **5.2)** The reasons to use pivoting are:
 - Mathematically: avoid dividing by 0.
 - Numerically: avoid large multipliers in row eliminations, which can lead to loss of significance.

Question 6: A boundary-value problem (20%)

6.1) Set

$$Y = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} x \\ x' \end{bmatrix},$$

then we have

$$Y' = \begin{bmatrix} x' \\ x'' \end{bmatrix} = \begin{bmatrix} y_2 \\ y_2 + y_1 - (2t - 1)e^t \end{bmatrix},$$

The Matlab code

6.2) The value of x(2) in these two shootings are 29.71 and 59.93. The Matlab code:

```
tspan=[1 2];
Y1=[3*exp(1); 10];
Y2=[3*exp(1); 25];
```

[tODE1,YODE1] = ode45(@odefun_sol,tspan,Y1); [tODE2,YODE2] = ode45(@odefun_sol,tspan,Y2);

YODE1(end,1) YODE2(end,1)

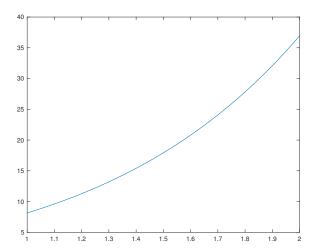
6.3) We need find the root of the equation $f(z) = \varphi(z) - 5e^2 = 0$. Use the secant method, we get

$$\hat{z} = z_2 - \left(\frac{z_2 - z_1}{f(z_2) - f(z_1)}\right) f(z_2) = 13.59$$

The Matlab code for the plot:

%%

```
tspan=[1 2];
Y3=[3*exp(1); Y3_2];
[t0DE3,Y0DE3]=ode45(@odefun_sol,tspan,Y3);
Y0DE3(end,1)
figure, plot(t0DE3,Y0DE3(:,1))
```



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