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Assignment 1: forward substitution

Function structure: The program is designed as a nested for-loop, which calculates the sum $\sum_{i=1}^{k-1} (b_i R_{ik})$ for each value of i and followingly updates the k 'th solutional element in b with $b_k = (b_k - \sum_{i=1}^{k-1} (b_i R_{ik})) / (\alpha + R_{diag_k})$, with k also indexing the k 'th diagonal element of the matrix. The sum is reset to zero on every iteration of k . Using row major storage order for storing the matrix, the k 'th diagonal element can be accessed in a for-loop with $(k = 0; k < n)$ using $R_{diag_k} = R[k + n \cdot k]$, as the first diagonal element is located in $R_{0,0}$. This method is only valid for square matrices. The program returns value $\{-1, 0\}$ whether it fails/succeeds.

The program checks the input for different errors: **1.** If pointers point to elements. **2.** If $\alpha \in \{NaN, \infty\}$. **3.** If input-pointer contains any values $b_k \in \{NaN, \infty\}$. **4.** If n exists, and has a valid value. **5.** If R contains invalid values $R_{ij} \in \{NaN, \infty\}$. **6.** Checking if there is a unique solution to the system of equations, by ensuring $\alpha + R_{ii} \neq 0$ for all $i = 1, \dots, n$. If this is untrue, the program returns -1 , as proceeding also would lead to undefined behavior in the program (division by 0). **7.** If R is an upper triangle matrix, which is a necessity for using backwards substitution. **8.** Detecting overflow and underflow by checking if $b_k \in \{NaN, \infty\}$ ever evaluates to true. Sadly, there is no way of checking whether the dimensions of R and b match, if R is a squared matrix, and if the matrix actually square with $n \times n$, in C. This would require a different input than a pointer.

Unimplemented numerical considerations: as b_k is updated using subtraction, loss of precision due to cancellation will occur. It would be easy to implement a check whether $b[k] - \sum_{i=1}^{k-1} (b_i R_{ik}) \in [-\sigma; \sigma]$ to a certain tolerance σ , and display a warning as cancellation will be worst when the numbers are close. Special cases where the fraction $f > DBL_MAX \rightarrow f = \infty$, this returns -1 – even though a solution actually exists. The issue also arises when $f < DBL_MIN \rightarrow f = 0$. Thus, some valid equations sadly will return -1. In general, the program will be prone to failure when the magnitudes of numbers are very large/small.

Assignment 2: solving the triangular Sylvester equation

Function structure: The program takes two pointers to array2d_t-structs. After input-checks described below, a double-nested loop is initiated with the structure $k\{i\{j\}\}$. The j -loop is used for calculating $\sum_{j=1}^{k-1} c_j R_{jk}$. The ij -loop is used for looping columnwise through C in order to update each element of row k with the expression $c_k = c_k - \sum_{j=1}^{k-1} c_j R_{jk}$, as c_k actually is $\{c_{k,1}, \dots, c_{k,n}\}$ in matrix C . In the beginning of the i -loop, the sum is reset, which is necessary as it is a function of k . The k -loop contains the second step of solving the system, which is equivalent to a forward-substitution (earlier described) using $\alpha_k = R_{kk}$. The substitution is only made for c_k , and thus only runs one row at a time by pushing the start-element of the pointer C by $+n \cdot k$ and using the next n elements. Function outputs $\{-2, -1, 0\}$ are mapped to $\{\text{invalid input, num. error, success}\}$.

The program has input-validation: **1.** Do pointers to the structs exist. **2.** does n have a valid value. **3.** Are the matrices square and both of size $n \times n$. **4.** Is R an upper-triangle matrix. **5.** are both structs stored using RowMajor. **6.** Are any $c_{ij} \in \{NaN, \infty\}$, indicating earlier numerical errors/rounding. Likewise for r_{ij} . If any of these checks are true, the program returns -2 . **7.** All checks in assignment 1 are carried out. This ensures, that numerical errors in the updated C return -1 . In case that forwardsub fails, the Sylvester-solver outputs -1.

Unimplemented numerical considerations: The program presents a numerical error if $\text{sumk} > DBL_MAX \rightarrow \text{sumk} = \infty$. In order to avoid this, the sum should be implemented more elegantly than using $+=$ (e.g. adding negative and positive terms pairwise, starting with smallest numbers), as the program will fail even though a solution may exist. Also, precision is lost when sumk is very large/small, due to floating point precision. Using the $+=$ operation should be avoided due to error accumulation (instead e.g. Kahan summation could be used).

Testing: Forward substitution is tested using mock-input. We know which values are expected, e.g.:

$$R = \begin{bmatrix} 1 & 3 \\ 0 & 4 \end{bmatrix}, b = \begin{bmatrix} 3 \\ 5 \end{bmatrix}, n = 2, \alpha = 3 \rightarrow \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 3 \cdot (3 + 1)^{-1} \\ (5 - (x_1 \cdot 3)) \cdot (3 + 4)^{-1} \end{pmatrix} = \begin{pmatrix} 0.75 \\ 0.39 \end{pmatrix}$$

Which is compliant with the program-output when printing results. Testing the code with incompatible matrix-vector-dimensions returns 0 and results in undefined behavior which yields a wrong result. This is considered the *user's responsibility*. Both programs are tested with invalid entries (non-triangular, wrong dimensions, non-square, NaN and ∞ values, unspecific solutions) and designed matrixes expected prone to numerical issues. Cross-testing has been carried out with Maple, yielding consistent results. CodeJudge has been the final test for both programs.