SVM (Support Vector Machine):

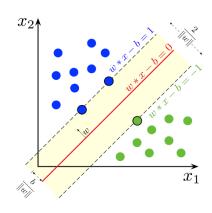
- used for classification

Goal:

- the goal is to maximize the margin between the two classes
- we basically minimize the objective function $\frac{1}{2}||w||^2$ using QP (Quadratic Programing) \implies we are maximizing the margin from the data point to the hyperplane given by $\frac{1}{||w||'}$ while applying the constraint that each classified point must be ≥ 1

Input data:

| i | X _{1i} | X _{2i} | label y _i |
|---|-----------------|-----------------|----------------------|
| 0 | 1 | 1 | а |
| 1 | 2 | 0.5 | а |
| 2 | 40 | 40 | b |
| 3 | 50 | 35 | b |



Constraint:

- $\forall i$ for all i
- w is the weight

$$y_i(\mathbf{w}^T. \, \mathbf{x} + \mathbf{b}) \ge \mathbf{1} \quad \forall i \tag{1}$$

- verify the constraint is true

$$y_i = 1$$
:

$$1(w^T.x + b) \ge 1 \rightarrow (w^T.x + b) \ge 1$$
 (2) $y_i = -1$:

$$-1(w^T.x + b) \ge 1 \rightarrow (w^T.x + b) \le -1$$

Primal problem - objective function:

$$min\frac{1}{2}\|w\|^2\tag{3}$$

QP (Quadratic Programming)-equation:

- it is used to solve optimization problems where the objective function is quadratic, and the constraints (if any) are typically linear

$$min\frac{1}{2}x^T.P.x + q^T.x \tag{5}$$

- in the code we can skip (set to zero) the linear term q^T . x because we try to find the maximum margin between classes without any offset or linear bias:

QP (Quadratic Programming)-code:

- relabel the values and ad bias to the matrix

- Define matrices P and q

```
# Define identity matrix (P = I for quadratic term)

P = np.eye(X_with_bias.shape[1])

v 0.0s 哪 Open 'P' in Data Wrangler

array([[1., 0., 0.],
        [0., 1., 0.],
        [0., 0., 1.]])

# Define quadratic term-setting it into zero we neglect the impact (we are interested in maximazing the margin)

q = np.zeros(X_with_bias.shape[1])

q

v 0.0s 哪 Open 'q' in Data Wrangler

array([0., 0., 0.])
```

- define objective function and constraint with the initial guess and run the optimization

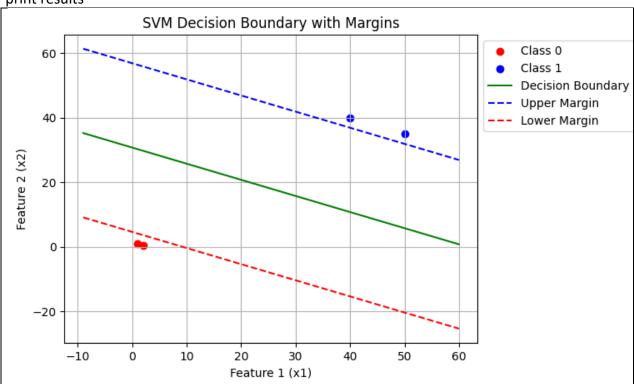
```
# Objective function: 1/2 * w^T * P * w + q^T * w
   def objective(w):
      return 0.5 * np.dot(w.T, np.dot(P, w)) + np.dot(q.T, w)
  def constraints(w):
     return y * (np.dot(X_with_bias, w)) - 1
 ✓ 0.0s
   # Initial guess for the variables: weights + bias
   w0 = np.zeros(X_with_bias.shape[1])
  # Solve the optimization problem using SLSQP
   result = minimize(objective, w0, constraints={'type': 'ineq', 'fun': constraints}, method='SLSQP')
 ✓ 0.0s
   if result.success:
       print("Optimal weights (w1, w2):", result.x[:-1])
       print("Optimal bias (b):", result.x[-1])
   else:
       print("Optimization failed:", result.message)
 ✓ 0.0s
Optimal weights (w1, w2): [0.01709402 0.03418803]
Optimal bias (b): -1.0512820512820509
```

- predict the values and calculate the accuracy

$$y_i = sign(w^T.x + b)$$

Predict function to evaluate the decision function on the training data def predict(X, w, b): return np.sign(np.dot(X, w) + b) optimal_weights = result.x[:-1] optimal_bias = result.x[-1] # Make predictions on the training data predictions = predict(X, optimal_weights, optimal_bias) # Print predictions and true labels print("Predictions:", predictions) print("True Labels:", y) accuracy = np.mean(predictions == y) print("Accuracy:", accuracy) ✓ 0.0s Predictions: [-1. -1. 1. 1.] True Labels: [-1 -1 1 1] Accuracy: 1.0

-print results



- test model for new data

Dual Problem

Lagrangian for the primal problem:

 $L(w, b, \lambda) = objective function - constraint$

$$L(w, b, \lambda) = \min \frac{1}{2} ||w||^2 - \sum_{i=1}^{n} \lambda_i [y_i(w^T.x + b) - 1]$$

$$\frac{\partial L}{\partial w} = 0 \to w$$

$$\frac{\partial L}{\partial b} = 0 \to b$$
(4)

Dual objective function:

$$max_{(\lambda)} \left(\sum_{i=1}^{n} \lambda_i - \frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{n} \lambda_i \lambda_j y_i y_j (x_i^T x_j) \right)$$

$$\tag{4}$$