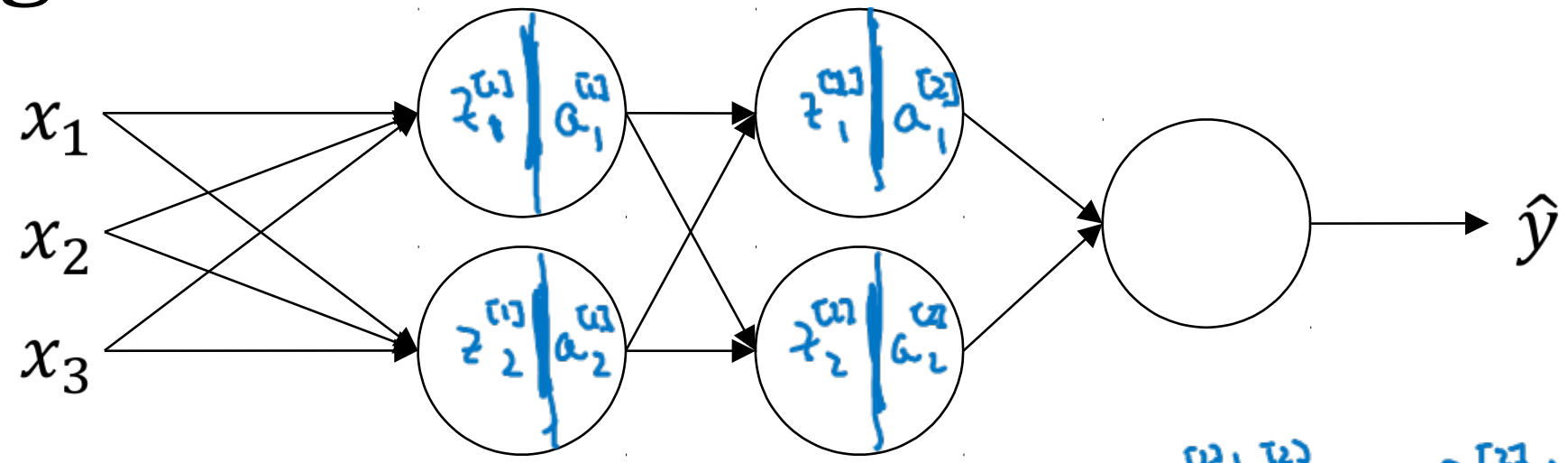
deeplearning.ai

Batch Normalization

Fitting Batch Norm into a neural network

Adding Batch Norm to a network



$X \xrightarrow{W^{[1]}, b^{[1]}} z^{[1]} \xrightarrow[\text{Batch Norm (BN)}]{\beta^{[1]}, \gamma^{[1]}} \tilde{z}^{[1]} \rightarrow a^{[1]} = g^{[1]}(\tilde{z}^{[1]}) \xrightarrow{W^{[2]}, b^{[2]}} z^{[2]} \xrightarrow[\text{BN}]{\beta^{[2]}, \gamma^{[2]}} \tilde{z}^{[2]} \rightarrow a^{[2]} \rightarrow \dots$

Parameters: $W^{[1]}, b^{[1]}, W^{[2]}, b^{[2]}, \dots, W^{[L]}, b^{[L]}, \beta^{[1]}, \gamma^{[1]}, \beta^{[2]}, \gamma^{[2]}, \dots, \beta^{[L]}, \gamma^{[L]}$

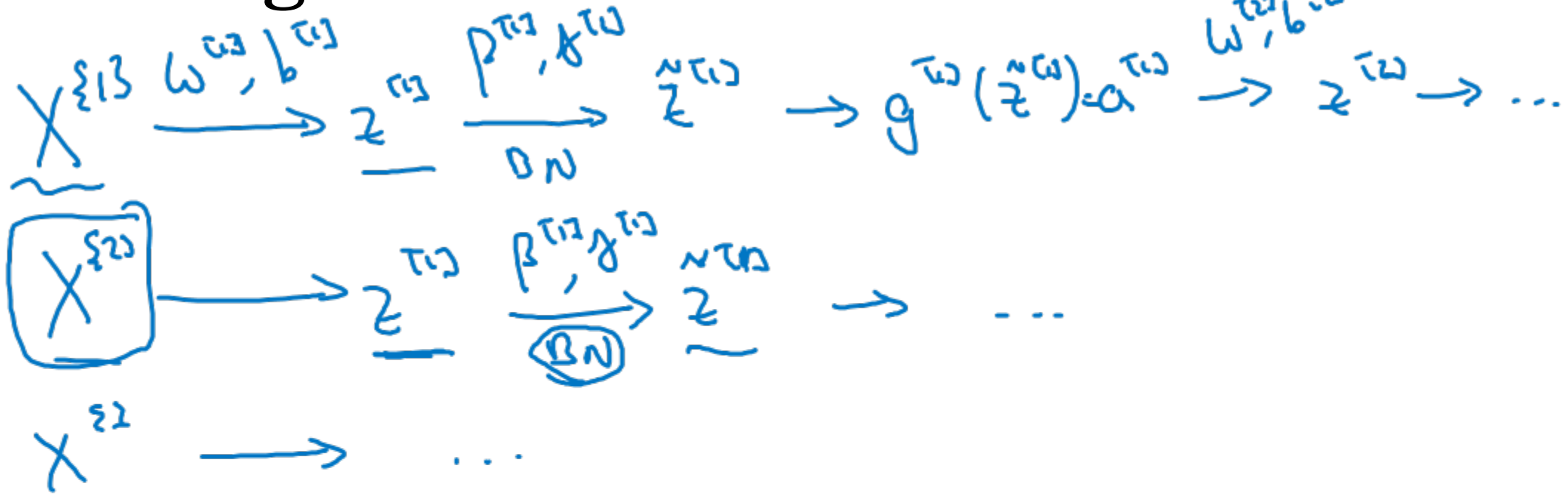
$\rightarrow \beta$

$d\beta^{[2]}$

$\beta^{[2]} = \beta^{[2]} - \alpha\, d\beta^{[2]}$

tf.nn.batch_normalization ⇐

Working with mini-batches



Parameters: $w^{[l]}$, ~~$b^{[l]}$~~, $\beta^{[l]}$, $\gamma^{[l]}$.

$(n^{[l]}, 1)$

$z^{[l]}$

$(n^{[l]}, 1)$

$z^{[l]} = w^{[l]} a^{[l-1]} + b^{[l]}$

$z^{[l]} = w^{[l]} a^{[l-1]}$

$z^{[l]}_{norm}$

$z^{[l]} = \gamma^{[l]} z^{[l]}_{norm} + \beta^{[l]}$

Implementing gradient descent

for $t = 1 \ldots$ numMiniBatches

Compute forward prop on $X^{\{t\}}$.

In each hidden layer, use BN to replace $z^{[l]}$ with $\tilde{z}^{[l]}$.

Use backprop to compute $dW^{[l]}$, ~~$db^{[l]}$~~, $d\beta^{[l]}$, $d\gamma^{[l]}$

Update parameters $W^{[l]} := W^{[l]} - \alpha\, dW^{[l]}$

$\beta^{[l]} := \beta^{[l]} - \alpha\, d\beta^{[l]}$

$\gamma^{[l]} := \ldots$ ←

Works w/ momentum, RMSprop, Adam.