

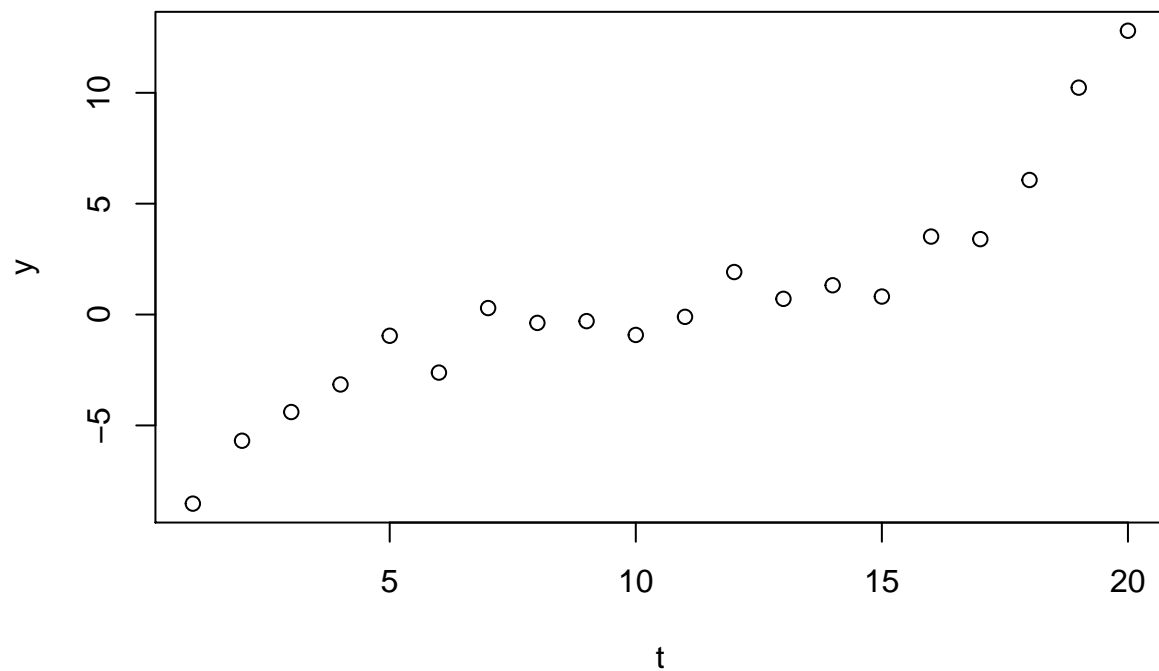
Oblig2-TMA4300

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Problem B

```
# Read and plot data  
gaussiandata = read.delim("gaussiandata.txt")  
y = gaussiandata[,1]  
t = seq(from=1,to=length(y),by=1)  
plot(t,y)
```



1.

We consider the problem of smoothing the time series that is plotted above. We assume that given the vector of linear predictors $\eta = (\eta_1, \dots, \eta_T)$, where in this case $T = 20$, the observations y_t are independent

and distributed according to

$$y_t \mid \eta_t \sim \mathcal{N}(\eta_t, 1) \quad ,$$

for $t = 1, \dots, T$. The linear predictor for time t is $\eta_t = f_t$, where f_t is the smooth effect for time t . For the prior distribution of $\mathbf{f} = (f_1, \dots, f_T)$ we have a second order random walk model, that is,

$$\pi(\mathbf{f} \mid \theta) \propto \theta^{(T-2)/2} \exp \left\{ -\frac{\theta}{2} \sum_{t=3}^T (f_t - 2f_{t-1} + f_{t-2}^2) \right\} = \mathcal{N}(\mathbf{0}, \mathbf{Q}(\theta)^{-1}) \quad ,$$

where \mathbf{Q} is the precision matrix and θ is the precision parameter that controls the smoothness of \mathbf{f} . We assume that the $Gamma(1, 1)$ -distribution is the prior for θ .

The model described here can be written as the hierarchichal model:

$$\begin{aligned} \mathbf{y} \mid \mathbf{f} &\sim \prod_{t=1}^T P(y_t \mid \eta_t) \\ \mathbf{f} \mid \theta &\sim \pi(\mathbf{f} \mid \theta) = \mathcal{N}(\mathbf{0}, \mathbf{Q}(\theta)^{-1}) \\ \theta &\sim Gamma(1, 1) \end{aligned}$$

Here, the first line is the likelihood of the response $\mathbf{y} = (y_1, \dots, y_T)$, the second line gives the prior distribution of the latent field, and the third line gives the prior distribution of the hyperparameter θ . Since our model has this particular structure, it is a latent Gaussian model. INLA can be used to estimate the parameters because we have a latent gaussian model where each data point y_t depends only on the one element f_t in the latent field, the dimension of the hyperparameter is one and the precision matrix $\mathbf{Q}(\theta)$ of the latent field is sparse.

2.

Here, we implement a block Gibbs sampling algorithm for $f(\eta, \theta \mid \mathbf{y})$, where we propose a new value for θ from the full conditional $\pi(\theta \mid \eta, \mathbf{y})$ and a new value for η from the full conditional $\pi(\eta \mid \theta, \mathbf{y})$. Thus, we need to find these distributions. We start with the posterior

$$\pi(\eta, \theta \mid \mathbf{y}) \propto \pi(\theta) \pi(\eta \mid \theta) \prod_{t=1}^T \pi(y_t \mid \eta_t, \theta) \propto \frac{\theta^{(T-2)/2}}{(2\pi)^{T/2}} \exp \left\{ -\theta - \frac{\theta}{2} \sum_{t=3}^T (\eta_t - 2\eta_{t-1} + \eta_{t-2})^2 - \frac{1}{2} \sum_{t=1}^T (y_t - \eta_t)^2 \right\}.$$

Then we find the full conditional for θ to be

$$\begin{aligned} \pi(\theta \mid \mathbf{y}, \eta) &\propto \theta^{T/2-1} \exp \left\{ -\theta \left(1 + \frac{1}{2} \sum_{t=3}^T (\eta_t - 2\eta_{t-1} + \eta_{t-2})^2 \right) \right\} \\ &\propto Gamma \left(\frac{T}{2}, 1 + \frac{1}{2} \sum_{t=3}^T (\eta_t - 2\eta_{t-1} + \eta_{t-2})^2 \right) \end{aligned}$$

The full conditional for η is

$$\begin{aligned} \pi(\eta \mid \theta, \mathbf{y}) &\propto \exp \left\{ -\frac{\theta}{2} \sum_{t=3}^T (\eta_t - 2\eta_{t-1} + \eta_{t-2})^2 - \frac{1}{2} \sum_{t=1}^T (y_t - \eta_t)^2 \right\} \\ &= \exp \left\{ -\frac{1}{2} \left(\eta^T \mathbf{Q} \eta + (\mathbf{y} - \eta)^T (\mathbf{y} - \eta) \right) \right\} \\ &= \exp \left\{ -\frac{1}{2} \eta^T (\mathbf{Q} + \mathbf{I}) \eta + \mathbf{y}^T \eta \right\} \end{aligned}$$

Here, $\mathbf{Q}(\theta) = \theta \mathbf{L} \mathbf{L}^T$ is the precision matrix, where \mathbf{L} is the $T \times (T - 2)$ matrix

$$\mathbf{L} = \begin{bmatrix} 1 & -2 & 1 & 0 & 0 & 0 & \dots \\ 0 & 1 & -2 & 1 & 0 & 0 & \dots \\ \vdots & & \ddots & \ddots & \ddots & & \\ 0 & 0 & 0 & 0 & 1 & -2 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}.$$

By looking at the last line in the above expression for $\pi(\eta \mid \theta, \mathbf{y})$, we recognize that the canonical parametrization is $\mathcal{N}(\mathbf{y}, \mathbf{Q} + \mathbf{I})$, and find that $\pi(\eta \mid \theta, \mathbf{y}) \propto \mathcal{N}((\mathbf{Q} + \mathbf{I})^{-1} \mathbf{y}, (\mathbf{Q} + \mathbf{I})^{-1})$. In the algorithm we sample the new proposals for the parameters from these two distributions that we have found for the full conditionals. We always use the last updated parameters.

```
library(Matrix)
library(mvtnorm)
library(MASS)

# Function to make the precision matrix
make.Q = function(T, theta) {
  # Make the matrix L as described in the text
  L = diag(T)
  d1 = rep(-2, T-1)
  d2 = rep(1, T-2)
  L[row(L)-col(L)==1] = d1
  L[row(L)-col(L)==2] = d2
  L = L[, -c(T-1, T)]
  # Compute Q(theta)
  Q = theta * L %*% t(L)
  return(Q)
}

set.seed(0)
# Function for block Gibbs sampling
# n is the number of samples including the initial value
sample.Gibbs = function(n, theta.init, f.init, y) {
  T = length(f.init)
  # Make vector and matrix for storing the samples
  theta.vec = rep(0, n)
  f.matrix = matrix(1:T*n, nrow = T, ncol = n)
  # Initialize
  theta.vec[1] = theta.init
  f.matrix[, 1] = f.init
  # Iterations
  for(i in 2:n) {
    # Sample theta
    summ = 0
    for(t in 3:T) {
      summ = summ + (f.matrix[t, i-1] - 2*f.matrix[t-1, i-1] + f.matrix[t-2, i-1])^2
    }
    theta.vec[i] = rgamma(1, shape = T/2, rate = 1 + 0.5*summ)
    # Sample f
    Q = make.Q(T, theta.vec[i]) # Use the last updated theta
    f.mean = solve(Q+diag(T)) %*% y
    f.sigma = solve(Q+diag(T))
  }
}
```

```

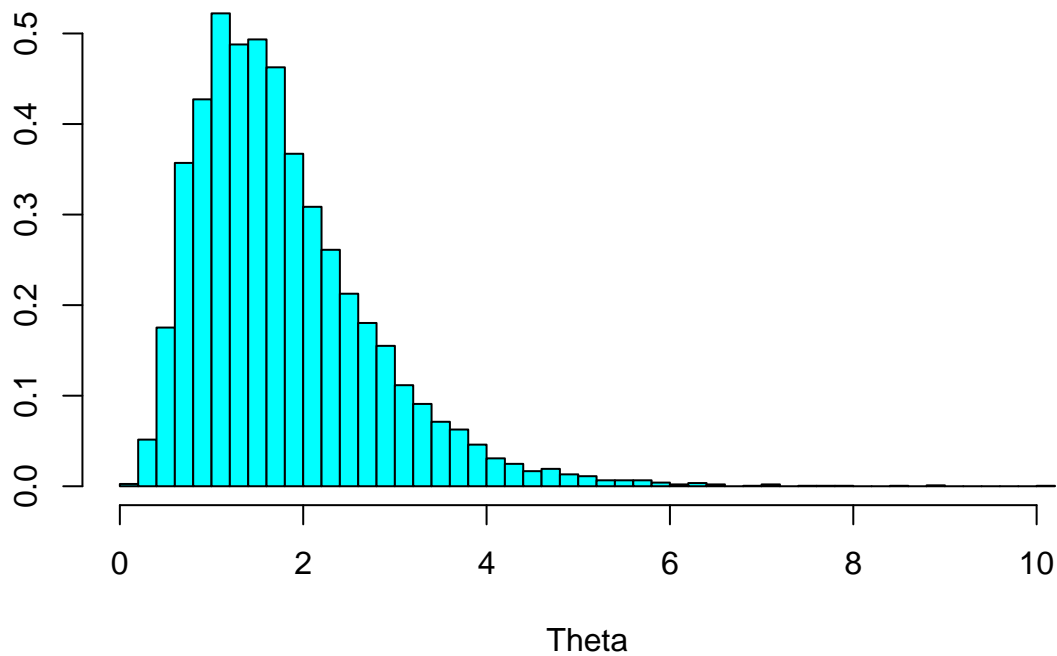
    f.matrix[, i] = rmvnorm(1, f.mean, f.sigma)
  }
  return(rbind(f.matrix, theta.vec))    # Return concatenated matrix with f and theta samples
}

# Set values
n = 10000
T = length(y)
theta.init = 1
f.init = rep(2,T)
# Sample
result = sample.Gibbs(n, theta.init, f.init, y)
result.theta = result[length(result[,1]), -c(1:100)]    # Extracting the theta samples, excluding the first 100
result.f = result[-length(result[,1]), -c(1:100)]        # Extracting the f samples, excluding the first 100

# Estimate for the posterior marginal for theta
truehist(result.theta, xlab = "Theta", main = "Histogram of theta samples")

```

Histogram of theta samples



```

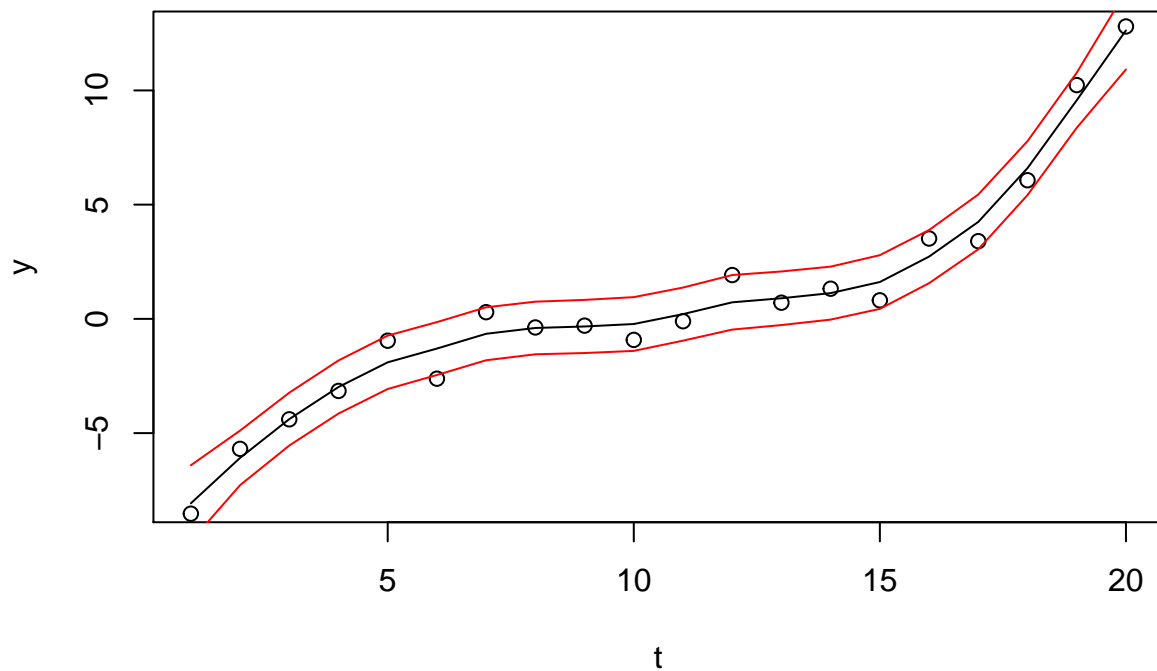
# Vectors for storing the mean, variance and confidence bounds
f.mean = rep(0,T)
f.var = rep(0,T)
conf.upper = rep(0,T)
conf.lower = rep(0,T)
# Calculate the mean and variance
for(t in 1:T) {

```

```

f.mean[t] = mean(result.f[t,])
f.var[t] = var(result.f[t,])
}
# Calculate 95% confidence bounds
for(t in 1:T) {
  z = qnorm(0.025)
  conf.upper[t] = f.mean[t] + z * sqrt(f.var[t])
  conf.lower[t] = f.mean[t] - z * sqrt(f.var[t])
}
# Plotting
t = seq(from = 1, to = T, by = 1)
plot(t, f.mean, type = "l", ylab = "y")
points(t, y)
lines(t, conf.lower, col = "red")
lines(t, conf.upper, col = "red")

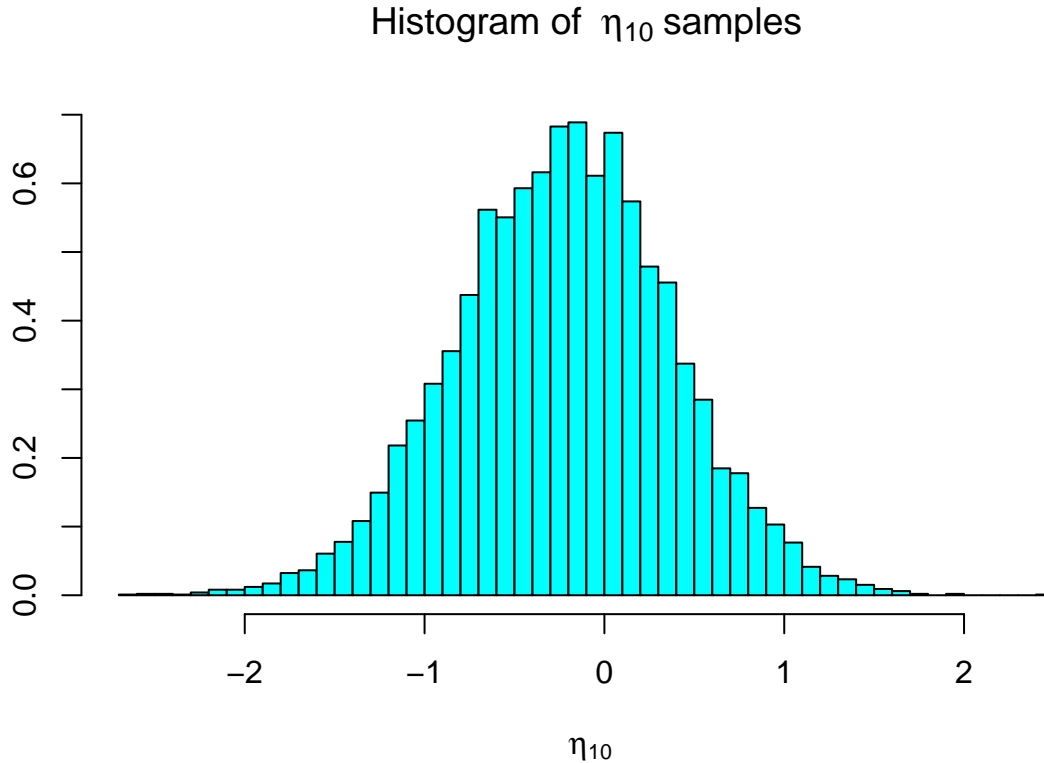
```



```

# Estimate of  $\pi(\eta_{10}|y)$ 
f_10 = result.f[10,]
truehist(f_10, xlab = bquote(~eta[10]), main = bquote("Histogram of " ~eta[10] ~"samples"))

```



The first histogram shows an estimate for $\pi(\theta \mid \mathbf{y})$. In the plot the data points are plotted as circles. The black line is plotted using the estimates of the smooth effects. The red lines are the 95% confidence bounds. Almost all the data points are within the bounds. The last histogram of the η_{10} samples provides an estimate of $\pi(\eta_{10} \mid \mathbf{y})$.

3.

We want to approximate $\pi(\theta \mid \mathbf{y})$ using the INLA scheme. Since we found that $\pi(\eta \mid \theta, \mathbf{y}) \propto \mathcal{N}((\mathbf{Q} + \mathbf{I})^{-1}\mathbf{y}, (\mathbf{Q} + \mathbf{I})^{-1})$, we can calculate

$$\begin{aligned} \pi(\theta \mid \mathbf{y}) &\propto \frac{\pi(\mathbf{y} \mid \eta, \theta) \pi(\eta \mid \theta) \pi(\theta)}{\pi(\eta \mid \theta, \mathbf{y})} \\ &\propto \frac{\exp(-\frac{1}{2}(\mathbf{y} - \eta)^T(\mathbf{y} - \eta)) \theta^{(T-2)/2} \exp(-\frac{1}{2}\eta^T \mathbf{Q} \eta) \exp(-\theta)}{|\mathbf{Q} + \mathbf{I}|^{1/2} \exp(-\frac{1}{2}(\eta - (\mathbf{Q} + \mathbf{I})^{-1}\mathbf{y})^T(\mathbf{Q} + \mathbf{I})(\eta - (\mathbf{Q} + \mathbf{I})^{-1}\mathbf{y}))} , \\ &= \theta^{(T-2)/2} |\mathbf{Q} + \mathbf{I}|^{-1/2} \exp\left(-\theta - \frac{1}{2}\mathbf{y}^T(\mathbf{I} - (\mathbf{Q} + \mathbf{I})^{-1})\mathbf{y}\right) \end{aligned}$$

where $|\cdot|$ denotes the determinant and we have used that $|\mathbf{A}^{-1}| = \frac{1}{|\mathbf{A}|}$. We use a grid θ_{grid} of values for θ and calculate the posterior marginal. The plot below shows the result, and it seems to be in concordance with the MCMC estimate displayed by the histogram.

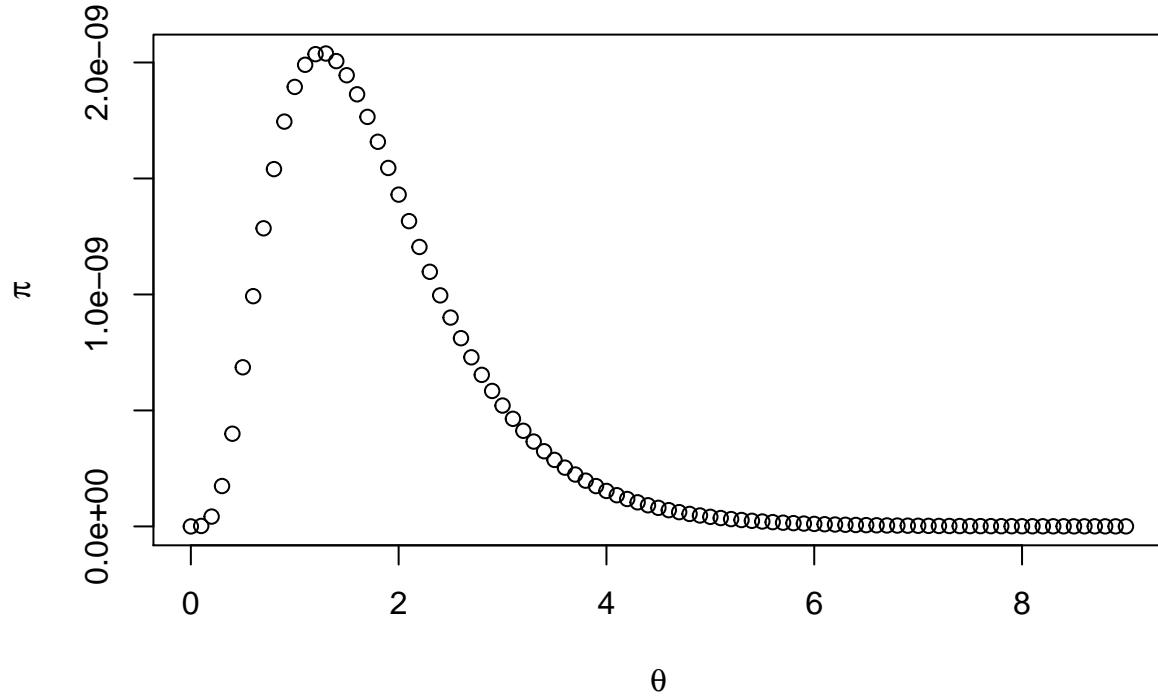
```
# Function to calculate pi(theta|y) for each theta in the grid
pi_theta_y = function(theta.grid, y) {
  pi = rep(0, length(theta.grid))
  T = length(y)
```

```

for(i in 1:length(pi)){
  theta = theta.grid[i]
  Q = make.Q(T, theta)
  deter = det(solve(Q+diag(T)))
  pi[i] = theta^(T/2-1) * exp(-theta) * deter^(0.5) * exp(-0.5 * t(y) %*% (diag(T)-solve(Q+diag(T))))
}
return(pi)
}

thetas = seq(from = 0, to = 9, by = 0.1)    # Theta grid
pi = pi_theta_y(thetas, y)                  # Corresponding values for pi(theta/y)
plot(thetas, pi, xlab = bquote(theta), ylab = bquote(pi)) # Plotting

```



4.

We also want to implement the INLA scheme for the approximation of $\pi(\eta_i | \mathbf{y})$. We have

$$\begin{aligned}
\pi(\eta_i | \mathbf{y}) &= \int \pi(\eta_i | \mathbf{y}, \theta) \pi(\theta | \mathbf{y}) d\theta \\
&\approx \sum_{\theta_k \in \theta_{\text{grid}}} \pi(\eta_i | \mathbf{y}, \theta_k) \pi(\theta_k | \mathbf{y}) \Delta \quad ,
\end{aligned}$$

where θ_{grid} is the grid of theta values from point 3, and Δ is the step size between the values in the grid. Since $\pi(\eta | \theta, \mathbf{y}) \propto \mathcal{N}((\mathbf{Q} + \mathbf{I})^{-1}\mathbf{y}, (\mathbf{Q} + \mathbf{I})^{-1})$, we assume that $\pi(\eta_i | \mathbf{y}, \theta) \sim \mathcal{N}([\mathbf{A}\mathbf{y}]_i, \mathbf{A}_{ii})$, where $\mathbf{A} = (\mathbf{Q} + \mathbf{I})^{-1}$.

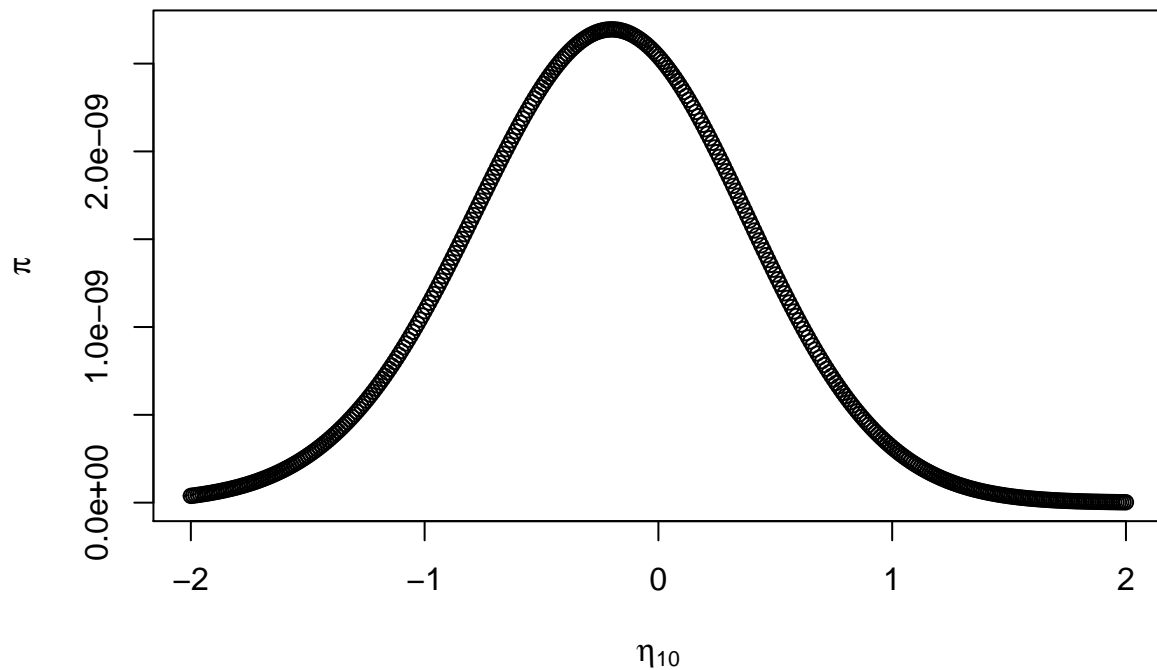
We calculate $\pi(\eta_i | \mathbf{y})$ for $i = 10$ and values for $\eta_{10} \in [-2, 2]$. The plot below shows the result. The graph looks approximately normal with a small and negative mean, which also the estimation obtained using the block Gibbs sampling (displayed by the last histogram in point 2) does.

```
# Function for calculating pi(eta_10/y, theta_k) for each eta_10 in the grid
pi_eta1_y_theta = function(eta1.grid, theta, y) {
  i = 10
  T = length(y)
  Q = make.Q(T, theta)
  A = solve(Q + diag(T))
  mean = (A %*% y)[i]
  var = A[i,i]
  pi = dnorm(eta1.grid, mean = mean, sd= sqrt(var))
  return(pi)      # Return the vector corresponding to each eta_10 in the grid
}

# Function for calculating pi(eta_10/y) for each eta_10 in the grid
pi_eta1_y = function(y, theta.grid, eta.grid) {
  sums = rep(0, length(eta.grid))      # Vector for storing the approximations
  step = theta.grid[2]-theta.grid[1]   # Step size
  theta_y = pi_theta_y(theta.grid, y)  # vector of pi(theta/y) for each theta in the grid
  for(k in (1:length(theta.grid))) {
    theta = theta.grid[k]              # theta_k
    sums = sums + pi_eta1_y_theta(eta.grid, theta, y) * theta_y[k] * step # Adding the terms for theta_k
  }
  return(sums)
}

thetas = seq(from = 0, to = 9, by = 0.1)      # Theta grid
eta.grid = seq(-2,2,0.01)                     # Eta grid
eta1_y = pi_eta1_y(y, thetas, eta.grid)        # Vector of pi(eta_10/y) for each eta_10 in the grid

plot(eta.grid, eta1_y, ylab = bquote(pi), xlab = bquote(eta[10]))      # Plotting the result
```

5.

We now use built in inla function for the same estimates as above. In the first figure the estimated smooth effects using inla are plotted as a red line. The MCMC estimates are also plotted in the same figure as a black line. The estimates are very similar, so the lines are overlapping. The second figure shows the estimate of $\pi(\theta | \mathbf{y})$, which looks very similar to the ones from point 2 and 3. The last figure shows the estimate for $\pi(\eta_{10} | \mathbf{y})$, and it looks like the estimates from point 2 and 4.

```
library(INLA)
```

```
## Loading required package: sp
```

```
## Warning: package 'sp' was built under R version 3.6.3
```

```
## Loading required package: parallel
```

```
## This is INLA_19.09.03 built 2019-09-03 09:03:02 UTC.
```

```
## See www.r-inla.org/contact-us for how to get help.
```

```
T = 20
```

```
t = seq(from = 1, to = T, by = 1)
```

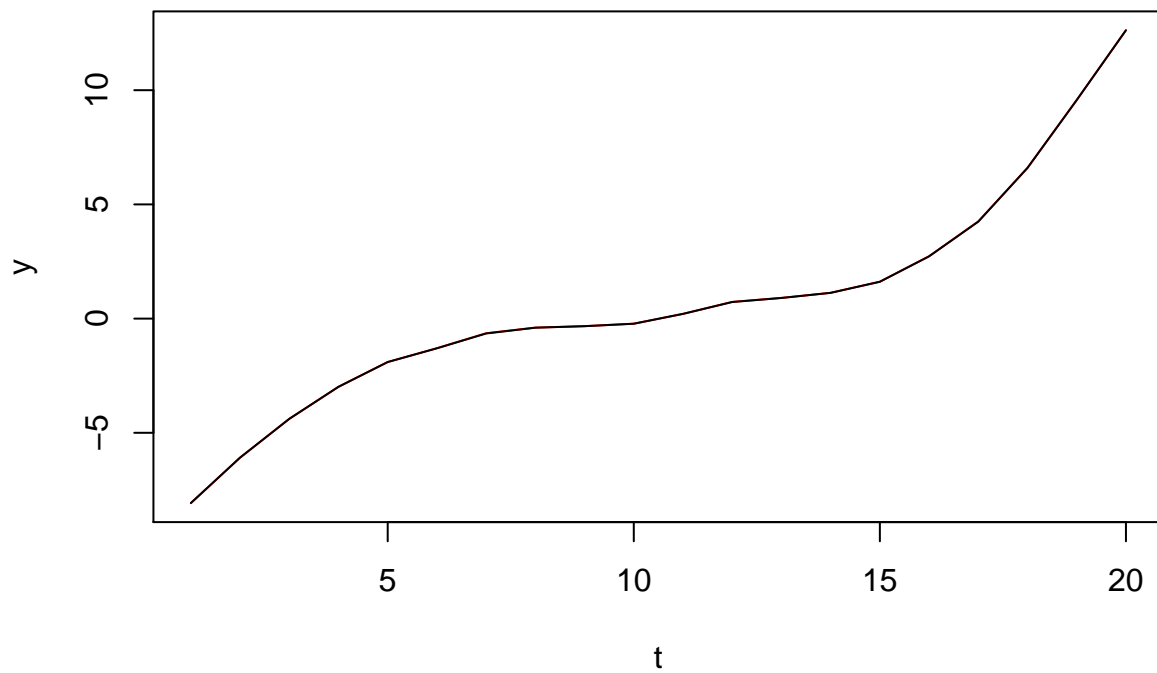
```
data = data.frame(y = y, t = t)
```

```

thetahyper = list(theta = list(prior = "log.gamma", param = c(1, 1)))
formula = y ~ f(t, model = "rw2", hyper = thetahyper, constr = FALSE) - 1
result1 = INLA::inla(formula = formula, family = "gaussian", data = data, control.family = list(hyper=1

plot(result1$summary.random$t$mean, xlab="t", ylab="y", type="l", col="red")
lines(t, f.mean)

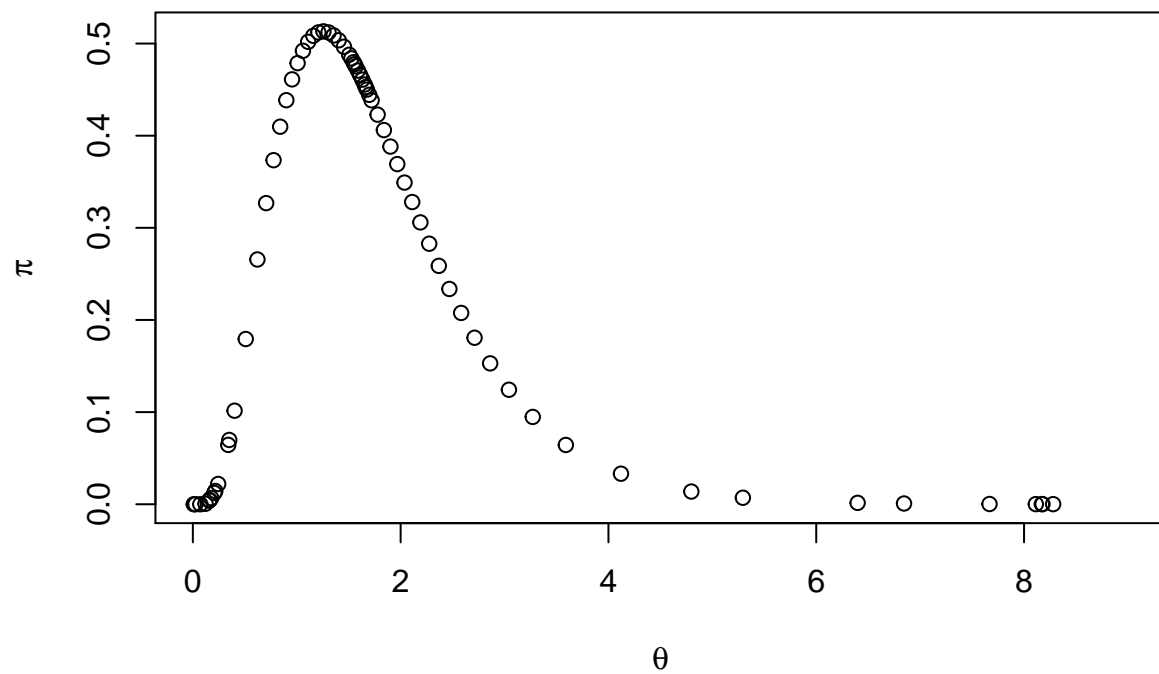
```



```

plot(result1$marginals.hyperpar$`Precision for t`, xlim =c(0,9), xlab=bquote(theta),ylab=bquote(pi))

```



```
plot(result1$marginals.random$t$index.10,xlim=c(-4,4),xlab=bquote(eta[10]),ylab=bquote(pi))
```

