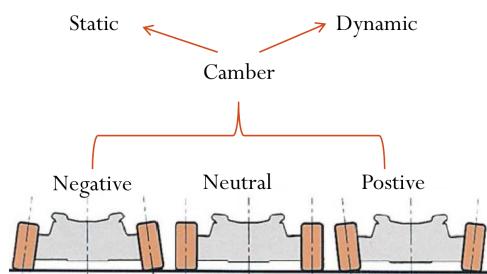
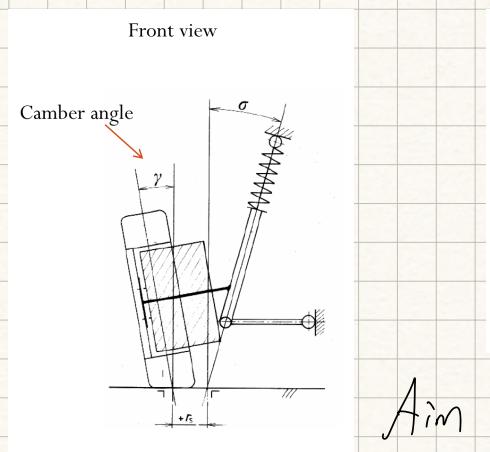


# Suspensions

## Functions

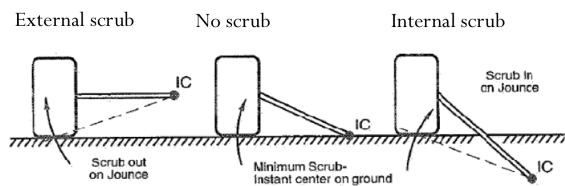
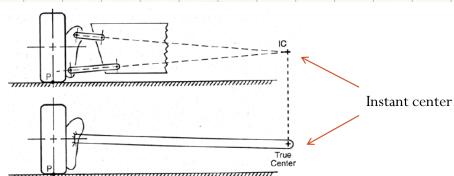
- 1) Isolate sprung mass ( $M_s$ ) from unsprung mass ( $M_u$ ) (comfort)
- 2) Transfer (react to) control forces
- 3) Limit roll motion
- 4) Limit load transfer
- 5) Control wheel motion (proper ranges for kinematic parameters).

## Camber angle



Aim is to maximize the contact area.

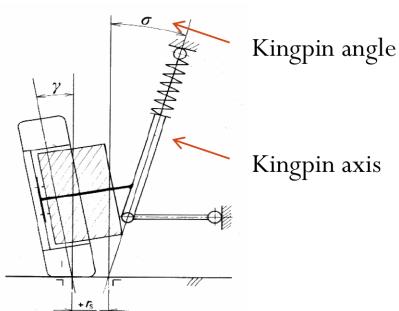
## Scrub



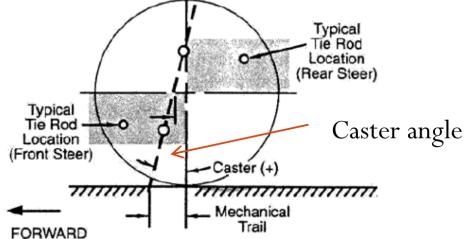
- Track variation
- Unwanted lateral dynamics

## Kingpin axis and angle

Front view

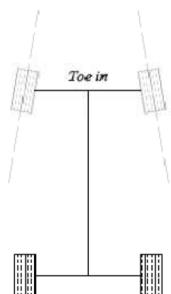


Lateral view

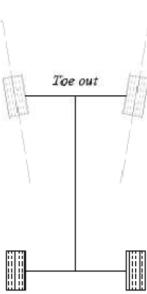


## Toe angle

Toe In



Toe out

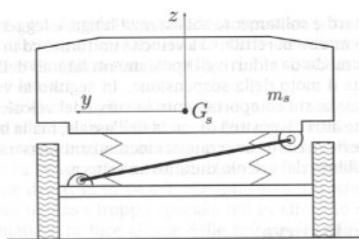


Impact on lateral slip

## Types of suspensions

### 1) Solid axle suspensions

- Solid axles
- 2 DoF mechanism
- Ease of manufacturing



## 2) Independent suspensions

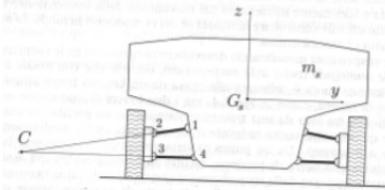
1 Dof mechanism per wheel

- Bigger space to host the engine

- $\mu$  limited

- higher roll stiffness

- Independent motion for the wheels



4-bar linkage susp.

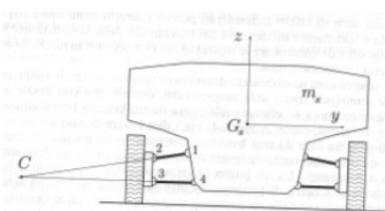
## 4-bar / double wishbone

Pros:

- lower weight

- flexible design

- low aerodynamic drag



Cons:

- Camber worsening for the inner wheel

Applications:

- Front suspensions for vehicles with rear traction

- (longitudinal engine)

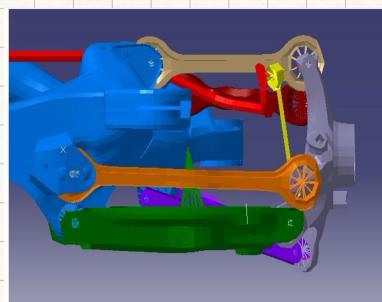
## Multi-link

Pros:

- flexible design

- 3D kinematic chain

Cons:



- Difficult development

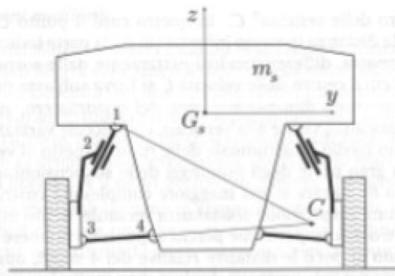
Applications:

- Rear suspensions

## Mac Pherson

Pros:

- Wide room for engine and transmission
- load distribution along a wide region
- Reduced number of components



Cons:

- Huge size in z-direction (height)

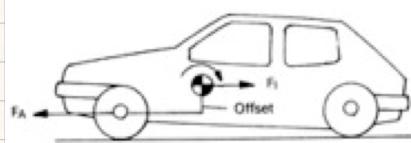
Applications:

- Front suspensions

## Anti-features:

Acceleration:

- Anti-squat
- Anti-pitch



Braking:

- Anti-dive
- Anti-lift

