

Test Chapter

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Exponential Inequalities

Chernoff Inequalities

Theorem 0.1 (Chernoff Inequality for Upper Tails). *Let X_i be Bernoulli random variables with parameters p_i , $S_N = \sum_{i=1}^N X_i$ and $\mu_N =$*

Application to Estimation of Data Dimension

The article (ref) explains how we can estimate the dimension d of a manifold M embedded on a Euclidean space of dimension m , say \mathbb{R}^m . First, we are going to introduce the method they used, and then, we will show how does the exponential inequalities can be used to prove two important results in the paper. The procedure starts with an example on a uniformly distributed sample on a d -sphere $\mathbb{S}^{d-1} \subset \mathbb{R}^d$, but will be later generalized for samples of any distribution on any manifold.

In the first place, let Z_1, \dots, Z_k be a i.i.d. sample uniformly distributed on \mathbb{S}^{d-1} . Then, we have the following formula for the variance of the angles between $Z_i, Z_j, i \neq j$:

$$\beta_d := \text{Var}(\arccos \langle Z_i, Z_j \rangle) = \begin{cases} \frac{\pi^2}{4} - 2 \sum_{j=1}^k (2j-1)^{-2}, & \text{if } d = 2k+1 \text{ is odd,} \\ \frac{\pi^2}{12} - 2 \sum_{j=1}^k (2j)^{-2}, & \text{if } d = 2k+2 \text{ is even.} \end{cases} \quad (1)$$

The previous formula for the angle variance is proven in (ref) and will be skipped (**TODO**: Should it really be skipped?). In order to give more insight on how we will be choosing the estimator \hat{d} for the dimension of the sphere, consider the following theorem.

Theorem 0.2 (cool name). *For every $d > 1$, the following bound holds:*

$$\frac{1}{d} \leq \beta_d \leq \frac{1}{d-1}.$$

Proof. The even and the odd cases must be distinguished:

(1) When $d = 2k + 2$ is even: In the first place, remember that,

$$\lim_{k \rightarrow \infty} \sum_{j=1}^k j^{-2} = \frac{\pi^2}{6}.$$

It follows that

$$\begin{aligned}
\beta_d &= \frac{\pi^2}{12} - 2 \sum_{j=1}^k (2j)^{-2} \\
&= \frac{\pi^2}{12} - \frac{1}{2} \sum_{j=1}^k j^{-2} \\
&= \frac{1}{2} \sum_{j=k+1}^{\infty} j^{-2}.
\end{aligned}$$

Since $(j^{-2})_{j \in \mathbb{N}}$ is a monotonically decreasing sequence, it follows that (**TODO**: Improve array syntax)

$$\begin{aligned}
\frac{1}{d} &= \frac{1}{2k+2} = \frac{1}{2} \int_{k+1}^{\infty} x^{-2} dx \\
&\leq \beta_d \leq \frac{1}{2} \int_{k+1/2}^{\infty} x^{-2} dx \\
&= \frac{1}{2k+1} = \frac{1}{d-1}.
\end{aligned}$$

(2) When $d = 2k + 3$ is odd: On the other hand, note that

$$\begin{aligned}
\lim_{k \rightarrow \infty} \sum_{j=1}^k (2j-1)^{-2} &= \lim_{k \rightarrow \infty} \sum_{j=1}^{2k-1} j^{-2} - \sum_{j=1}^{k-1} (2j)^{-2} \\
&= \lim_{k \rightarrow \infty} \sum_{j=1}^{2k-1} j^{-2} - \frac{1}{4} \sum_{j=1}^{k-1} j^{-2} \\
&= \frac{\pi^2}{6} - \frac{\pi^2}{24} = \frac{\pi^2}{8}
\end{aligned}$$

Then,

$$\begin{aligned}
\beta_d &= \frac{\pi^2}{4} - 2 \sum_{j=1}^k (2j-1)^{-2} \\
&= 2 \sum_{j=k+1}^{\infty} (2j-1)^{-2}.
\end{aligned}$$

Using a similar argument we conclude that (**TODO**: Improve array syntax)

$$\begin{aligned}
\frac{1}{d} &= \frac{1}{2k+1} = 2 \int_{k+1}^{\infty} (2x-1)^{-2} dx \\
&\leq \beta_d \leq 2 \int_{k+1/2}^{\infty} (2x-1)^{-2} dx \\
&= \frac{1}{2k+2} = \frac{1}{d-1}.
\end{aligned}$$

□

Knowing that for every $d > 1$, β_d is in the interval $[\frac{1}{d}, \frac{1}{d-1}]$, we are going to guess the dimension of the sphere by estimating β_d , and then, taking d from the lower bound of the interval where our estimator is. Since β_d is the variance of the angles in our sphere, our best choice for an estimator is the angle's sample variance,

$$U_k = \binom{k}{2}^{-1} \sum_{i < j \leq k} \left(\arccos \langle Z_i, Z_j \rangle - \frac{\pi^2}{2} \right)^2. \quad (2)$$

In Proposition 1. of (ref) the authors prove that it's the Minimum Variance Unbiased Estimator for β_d on the unit sphere. However, the authors also prove that this result can be generalized for any manifold with samples of any distribution.

Let X_1, \dots, X_n be a i.i.d. sample from a random distribution P on a manifold $M \subset \mathbb{R}^m$, and let $p \in M$ a point. For $C > 0 \in \mathbb{R}$, let $k = \lceil C \ln(n) \rceil$ and define $R(n) = L_{k+1}(p)$ as the distance between p and its $(k+1)$ -nearest neighbor. W.L.O.G. assume that $p = 0$ and that X_1, \dots, X_k are the k -nearest neighbors of p

Theorem 0.3. *For any sufficiently large $C > 0$, we have that, there exists n_0 such that, with probability 1, for every $n \geq n_0$,*

$$R(n) \leq f_{p,P,C}(n) = O(\sqrt[d]{\ln(n)/n}).$$

The function $f_{p,P,C}$ is a deterministic function which depends on p , P and C .

Let $\pi : \mathbb{R}^m \rightarrow T_p M$ be the orthogonal projection on the Tangent Space of M at p . Also, define $W_i := \pi(X_i)$ and then normalize,

$$Z_i := \frac{X_i}{\|X_i\|}, \quad \widehat{W}_i := \frac{W_i}{\|W_i\|}.$$

What follows from the previous and the following lemma is that if we know that W_1, \dots, W_k behave similar to a uniformly distributed sample on the sphere \mathbb{S}^d , then, Z_1, \dots, Z_k (the normalized k -nearest neighbors of p) also behave like they are uniformly distributed on \mathbb{S}^d .

Theorem 0.4 (Projection Distance Bounds). *For any $i < j \leq n$,*

$$(i) \quad \|X_i - \pi(X_i)\| = O(\|\pi(X_i)\|^2)$$

$$(ii) \quad \|Z_i - \widehat{W}_i\| = O(\|\pi(X_i)\|)$$

(iii) *The inner products (cosine of angles) can be bounded as it follows:*

$$|\langle Z_i, Z_j \rangle - \langle \widehat{W}_i, \widehat{W}_j \rangle| \leq Kr,$$

for a constant $K \in \mathbb{R}$, whenever $r \geq \max(\|\pi(X_i)\|, \|\pi(X_j)\|)$.

The last result in the article shows that if we estimate β_d as we did with $U_{k,n} = U_k$ in equation (2), and then, extract \widehat{d} from the interval where $U_{k,n}$ is located, it follows that,

Theorem 0.5 (Consistency). *When $n \rightarrow \infty$,*

$$\mathbf{P}\{\widehat{d} \neq d\} \rightarrow 0.$$