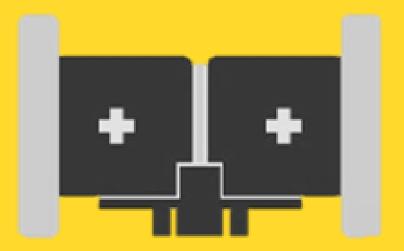
## **Users guide for BrailleBot**

Open platform IoT robotics module





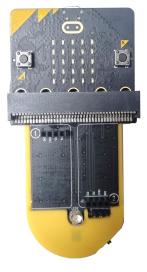
qna@roborisen.com www.roborisen.com

#### **BrailleBot**

■ Braille board : Detect color and lines with color sensor and line sensor

■ BrailleBot : Braille board + GCube 2EA

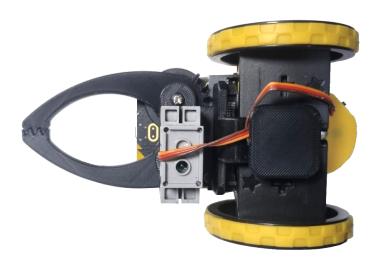
■ Braille Gripper Bot : BrailleBot + gripper



Braille board



BrailleBot



Braille Gripper Bot

#### **Braille board**

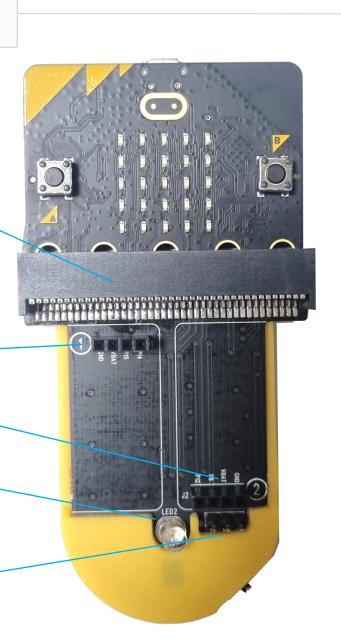
micro:bit connector

**GCube1 port** 

**GCube2 port** 

**Rear color LED** 

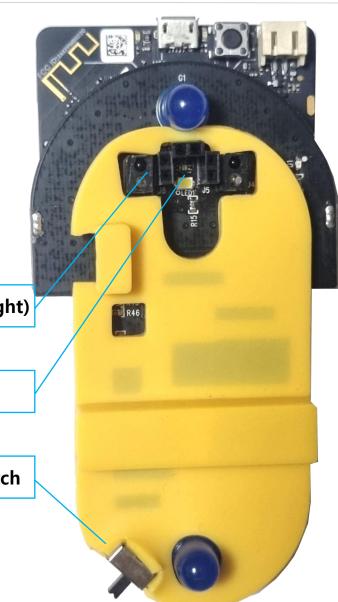
RC servo motor for gripper



IR sensor (Left, Right)

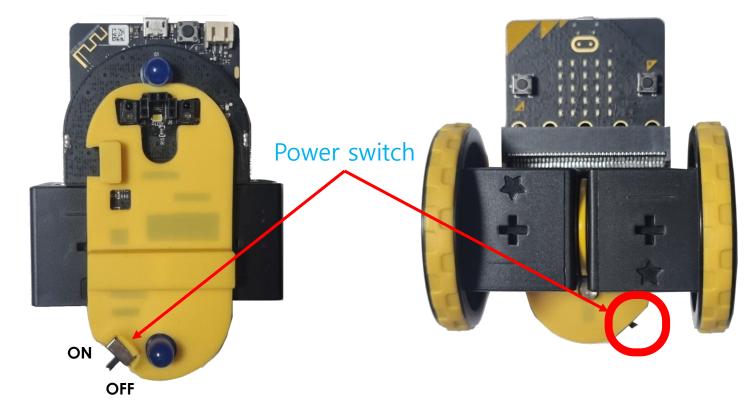
**Color sensor** 

**Board power switch** 



## <BrailleBot Assembly>





## **GCube Assembly**

\* Use C2-12 to attach two GCubes.

## Braille board Assembly

\* Insert the Braille board into the two GCubes.

\* Assemble so that the square shape faces up and down.

## Wheel Assembly

\* Assemble two wheels to complete.

## <Gripper bot Assembly>



## **Gripper Assembly**

\* Assemble the gripper and attach it on top of the BrailleBot.



## Connect RC servo motor

- \* Connect the servo motor to the Braille board.
- \* Insert it so that the orange wire faces inward.

#### <Color rules>

## Start and ignore near next color

- \* Hold on 0.5sec and start
- \* Ignore the near next color

#### Gripper close

\* Go forward → close → go backward → U turn

#### Gripper open

\* Go forward → open → go backward → U turn

#### Left turn

\* Left turn

#### Right turn

\* Right turn

#### U turn

\* U turn

#### Stop

\* Stop

## <Color Rules – Unplugged Mode>

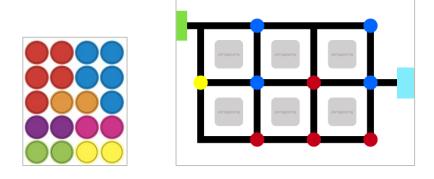
## BrailleBot RGB color code

| Start & ignore the near next color |
|------------------------------------|
| Right turn                         |
| Left turn                          |
| U turn                             |
| Stop                               |
| Gripper open                       |
| Gripper close                      |

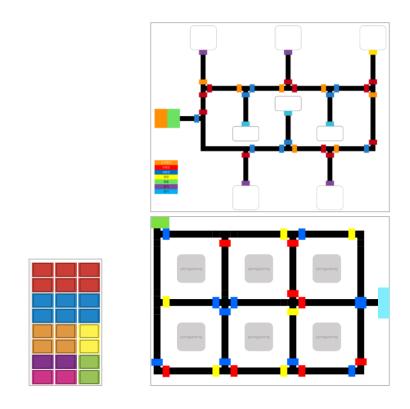
# 81ECFB
# FF0000
# 0066FF
# FFFF00
# B4FF00
# FF00FF
# 9600C8

When the sky color is detected, the next color command within 5 cm is ignored.

## Types of braille stickers



Activities using round stickers

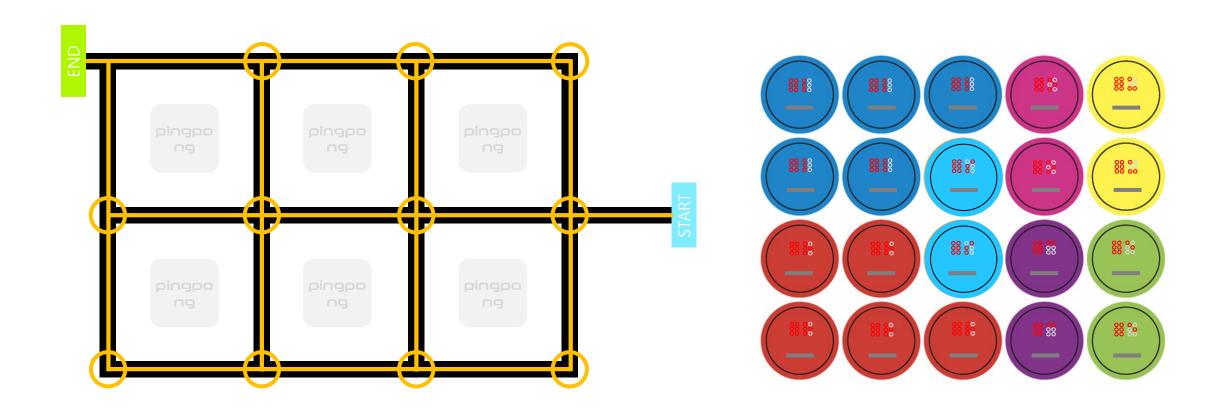


Activities using square stickers

## **Braille & color matching**



## Braille map & Braille color coin

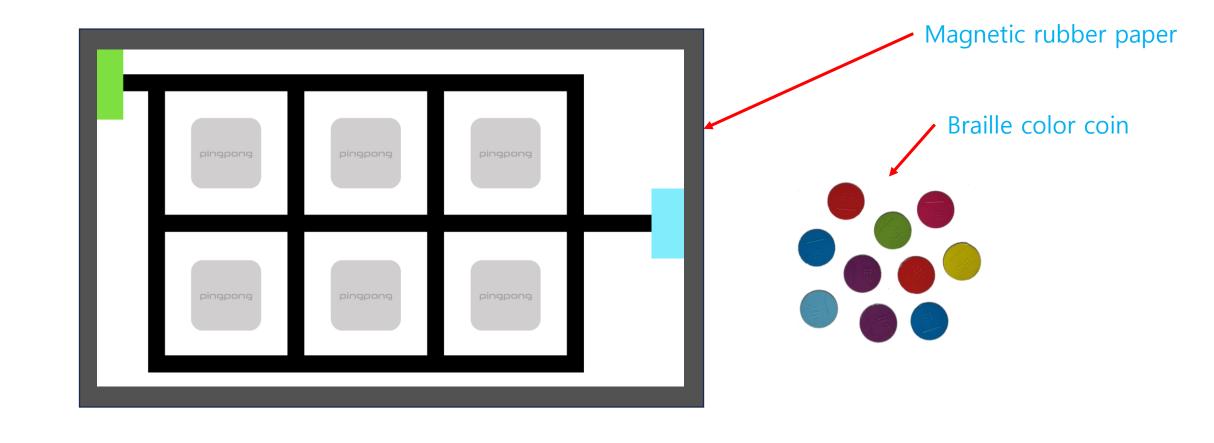


Braille tactile map

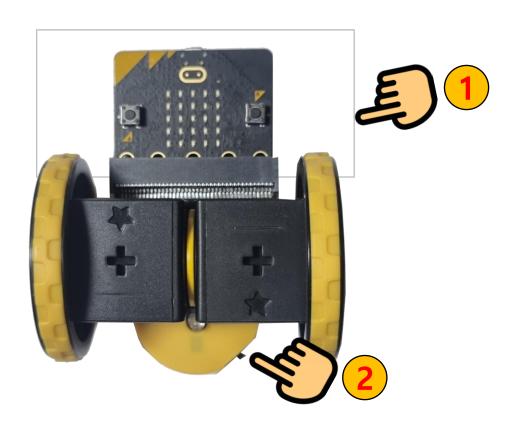
Braille tactile color coin

#### Braille color coin

If you place the map on magnetic rubber paper, you can use metallic color coins.

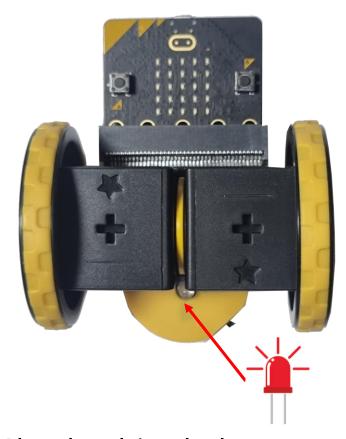


## <Steps to Turn On and Operate BrailleBot>



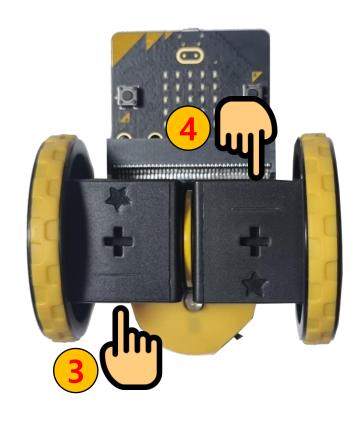
#### Turn on the board

- 1. Place the color sensor part of the Braille board on white paper.
- 2. Turn on the Braille board's power switch.



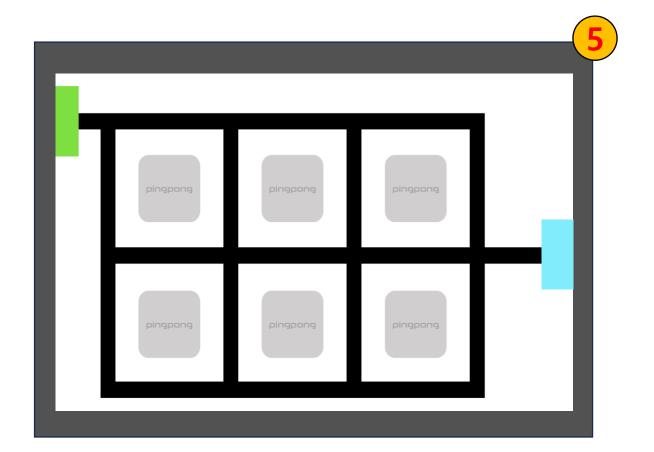
#### Check white balance

- \* After the red LED blinks 3 times
- If calibration succeeds, a short low "Do (C4)" sound plays.
- If calibration fails, a long high "Do (C5)" sound plays.



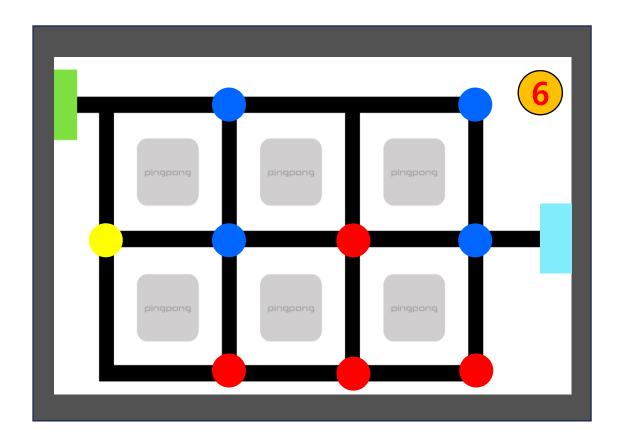
## Turn on the board and GCubes

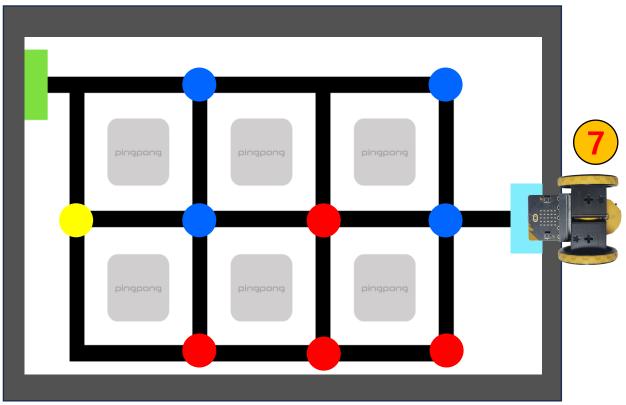
- 3. Press the power button on GCube #1 once to turn it on.
- 4. Press the power button on GCube #2 once to turn it on.
- When the two GCubes connect, the Hello melody plays on the micro:bit.



## Place the Braille map on the magnetic mat

5. Place the Braille map on the magnetic mat.



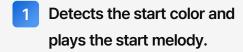


## Attach color coins to the Braille map

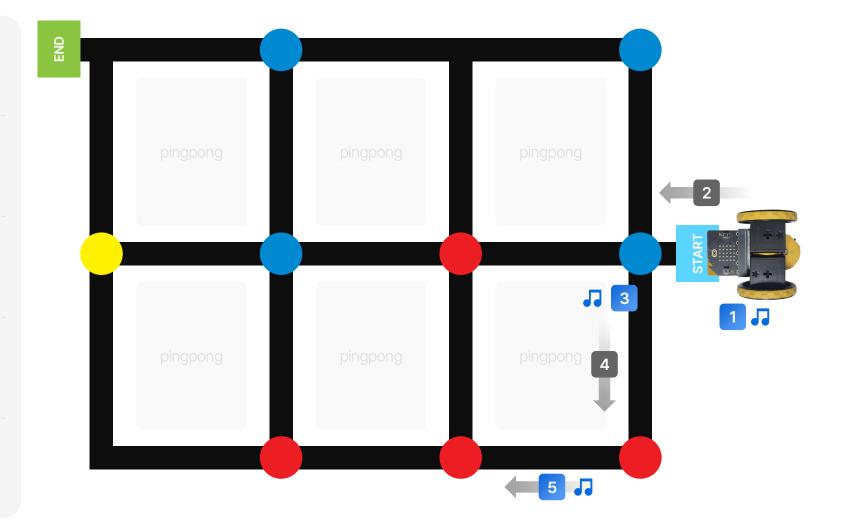
6. Attach the color coin at the desired position on the Braille map.

## Place BrailleBot at the starting position

7. Place the color sensor on light blue, and BrailleBot will start.

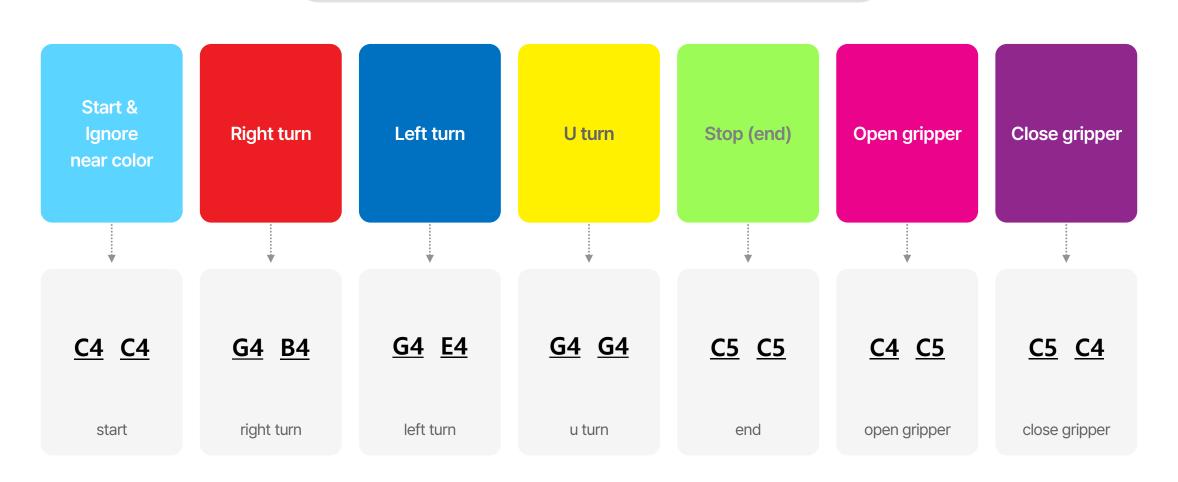


- 2 Moves forward and turns left when it detects blue.
- 3 After turning left, it plays a melody indicating the left turn.
- 4 Moves forward and turns right when it detects red.
- 5 After turning right, it plays a melody indicating the right turn.

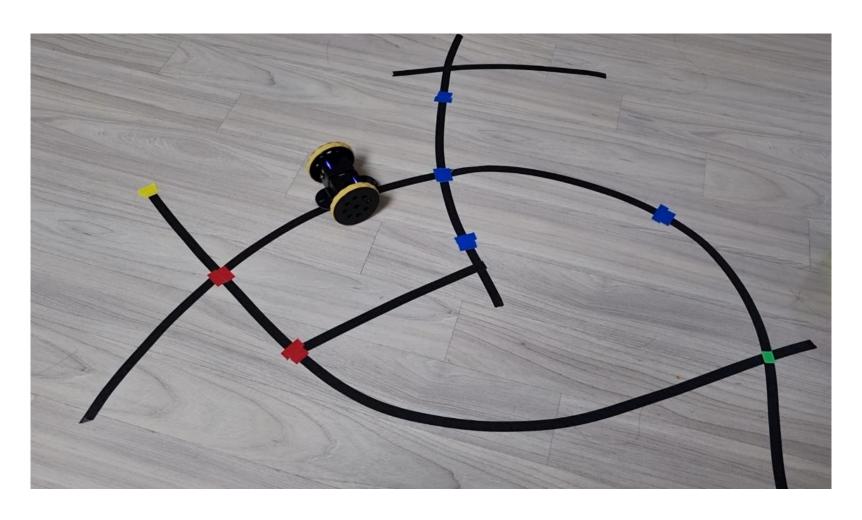


## **Melody for Braille Bot**

#### Melody & color matching

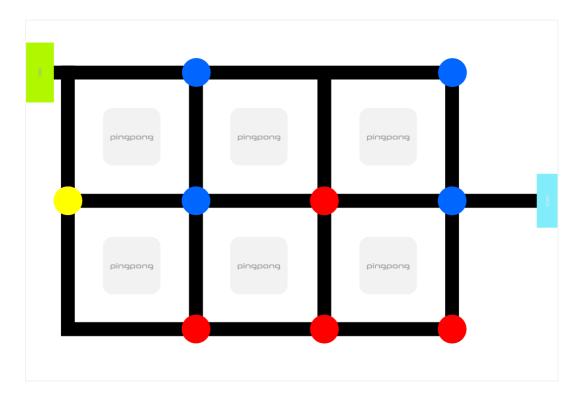


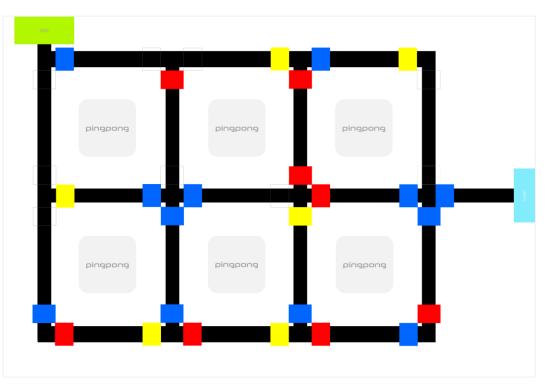
## Example #1 - Line Following



A mission where the robot detects black tape or drawn lines and follows them.

## Example #2 - Mission Using Colors



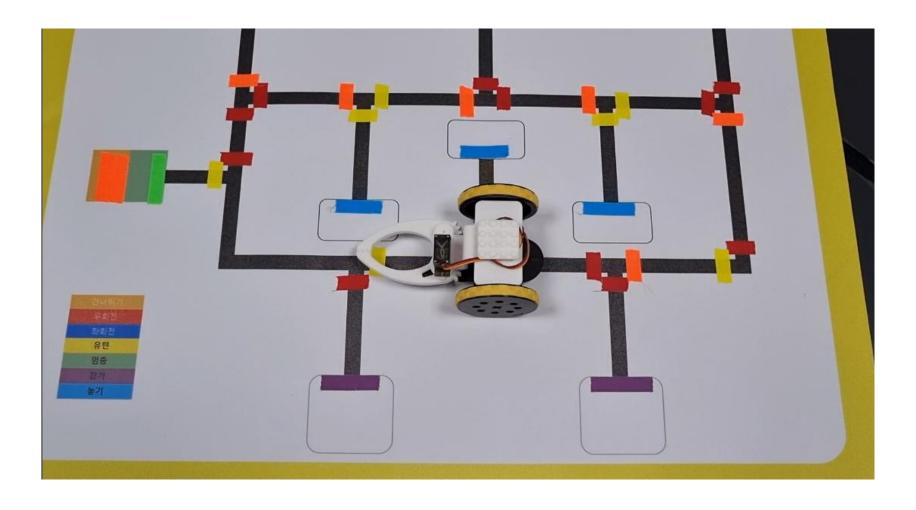


Round type activity map

Square type activity map

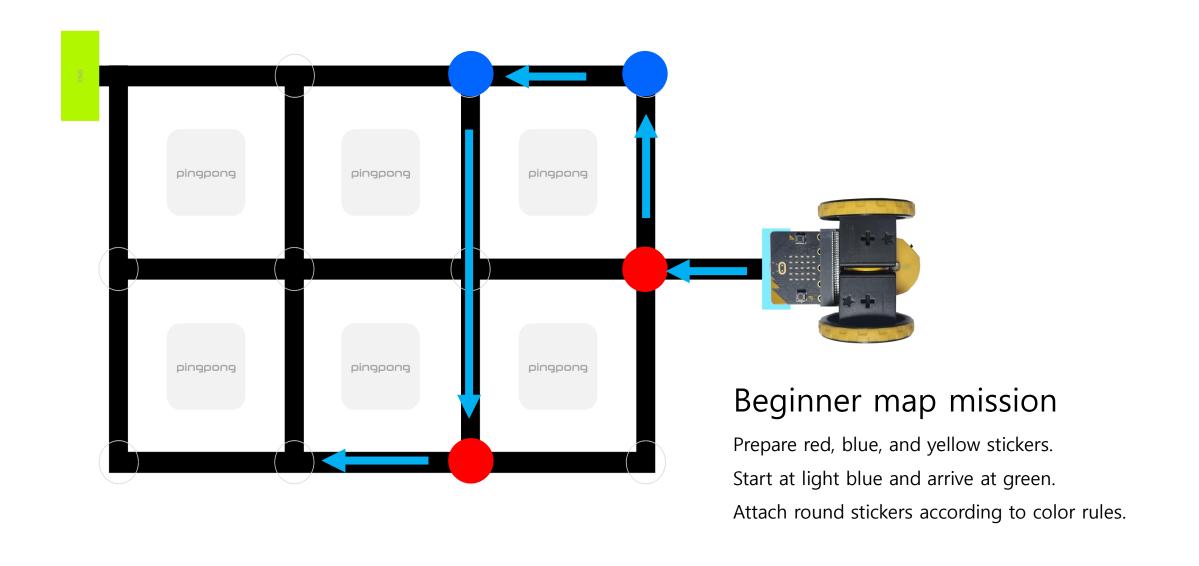
Perform missions by attaching or removing square and round stickers on the map, such as reaching a destination or staying longer in a specific area.

## Example #3 – Delivery Mission Using the Gripper

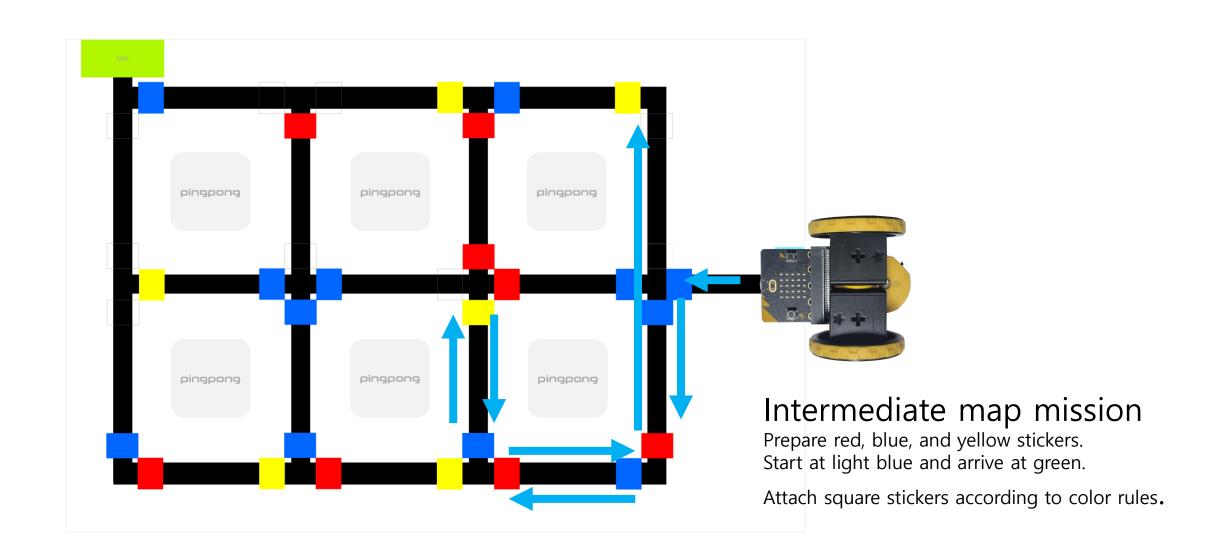


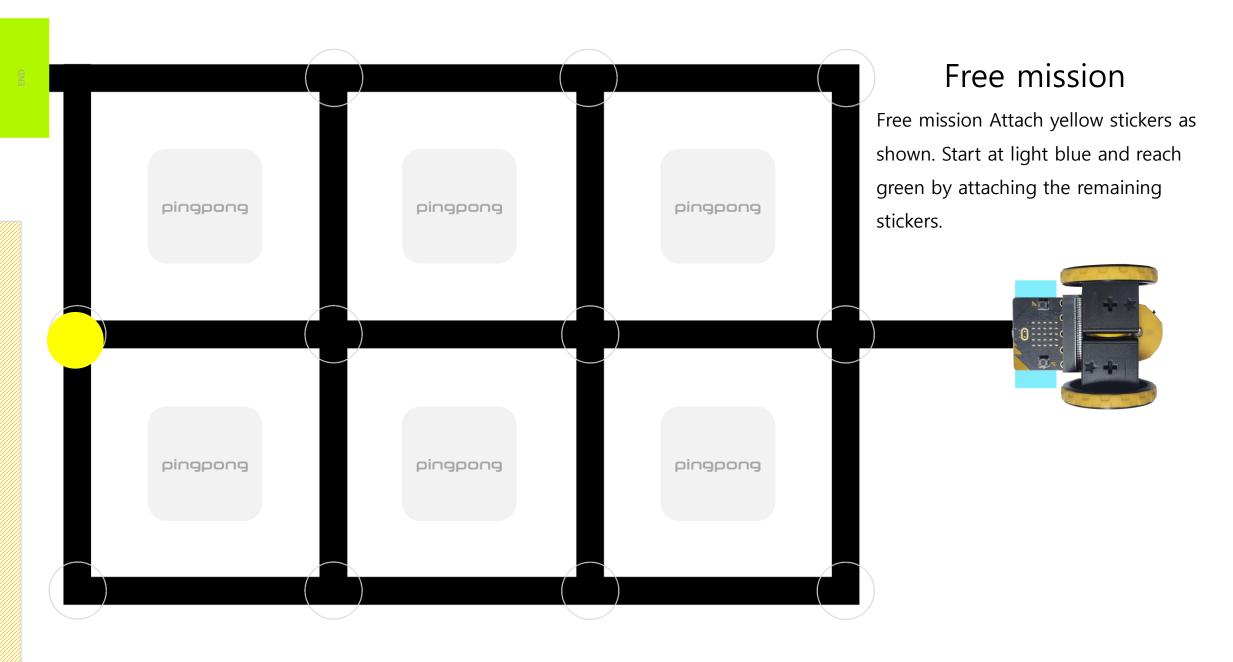
Attach color stickers on the map and use the gripper to move objects to desired locations.

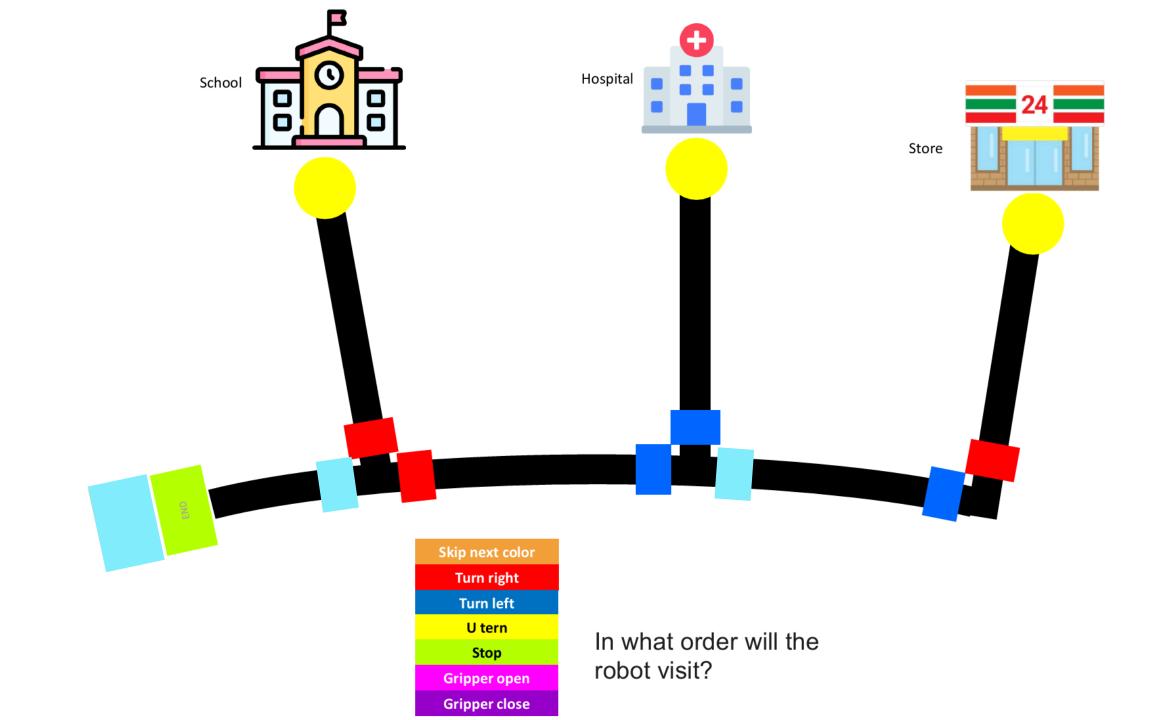
## <Placing the round type color coin on the map>



## <Placing the square type color coin on the map>









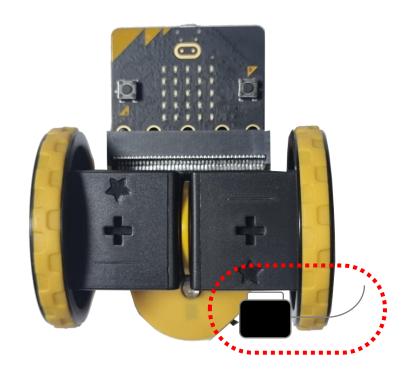
# **Precautions When Using BrailleBot**



## **Precautions When Using BrailleBot**

- After use, always pull the power switch on the front right side of the board backward to turn it off.
- If the robot recognizes blue when placed at the starting point (light blue), hold it briefly until it recognizes light blue, then release it.
- Whenever possible, use the color stickers provided by the manufacturer.

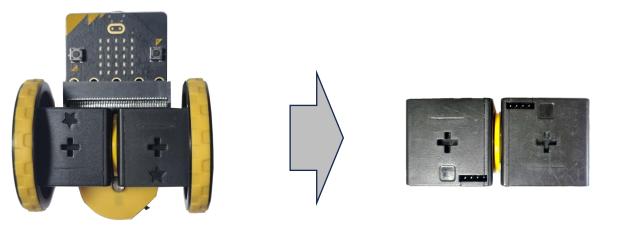
## < Charging Method 1: Individual Robot Charging >



1 Attach the charging cable to the back of the right GCube to charge.

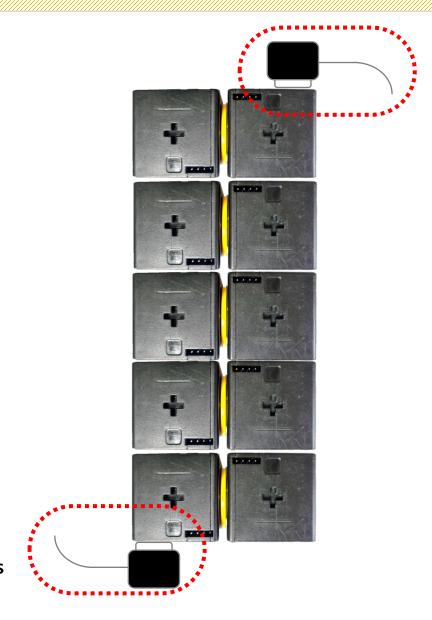
\* Since the two GCubes in the BrailleBot are connected via the Braille board, charging one GCube will also charge the other.

## < Charging Method 2: Simultaneous Charging >

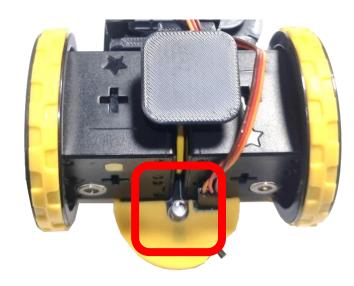




- 2 Attach the bodies together (magnets attach to each other)
- 3 Attach two magnetic charging cables above and below for charging
  - \* Dozens of bodies can be connected for simultaneous charging
  - \* Charging 6 GCubes takes about 1 hour, 60 GCubes about 10 hours



## <Detected color display — Read color LED>



Rear color LED

Detected color

Start & Ignore next color

**Right turn** 

**Left turn** 

U turn

Stop

Gripper open

**Gripper close** 

Rear LED color

White

Red

Blue

Yellow

Green

**Black** 

Violet