## Assignment 1 – Selected Model Answers

EXERCISE 1. For  $k \in \mathbb{N}, k \geq 1$  define an operation  $delete\_last(\ell, k)$ , which deletes the last k elements in a list  $\ell$ . Analyse the amortised complexity of this operation and show that it is in  $\Theta(1)$ , independent of k.

SOLUTION. For the deletion of the last k elements of a list (represented by an array) it suffices to decrement the length variable by k (or set length to 0 in case k > length). As a single execution of  $delete\_last(\ell, k)$  may trigger a cascade of deallocate operations, it is impossible to distribute the costs for deallocate to  $delete\_last$  operations.

Instead let us modify the contribution of append and insert to become 3c (instead of 2c), and  $3c|\ell|$  for concat. In order to simply the argumentation let us use a second counter C', and let the contribution to C be still 2c (or  $3c|\ell|$ , respectively), while the remaining contribution of c (or  $c|\ell|$ , respectively) is added to C'.

Consequently, when the list has reached the length m, there has been at least the contribution mc to the counter C'. If we execute now an operation  $delete\_last(\ell, k)$ , the triggered deallocate operations require a cost of c for each element in the list. Subtracting these costs from C' still maintains the condition that the value of C' is c-times the actual size of the list, in particular  $\geq 0$ .

In doing so we can have a contribution of 0 by the  $delete\_last(\ell, k)$  operation, which shows that the amortised complexity is in  $\Theta(1)$ .

EXERCISE 2. Explore structural recursion on list objects, i.e. define an operation src[e, f, g] in the following way:

- If  $\ell$  is the empty list, then  $src[e, f, g](\ell) = e$ , where  $e \in T'$  is some constant.
- If  $\ell$  is a singleton list containing just one element x, then  $src[e, f, g](\ell) = f(x)$ , where f is a function that maps elements of a set T (the set of list elements) to elements of a set T'.
- If  $\ell$  can be written as the concatenation of two lists, say  $\ell = concat(\ell_1, \ell_2)$ , then

$$src[e, f, g](\ell) = g(src[e, f, g](\ell_1), src[e, f, g](\ell_2))$$
,

i.e. apply structural recursion to both sublists separately, then apply the operation  $g:T'\times T'\to T'$  to the resulting pair.

- (i) Discuss the conditions, under which src[e, f, g] is well-defined.
- (ii) Show how to use structural recursion to define operations on lists such as
  - determining the length,
  - applying a function to all elements of a list, and
  - creating a sublist of list elements satisfying a condition  $\varphi$ .

(iii) Analyse the time complexity of structural recursion.

SOLUTION.

(i) From the definition of src[e, f, g] we see that for a list  $\ell = [x_1, \ldots, x_n]$  we have to apply f to all  $x_i$ , then apply  $g(f(x_i), f(x_j))$  (or  $g(f(x_i), e)$ ) consecutively. The result is uniquely determined, if g is associative with neutral element e.

Conversely,

$$g(src[e, f, g](\ell), e) = g(src[e, f, g](\ell), src[e, f, g]([])) = src[e, f, g](\ell)$$

so if src[e, f, g] is surjective, e must be a neutral element of g. Furthermore,

$$\begin{split} g(src[e,f,g](\ell_1),g(src[e,f,g](\ell_2),src[e,f,g](\ell_3))) &= g(src[e,f,g](\ell_1),src[e,f,g](\ell_2+\ell_3)) \\ &= src[e,f,g](\ell_1+(\ell_2+\ell_3)) \\ &= g(src[e,f,g](\ell_1+\ell_2),src[e,f,g](\ell_3)) \\ &= g(g(src[e,f,g](\ell_1),src[e,f,g](\ell_2)),src[e,f,g](\ell_3)) \end{split}$$

so if src[e, f, g] is surjective, g must be associative.

(ii) For the *length* function we have

$$length(\ell) = src[0, 1, +](\ell) = \begin{cases} 0 & \text{if } \ell = []\\ 1 & \text{if } \ell = [x]\\ length(\ell_1) + length(\ell_2) & \text{if } \ell = \ell_1 + \ell_2 \end{cases}$$

For the map[h] function applying h to every list element we have

$$map[h](\ell) = src[[], single \circ h, +](\ell) = \begin{cases} [] & \text{if } \ell = [] \\ [h(x)] & \text{if } \ell = [x] \\ map[h](\ell_1) + map[h](\ell_2) & \text{if } \ell = \ell_1 + \ell_2 \end{cases}$$

For the  $filter[\varphi]$  function selecting the sublist of those elements x satisfying  $\varphi$  we have

$$filter[\varphi](\ell) = src[[], \alpha, +](\ell) = \begin{cases} [] & \text{if } \ell = [] \\ \alpha(x) & \text{if } \ell = [x] \\ filter[\varphi](\ell_1) + filter[\varphi](\ell_2) & \text{if } \ell = \ell_1 + \ell_2 \end{cases}$$

using the function

$$\alpha(x) = \begin{cases} [x] & \text{if } \varphi(x) \\ [] & \text{else} \end{cases}.$$

(iii) If n is the length of the input list, we have to apply the function f n-times, so if m is the size of a list element and  $\bar{f}(x)$  is the complexity of computing f(x), we get a complexity in  $O(m \cdot n)$  for the applications of f. Furthermore, we have to apply g (n-1) times, so if

barg is a function measuring the complexity of computing g, this amounts to a complexity in  $O(\sum_{i=1}^{n-1} \bar{g}(y_i))$ , where the  $y_i$  are a measure of the sizes of the different inputs to g.

If we have a bound c on the size of elements in T or T', the total complexity amounts to O(mn + n) = O(mn).

EXERCISE 3. Explain how to implement a FIFO queue using two stacks so that each FIFO operation takes amortised constant time.

SOLUTION. Let the two stacks be s1 and s2. For the pushback operation—accordingly also for back—we use only s1. If we have a popfront operation, we have to distinguish two cases:

- Case 1. If  $s_2$  is empty, we first move all elements from  $s_1$  to  $s_2$ , where a move consists of a pop operation on  $s_1$  followed by a push operation on  $s_2$ . Then proceed as in Case 2.
- Case 2. If s2 is not empty, then the *popfront* operation becomes simply a *pop* operation on s2.

The operation topfront is handled analogously without changing s2 is the second case. The emptiness check amounts to checking, if both stacks are empty.

For the amortised complexity let each pushback operation make a constant contribution 2c to a counter C, where c is the cost required by any push or pop operation. Thus, moving all elements from s1 to s2 in Case 1 above requires the cost of 2nc, where n is the number of elements moved.

When a move becomes necessary, there have been n pushback operations since the latest move, which altogether contributed 2nc to the counter C. By executing the move the counter is reset to 0. The constant contribution of the pushback operation guarantees that its amortised complexity remains in  $\Theta(1)$ . No other operation is affected.

## Exercise 4.

- (i) Implement the function  $delete\_last(\ell, k)$  from Exercise 1 on the class ALIST.
- (ii) Implement your solution from Exercise 3 using the class STACK.

## SOLUTION.

See the C++ header and program files in Ass1\_Ex4isolution.zip and Ass1\_Ex4iisolution.zip.