## Assignment 8 – Selected Model Answers

## Exercise 1.

- (i) Explain how to find the minimum and the maximum key stored in a B-tree.
- (ii) Implement operations on B-trees to return the record associated with the minimum and maximum keys, respectively.
- (iii) Explain how to find the predecessor and the successor keys of a given key stored in a B-tree.
- (iv) Implement operations on B-trees to return the record associated with the predecessor and the successor of a given key.

## Exercise 2.

- (i) Explain how to find the minimum and the maximum key stored in a B<sup>+</sup>-tree.
- (ii) Implement operations on B<sup>+</sup>-trees to return the record associated with the minimum and maximum keys, respectively.
- (iii) Explain how to find the predecessor and the successor keys of a given key stored in a B<sup>+</sup>-tree.
- (iv) Implement operations on B<sup>+</sup>-trees to return the record associated with the predecessor and the successor of a given key.

EXERCISE 3. For the bipartite matching problem we are given a finite bipartite graph (V, E), where the set V of vertices is partitioned into two sets Boys and Girls of equal size. Thus, the set E of edges contains sets  $\{x,y\}$  with  $x \in Boys$  and  $y \in Girls$ . A perfect matching is a subset  $F \subseteq E$  such that every vertex is incident to exactly one edge in F. A partial matching is a subset  $F \subseteq E$  such that every vertex is incident to at most one edge in F. So the algorithm will create larger and larger partial matchings until no more unmatched boys and girls are left, otherwise no perfect matching exists.

We use functions girls\_to\_boys and boys\_to\_girls turning sets of unordered edges into sets of ordered pairs:

girls\_to\_boys
$$(X) = \{(g, b) \mid b \in Boys \land g \in Girls : \{b, g\} \in X\}$$
boys\_to\_girls $(X) = \{(b, g) \mid b \in Boys \land g \in Girls : \{b, g\} \in X\}$ 

Conversely, the function unordered turns a set of ordered pairs (b,g) or (g,b) into a set of two-element sets:

$$\operatorname{unordered}(X) = \{\{x, y\} \mid (x, y) \in X\}$$

We further use a predicate reachable and a function path. For the former one we have  $\operatorname{reachable}(b,X,g)$  iff there is a path from b to g using the directed edges in X. For the latter one  $\operatorname{path}(b,X,g)$  is a set of ordered pairs representing a path from b to g using the directed edges in X.

Then an algorithm for bipartite matching can be realised by iterating the following rule:

```
par if
             mode = init
     then par
                     mode := examine
                     partial\_match := \emptyset
             endpar
     endif
     if
             mode = examine
     then if
                      \exists b \in Boys. \forall g \in Girls. \{b, g\} \notin partial\_match
             then mode := build-digraph
             else
                     par
                              Output := \mathbf{true}
                              Halt := \mathbf{true}
                              mode := final
                      endpar
             endif
     endif
             mode = build-digraph
     if
     then par
                      di\_graph := girls\_to\_boys(partial\_match)
                                   \cup boys_to_girls(E-partial\_match)
                     mode := build-path
             endpar
     endif
     if
             mode = build-path
     then choose b \in \{x \mid x \in Boys : \forall g \in Girls.\{b,g\} \notin partial\_match\}
                     if \exists g' \in Girls. \forall b' \in Boys. \{b', g'\} \notin partial\_match
                                   \land reachable(b, di\_graph, g')
                      then choose g \in \{y \mid y \in Girls. \forall x \in Boys. \{x, y\}
                           \notin partial\_match \land reachable(b, di\_graph, y)
                              do par path := path(b, di\_graph, g)
                                         mode := modify
                                   endpar
                              enddo
                              par \ Output := false
                      else
                                   Halt := \mathbf{true}
                                   mode := final
                              endpar
                      endif
             enddo
     endif
     if
             mode = modify
     then par
                     partial\_match = (partial\_match - unordered(path))
                                         \cup (unordered(path) - partial\_match)
                      mode := examine
             endpar
     endif
endpar
```

(i) Implement the above algorithm for the determination of a perfect matching on a bipartite graph (provided such a matching exists).

## Exercise 4.

- (i) Implement a class BIPARTITEGRAPH of bipartite graphs covering basic operations for insertion and deletion of vertices and edges and for the determination of edges incident to a given vertex.
- (ii) Implement a program that determines, whether a perfect matching exists for a given bipartite graph (not the algorithm from the previous exercise).