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 Section: LA1.

Part I. ___ /8

State Space Model Representation of $H_1(s)$

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Compare the plots of y_{dot} and y obtained in Part I of the lab with the plots previously made for the prelab. Why are they identical? Attach plots – if your prelab plot was wrong, fix it and attach the corrected plot.

The one in Part I is the state-space model for \check{y} prelab.

$$\begin{aligned} \dot{\check{x}} &= \begin{bmatrix} -6 & -25 \\ 1 & 0 \end{bmatrix} \check{x} + \begin{bmatrix} 25 \\ 0 \end{bmatrix} u & \Rightarrow \begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} &= \begin{bmatrix} -6x_1 - 25x_2 \\ x_1 \end{bmatrix} + \begin{bmatrix} 25u \\ 0 \end{bmatrix} \\ \text{Part II. } & y = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \check{x} \Rightarrow y_1 = x_1, y_2 = x_2, & \Rightarrow x = y_1, \dot{x} = \dot{y} & \Rightarrow \dot{x}_1 = -6x_1 - 25x_2 + 25u, x_2 = x_1 \\ & & & \Rightarrow \ddot{y} + 6\dot{y} + 25y = 25u. \quad /2 \end{aligned}$$

thus the same transfer function.

Fill the table and attach plot for part II.

Property	No Zero $H_1(s)$	$H_2(s)$ with Zero at $s = -30$	$H_2(s)$ with Zero at $s = -3$	$H_2(s)$ with Zero at $s = -1.5$	$H_2(s)$ with Zero at $s = 1.8$	$H_2(s)$ with Zero at $s = 18$
M_p %	9.5 %	9.6 %	41.1 %	114.9 %	19.5 %	9.78 %
$t_r(s)$	0.4 s	0.37 s	0.13 s	0.06 s	0.21 s	0.36 s
$t_s(s)$	1.04 s	1.02 s	0.85 s	1.38 s	1.34 s	1.10 s

Table 1: Effects of Zero

Discuss the Effects of a LHP Zero

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Explain how M_p , t_r , and t_s are affected by the zero's location. When can the zero be ignored? ↗ when zero is far from the origin.

M_p increased ↗ when the zero moves closer to the origin in LHP & RHP.

t_r decreased when moving to origin in LHP, but remain unchanged in RHP.

t_s remains unchanged for a LHP zero but decreased when moving to origin in RHP.

Effects of a Non-minimum Phase (RHP) Zero

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What is unique in this situation?

It creates an undershoot before the response overshoots.

Decomposition of $H_2(s)$

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Take $H_2(s)$, set ζ to the value found in the prelab, and separate the numerator into two terms so that $H_2(s)$ is a sum of 2 fractions. Discuss how this decomposition helps to explain the effect of the zero location. In particular, discuss what each term represents. Also discuss α 's effect.

Which term dominates as α approaches 0? As α approaches ∞ ? What happens when α is negative?

$$H_2 = \frac{25 + \frac{25s}{\alpha s}}{s^2 + 10s + 25} = \frac{25 \cdot \left(\frac{s}{\alpha s}\right)}{s^2 + 10s + 25} + \frac{\frac{25}{\alpha s}}{s^2 + 10s + 25} \quad \text{Output regarded as } y_2(t) = y_1(t) + \frac{m}{\alpha s} y_1(t).$$

This is the sum of two responses; one is the original, another has a zero at the origin. The additional term is the first-order derivative of the original output with a coefficient $\frac{1}{\alpha s}$.

For α : it controls the amount of contribution by $y_2(t)$ to $y_1(t)$, the new output. When $\alpha \rightarrow 0$, the original output dominates; $\alpha \rightarrow \infty$, the original term dominates. When α is negative, it creates undershoot, as $\alpha \rightarrow -\infty$, the output looks similar to the original.

Part III. ____/20**Effects of an Extra Pole on M_p , t_r , and t_s .**

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Fill the table and attach plot for part III. Attach Plots.

Property	No Pole $H_1(s)$	$H_3(s)$ with Pole at $s = -30$	$H_3(s)$ with Pole at $s = -3$	$H_3(s)$ with Pole at $s = -1.5$
$M_p \%$	9.5 %	9.3 %	8.5 %	1.5 %
$t_r (s)$	0.4 s	0.4	0.7	1.4
$t_s (s)$	1.04 s	1.01	1.05	2.21

Table 2: Effects of Extra Pole

Discuss the Effects of an Extra Pole

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Explain how M_p , t_r , and t_s are affected by the location of the additional pole. When can the extra pole be ignored?

The closer the poles are to the origin, the ~~smaller~~ ^{smaller} the overshooting percentage and rising time.

The extra pole can be ignored when the pole is far away in LHP.

Decomposition of $H_3(s)$

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Take $H_3(s)$, set ζ to the value found in the prelab, and perform a partial fraction expansion to make three terms in the form of the expansion on page 18 in the lab manual. Determine the values of k_1 , k_2 , and k_3 . Discuss how this decomposition helps to explain the effect of the location of an additional pole. In particular, discuss what each term represents. Also discuss α 's effect.

Which term dominates as α approaches 0? As α approaches ∞ ?

By partial fraction:

$$H_3 = \frac{-25}{s + 10\zeta} + \frac{25}{s^2 + 10\zeta s + 25} + \frac{25}{s^2 + 10\zeta s + 25} \Rightarrow k_1 = \frac{625}{9\zeta^2 - 90\zeta + 625}$$

$$k_2 = \frac{375\zeta}{90\zeta^2 - 90\zeta + 625}$$

$$k_3 = \frac{225\zeta^2 - 2250\zeta}{9\zeta^2 - 90\zeta + 625}$$

Attachments (4)

- Plot from PreLab
- Plots for Part I, II and III.

This shows a composition by the original output, its

first-order derivative, and the extra pole.

All the plots are included in the compressed archive submitted.