

# MARTIN (ZIWEN) MA

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*I am passionate about developing computational models for autonomous laboratory.*

## EDUCATION

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### Massachusetts Institute of Technology

MS Chemical Engineering Practice

Cambridge, US

Sept 2021 - Aug 2022

- **Relevant Courses:** Numerical Methods, Systems Engineering, Machine Learning for Molecular Engineering

### University of Waterloo

BASc Chemical Engineering

Waterloo, Canada

Sept 2016 - Apr 2021

- Cumulative GPA: 95%, Rank: 2/50, Dean's Honours List
- Option (similar to Minor) in Artificial Intelligence, Option in Management Science, Specilization in Process Modelling, Optimization and Control
- **Relevant Courses:** Intro to ML, Intro to AI, Advanced Optimization, Data Mining, Autonomous Vehicles, Game Theory, Methods and Tools for Software Engineering, Algorithms & Data Structures, Algorithm Design & Analysis, CNN for Computer Vision (Stanford), Reinforcement Learning (Stanford)

## AWARDS & HONOURS

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Vice President of Chemical Engineering Student Society (2018-2021)

First-in-class Scholarship (2020, 2021)

Engineering Faculty Upper Year Scholarship (2020)

President's Scholarship (2017)

## RESEARCH EXPERIENCE

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### Professor George Shaker

*Machine Learning Applications in Wireless Sensing*

Waterloo, Canada

Sept 2020 - Feb 2021

- Developed a novel Convolutional LSTM network to localize passenger and classify occupant type using multi-input multi-output (MIMO) frequency modulated continuous wave (FMCW) radar, improved accuracy by 20% compared to the previous method.
- Model detected unattended children in-vehicle with 0.9 precision and 0.95 recall.

### Professor Krzysztof Czarnecki

*Autonomous Vehicle*

Waterloo, Canada

May 2020 - Aug 2020

- Designed and implemented an active learning framework for LiDAR-based 3D object detection and improved sample efficiency by 5% through designing uncertainty-based acquisition functions.
- Characterized epistemic and aleatoric uncertainty using Monte Carlo dropout and minimized expected calibration error by calibrating network output using temperature scaling.
- Developed a visualization tool for users to easily interpret 3D object detection result and gain confidence in model output, using saliency and integrated gradient with Captum.

## INDUSTRIAL EXPERIENCE

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### Suncor Energy

*Production Engineer*

Calgary, Canada

Sept 2019 - Dec 2019

- Reduced unreachable underground oil field temperature prediction error by 30% through constructing a physics-based regression neural network, this led to 1.3 million dollar annual benefit.
- Enabled refinery system malfunction alert 1-3 days in advance with 83% precision using an autoencoder for anomaly detection in operating data with Keras.
- Automated tasks of calculating oil sample saturation level from lab pictures, with normalization for different lighting conditions using OpenCV.

**Petro-Canada Lubricants**  
*Process Engineer*

Mississauga, Canada  
Jan 2019 - Apr 2019

- Reduced plant power consumption by 12% through optimizing the plant controller operating functions based on the cost/benefit analysis.
- Predicted quality-control results with 90% accuracy by designing a greedy selection algorithm and optimized parameters using dynamic simulation in Python.

## PROJECTS

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### **Manufacturing Design of Gluten-Free Beer** - *Professor Christine Moresoli*

Developed a beer production model using fungal peptidase to produce beer with a gluten content  $< 20$  ppm for people with Celiac Disease, at a cost lower than commercially available gluten-reduced beer.

### **Robust Shortest Path** *Professor James Bookbinder*      [github.com/martinzwm/robust-shortest-path](https://github.com/martinzwm/robust-shortest-path)

Applied Benders decomposition to solve real-world shortest path problem, in which arc length is a random variable within an upper and lower bound.

### **Tetris.ai** - *Personal Project*

[github.com/martinzwm/tetris-ai](https://github.com/martinzwm/tetris-ai)

Trained an RL agent from raw pixels with Double Deep Q-Learning and Prioritized Experience Replay to achieve super-human performance in Tetris.

### **Path Planner** - *Personal Project*

[github.com/martinzwm/lane-detection](https://github.com/martinzwm/lane-detection)

Pipeline: Gaussian blur, Canny edge detection, RoI identification, Hough transform, Lane following / planning.

## SKILLS

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Languages:      Python, Java, C++, C, MATLAB, SQL  
Tools:            Docker, CPLEX, COMSOL, ROS, Simulink  
ML Libraries:    PyTorch, Tensorflow, Keras, Captum

## EXTRA CURRICULARS

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Champion of intramural hockey  
Assistant soccer coach for U15  
Intramural basketball  
Guitarist in a band  
Rock climbing