

Active Matter Lectures 1 & 2

- * Contents: Introduction to active matter and presentation of some background material (mathematical and conceptual tools).

Explain: lectures every week, 10:15 → 11:45
 Exam: oral exam (Format TBD)

- * What is active matter?

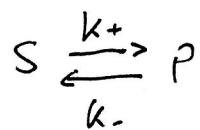
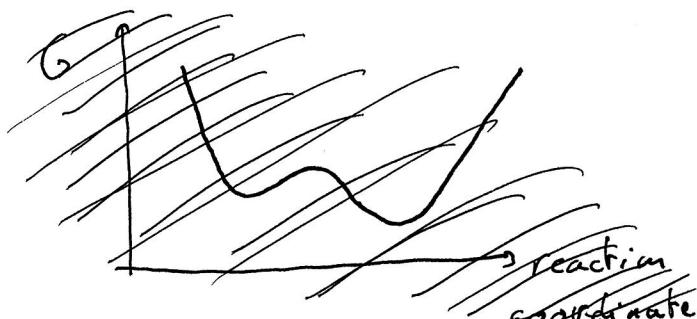
Commonly accepted definition: AM is made of elementary units composed able to locally dissipate energy in a continuous and sustained manner.

→ Dynamics of AP breaks TRS (far from eq.)

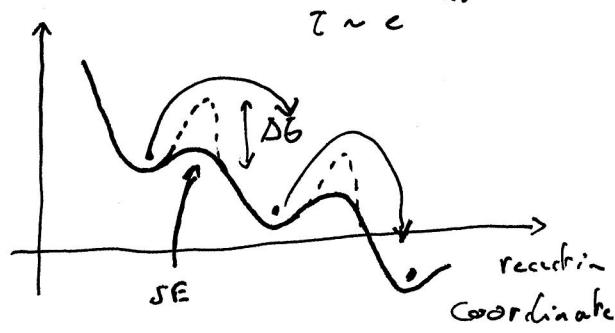
→ In many cases: activity = persistent motion, but can also be local production of forces, chemicals, or growth (reproduction), or several of them. Definition is very broad, includes multiple biological examples:

Enzymes fluctuations	Bacteria cells	Insect swarms	Bird flocks, sheep herds, human crowds.
10^{-9}	10^{-6}	10^{-3}	1 (m)

Enzymes = biological catalysts.



$$\frac{\Delta G}{k_B T}$$



(II)

→ E locally turn S into P → locally "produces" chemical currents

$$E + S \rightarrow \underbrace{SE}_{\text{Substrate}} \rightarrow EP$$

(Addressed in lectures)
7 & 8

binds to E.

→ Molecular motors: chemical cycle is coupled to displacement / rotations:

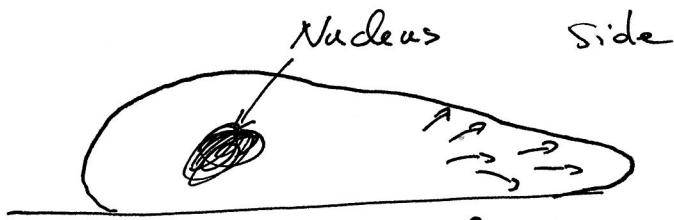


→ Bacteria / algae



Flagella powered by molecular motors.

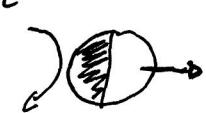
→ crawling cells (May be skip this part)



Actin polymerization
at the front.

* Why study active matter?

111

- Active matter is driven in bulk (at micro level), unlike passive systems (turbulent flows, granulars, etc...)
- Unique self-organization properties (creation of macro structures, self-assembly)
- Ideas relevant to many examples in the living world (architecture of cytoskeleton, morphogenesis, collective motion).
- Application (on the long run): design of bio-inspired materials - Large part of the field: synthetic active particles:

$$2\text{H}_2\text{O}_2 \rightarrow \text{H}_2\text{O} + \text{O}_2$$

(lecture 7)

* Equilibrium properties of AML systems (generally lack):

- Loss of memory
- TRS (global currents) (Forward / Backward movie)
- ~~No minimization principle~~ (dynamics does not converge to a state that minimizes a FE). SS generally unknown.
- Lack of thermodynamic framework: Basic concepts (T , P)

not defined in active matter
more complex

| δ action-react principle (L6)
"Exotic Forces"

→ Collectives properties of AM generally break intuition
based on Eq. 4.

L> Development of new tools, in particular to construct
field theory describing active systems: ~~Lectures~~
- IRR Thermodynamics (L4)
- Coarse-graining, kinetic theory (L5)

* Idea of this course:

→ AM is a (very) large and quickly growing field at
the interface of SM, GroC, hydro, statC. This course =
introduction to basic phenomenology of AM and how it
is usually approached.

→ Two important questions (still ~~partially~~ ^{actively} studied):

- How is active motion generated ? and csgs on the dynamics?
- Consequences of activity on the self-organizing
properties at macro-scale (Micro → Macro?)

* Hydrodynamics of active motion (Intro for L3) V

Flory active particles = swimmers.

Fluid obey NS eq:

$$\rho \left(\partial_t \underline{v} + (\underline{v} \cdot \nabla) \underline{v} \right) = \eta \nabla^2 \underline{v} - \nabla p + \underline{f}$$

pressure
 ↓
 —
 active force

$$\nabla \cdot \underline{v} = 0 \quad \text{Incompressibility}$$

$\textcircled{2} + \textcircled{1}$ = Inertia / convection

$\textcircled{3}$ = dissipation

Dimensional analysis: ~~Dimensional analysis~~

$$v \rightarrow V v$$



$x_B \rightarrow L x$ Typical velocity & length scales-

$$t \rightarrow T t \text{ with } T = \frac{L}{V}$$

$$p \rightarrow P p \text{ with } P = \frac{\eta V}{L}$$

$$f \rightarrow F f \text{ with } F = \frac{\eta V}{L^2}$$

$$\text{NS: } Re \left(\partial_t \underline{v} + (\underline{v} \cdot \nabla) \underline{v} \right) = \nabla^2 \underline{v} - \nabla p + \underline{f}$$

$$\frac{\rho V L}{\eta} \text{ Reynolds number}$$

$$\text{water: } \begin{cases} \rho = 10^3 \text{ kg/m}^3 \\ \eta = 10^{-3} \text{ Pa} \cdot \text{s} \end{cases}$$

$$\text{Bacteria (Ecoli): } V \approx 10 \mu\text{m} \cdot \text{s}^{-1} \\ L \approx 1 \mu\text{m}$$

$$\Rightarrow \boxed{Re \approx 10^{-5}}$$

⇒ Microswimmers move in the Stokes regime

IA

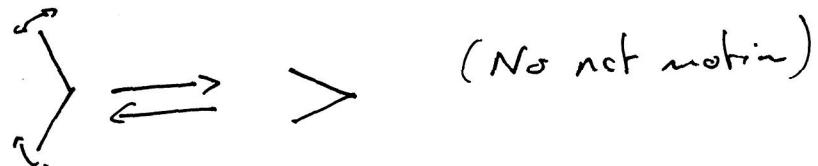
$$\left\{ \begin{array}{l} \nabla^2 \underline{\upsilon} - \nabla p + \underline{f} = 0 \\ \nabla \cdot \underline{\upsilon} = 0 \end{array} \right.$$

kinematically

→ Important consequence: Seq. are time-reversible:

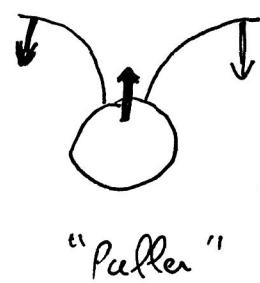
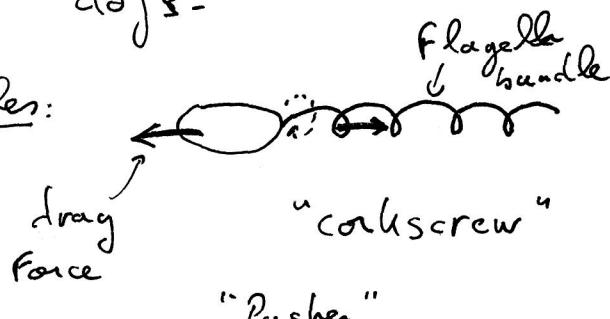
$$\boxed{\underline{f} \rightarrow -\underline{f} \Rightarrow \underline{\upsilon} \rightarrow -\underline{\upsilon}}$$

→ Scoleop theorem: Sp. cannot be achieved with reciprocal motion:



⇒ self-propulsion requires at least 2 independent dofs.

Examples:



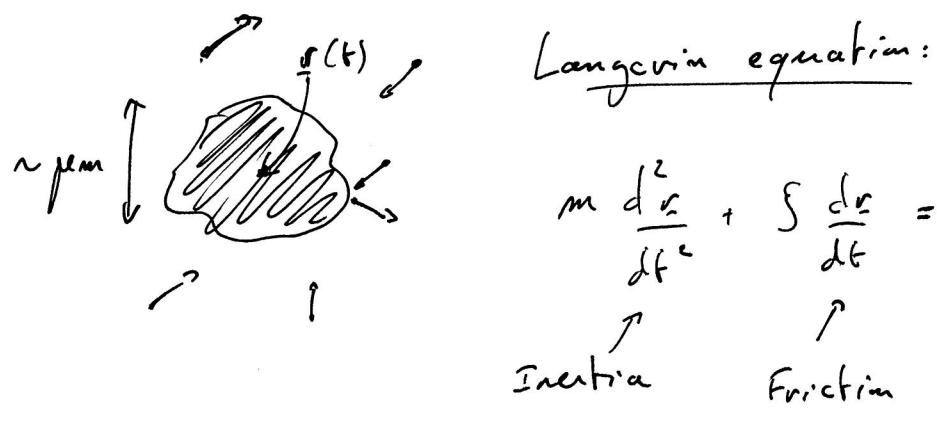
→ Swimmers are force and torque - free

* Complementary approach: minimal description of active motion

→ How do describe

→ How to describe the motion of a particle out-of-equilibrium?

→ start by simple example: Brownian motion



Def $\tau = \frac{m}{\zeta} \rightarrow 0$ (in general) → inertia can be neglected
(HW)

$$\zeta \sim 6\pi\eta d \sim 6\pi \cdot 10^3 \text{ Pa}\cdot\text{m}\cdot\text{s}$$

$$m \sim 10^{-15} \text{ kg}$$

$$\Rightarrow \tau \sim 10^{-17} \text{ s}$$

1 pg

$$\Rightarrow \left\{ \frac{d\vec{r}}{dt} = \frac{1}{\zeta} \vec{f}(t) \right\}$$

overdamped BR

(Law of Large Numbers) CLT

\vec{f} : independent random events → distribution approaches $N(0, \sigma)$

$$\Rightarrow \langle \vec{f}_i \rangle = 0 \quad \langle \vec{f}_i(t) \vec{f}_j(t') \rangle = 2D \underbrace{\delta(t-t')}_{S_{ij}}$$

No time correlations

$$\Rightarrow \vec{r}(t) - \vec{r}(0) = \int_0^t dt' \frac{1}{\zeta} \vec{f}(t')$$

$$\Rightarrow \langle \vec{r}(t) - \vec{r}(0) \rangle = 0 \quad \langle [\vec{r}(t) - \vec{r}(0)]^2 \rangle = \int_0^t dt_1 dt_2 2D \delta(t_1 - t_2) = 2Dt$$

- $\left\{ \begin{array}{l} \rightarrow \text{No mean motion} \\ \rightarrow \text{MSD is linear in time} \end{array} \right.$ Diffusion -

Distribution of \underline{r} : $P(\underline{x}, t) = \langle \delta(\underline{x} - \underline{r}(t)) \rangle$

obeys the FP equation: $\partial_t P - D \nabla^2 P = 0$

$$\Rightarrow P(\underline{x}, t) = \frac{e^{-\frac{\|\underline{x}\|^2}{4Dt}}}{(4\pi Dt)^{d/2}} \quad \text{assuming that } P(\underline{x}, t=0) = \delta(\underline{x})$$

* Active Brownian motion:

-> Langevin description is ~~also~~ not restricted to systems at equilibrium. Adding activity in a minimal way via a self-generated propulsion velocity:

$$\frac{d\underline{r}}{dt} = \underline{v}_a + \frac{1}{\zeta} \underline{f}(t)$$

↑ active velocity

-> Dynamics of \underline{v}_a ?

Ex: - R & T Robin



- smooth active motion (direct* of \underline{v}_a is diffusing in time)



- In practice, important parameter is the persistence length of the active motion l_p .

→ Dimensional analysis:

$$l_p = v_0 \tau_R$$

LIX

\uparrow Timescale associated
typical with tumblings /
speed decorrelation of spp direct

On scales: $\ll l_p$: ballistic motion with speed $\sim v_0$

$\gg l_p$: diffusive motion with diffusivity ?
effective

→ Minimal description $v_a = v_0 \hat{e}$
unit vector

$$\text{with } \langle \hat{e}(t) \cdot \hat{e}(t+\tau) \rangle = e^{-\tau/\tau_R}$$

Homework: in d=2 $\hat{e}(\theta) = (\cos \theta, \sin \theta)$

$$\frac{d\hat{e}}{dt} = \sqrt{2D_R} \gamma(t) \quad \text{with} \quad \langle \gamma(t) \gamma(t') \rangle = \delta(t-t') \\ \langle \gamma(t) \rangle = 0$$

Show that $\langle \hat{e}(\theta(t)) \cdot \hat{e}(\theta(t+\tau)) \rangle = e^{-\tau/\tau_R}$ with $\tau_R = \frac{1}{D_R}$

$$\Rightarrow \Delta r(t) = v_0 \int_0^t \hat{e}(\tau) d\tau + \frac{1}{2} \int_0^t d\tau f(\tau)$$

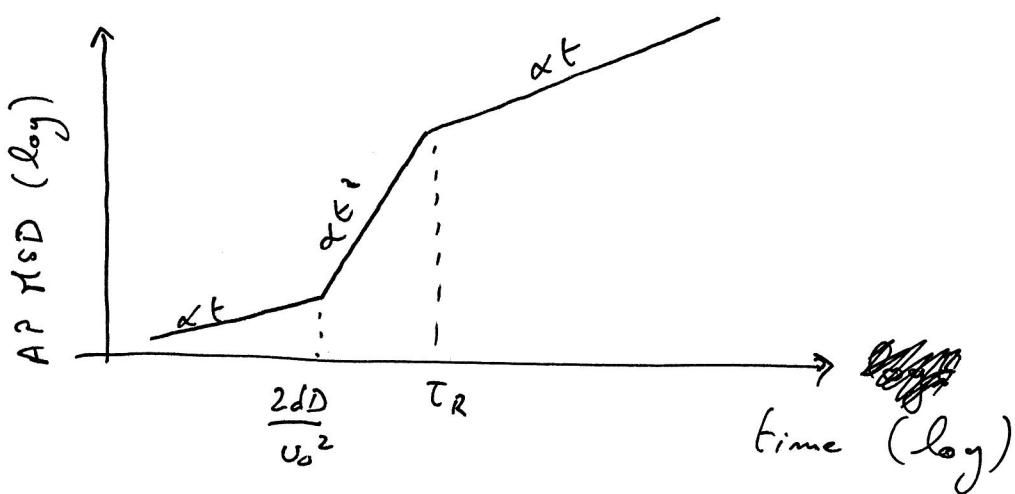
$$\Rightarrow \langle \Delta r^2(t) \rangle = 2D_R t + v_0^2 \int_0^t d\tau_1 \int_0^t d\tau_2 e^{-(|\tau_1 - \tau_2|/\tau_R)}$$

$$\langle \Delta r^2 \rangle = 2D_R t + 2 \frac{v_0^2 \tau_R^2}{l_p^2} \left(\frac{t}{\tau_R} - 1 + e^{-t/\tau_R} \right)$$

$$\left\{ \begin{array}{l} t \ll \tau_R : \langle \Delta r^2 \rangle \approx 2D_R t + v_0^2 t^2 \end{array} \right.$$

$$\left\{ \begin{array}{l} t \gg \tau_R : \langle \Delta r^2 \rangle \approx 2D_{\text{app}} t \quad D_{\text{app}} = D + \frac{v_0^2 \tau_R^2}{d} \quad (> D) \end{array} \right.$$

\boxed{x}



→ Recover same result from FP description?

$$\text{Focus on 2D: } \dot{\epsilon}(\theta) = \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix} \quad \frac{d\theta}{dt} = \sqrt{2D_{12}}$$

(Homework)

$$\text{Define: } P(x, \phi, t) = \langle \delta(x - r(F)) \delta(\phi - \theta(F)) \rangle \quad \text{HW}$$

$$FP: \partial_t P + \nabla \cdot (v_0 \dot{\epsilon}(\theta) P - D \nabla P) - \underbrace{\partial_{\theta} \partial_{\theta}}_{= D_{12}} P = 0$$

→ No simple analytical solution, but regime $t \gg \frac{1}{D_{12}} = \tau_R$
can be described by moment expansion (also very useful
for more complex situations)

$$\text{Define density: } \rho(r, t) = \int_0^{2\pi} d\theta P(r, \theta, t)$$

$$\Rightarrow \partial_t \rho + v_0 \nabla \cdot (\rho \dot{\epsilon}_f) - D \nabla^2 \rho = 0$$

$$\text{with } \dot{\epsilon}_f = \frac{1}{\rho} \int_0^{2\pi} d\theta \dot{\epsilon}(\theta) P(r, \theta, t) \quad \text{the mean orientation}$$

Equation for ρ_f ?

XI

$$\partial_t \rho_f = -\frac{v_0}{2} \nabla \rho - D_R \rho_f - v_0 \nabla \cdot (\rho \underline{Q}) + D \nabla^2 (\rho_f)$$

with $\rho \underline{Q}_{ij} = \int_0^{2\pi} d\theta \left[\hat{e}_i(\theta) \hat{e}_j(\theta) - \frac{1}{2} \delta_{ij} \right] \rho(r, \theta, t)$

Tensor
(Nematic order parameter)

ensure $\text{Tr}(Q) = 0$
(why?) HW

Eq. for Q will depend on $\langle e^3 \rangle$ etc...

↳ Need a closure relation: $\underline{Q} = 0$

↳ Express f as function of ρ

Write:

$$\partial_t \rho_f = -D_R \rho_f + A(r, t)$$

$$\begin{aligned} \Rightarrow \rho_f &= e^{-t D_R} \left[\rho_f(0) + \int_0^t e^{t' D_R} A(r, t') dt' \right] \\ &\stackrel{t \gg \frac{1}{D_R}}{\approx} \int_0^t dt' e^{-(t-t') D_R} A(r, t') \\ &\stackrel{\tau = t-t'}{\approx} \int_0^t d\tau e^{-\tau D_R} A(r, t-\tau) \\ &\approx \int_0^\infty d\tau e^{-\tau D_R} \left[A(r, t) - \tau \partial_\tau A(r, t) + \dots \right] \\ &\approx \frac{1}{D_R} A(r, t) \end{aligned}$$

If A does not vary much on a time scale $1/D_R$

$$\Rightarrow \boxed{\rho_f \approx -\frac{v_0}{2 D_R} \nabla \rho}$$

$$\Rightarrow \left[\partial_t \rho - D_{\text{eff}} \nabla^2 \rho = 0 \right]$$

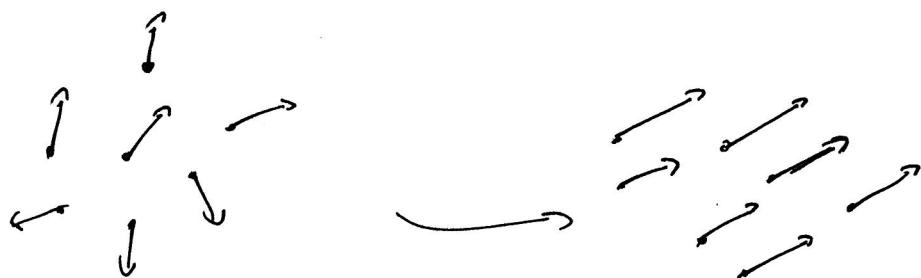
$$D_{\text{eff}} = D + \frac{v_0^2}{2 D_n}$$

\rightsquigarrow Equivalent to BM with diffusivity D_{eff}

- * Q transitions is a central concept in AM (Flocking),
in L2 review basics of QT and order from field
theory perspective-

* Q transitions: central concept in AM studies-

(> Example:



Flocking \leftrightarrow ordering transition

"like" ferromagnetism

"active paramagnet"

→ Here, review some basic features of the theories of Q transition at equilibrium, and introduce some tools that we will use for study later in the context of AF

* Important feature: Q transitions are associated with the notion of scale-invariance

(minimal example: the Ising model:

Sum of over all pairs
of nn.

N spins $s_i = \pm 1$ on a lattice, energy $E = -\frac{J}{2} \sum_{\langle i,j \rangle} s_i s_j$

(\hookrightarrow Simple MF analysis: Partition function $Z = \sum_{\{s_i\}} e^{-\beta E}$

~~SMW~~ Define order parameter $m = \frac{1}{N} \sum_i s_i$ (magnetization)

MF assumption: $s_i \approx m + \delta s_i$

$$\Rightarrow s_i s_j = m^2 + m(\delta s_i + \delta s_j) + O(\delta s^2) \approx m(s_i + s_j - m)$$

Rewrite: $E_{MF} \approx -\frac{Jm}{2} \sum_{\langle ij \rangle} (s_i, s_j - m)$

$$= -\frac{Jm}{2} \left[2z \sum_i s_i - mNz \right]$$

$z = \# \text{ neighbors}/\text{site}$
 $= \text{coordination number}$
of the lattice

$$\Rightarrow Z_{MF} = \sum_{\{s_i\}} e^{\beta \frac{Jm^2}{2} \left[2 \sum_i s_i - mN \right]}$$

$$= e^{-\beta \frac{Jm^2 N z}{2}} \left(\sum_{s_i = \pm 1} e^{\beta Jm z s_i} \right)^N$$

$$Z_{MF} \approx e^{-\beta N \frac{Jm^2 z}{2}} (2 \cosh(\beta Jm z))^N$$

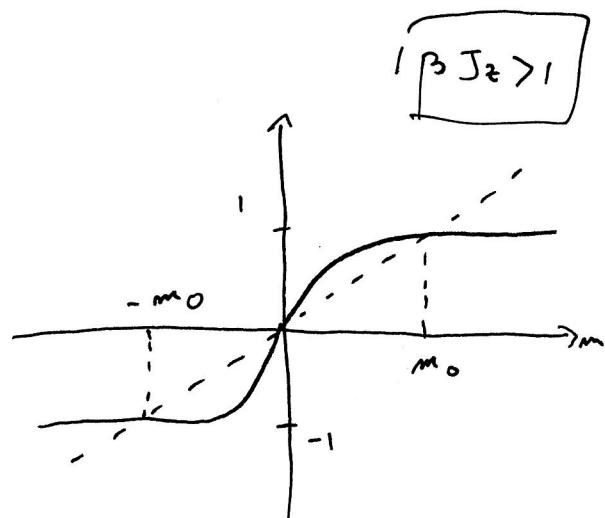
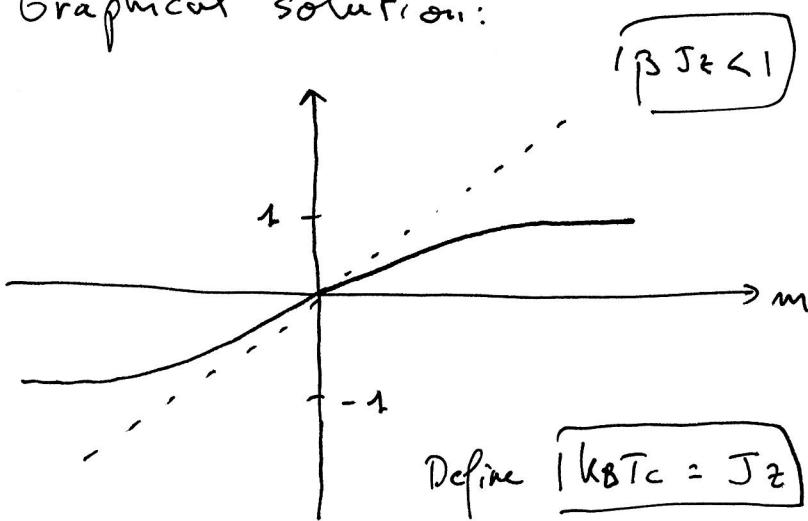
Free energy: $F_{MF} = -k_B T \ln Z_{MF}$

$$= N k_B T \left(\beta \frac{Jm^2 z}{2} - \ln (\cosh(\beta Jm z)) \right)$$

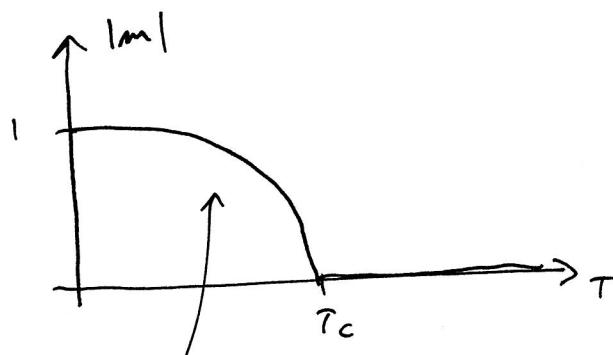
Minimization:

$$\frac{\partial F_{MF}}{\partial m} = 0 \Leftrightarrow \boxed{m - \tanh(\beta Jm z) = 0}$$

Graphical solution:



Phase transition at a finite temperature T_c
at which the system becomes ordered-



$m = \pm m_0$ (symmetry of the FE is spontaneously broken)

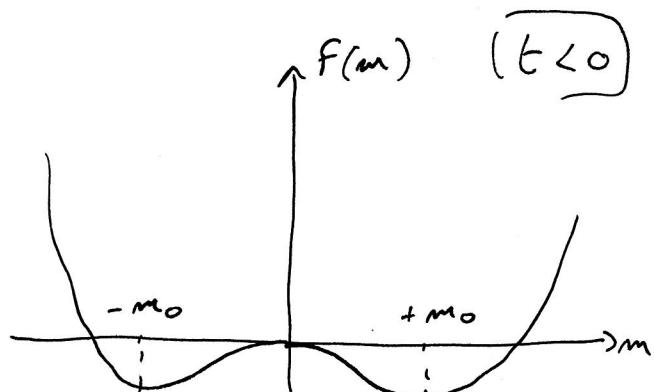
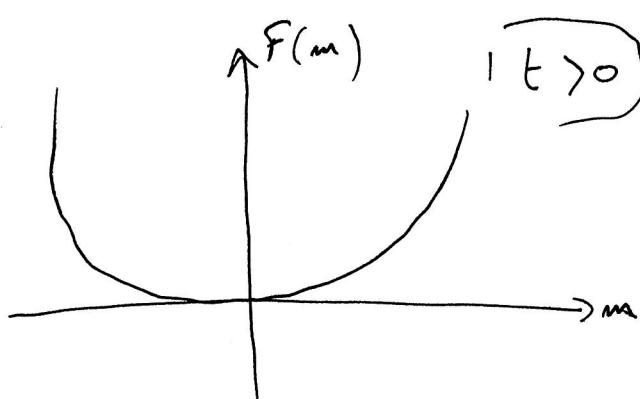
Expand the free energy at $T \approx T_c$ (m small):

$$F_{\text{HF}} \approx Nk_B T \left[\frac{T_c m^2}{T^2} - \ln \left(\cosh \left(\frac{m T_c}{T} \right) \right) \right]$$

$$\boxed{F_{\text{HF}} \underset{m \rightarrow 0}{\approx} \frac{Nk_B T_c}{2} \left[\left(\frac{T-T_c}{T} \right) m^2 + \left(\frac{T_c}{T} \right)^3 \frac{m^4}{6} + \mathcal{O}(m^6) \right]}$$

\hookrightarrow London free energy -

Define $t = \frac{T-T_c}{T_c}$



→ Include spatial dynamics -

$$F[m] = \int d\mathbf{r} \left(f(m) + \frac{K}{2} |\nabla m|^2 \right)$$

$\boxed{\begin{array}{l} \text{Ginzburg-Landau} \\ \text{free energy} \end{array}}$

[cost of interface]

term is invariant by rotations
and under $m \rightarrow -m$ as allowed
by the symmetries of the dynamics -

take $T \approx T_c$

$$\Rightarrow f(m) = \alpha t \frac{m^2}{2} + \beta \frac{m^4}{4}$$

$$\begin{cases} \alpha \approx Nk_B T_c \\ \beta \approx \frac{Nk_B T_c}{3} \approx \frac{\alpha}{3} \end{cases}$$

"bulk free energy density"

Dynamical equation for m ?

$$\frac{\partial m}{\partial t} = -\frac{\delta F}{\delta m} = -(\alpha t + \beta m^2)m + K \nabla^2 m$$

Steady-state homogeneous solution: $(\alpha t + \beta m_0^2)m_0 = 0$

$$\Rightarrow \begin{cases} m_0 = 0 \quad (t > 0) \\ m_0 = \sqrt{-\frac{\alpha t}{\beta}} \quad (t < 0) \end{cases}$$

Behavior of m in response to fluctuations?

write $m = m_0 + \delta m$ and study the dynamics of δm
at linear ~~order~~ ^{2nd} order.

$$\frac{\partial \delta_m}{\partial t} = -v^2 \delta_m + K \nabla^2 \delta_m + \xi(\underline{x}, t)$$

$$v^2 = \begin{cases} \alpha t & t \geq 0 \\ -2\alpha t & t < 0 \end{cases} \quad (>0)$$

ξ is a GWN satisfying $\langle \xi \rangle = 0$

$$\langle \xi(\underline{x}, t) \xi(\underline{x}', t') \rangle = \Xi \delta^d(\underline{x} - \underline{x}') \delta(t - t')$$

→ In Fourier space: $\hat{\delta}_m(\underline{q}, \omega) = \int d^d \underline{r} dt e^{i \underline{q} \cdot \underline{r} + i \omega t} \delta_m(\underline{r}, t)$

$$\Rightarrow (i\omega + \cancel{K q^2} + K q^2) \hat{\delta}_m(\underline{q}, \omega) = \hat{\xi}_{\underline{q}, \omega}$$

$$\text{with } \langle \hat{\xi}_{\underline{q}, \omega} \hat{\xi}_{\underline{q}', \omega'} \rangle = \cancel{(2\pi)^{d+1}} \delta(\omega + \omega') \delta^d(\underline{q} + \underline{q}')$$

Fourier transform of the two-point correlation function:

$$\hat{C}_{\underline{q}, \omega} = \frac{\langle \hat{\delta}_m(\underline{q}, \omega) \hat{\delta}_m(-\underline{q}, -\omega) \rangle}{(2\pi)^{d+1} \delta(\omega + \omega') \delta^d(\underline{q} + \underline{q}')}$$

$$= \frac{\Xi}{\omega^2 + (v^2 + K q^2)^2}$$

Equal-time correlation: $\hat{C}_q = \int \frac{d\omega}{2\pi} \hat{C}_{\underline{q}, \omega} = \frac{\Xi}{2(v^2 + K q^2)}$

$$\Rightarrow C(\underline{r}) = \langle \delta_m(0) \delta_m(\underline{r}) \rangle = \frac{\Xi}{2K} \int \frac{d^d \underline{q}}{(2\pi)^d} \frac{e^{-i \underline{q} \cdot \underline{r}}}{\Xi^2 + q^2}$$

Correlation length:

$$\xi = \sqrt{\frac{k}{\nu^2}}$$

~ Limits of the integral:

$$\left\{ \begin{array}{l} C(r) \sim \frac{e^{-r/\xi}}{r^{(d-1)/2}} \\ r \gg \xi \\ r \ll \xi \end{array} \right.$$

When

Case 1: $\xi \sim |t|^{-1/2}$ is finite \Rightarrow spins are correlated over a typical scale $\sim \xi$.

As $t \rightarrow 0$, $\xi \rightarrow +\infty$ and the behavior of the system becomes scale free.

~ At the CP, the physics is independent of the microscopic details of the dynamics; all the large scale behavior of the system is set by the CL which can be arbitrarily long -

↳ Ideas at the root of the concept of universality: physics at a CP only depends on fundamental characteristics like symmetry, conservation laws & dimensionality -

→ CP is characterized by a set of critical exponents:

$$\text{Ex: } |m_0| \sim |t|^{\beta}, \quad \xi \sim |t|^{-\nu}, \quad C(r) \sim r^{-(d-2+\gamma)}.$$

↳ BUT: MF predictions are generally incorrect (because we have neglected nonlinearities in the equations). Here, MF breaks down for all $d < d_c = 4$

Cupper critical dimension

Ising Model:

d	2	3	> 4
β	$1/8$	$0,3264$	$1/2$
ν	1	$0,6300$	$1/2$
γ	$1/4$	$0,0363$	0
	Exact	Numerics	MF

Beyond MF: use RG

→ Similar ideas hold for systems out of equilibrium (when scale-free behavior is present) → motivate classification of active systems in terms of their symmetries -

→ Spins with continuous orientation



$$\text{Vector magnetization: } \underline{m} = \frac{1}{N} \left(\sum_i \underline{s}_i \right) \quad E = -\frac{J}{2} \sum_{\langle ij \rangle} s_i \cdot s_j$$

$$\text{GL free energy: } F = \int d^d r \quad t \frac{|m|^2}{2} + \frac{|m|^4}{4} + \frac{K}{2} \underbrace{|\nabla m|^2}_{(\nabla_\alpha m_\beta) \nabla_\alpha m_\beta}$$

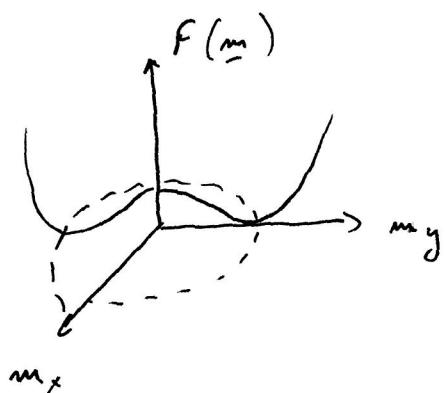
$$(\nabla_\alpha m_\beta) \nabla_\alpha m_\beta$$

Some procedure:

XX

$$\frac{\partial \underline{m}}{\partial t} = - (t + |\underline{m}|^2) \underline{m} + K \nabla^2 \underline{m}$$

SS sol: $|\underline{m}|^2 = \begin{cases} 0 & t > 0 \\ -t & t < 0 \end{cases} = m_0^2$



$$\hookrightarrow \underline{m} = m_0 \hat{u}_{\parallel}$$

⇒ spontaneous symmetry breaking -

Write: $\underline{m} = (m_0 + \delta m_{\parallel}) \hat{u}_{\parallel} + \delta m_{\perp} \hat{u}_{\perp}$ with $\delta m_{\perp} \cdot \hat{u}_{\parallel} = 0$

and focus on the ordered phase: $m_0 > 0 \quad (t < 0)$

$$\Rightarrow \begin{cases} \frac{\partial \delta m_{\parallel}}{\partial t} = +2t \delta m_{\parallel} + K \nabla^2 \delta m_{\parallel} + \xi_a(r, t) \\ \frac{\partial \delta m_{\perp}}{\partial t} = K \nabla^2 \delta m_{\perp} + \xi_L(r, t) \end{cases} \quad (\text{At linear order})$$

$\Rightarrow \delta m_{\parallel}$ follows a similar equation as for the Ising model

with $\xi = \sqrt{\frac{K}{-2t}}$, while $\boxed{\text{for } \delta m_{\perp} \quad \xi = 0}$!!

δm_{\perp} is a Goldstone mode (massless) \rightarrow results from spontaneous symmetry breaking (No energetic cost associated with global rotation of the system).

Also implies that

$$\hat{C}_{\perp q} = \frac{\gamma_{\perp}(d-1)}{2kq^2} \quad \overbrace{\quad \quad \quad}^{\# \perp \text{ components}}$$

$$\Rightarrow \underbrace{\langle |\delta m_+(r)|^2 \rangle}_{\substack{\text{typical amplitude} \\ \text{of fluctuations}}} = \int \frac{d^d q}{(2a)^d} \hat{C}_{\perp q}$$

$$\propto \int_{L/a}^{L/a} dq \quad q^{d-3} \sim \begin{cases} L^{2-d} & d < 2 \\ \ln(L/a) & d = 2 \\ a^{2-d} & d > 2 \end{cases}$$

\Rightarrow Fluctuations diverge in all $d < 2 \rightarrow$ no long-range order is possible . Herrin - Wagner theorem