## Classical Mechanics TFY4345 - Exercise 1

#### 1. Halley's comet - conservation of angular momentum

Halley's comet follows an elliptical orbit around the Sun, with a period of about 76 years. The Sun is a focal point of the ellipse. The closest distance between the comet and the Sun is 0.6 AU, and the farthest distance is 35AU. (1AU = mean distance between the Sun and the earth)

Use the sun as origin in your coordinate system.

- (a) Explain why the net torque on Halley's comet is zero. This implies that the angular momentum is conserved.
- (b) When the comet is closest to the Sun, it's velocity is measured to be 54km/s. Use conservation of angular momentum to calculate the velocity when the comet is farthest from the Sun.

### 2. Simple Pendulum

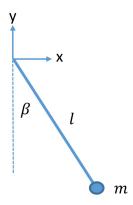


Figure 1: Simple pendulum: a mass m suspended in a massless cord. l is the distance between the pivot point and the center of the mass m.  $\beta$  is the angle between the y-axis and the cord.

Consider a simple pendulum subject to a uniform gravitational field  $\vec{g} = -g\vec{e_y}$ . Choose the pivot point as origin of your coordinate system. There are no friction forces.

- (a) Show that the position vector of the mass m is:  $\vec{R} = l \sin(\beta) \vec{e}_x l \cos(\beta) \vec{e}_y$
- (b) Find the potential energy of the mass, as a function of the angle  $\beta$ .
- (c) Find the kinetic energy of the mass, as a function of  $\beta$  and  $\dot{\beta} = \frac{d\beta}{dt}$
- (d) The Lagrangian of the pendulum is L = T V. Use Lagrange's equations to obtain the equation of motion for the pendulum.

#### 3. Double Pendulum

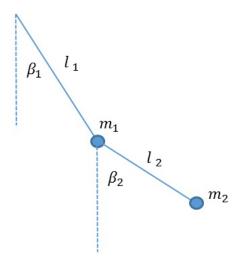


Figure 2: Double pendulum

(a) Find the Lagrangian L=T-V for the coplanar double pendulum in a uniform gravitational field. Choose the angles  $\beta_1$  and  $\beta_2$  as coordinates.

(b Obtain the equations of motion using Lagrange's equations.

For one more assignment, see the next page!

<sup>&</sup>lt;sup>1</sup>coplanar objects = objects in the same plane

# 4. Show by direct substitution that

$$L'(q,\dot{q},t) = L(q,\dot{q},t) + rac{dF(q,t)}{dt}$$

where F is an arbitrary function and leads to the same Lagrangian equation as  $L(q,q^{\cdot},t)$ .

**Hint:** Start from the Lagrange's equation and use the chain rule for partial derivatives for the function *F*.