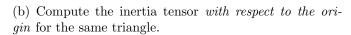
# Exercise 8 - TFY4345 Classical Mechanics

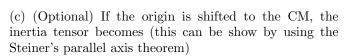
#### 2020

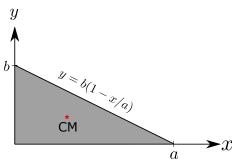
### 1 Principal moments of inertia of a triangular slab

(Exam Aug. 2019)

(a) Compute the center-of-mass (CM) for the planar triangle in the figure, assuming it to be of uniform two-dimensional mass density  $\rho$ .







$$I_{CM} = \begin{pmatrix} I_{11} & I_{12} & 0 \\ I_{21} & I_{22} & 0 \\ 0 & 0 & I_{33} \end{pmatrix} = \frac{M}{18} \begin{pmatrix} b^2 & \frac{1}{2}ab & 0 \\ \frac{1}{2}ab & a^2 & 0 \\ 0 & 0 & a^2 + b^2 \end{pmatrix}$$

where  $I_{xy}=I_{yx}$  and  $I_{xx}+I_{yy}=I_{zz}$  in the general form show first. Define next

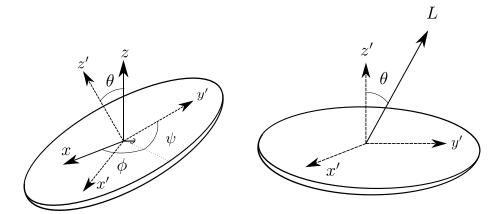
$$A = \frac{1}{2}(I_{xx} + I_{yy}), \quad B = \sqrt{\frac{1}{4}(I_{xx} - I_{yy})^2 + I_{xy}^2}, \quad \vartheta = \tan^{-1}\left(\frac{2I_{xy}}{I_{xx} - I_{yy}}\right).$$

Derive the principal moments of inertia and the principal axes by using the general form of the inertia tensor, and these new variables. [Hint] The last equations comprises a relationship that can be described by a right triangle.

#### 2 Precession of a frisbee

(Exam Aug. 2016)

Consider an axial-symmetric body with the principal moments of inertia  $I_1 = I_2 \neq I_3$ , rotating with angular momentum  $\mathbf{L} = L\mathbf{e}_z$  in the laboratory frame. (The unmarked coordinate system.)



- (a) Derive the equations of motion for the body, using the Euler equations and the angles  $\theta, \psi$  and  $\phi$ . Find the components of  $\omega$  in the body system. (See lecture notes, we derived this already!)
- (b) Find the expression for the Euler angles  $\dot{\theta}, \dot{\psi}, \dot{\phi}$  as a function of  $I_i, L, \theta$ .
- (c) Assume  $I_3 = 2I_1$ . The precession (wobble) of the frisbee is given by  $\dot{\phi}$ . Show that the precession is twice as fast as the rotation frequency of the frisbee, assuming that  $\theta$  is small (i.e. that  $\cos(\theta) \approx 1$ ).

## 3 Precession of a heavy spinning top

(Based on example p. 208-223 in Goldstein 3rd. ed., p. 70-74 in the compendium) In the example we define the shifted energy as

$$E' = \frac{1}{2}I_1\dot{\theta}^2 + V(\theta), \quad V(\theta) = \frac{(p_\phi - p_\psi \cos(\theta))^2}{2I_1 \sin^2(\theta)} + Mgh\cos(\theta),$$

which is a constant of motion. We also found the constants of motion

$$p_{\psi} = I_3(\dot{\phi}\cos(\theta) + \dot{\psi}) = I_3\omega_3, \quad p_{\phi} = (I_1\sin^2(\theta) + I_3\cos^2(\theta))\dot{\phi} + I_3\dot{\psi}\cos(\theta).$$

 $\theta_0$  was defined to be the constant angle of inclination of spinning top with regular precession. This means that the symmetry axis rotates around the z at a fixed angle  $\theta_0$ . Consider the shape of the effective potential  $V(\theta)$  at  $\theta_0$ . What is the condition for the spinning top to stay at a constant angle  $\theta_0$ ? Think back to our treatment of orbits. The following change of variables will come in handy for the result:

$$\beta = p_{\phi} - p_{\psi} \cos(\theta_0) = I_1 \sin^2(\theta_0) \dot{\phi}_0$$

You will encounter a quadratic equation for  $\beta$ . Show that for the equilibrium precession inclination angle  $\theta_0$ , the following must hold true:

$$\omega_3 \ge \frac{2}{I_3} \sqrt{MghI_1\cos(\theta_0)}.$$

What can you say about the corresponding precession angular velocity  $\dot{\phi}_0$ ? Express  $\dot{\phi}_0$  when  $\omega_3 \gg \frac{2}{I_3} \sqrt{MghI_1\cos(\theta_0)}$