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A pair of black-rimmed glasses is centered in the frame. The lenses reflect a vibrant, stylized cityscape with various buildings and greenery. The background of the slide is a dark, blurred image of a city at night.

# Panoptic FPN

Presented By:  
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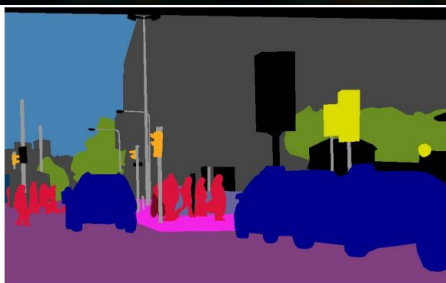
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# What is panoptic segmentation?

“including **everything** visible in one view”



(a) image



(b) semantic segmentation

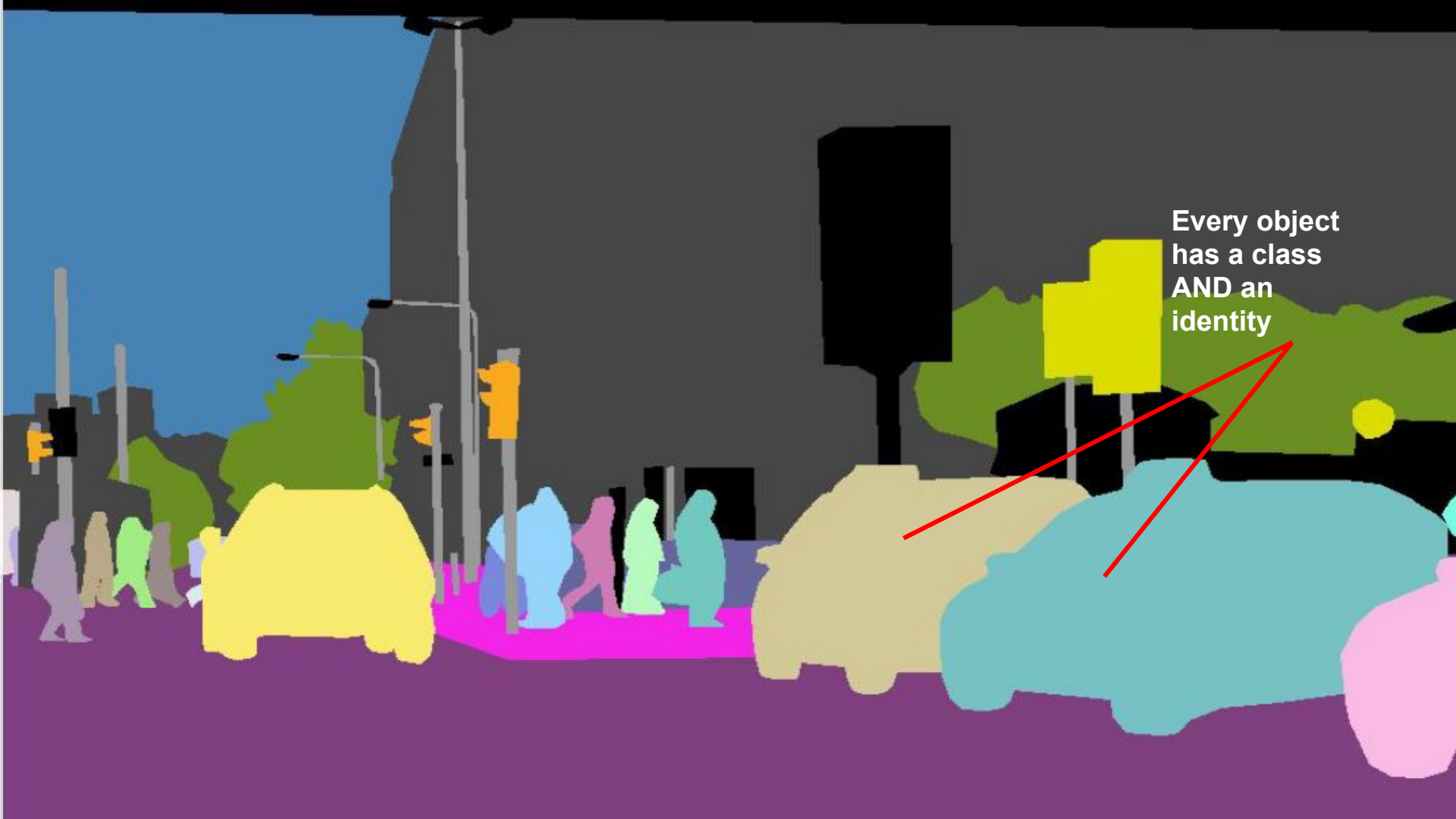


(c) instance segmentation



(d) panoptic segmentation

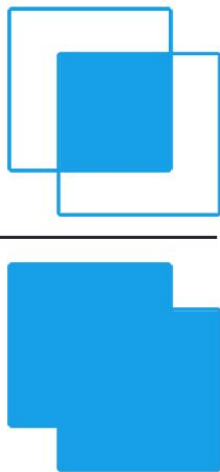
Every object  
has a class  
AND an  
identity



# Panoptic Segmentation Metric

"...existing metrics are specialized for **either** semantic or instance segmentation and **cannot** be used to evaluate the joint task involving both..."

$$\text{IoU} = \frac{\text{Area of Overlap}}{\text{Area of Union}}$$



## PREDICTIVE VALUES

POSITIVE (1)    NEGATIVE (0)

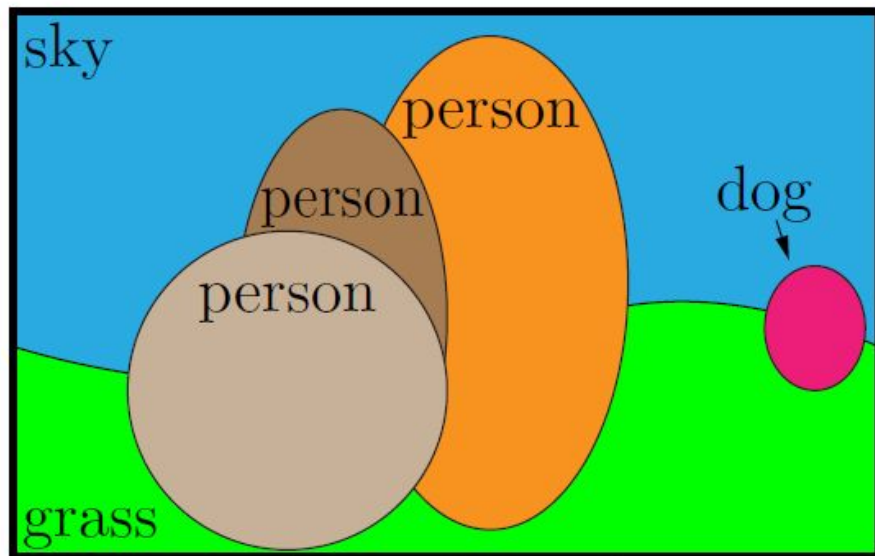
ACTUAL VALUES	POSITIVE (1)	TP	FN
	NEGATIVE (0)	FP	TN

**$\text{IoU} > 0.5 = \text{Match}$**

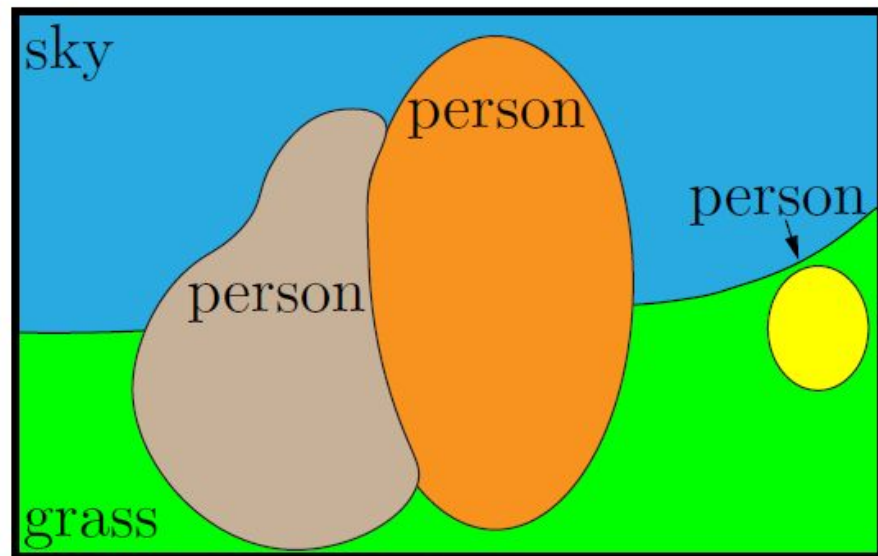
$$\text{PQ} = \underbrace{\frac{\sum_{(p,g) \in TP} \text{IoU}(p,g)}{|TP|}}_{\text{segmentation quality (SQ)}} \times$$

$$\underbrace{\frac{|TP|}{|TP| + \frac{1}{2}|FP| + \frac{1}{2}|FN|}}_{\text{recognition quality (RQ)}}$$






p = predicted segment  
g = ground truth segment



Ground Truth



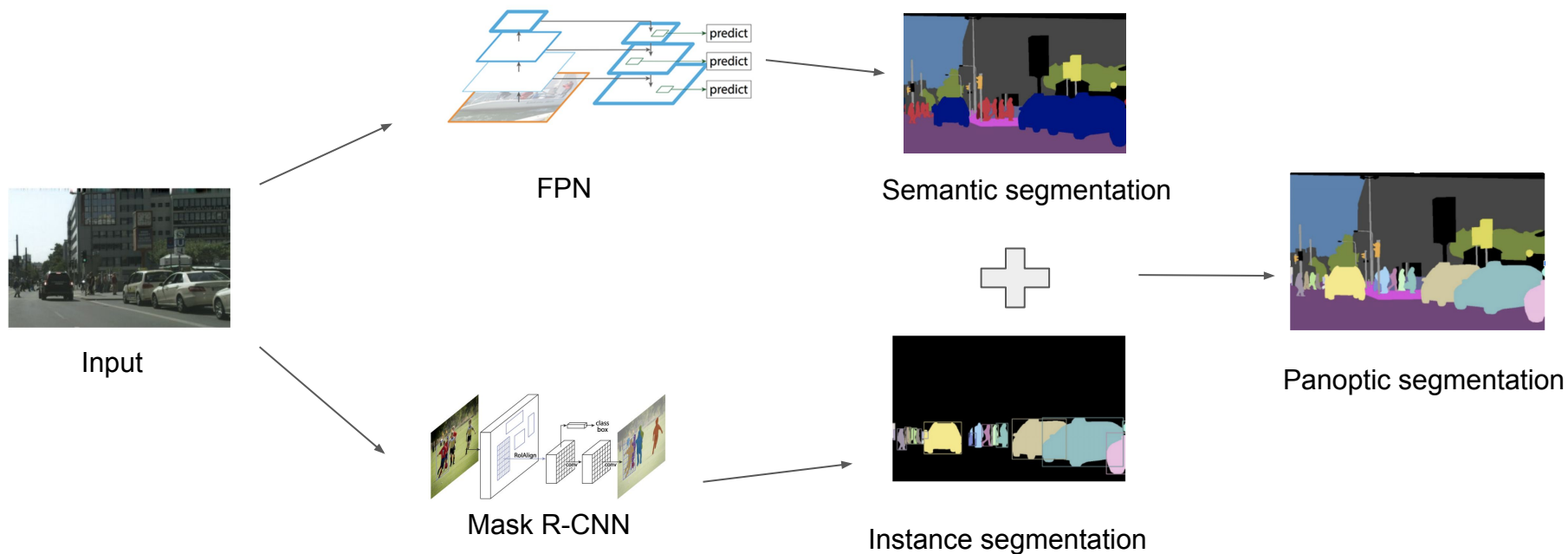
Prediction

Person — TP: {  ,  }; FN: {  }; FP: {  }

# Contribution of Panoptic FPN

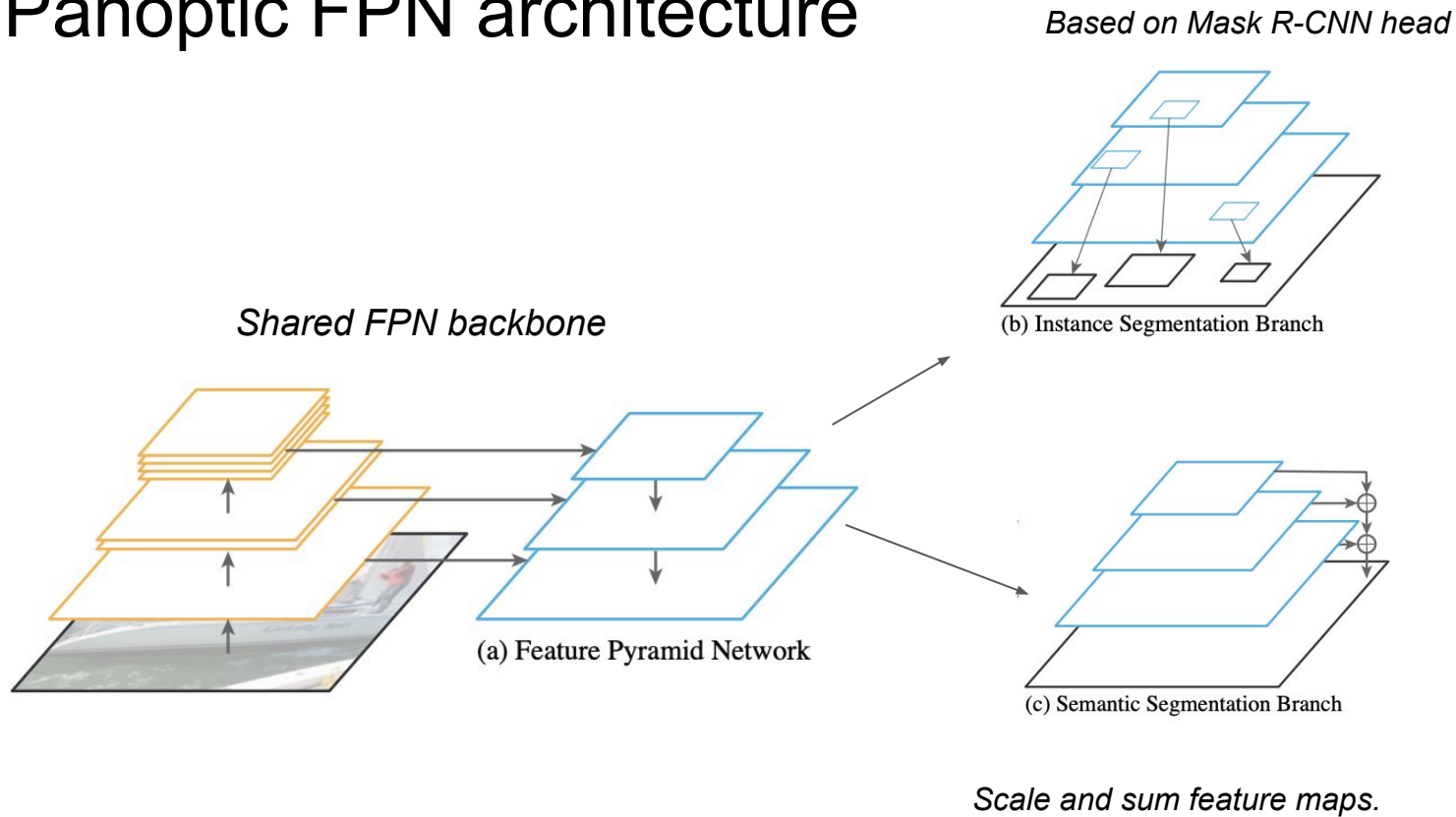
- Previous approaches used separate networks:
  - One for instance segmentation
  - One for semantic segmentation.
- Panoptic FPN uses a single network.
- Increased efficiency and memory footprint.
- Established a baseline performance for future work.

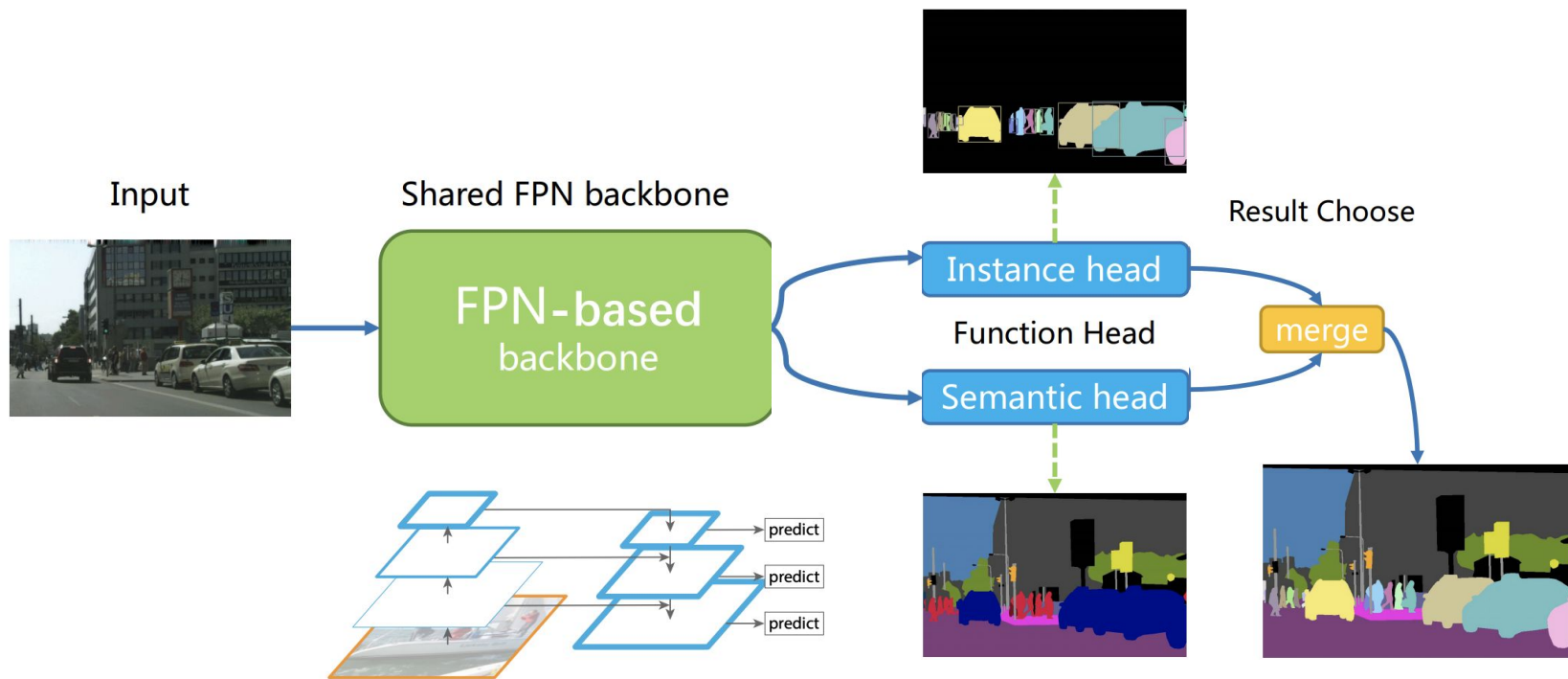
# Inefficient approach: Semantic + instance = Panoptic





# Panoptic FPN architecture





Source: <http://presentations.cocodataset.org/ECCV18/COCO18-Panoptic-Caribbean.pdf>

# Results: some example output



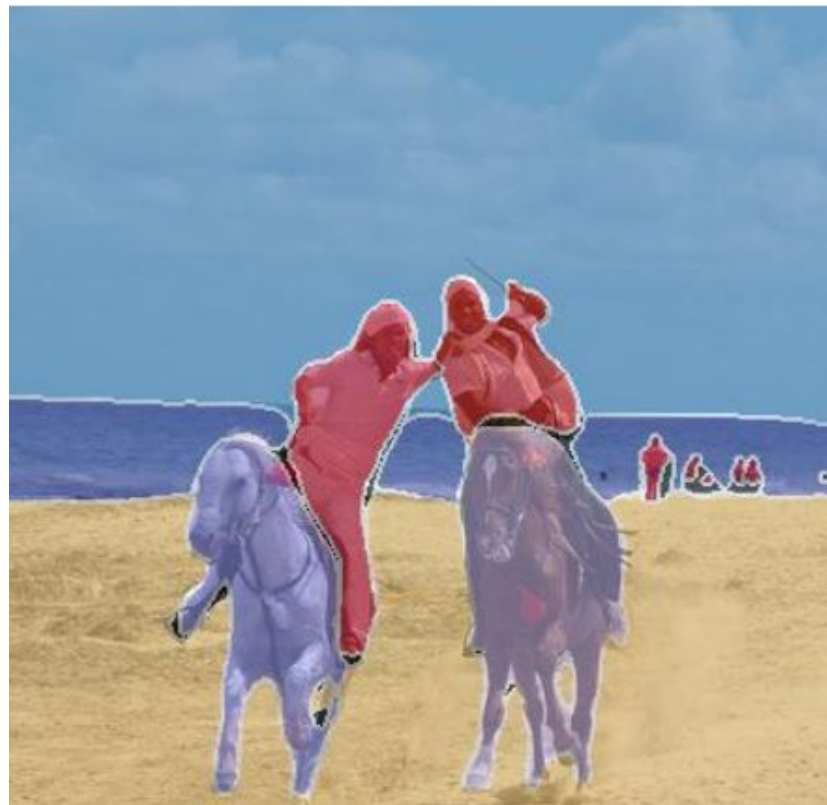
# Results: the metric values

Loss:  $\lambda_s \text{Loss}_s + \lambda_i \text{Loss}_i$

Scaling of the individual losses:

- Semantic seg. loss with  $\lambda_s$
- Instance seg. loss with  $\lambda_i$

The following results use the optimal  $\lambda_s$  and  $\lambda_i$  from the set  $\{0.5, 0.75, 1.0\}$



## Results: Two FPN networks VS combined

	backbone	AP	PQ <sup>Th</sup>	mIoU	PQ <sup>St</sup>	PQ
COCO	R50-FPN $\times 2$	33.9	46.6	40.2	27.9	39.2
	R101-FPN	35.2	47.5	42.1	29.5	40.3
		+1.3	+0.9	+1.9	+1.6	+1.1
Cityscapes	R50-FPN $\times 2$	32.2	51.3	74.5	62.4	57.7
	R101-FPN	33.0	52.0	75.7	62.5	58.1
		+0.8	+0.7	+1.3	+0.1	+0.4

(b) **Panoptic Segmentation: Panoptic R101-FPN vs. R50-FPN $\times 2$ .**  
*Given a roughly equal computational budget, a single FPN network for the panoptic task outperforms two independent FPN networks for instance and semantic segmentation by a healthy margin.*



## Results: COCO + Cityscapes panoptic (as of 2018)\*

	coarse	PQ	PQ <sup>Th</sup>	PQ <sup>St</sup>	mIoU	AP
DIN [1, 34]	✓	53.8	42.5	62.1	<b>80.1</b>	28.6
Panoptic FPN		<b>58.1</b>	<b>52.0</b>	<b>62.5</b>	75.7	<b>33.0</b>

(b) **Panoptic Segmentation on Cityscapes.** For Cityscapes, there is no public leaderboard for panoptic segmentation at this time.

see <http://cocodataset.org/#panoptic-leaderboard>).

\*Single-network entries only

# Summarized: Main contributions of Panoptic FPN

- A single network:
  - A common Feature Pyramid Network (FPN)
  - Mask R-CNN (instance segmentation)  
+ branch with semantic segmentation
- State-of-the-art performance in both instance- and semantic segmentation, with **only ~0.5x computing resources** compared to multi-network
- Outperforms all *single-model* entries in the 2018 COCO Panoptic Segmentation Challenge
- A good baseline for the panoptic segmentation task

# References

- [Panoptic Feature Pyramid Networks](#)
- [CVPR 2019 Oral Session 2-2A: Recognition](#)
- [Feature Pyramid Networks for Object Detection](#)
- [Panoptic Segmentation](#)