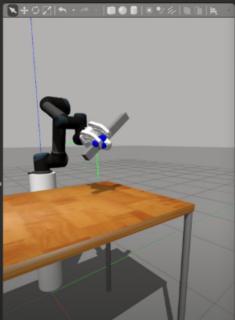


Value



```
@ □ □ inmo@inmo-workstation: ~
                inmo@inmo-workstation: ~ 57x35
Position Control: (NR: Increment = 0.61 (m))
    - Up/Down (z-axis): t / q
Orientation Control: (NB: Increment = pi/50 (rad))
    - Boll Left/Right: a / d
Pose Command : 1, 2
Reading from the keyboard and Publishing to move URS!
Position Control: (NB: Increment = 0.01 (m))
     Forward/Backware/Left/Right (x-y-axis): u / i / h
Orientation Control: (NB: Increment = pi/50 (rad))
     Pitch Up/Down : w / s
Pose Connand : 1, 2
anything else : stop or CTRL-C to quit
Anome/inmo/catkin ws/src/rain/rain gazebo/faunch/ur5 robotig.lau
[ INFO] [1538565461,385548173, 176,3968888888]; gazebo
 control plugin is waiting for model URDF in parameter
 [ INFO| [1538565461.445235506. 176.396000000]: Loaded or
```

[spawn gazebo model-4] process has finished cleanly log file: /home/inno/.ros/log/eetabd4c-c6fd-lle8-9215-e0 f432900f5/spawn gazebo model-4*.log

[INFO] [1538565461.498499718, 176.426000080]: waitForSe