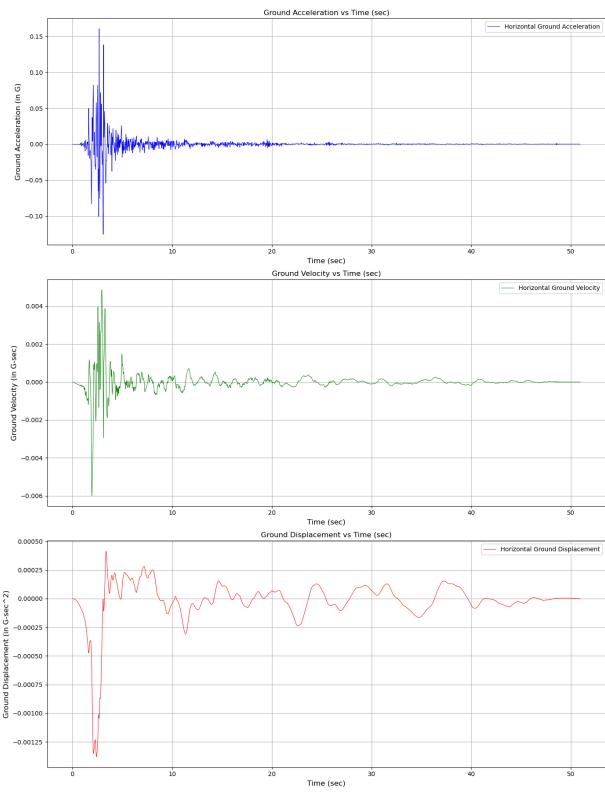
```
In [1]: import numpy as np
          import pandas as pd
          import matplotlib.pyplot as plt
          from scipy.integrate import cumtrapz
 In [ ]:
 In [9]: df_1 = pd.read_csv('Helena _180_.csv')
          df_1.head()
 Out[9]:
              delta t (sec) Ground Acceleration (in G)
          0
                     0.01
                                           -0.000210
           1
                     0.02
                                           -0.000211
          2
                     0.03
                                           -0.000212
                     0.04
                                           -0.000213
          3
          4
                     0.05
                                           -0.000214
In [10]: df_2 = pd.read_csv('Helena_down_.csv')
          df_2.head()
Out[10]:
              delta t (sec) Ground Acceleration (in G)
          0
                     0.01
                                           -0.000172
                     0.02
                                           -0.000171
          2
                     0.03
                                           -0.000170
                     0.04
          3
                                           -0.000168
          4
                     0.05
                                           -0.000167
```

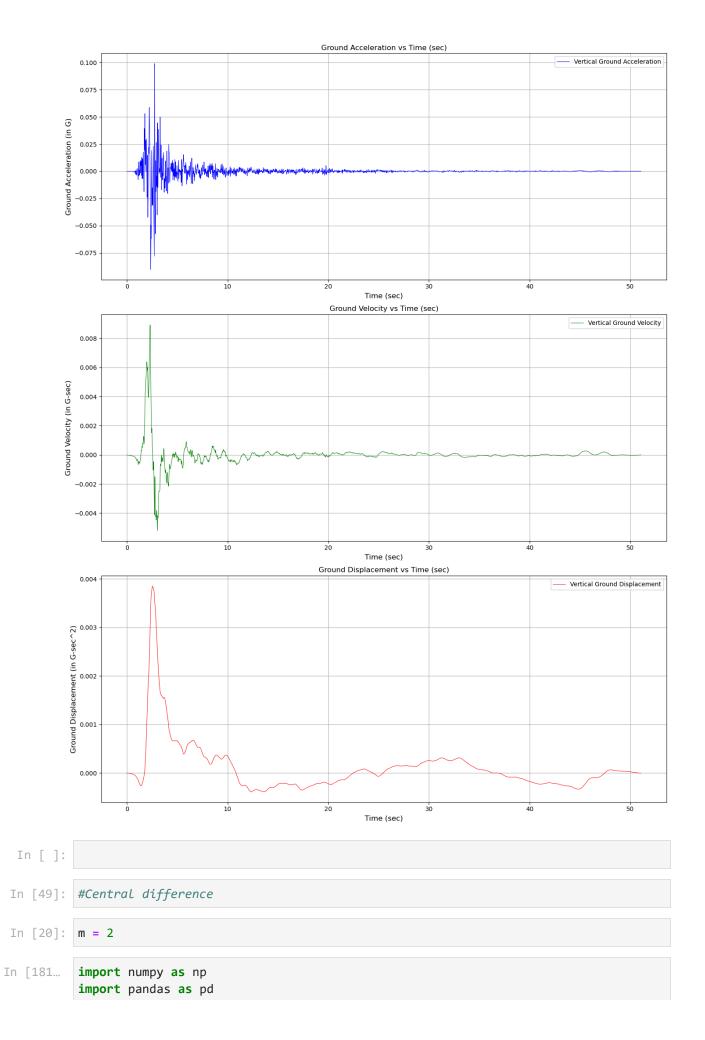
plot of ground aceleration versus time

```
In []: plt.figure(figsize=(14, 8))
In [11]: df_1.shape,df_2.shape
Out[11]: ((5093, 2), (5106, 2))
In [14]: df_1['Ground velocity'] = cumtrapz(df_1['Ground Acceleration (in G)'],df_1['delta t df_1['Ground Displacement'] = cumtrapz(df_1['Ground velocity'],df_1['delta t (sec)'])
In [15]: # Create subplots
fig, axes = plt.subplots(3, 1, figsize=(14, 18))
```

```
# Plot Ground Acceleration
axes[0].plot(df_1['delta t (sec)'], df_1['Ground Acceleration (in G)'], color='blue
axes[0].set_title('Ground Acceleration vs Time (sec)', fontsize=12)
axes[0].set_xlabel('Time (sec)', fontsize=12)
axes[0].set_ylabel('Ground Acceleration (in G)', fontsize=12)
axes[0].legend()
axes[0].grid(True)
# Plot Ground Velocity
axes[1].plot(df_1['delta t (sec)'], df_1['Ground velocity'], color='green', label='
axes[1].set_title('Ground Velocity vs Time (sec)', fontsize=12)
axes[1].set_xlabel('Time (sec)', fontsize=12)
axes[1].set_ylabel('Ground Velocity (in G-sec)', fontsize=12)
axes[1].legend()
axes[1].grid(True)
# Plot Ground Displacement
axes[2].plot(df_1['delta t (sec)'], df_1['Ground Displacement'], color='red', label
axes[2].set_title('Ground Displacement vs Time (sec)', fontsize=12)
axes[2].set_xlabel('Time (sec)', fontsize=12)
axes[2].set_ylabel('Ground Displacement (in G-sec^2)', fontsize=12)
axes[2].legend()
axes[2].grid(True)
# Adjust Layout
plt.tight_layout()
plt.show()
```



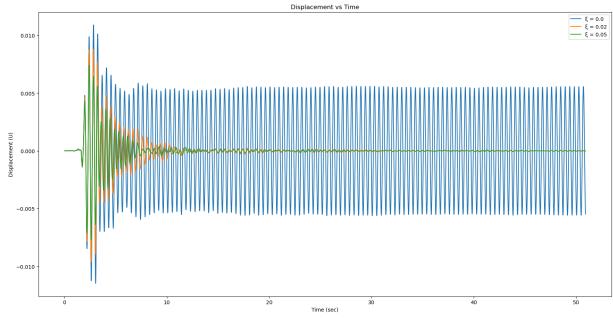
```
# Plot Ground Acceleration
axes[0].plot(df_2['delta t (sec)'], df_2['Ground Acceleration (in G)'], color='blue
axes[0].set_title('Ground Acceleration vs Time (sec)', fontsize=12)
axes[0].set_xlabel('Time (sec)', fontsize=12)
axes[0].set_ylabel('Ground Acceleration (in G)', fontsize=12)
axes[0].legend()
axes[0].grid(True)
# Plot Ground Velocity
axes[1].plot(df_2['delta t (sec)'], df_2['Ground velocity'], color='green', label='
axes[1].set_title('Ground Velocity vs Time (sec)', fontsize=12)
axes[1].set_xlabel('Time (sec)', fontsize=12)
axes[1].set_ylabel('Ground Velocity (in G-sec)', fontsize=12)
axes[1].legend()
axes[1].grid(True)
# Plot Ground Displacement
axes[2].plot(df_2['delta t (sec)'], df_2['Ground Displacement'], color='red', label
axes[2].set_title('Ground Displacement vs Time (sec)', fontsize=12)
axes[2].set_xlabel('Time (sec)', fontsize=12)
axes[2].set_ylabel('Ground Displacement (in G-sec^2)', fontsize=12)
axes[2].legend()
axes[2].grid(True)
# Adjust Layout
plt.tight_layout()
plt.show()
```



```
from scipy.integrate import cumtrapz
import matplotlib.pyplot as plt
# Assuming df_1 is your DataFrame and m is your mass
\# df_1 = \dots
# m = \ldots
k = 400
U_results = {}
V results = {}
A_results = {}
sheal = [0,0.02,0.05]
c_Val = []
for i in range(len(sheal)):
   c_n = 2*sheal[i]*m*np.sqrt(k/m)
   c__Val.append(c_n)
print()
c_values = c__Val
for c in c_values:
    k = 400
    delta_t = df_1['delta t (sec)'][1] - df_1['delta t (sec)'][0]
   # Initialize arrays for displacement, velocity, and acceleration
    U = np.zeros(df_1.shape[0])
   V = np.zeros(df_1.shape[0])
   A = np.zeros(df_1.shape[0])
    # Calculate ground velocity and displacement
    df_1['Ground velocity'] = cumtrapz(df_1['Ground Acceleration (in G)'], df_1['de
    df_1['Ground Displacement'] = cumtrapz(df_1['Ground velocity'], df_1['delta t (
    P = np.array(-m * df_1['Ground Acceleration (in G)'] * 9.81)
    a = m / (delta_t ** 2) - c / (2 * delta_t)
    b = k - (2 * m) / delta_t ** 2
    K_hat = m / (delta_t ** 2) + c / (2 * delta_t)
    for i in range(1, df_1.shape[0]-1):
        U[i+1] = (P[i] - a * U[i-1] - b * U[i]) / K_hat
        V[i] = (U[i+1] - U[i-1]) / (2 * delta_t)
        A[i] = (P[i] - c * V[i] - k * U[i]) / m
    # Store results
    U_results[c] = U.copy()
    V_results[c] = V.copy()
    A_{results[c]} = A.copy()
# Plotting the results
time = df_1['delta t (sec)']
# Plot displacement
plt.figure(figsize=(20, 10)) # Set the figure size to be large
```

```
# Plot displacement
for c in c_values:
    #plt.plot(time, U_results[c], label=f'c = {c}')
    plt.plot(time, U_results[c], label=f'\xi = {c/(2*m*np.sqrt(k/m))}')
plt.xlabel('Time (sec)')
plt.ylabel('Displacement (U)')
plt.legend()
plt.title('Displacement vs Time')
plt.show()

plt.tight_layout()
plt.show()
print(max(U_results[c]))
```

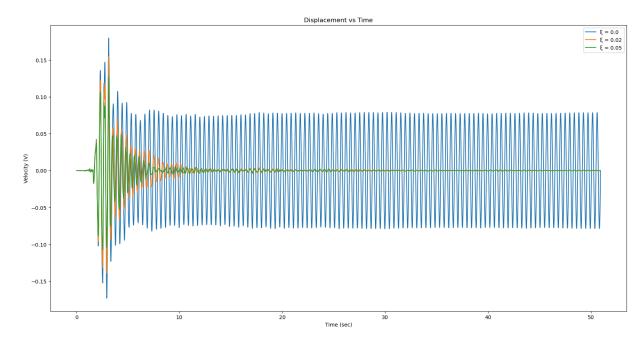


<Figure size 640x480 with 0 Axes>
0.007402078514890001

```
In [182... # Plot velocity

plt.figure(figsize=(20, 10)) # Set the figure size to be large

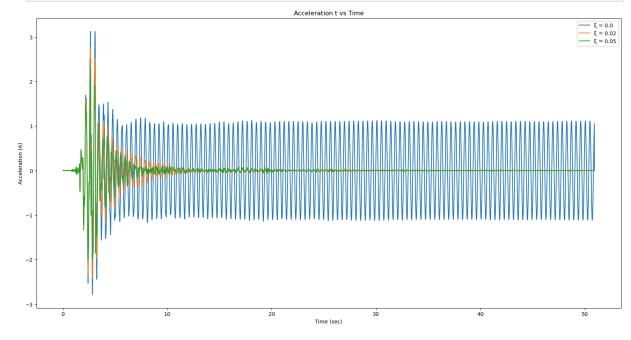
# Plot displacement
for c in c_values:
    plt.plot(time, V_results[c], label=f'ξ = {c/(2*m*np.sqrt(k/m))}')
plt.xlabel('Time (sec)')
plt.ylabel('Velocity (V)')
plt.legend()
plt.title('Displacement vs Time')
plt.show()
```



```
In [107... plt.figure(figsize=(20, 10)) # Set the figure size to be Large

# Plot displacement
for c in c_values:
    plt.plot(time, A_results[c], label=f'ξ = {c/(2*m*np.sqrt(k/m))}')

plt.xlabel('Time (sec)')
plt.ylabel('Acceleration (A)')
plt.legend()
plt.title('Acceleration t vs Time')
plt.show()
```



```
In [ ]:
```

```
In [19]:
In [26]:
In [36]: import pandas as pd
         from scipy.linalg import expm
         from numpy.linalg import pinv
         import numpy as np
         import matplotlib.pyplot as plt
         def El_Centro(data, dt, periods=np.arange(0, 10, 0.05), xi=0):
                     = numpy array type object (in acceleration (cm/s^2))
             data
                     = sampling interval
             periods = spectral periods (0.01 to 10 seconds with 100 samples)
                     = damping factor
                 OUTPUTS
             PSA = Pseudo-spectral acceleration ordinates
             PSV = Pseudo-spectral velocity ordinates
             SD = spectral displacement ordinates
             A = []; Ae = []; AeB = []
             displ_max = np.empty((len(periods)))
             veloc_max = np.empty((len(periods)))
             absacc_max = np.empty((len(periods)))
             foverm_max = np.empty((len(periods)))
             pseudo_acc_max = np.empty((len(periods)))
             pseudo_veloc_max = np.empty((len(periods)))
             PSA = np.empty((len(periods)))
             PSV = np.empty((len(periods)))
             SD = np.empty((len(periods)))
             acc = data
             for num, val in enumerate(periods):
                 omegan = 2 * np.pi / val # Angular frequency
                 C = 2 * xi * omegan # Two times the critical damping and angular freq.
                 K = omegan**2
                 y = np.zeros((2, len(acc)))
                 A = np.array([[0, 1], [-K, -C]])
                 Ae = expm(A * dt)
                 temp_2 = np.dot(Ae - np.eye(2, dtype=int), pinv(A))
                 AeB = np.dot(temp_2, np.array([[0.0], [1.0]]))
                 for k in np.arange(1, len(acc)):
                     y[:, k] = np.reshape(np.add(np.reshape(np.dot(Ae, y[:, k - 1]), (2, 1))
                 displ = np.transpose(y[0, :]) # Relative displacement vector (cm)
                 veloc = np.transpose(y[1, :]) # Relative velocity (cm/s)
                 foverm = (omegan**2) * displ # Lateral resisting force over mass (cm/s^2)
                 absacc = -2 * xi * omegan * veloc - foverm # Absolute acceleration from eq
                 displ_max[num] = max(abs(displ)) # Spectral relative displacement (cm)
                 veloc_max[num] = max(abs(veloc)) # Spectral relative velocity (cm/s)
```

```
absacc_max[num] = max(abs(absacc)) # Spectral absolute acceleration (cm/s^
        foverm_max[num] = max(abs(foverm)) # Spectral value of lateral resisting f
        pseudo_acc_max[num] = displ_max[num] * omegan**2 # Pseudo spectral acceler
        pseudo_veloc_max[num] = displ_max[num] * omegan # Pseudo spectral velocity
        PSA[num] = pseudo_acc_max[num] # PSA (cm/s^2)
        PSV[num] = pseudo_veloc_max[num] # PSV (cm/s)
        SD[num] = displ_max[num] # SD (cm)
    return PSA, PSV, SD
def plotting(results, periods, damping_factors, logplot=True):
    fig = plt.figure(figsize=(10, 12))
    ax1 = fig.add subplot(311)
    ax2 = fig.add_subplot(312)
    ax3 = fig.add_subplot(313)
    for i, xi in enumerate(damping_factors):
        PSA, PSV, SD = results[i]
        if logplot:
            ax1.loglog(periods, PSA, label=f'\xi = \{xi\}')
            ax2.loglog(periods, PSV, label=f'\xi = \{xi\}')
            ax3.loglog(periods, SD, label=f'\xi = \{xi\}')
        else:
            ax1.plot(periods, PSA, label=f'\xi = \{xi\}')
            ax2.plot(periods, PSV, label=f'\xi = \{xi\}')
            ax3.plot(periods, SD, label=f'\xi = \{xi\}')
    ax1.grid(True)
    ax2.grid(True)
    ax3.grid(True)
    ax1.set_title('Pseudo spectral acceleration ($\mathregular{cm/s^{2}}$)')
    ax2.set_title('Pseudo spectral velocity (cm/s)')
    ax3.set_title('Spectral displacement (cm)')
    ax2.set_ylabel('Amplitude', rotation='vertical', fontsize=14)
    ax1.legend()
    ax2.legend()
    ax3.legend()
    fig.text(0.5, 0.01, 'Periods (s)', ha='center', va='center', fontsize=14)
    plt.tight_layout()
    plt.show()
# Read the data from the Excel file
file_path = r"C:\Users\NGTs\Desktop\Helena _180_.csv" # Replace with the actual pa
df = pd.read_csv(file_path)
# Extract time and acceleration data
time = df['delta t (sec)'].values
acceleration = df['Ground Acceleration (in G)'].values
```

```
# Define the sampling interval
dt = time[1] - time[0]

# Define the spectral periods and damping factors
sPeriod = np.arange(0.01, 10, 0.01)
damping_factors = [0.02, 0.05, 0.1, 0.2]

# Compute the pseudo spectral acceleration, velocity, and displacement for each dam
results = []
for xi in damping_factors:
    PSA, PSV, SD = El_Centro(acceleration * 100, dt, periods=sPeriod, xi=xi)
    results.append((PSA, PSV, SD))

# Plot the results
plotting(results, sPeriod, damping_factors, logplot=True)
```

