

view\_frames Result  
Recorded at time: 262.510

odom

base\_footprint

base\_link

camera\_rgb\_frame

caster\_back\_link

caster\_front\_link

cliff\_sensor\_front\_link

cliff\_sensor\_left\_link

cliff\_sensor\_right\_link

gyro\_link

laser\_sensor\_link

pole\_kinect\_0\_link

pole\_kinect\_1\_link

wheel\_left\_link

wheel\_right\_link

camera\_depth\_frame

camera\_link

camera\_rgb\_optical\_frame

camera\_depth\_optical\_frame

Broadcaster: /gazebo  
Average rate: 20.286 Hz  
Most recent transform: 262.467 ( 0.043 sec old)  
Buffer length: 3.500 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 262.510 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 262.510 sec old)  
Buffer length: 0.000 sec

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Broadcaster: /robot\_state\_publisher  
Average rate: 20.286 Hz  
Most recent transform: 262.468 ( 0.042 sec old)  
Buffer length: 3.500 sec

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Most recent transform: 262.468 ( 0.042 sec old)  
Buffer length: 3.500 sec

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Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 262.510 sec old)  
Buffer length: 0.000 sec

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