Deformable Objects Using Fast Lattice Shape Matching

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1 Introduction

I attempted to use the paper by Alec R. Rivers and Doug L. James, explaining Fast Lattice Shape Matching (FLSM), to make our already fuzzy bunny deformable as well. I have omitted collision and other physics in the interest of time and am focusing on the deformations as single points move. I will also be using the unoptimized version SLSM (Slow LSM), to focus on the way that deformations happen.

2 Explanation of FLSM

2.1 Constructing the Lattice

The first step to FLSM is to build a lattice, or grid, that encloses the mesh. We start by creating a bounding box around the mesh. From here we round the dimensions of the bounding box up to fit an integral number of grid squares. Each grid square has an associated particle which will be used for movement and other calculations.

2.2 Creating Particles

From here we need to check which grid squares are actually in contact with the inside of the mesh. We can do this using a triangle mesh voxelization algorithm [Rosenburg]. Each particle will have a mass associated with it to properly simulate physical responses. To differentiate between inner and outer particles, we can set the particle mass of outside particles to 0.

2.2.1 Assigning Vertices

Now that we have our grid and particles, we can assign vertices to their associated particles. This allows us to move the vertices of the mesh as the particles move, essentially sharing the transform of the particle with that vertex. To do this, we can iterate through the vertices of the mesh, and calculate which grid square they lie in. We can then assign that vertex to the particle in that grid square.

2.3 Creating Regions

make regions

2.4 Dynamics

stuff moves

2.4.1 Particle Movement

particles move

2.4.2 Region Movement

regions move

2.4.3 Setting Particle Positions

you put them there

3 My Implementation

int i = 0;

4 Challenges

doesnt work

5 Optimizations

make faster

6 Works Cited

Rivers, Alec R., and Doug L. James. "FastLSM: Fast Lattice Shape Matching for Robust Real-Time Deformation." *ACM Transactions on Graphics*, vol. 26, no. 3, 2007, pp