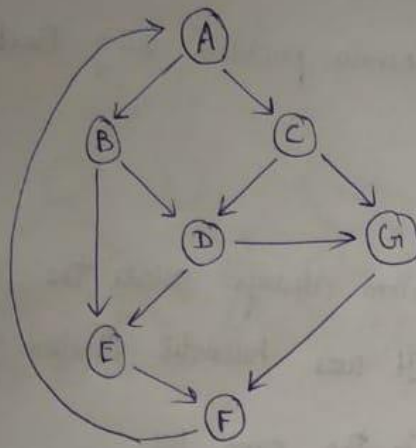


Aim:

To implement travelling salesman problem using Best First Search algorithm.

Algorithm:

- \* Best first search algorithm always selects the path which appears best at that moment. It uses heuristic function  $f(n) = h(n)$ .
- \* Place the starting node in the open list.
- \* If the open list is empty, stop and return.
- \* Remove the node  $n$  from the open list which has the lowest  $h(n)$  and place in any closed list.
- \* Expand the node  $n$  and generate the successors of node  $n$ .
- \* Check each successor of node  $n$ , and find whether any node is a goal node or not. If any successor node is goal node, then return success and terminate. The search else go to each successor node and check if  $f(n)$  and check if the node is not in both the list, then add it to open list.
- \* Return and check if the list is empty, then stop and return.

Sample Input And Output:

Node	$h(n)$
A	2
B	5
C	4
D	3
E	4
F	2
G	6

Start Node  $\rightarrow$  A

Best first search algorithm chooses the node with lowest heuristic value.

Node A  $\rightarrow$  Node C [heuristic value = 4]

Node C  $\rightarrow$  Node D [heuristic value = 3]

Node D  $\rightarrow$  Node E [heuristic value = 4]

Node F  $\rightarrow$  Node A [ $\therefore$  full tour completed]

Path followed by The graph :

A  $\rightarrow$  C  $\rightarrow$  D  $\rightarrow$  E  $\rightarrow$  F  $\rightarrow$  A

Total cost : 15

## **Program:**

```
import heapq as hq

def makeGraph(src, h_val, dest):
    global adj, heur
    adj[src] = dest[:]
    heur[src] = h_val

def best_first_search_tsp(src, adj, heur):
    pq, path, expanded_nodes = [], [], set()
    hq.heapify(pq)
    hq.heappush(pq, (heur[src], src))

    while(len(pq) != 0):
        curr_pair = hq.heappop(pq)
        curr_heur = curr_pair[0]
        curr_node = curr_pair[1]

        if(curr_node == src and src in expanded_nodes): # full tour complete
            path.append((curr_node, '$'))
            break
        elif(curr_node not in expanded_nodes):
            expanded_nodes.add(curr_node)
            path.append((curr_node, curr_heur))
        else:
            continue

        for dest in adj[curr_node]:
            hq.heappush(pq, (heur[dest], dest))

    return path

def displayResult(path, adj, heur, start):
    print("\nAdjacency List : ", adj)
    print("\nHeuristics : ", heur)
    print("\nStarting node = ", start)
    print("\nPath followed : ")
    total_cost = 0
    for node, h_val in path:
        if(h_val == "$"):
            print(node)
        else:
            total_cost += h_val
            print(f"{node} ({h_val}) -> ", end=" ")

    print("\nTotal Cost = ", total_cost)

if __name__ == "__main__":
    adj, heur = dict(), dict()
    makeGraph(src = 'A', h_val = 2, dest = ['D', 'C'])
    makeGraph(src = 'B', h_val = 5, dest = ['E'])
```

```
makeGraph(src = 'C', h_val = 4, dest = ['B', 'E'])
makeGraph(src = 'D', h_val = 3, dest = ['C'])
makeGraph(src = 'E', h_val = 6, dest = ['D', 'A'])    start
= 'A'
    path = best_first_search_tsp(start, adj, heur)
displayResult(path, adj, heur, start)
```

### **Output:**

```
Adjacency List : {'A': ['D', 'C'], 'B': ['E'], 'C': ['B', 'E'], 'D': ['C'], 'E': ['D', 'A']}
Heuristics : {'A': 2, 'B': 5, 'C': 4, 'D': 3, 'E': 6}
Starting node = A
Path followed :
A (2) -> D (3) -> C (4) -> B (5) -> E (6) -> A
Total Cost = 20
```

### **Result:**

Thus, travelling salesman problem is implemented using best first search.