

COMP 382: Reasoning about Algorithms

More NP-Complete Reductions and Approximation Algorithms

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December 2, 2025

Today's Lecture

1. Approximation Algorithms

- 1.1 2-Approximation Algorithm for Vertex Cover
- 1.2 (In)Approximability of TSP
- 1.3 Metric TSP and Its Approximation Algorithm

2. Set Cover

- 2.1 SET-COVER Is NP-Complete
- 2.2 Approximation Algorithm for Set Cover

Reading:

- Chapter 12 of the *Algorithms* book [Erickson, 2019]
- Chapter 8.1 of [Tardos and Kleinberg, 2005]

Content adapted from the same references.

Approximation Algorithms

If we relax optimality, does it get easier?

Approximation Algorithms

NP-complete problems are hard to solve *exactly*. A natural question is:

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- For minimization problems $\alpha > 1$, and smaller α means better approximation.

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Approximability of Problems

Often we seek a solution that is *close* to optimal: a constant-factor approximation, or an α that grows slowly with n (e.g., $\log n$).

A natural question:

Does every NP-hard optimization problem admit a polynomial-time approximation algorithm?

- Some problems *do* admit good approximations.
- Others remain hard even to approximate within any reasonable factor.

This leads to an entire area of study: **approximability theory**.

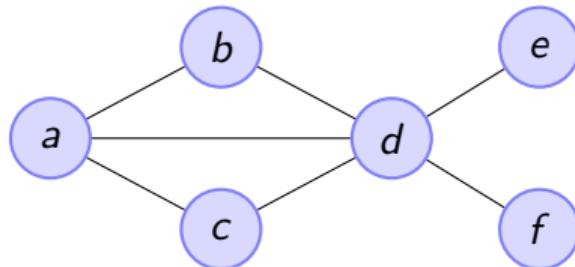
2-Approximation Algorithm for Vertex Cover

Recap: Vertex Covers

Let $G = (V, E)$ be a simple undirected graph.

A **vertex cover** in G is a subset $C \subseteq V$ such that every edge of G has at least one endpoint in C .

Equivalently: every edge is “touched” by C .

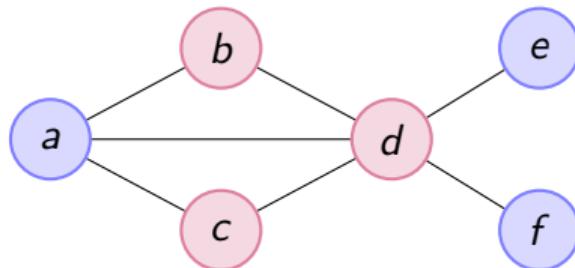


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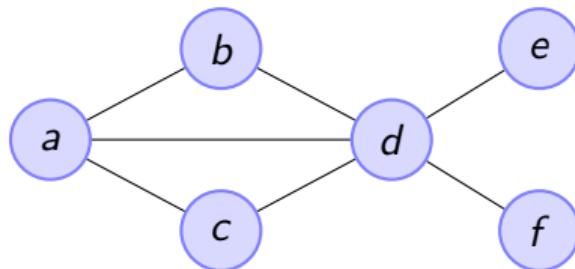
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A vertex cover $C = \{b, c, d\}$ touches all edges.

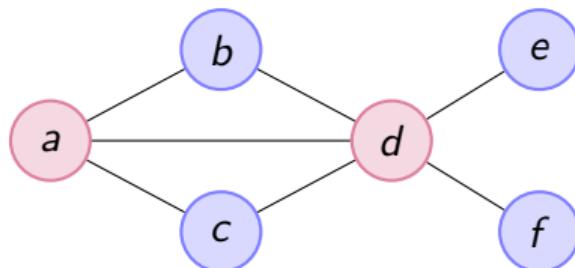
Minimum Vertex Cover Problem

VERTEX-COVER: Given a graph G and an integer k , does G contain a vertex cover of size at most k ?



Minimum Vertex Cover Problem

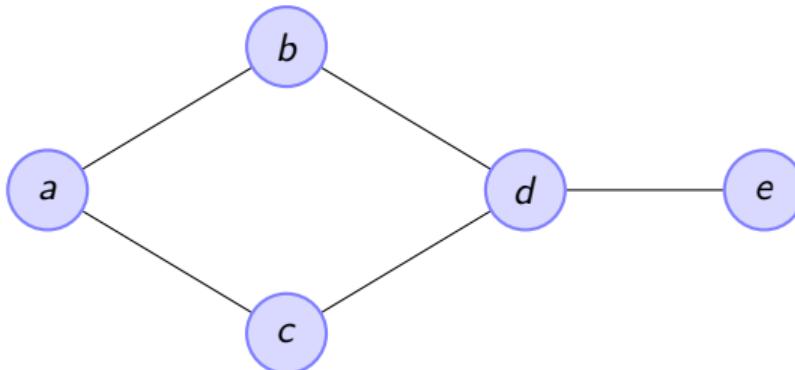
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Here $\{a, d\}$ is a vertex cover of size 2.

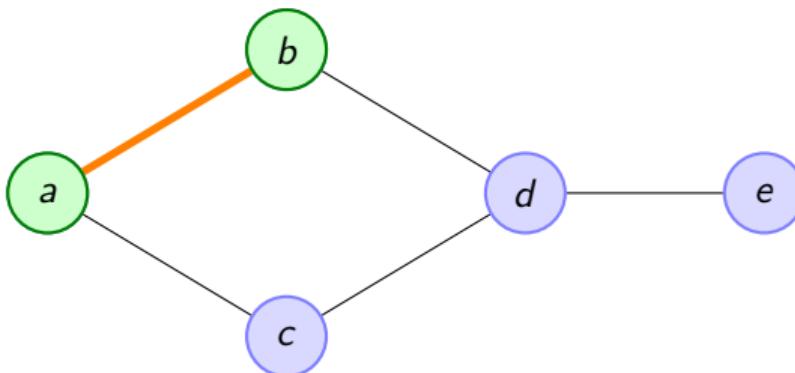
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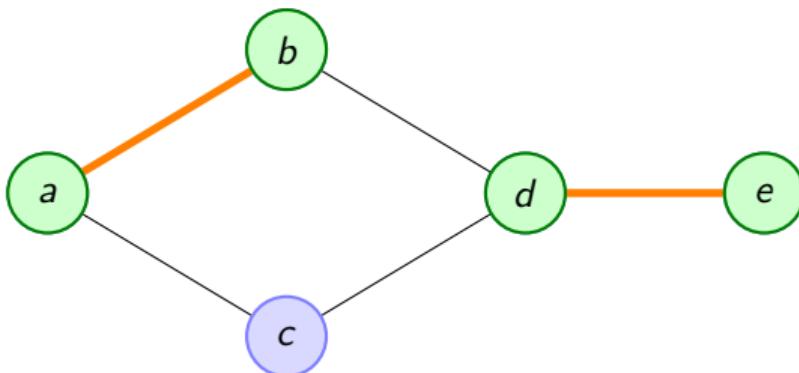
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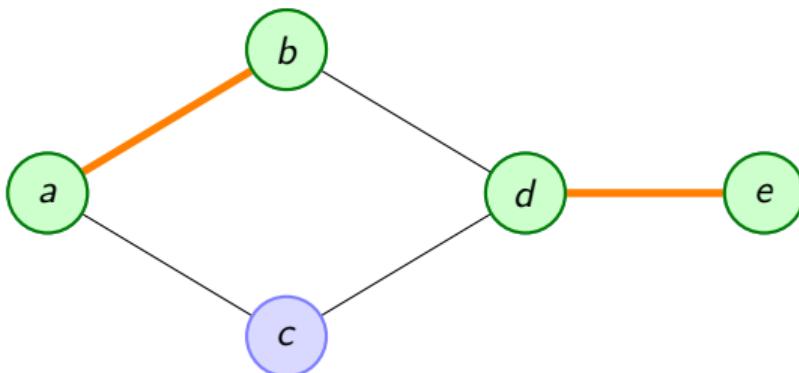


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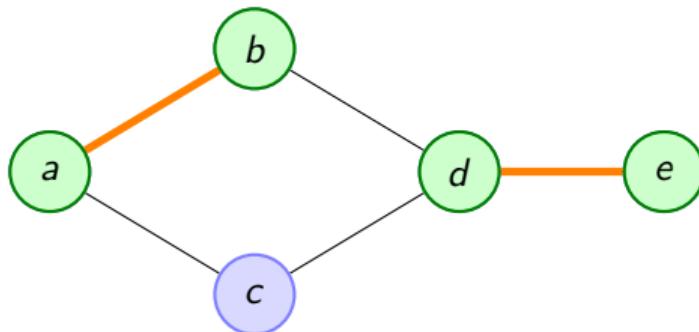
Step 1: pick an uncovered edge (here (a, b)), add a and b .

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All edges are covered. \Rightarrow Final cover = $\{a, b, c, d\}$.

Why the Greedy Algorithm Is a 2-Approximation

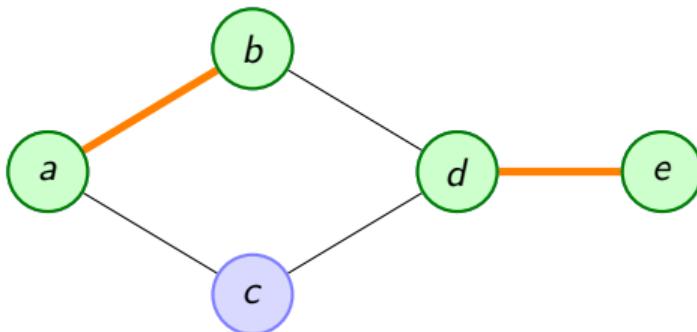
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Picked edges form a matching M

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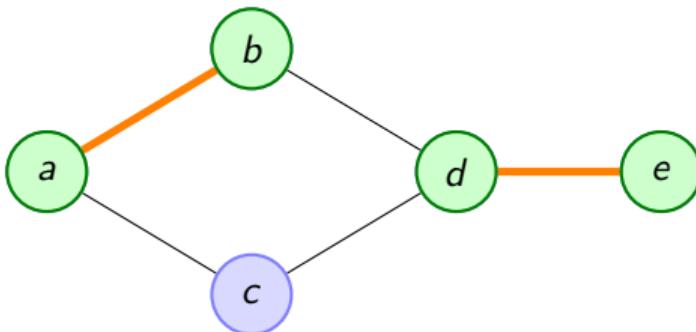
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- Any vertex cover must hit each edge of M . $\Rightarrow |C^*| \geq |M|$.



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- The algorithm adds *both* endpoints of each edge in M . $\Rightarrow |C_{\text{ALG}}| = 2|M|$.

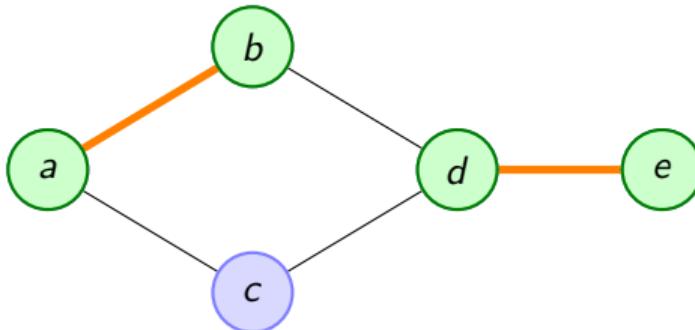


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- Therefore

$$|C_{\text{ALG}}| = 2|M| \leq 2|C^*|.$$



Picked edges form a matching M

(In)Approximability of TSP

Approximating TSP

APPROX-TSP Given a complete graph G and a constant $\alpha > 1$, output a tour in G with cost at most $\alpha \cdot \text{OPT}$.

Intuitively, this requirement is **weaker** than exact TSP.

- Any algorithm solving exact TSP automatically solves APPROX-TSP.

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However, APPROX-TSP and TSP have essentially the same difficulty.

Inapproximability of TSP

Theorem

TSP admits *no* polynomial-time α -approximation algorithm for any constant $\alpha \geq 1$, unless $P = NP$.

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How do we prove this? We return to our standard reduction recipe:

Reduce a known NP-complete problem (Hamiltonian Cycle) to APPROX-TSP.

The Strategy: Distinguishing by Gap

Goal: Reduce Hamiltonian Cycle to α -Approx TSP.

To do this, we construct an instance where the optimal cost falls into two disjoint ranges separated by a factor of α .

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To do this, we construct an instance where the optimal cost falls into two disjoint ranges separated by a factor of α .

If an algorithm guarantees an α -approximation, it returns a tour of cost $C \leq \alpha \cdot \text{OPT}$. We need a gap such that:

- **Case Yes (Hamiltonian):** $\text{OPT} = n \implies C \leq \alpha n$.
- **Case No (Not Hamiltonian):** $\text{OPT} > \alpha n$.

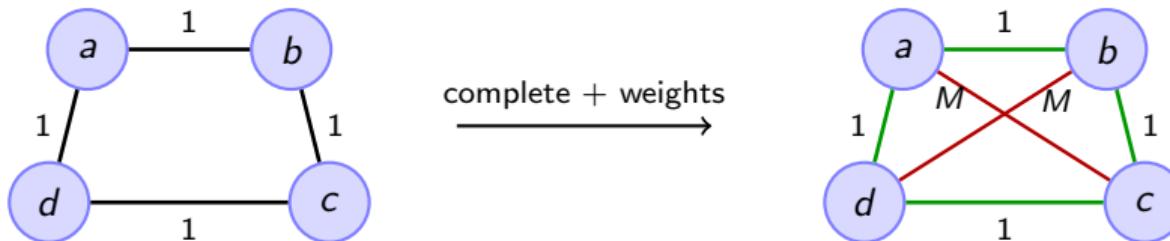
If we create this gap, checking if $C \leq \alpha n$ decides the Hamiltonian Cycle problem.

Creating the Gap

Construction: Build complete graph G' from G with weights:

$$w(u, v) = \begin{cases} 1 & \text{if } (u, v) \in E(G) \quad (\text{Original}) \\ M & \text{if } (u, v) \notin E(G) \quad (\text{Non-edge}) \end{cases}$$

where M is a large number (chosen later).



Creating the Gap

The Costs:

- **If G is Hamiltonian:** We use n edges of weight 1.
 $\Rightarrow \text{OPT}(G') = n.$
- **If G is NOT Hamiltonian:** We must use at least one weight M .
 $\Rightarrow \text{OPT}(G') \geq M + (n - 1).$

Forcing the Gap: Set $M = \alpha n$.

No Hamiltonian Cycle $\implies \text{OPT}(G') \geq \alpha n + (n - 1) > \alpha n.$

The Reduction Algorithm

The Procedure

Input: Graph G , Approximation factor α .

1. **Set the Penalty:** Let $n = |V|$ and choose a large weight $M = \alpha n + 1$.
2. **Construct G' :** Create a complete graph where:
 - Existing edges in G get weight 1.
 - Missing edges (non-edges) get weight M .
3. **Run the Solver:** Let C be the cost returned by APPROX-TSP(G').
4. **The Decision:**
 - If $C \leq \alpha n \rightarrow$ Return YES.
 - If $C > \alpha n \rightarrow$ Return NO.

Proof of Correctness

We analyze the output based on the structure of G :

Case 1: G has a Hamiltonian Cycle

- The optimal tour uses only original edges: $\text{OPT}(G') = n$.
- The α -approx algorithm returns cost $C \leq \alpha \cdot \text{OPT}$.
- Therefore, $C \leq \alpha n$.
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Case 2: G has NO Hamiltonian Cycle

- Any tour must use at least one non-edge (weight M).
- Therefore, $\text{OPT}(G') \geq M + (n - 1) > \alpha n$.
- Since any tour cost $C \geq \text{OPT}(G')$, we have $C > \alpha n$.
- **Result:** Procedure correctly returns NO.

Metric TSP and Its Approximation Algorithm

Turns out TSP is not so hopeless...

Metric TSP

Metric TSP An input instance to Metric TSP is a complete graph where edge weights are a metric.

- **Identity of indiscernibles:** $d(u, v) = 0 \Leftrightarrow u = v$.
- **Non-negativity:** $\forall u \neq v : d(u, v) > 0$.
- **Symmetric:** $d(u, v) = d(v, u)$.
- **Triangle inequality:** $\forall u, v, w : d(u, w) \leq d(u, v) + d(v, w)$.

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Why do we care?

- Many natural settings (FedEx, road networks, Euclidean distances) satisfy the triangle inequality.
- Triangle inequality enables good approximation algorithms.

2-Approximation for Metric TSP: MST Doubling

Algorithm (“double-tree”):

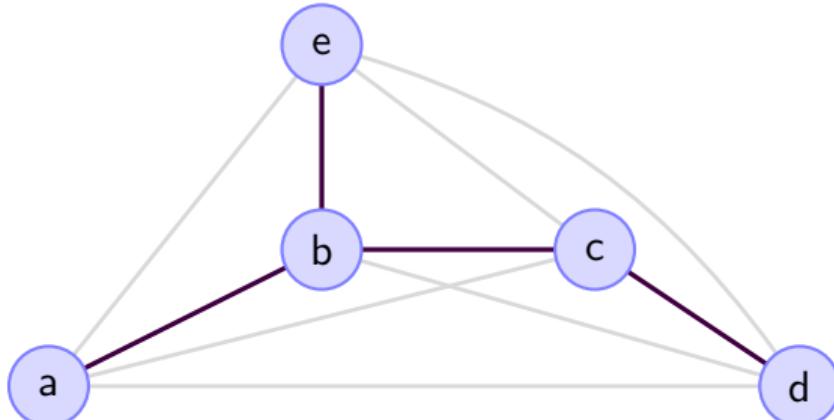
1. Compute a Minimum Spanning Tree (MST) T of the metric.
2. Double every edge of T to get an Eulerian multigraph.
3. Take an Euler tour and *shortcut* repeated vertices to obtain a TSP tour.

Visualizing the Double-Tree Algorithm

Step 1: Metric MST

We compute the MST of the metric graph (shown in **purple**).

Current Cost \leq OPT.



Why?

$$W(MST) \leq W(\text{ Hamiltonian Path}) \leq W(\text{OPT Hamiltonian Cycle})$$

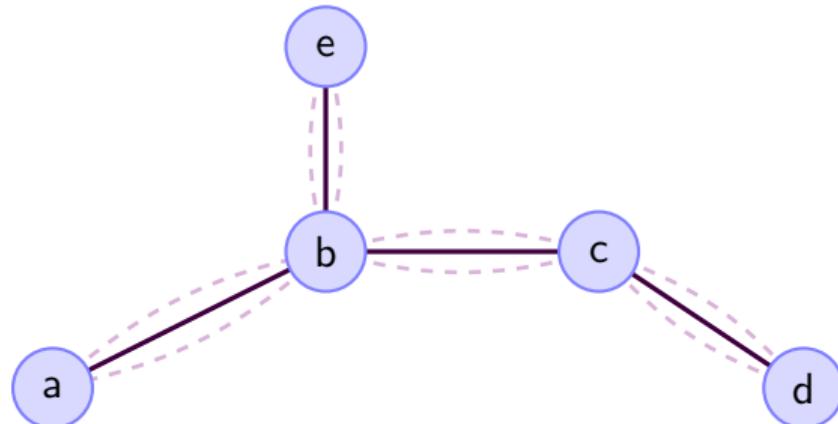
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Step 2: Doubling

We double every edge in the MST.

This creates an **Eulerian Multigraph**
(every node has even degree).

Current Cost $\leq 2 \cdot \text{OPT}$.

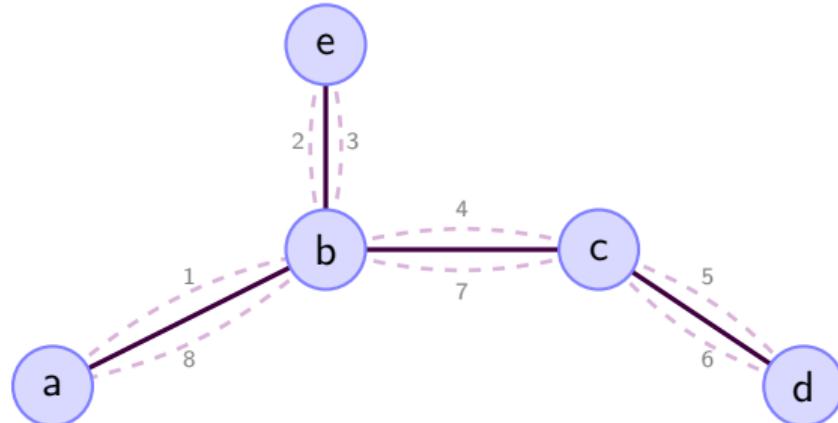


Visualizing the Double-Tree Algorithm

Step 3: Euler Tour

We traverse the doubled edges in a continuous loop (DFS order).

$a \rightarrow b \rightarrow e \rightarrow b \rightarrow c \rightarrow d \rightarrow c \rightarrow b \rightarrow a$

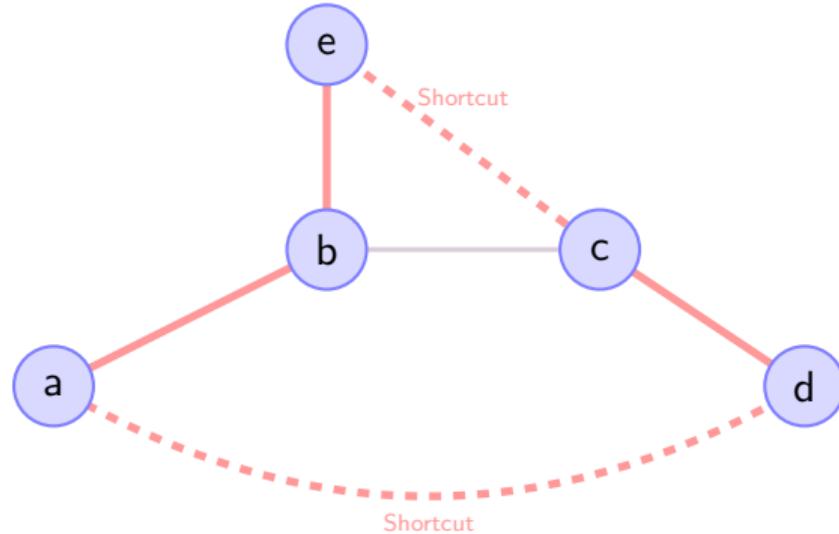


Visualizing the Double-Tree Algorithm

Step 4: Shortcutting

We delete repeated vertices from the Euler Tour. Thanks to the triangle inequality, taking a shortcut (red) is always cheaper.

Final Tour: $a \rightarrow b \rightarrow e \rightarrow c \rightarrow d \rightarrow a$



$$W(\text{Tour with shortcuts}) \leq 2 W(MST) \leq 2 W(\text{OPT Hamiltonian Cycle}).$$

2-Approximation!

Set Cover

NP-Hard and NP-Complete Problems

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NP-Complete Problem

A problem B is **NP-complete** if:

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2. For every problem $A \in \text{NP}$, A reduces to B .

The NP-Completeness Recipe

To show a new problem B is NP-complete, start from a known NP-complete problem A .
Show a polynomial-time reduction from A to B .

$$\begin{array}{l} \text{A is NP-complete:} \\ \text{A poly-time reduction from A to B:} \end{array} \quad \left. \begin{array}{c} \text{NP } \leq_p A \\ A \leq_p B \end{array} \right\} \implies \text{NP } \leq_p B$$

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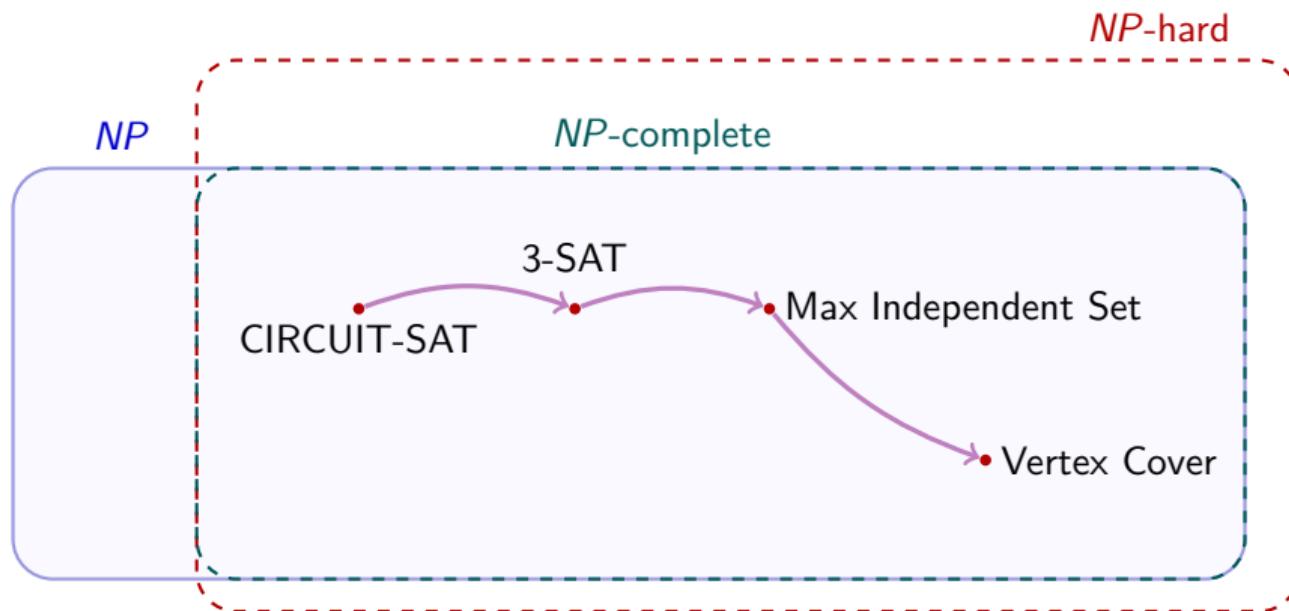
B is NP-hard.

If we also show that B is in NP, then \implies

B is NP-complete

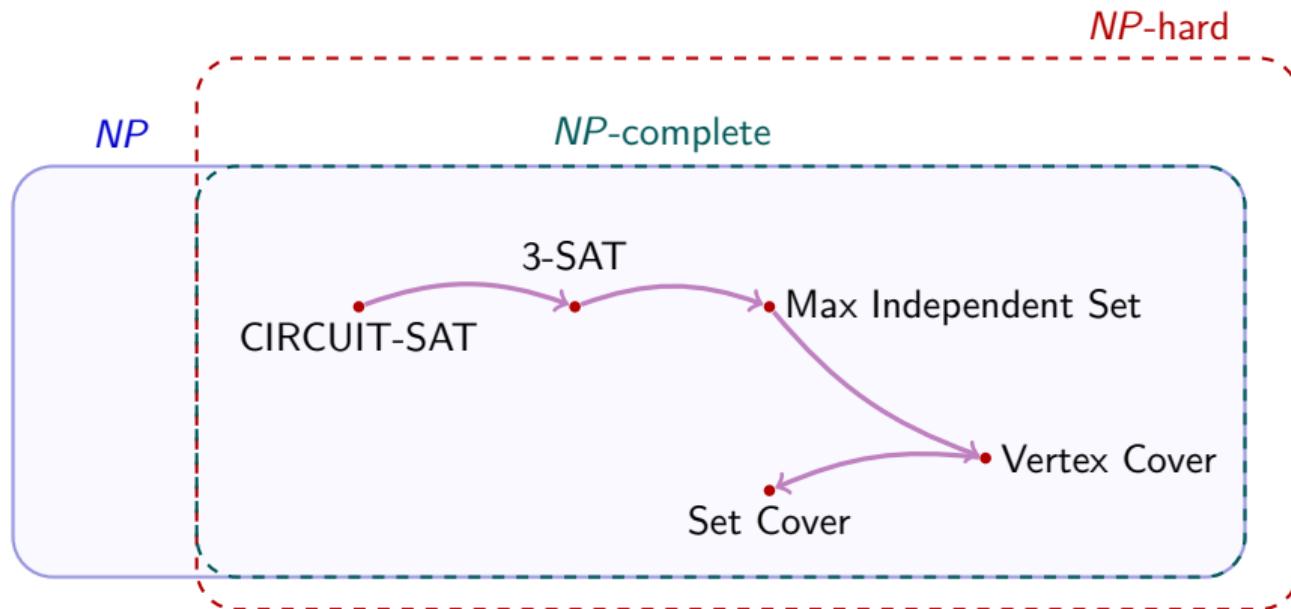
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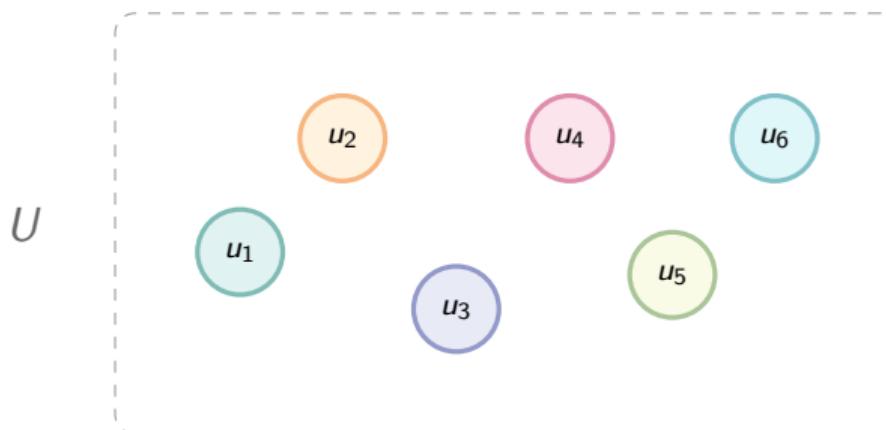
SET-COVER Is NP-Complete

A reduction from VERTEX-COVER

Set Cover

Let U be a finite set of n elements.

And, let $\mathcal{S} = \{S_1, \dots, S_m\}$ be a family of subsets with $S_i \subseteq U$.

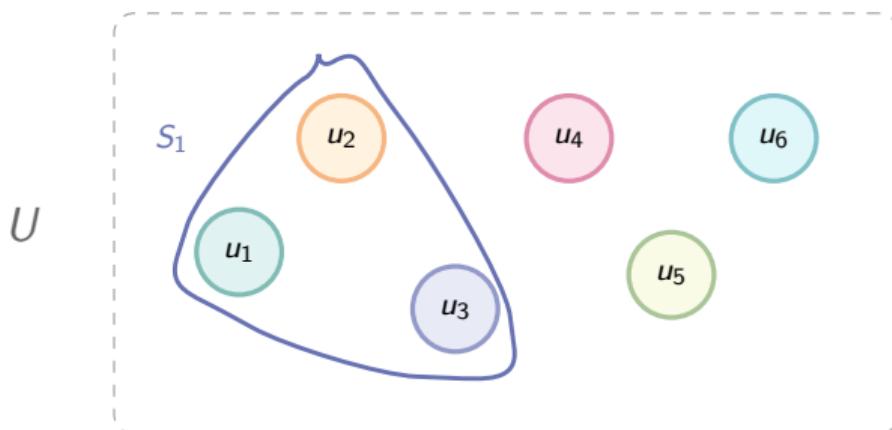


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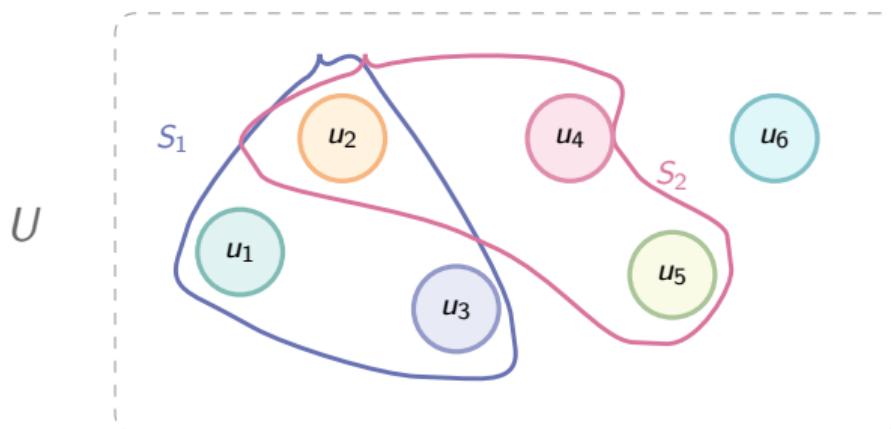


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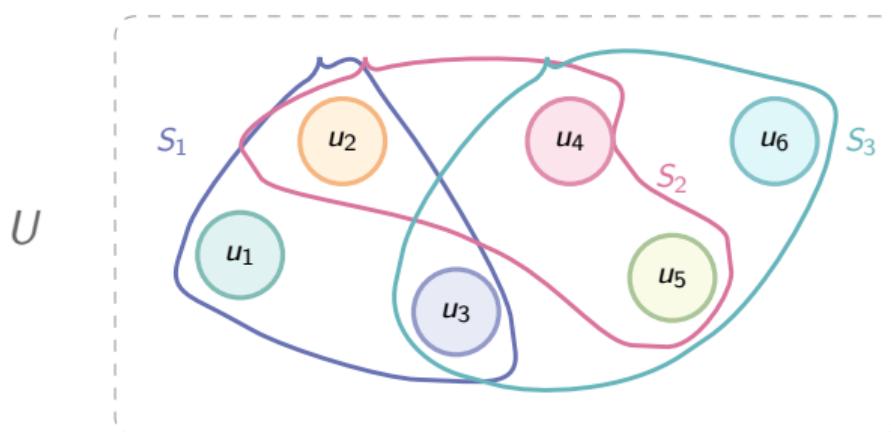


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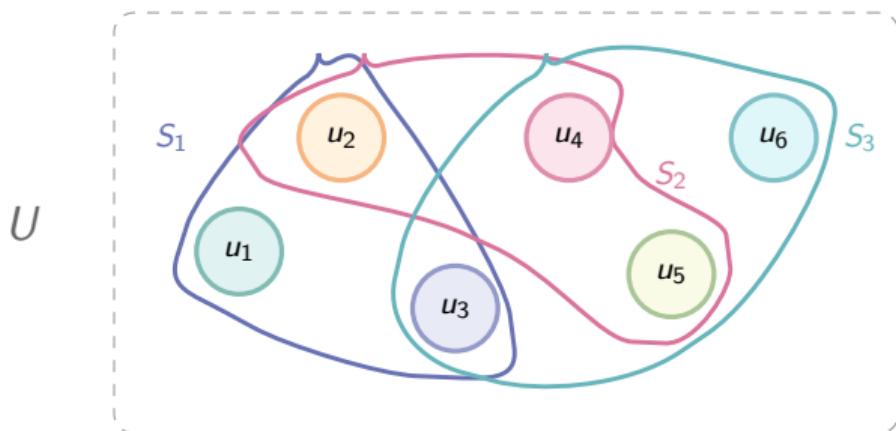
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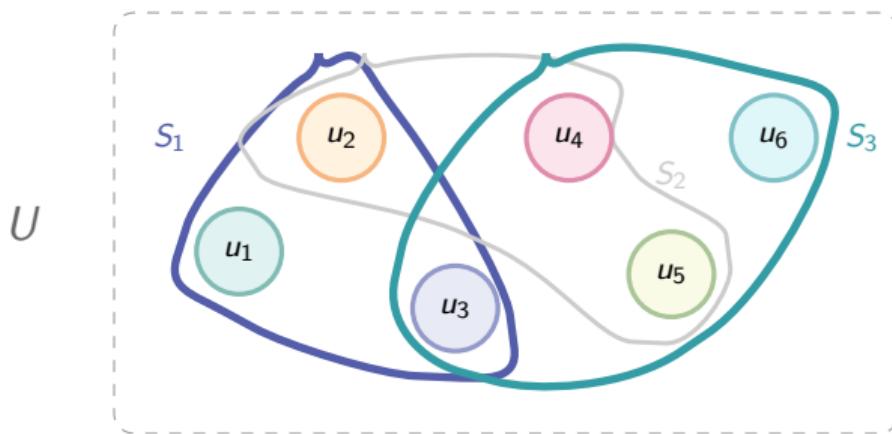
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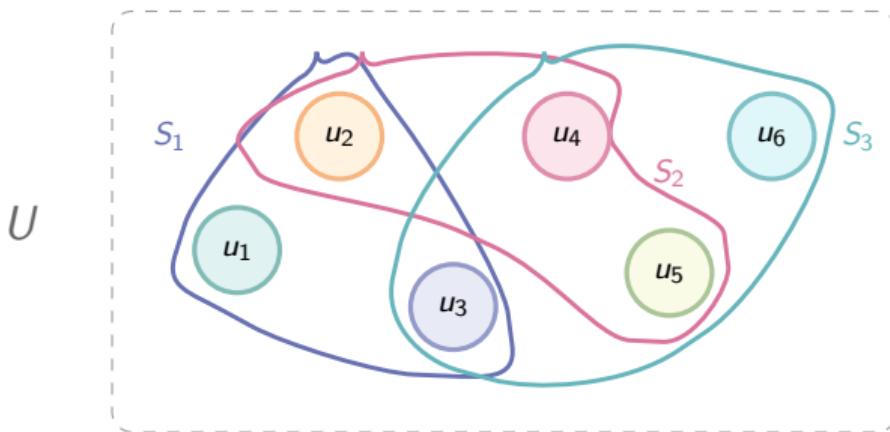
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A set cover is, for example, $C' = \{S_1, S_3\}$ since $S_1 \cup S_3 = U$.

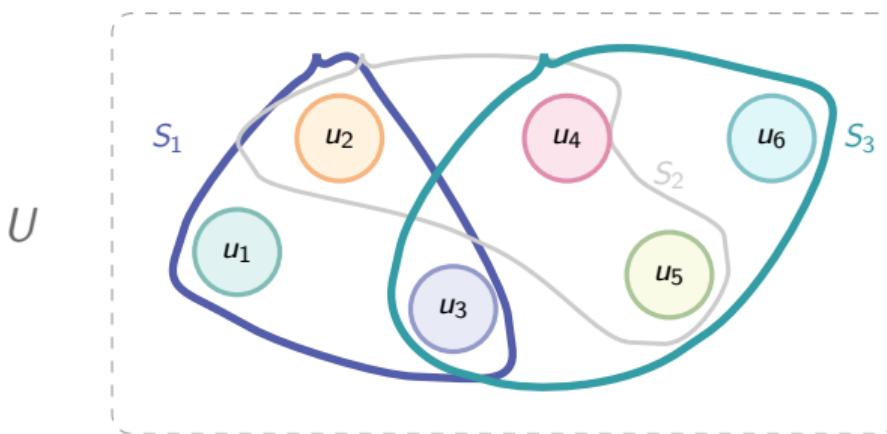
Set Cover (Decision Problem)

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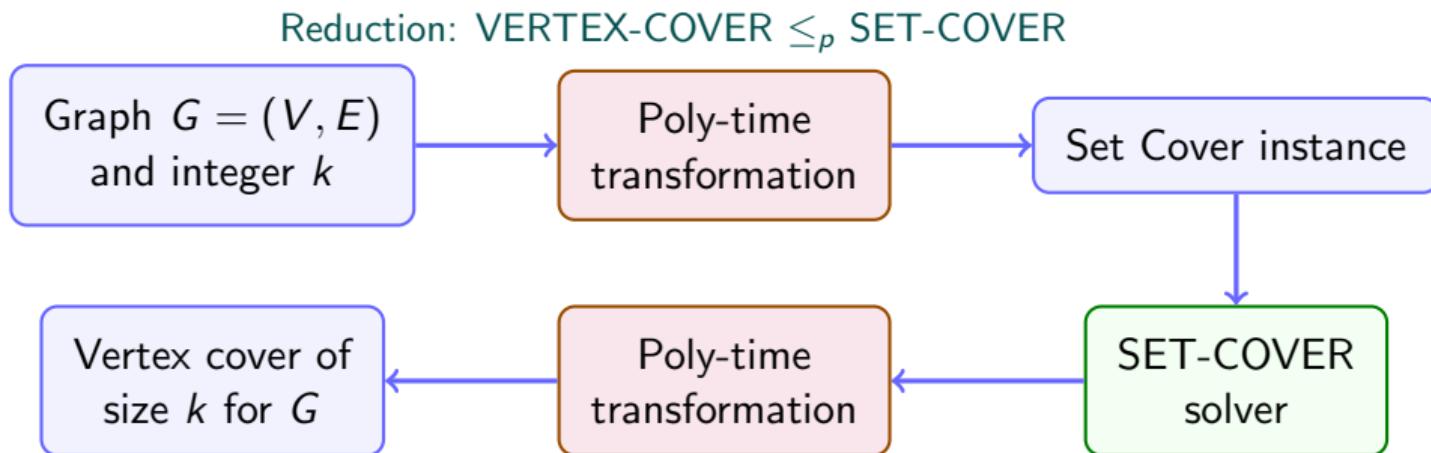
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Here $k = 2$ and $\{S_1, S_3\}$ is a valid cover.

Plan: Reduce VERTEX-COVER to SET-COVER

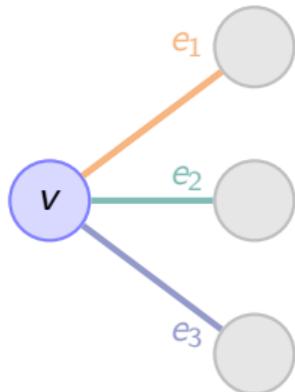
- Input on the Vertex Cover side: An undirected graph $G = (V, E)$ and an integer k .
- We will build a Set Cover instance such that G has a vertex cover of size k iff (U, \mathcal{S}, k) has a set cover of size k .



The Resemblance: Vertex Cover vs. Set Cover

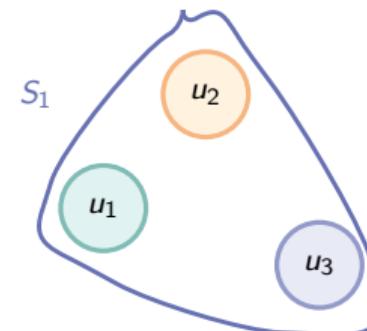
Vertex Cover

- **Items to cover:** Edges.
- **Objects to use:** Vertices.



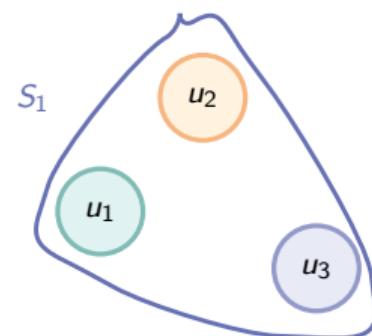
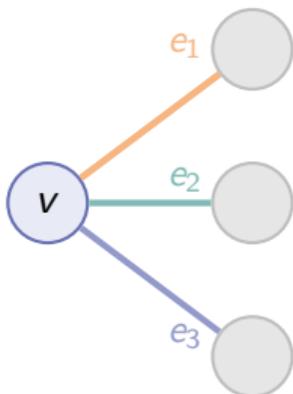
Set Cover

- **Items to cover:** Elements.
- **Objects to use:** Sets.



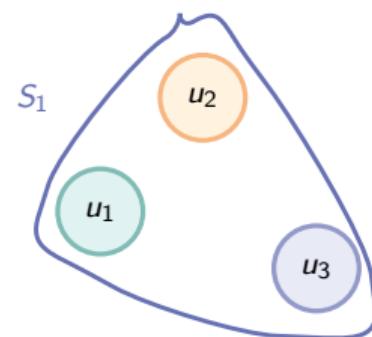
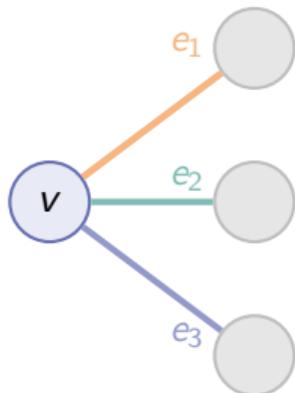
The Resemblance: Vertex Cover vs. Set Cover

- Vertex Cover is essentially a **special case** of Set Cover.



The Resemblance: Vertex Cover vs. Set Cover

- Vertex Cover is essentially a **special case** of Set Cover.
- Vertex Cover: cover all edges using the graph's vertex sets (each edge has 2 options).
- Set Cover: cover all elements using arbitrary sets (no limit on set size).



The Reduction: Vertex-Cover \leq_p Set-Cover

Given a graph $G = (V, E)$ and integer k , we build a Set Cover instance:

- The **universe** is the set of edges:

$$U := E.$$

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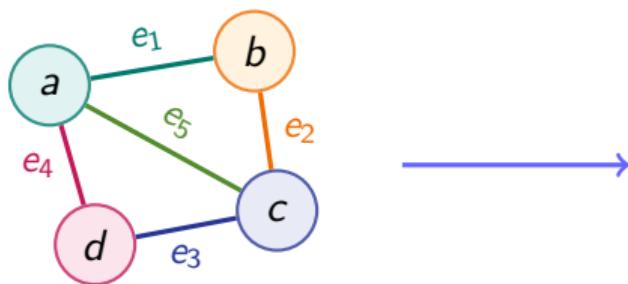
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- The Set Cover instance asks:

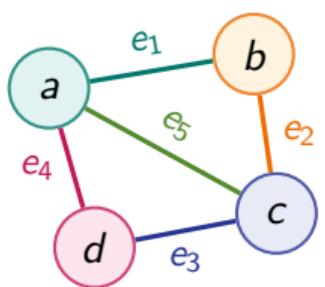
$$\exists C' \subseteq \mathcal{S} \text{ of size } \leq k \text{ such that } \bigcup_{S \in C'} S = U?$$

The Reduction: VERTEX-COVER \leq_p SET-COVER



Graph G

The Reduction: VERTEX-COVER \leq_p SET-COVER

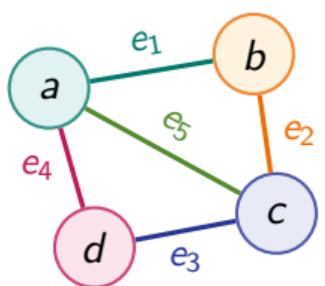


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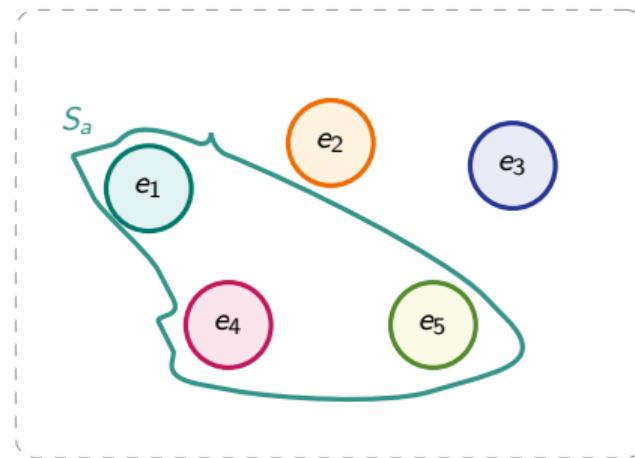


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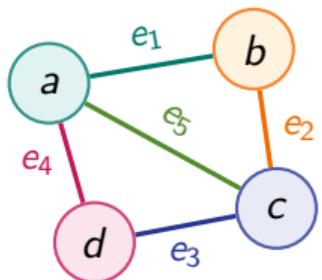


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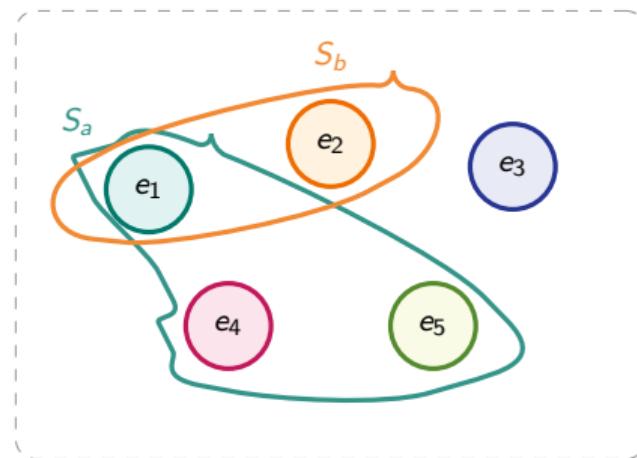


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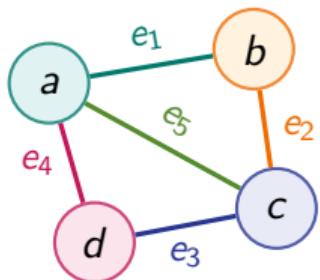


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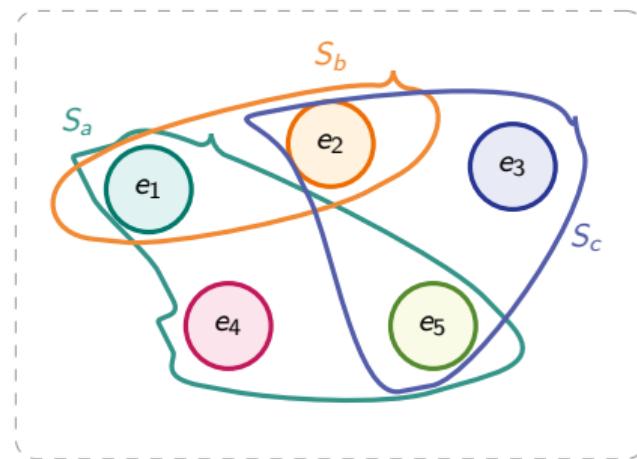


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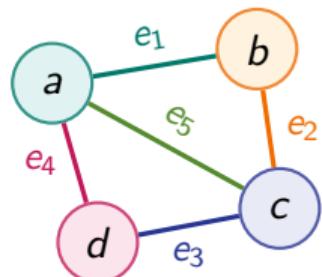


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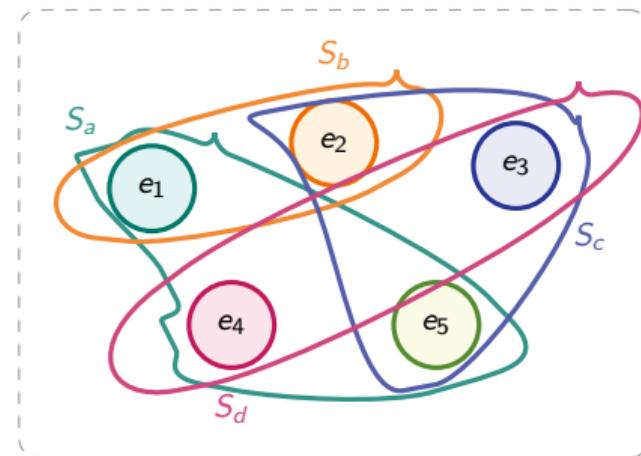


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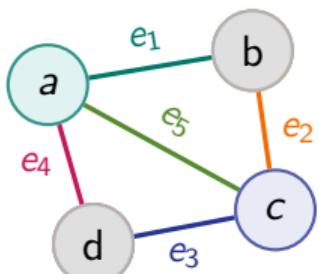


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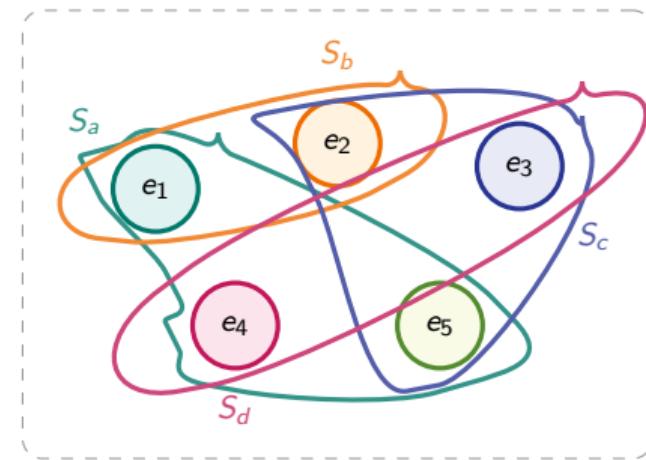


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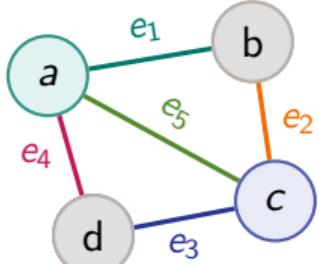
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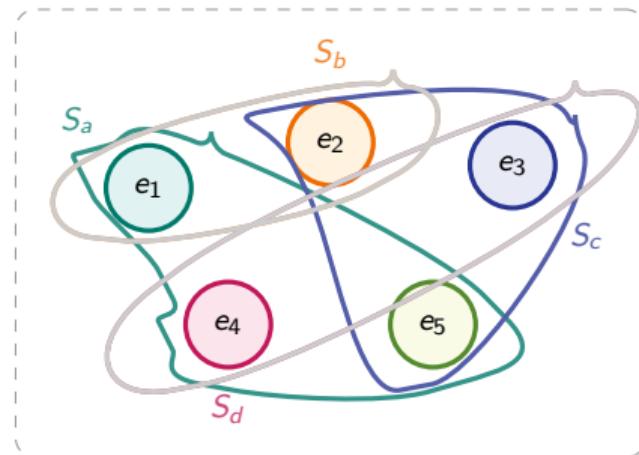
$$U = E$$

smallest vertex cover: $C = \{a, c\}$

The Reduction: VERTEX-COVER \leq_p SET-COVER



Graph G



$$U = E$$

smallest vertex cover: $C = \{a, c\}$

smallest set cover: $C' = \{S_a, S_c\}$

Correctness of the Reduction

To prove the reduction is correct, we must show that the two instances have the same answer.

(\Rightarrow) Suppose $C \subseteq V$ is a vertex cover of size at most k . Every edge $e = \{u, v\} \in E$ has at least one endpoint in C .

Thus every element $e \in U$ is contained in at least one of the sets $C' = \{S_v : v \in C\}$, meaning these $|C| \leq k$ sets form a valid set cover.

(\Leftarrow) Suppose we have a set cover $C' = \{S_{v_1}, \dots, S_{v_t}\}$ with $t \leq k$. Since C' covers all elements of $U = E$, for every edge $e = \{u, v\}$, at least one of the sets S_{v_i} contains e . However, $e \in S_{v_i}$ exactly when v_i is an endpoint of e .

Therefore the vertices $C = \{v_1, \dots, v_t\}$ touch every edge of G , so C is a vertex cover of size at most k .

Correctness of the Reduction

Efficiency. The construction is polynomial-time:

$$|U| = |E|, \quad |\mathcal{S}| = |V|, \quad \text{each edge is added to exactly two sets.}$$

SET-COVER is in NP. A certificate is a subfamily $\{S_{i_1}, \dots, S_{i_t}\}$ with $t \leq k$. A polynomial-time verifier checks:

- $t \leq k$,
- for every $u \in U$ there exists j with $u \in S_{i_j}$.

Conclusion. Since VERTEX-COVER is NP-complete and we have given a polynomial-time reduction from VERTEX-COVER to SET-COVER, it follows that SET-COVER is NP-hard. Since it is also in NP, SET-COVER is NP-complete.

Approximation Algorithm for Set Cover

Greedy Algorithm for Set Cover

Greedy rule: At each step, pick the set that covers the *largest number of currently uncovered elements*. Break ties arbitrarily; repeat until all elements are covered.

The Algorithm:

1. Initialize $C \leftarrow \emptyset$ and $U_{\text{left}} \leftarrow U$.

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3. Return C .

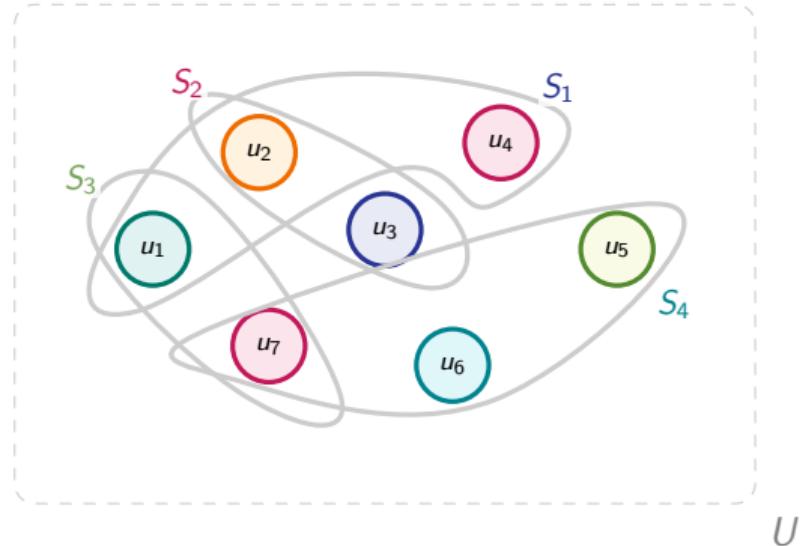
Greedy Set Cover Approximation

Algorithm Status:

Pick set with max *uncovered* elements.

Set	Elements	Count
S_1	u_1 , u_2 , u_4	3
S_4	u_5 , u_6 , u_7	3
S_2	u_2 , u_3	2
S_3	u_1 , u_7	2

Initial State: All elements uncovered.



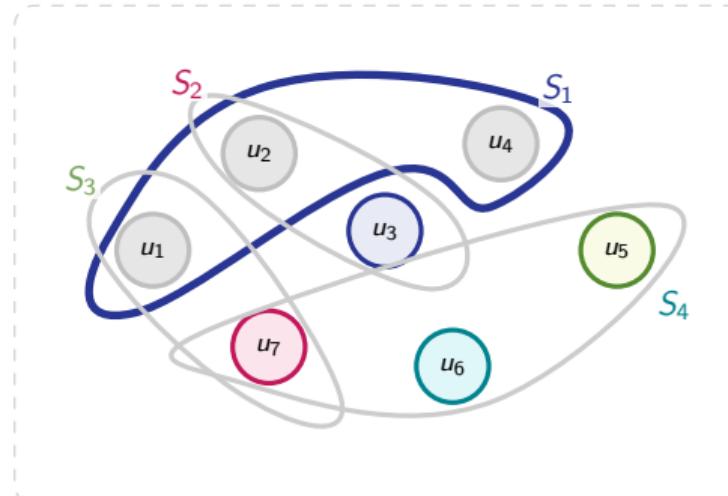
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Pick set with max *uncovered* elements.

Set	Elements	Count
S_4	u_5, u_6, u_7	3
S_2	u_2, u_3	1
S_3	u_1, u_7	1
S_4	Selected	-

Step 1: Pick S_1 . Covers $\{u_1, u_2, u_4\}$.



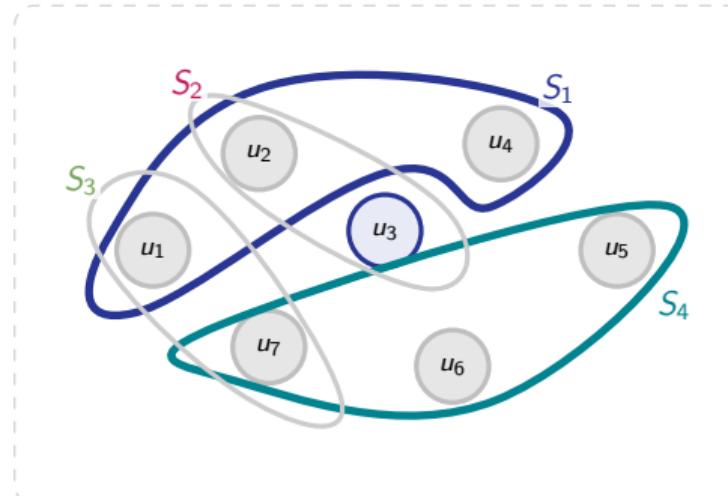
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Algorithm Status:

Pick set with max *uncovered* elements.

Set	Elements	Count
S_2	u_2, u_3	1
S_3	u_1, u_7	0
S_1	Selected	-
S_4	Selected	-

Step 2: Pick S_4 . Covers $\{u_5, u_6, u_7\}$.



Greedy Set Cover Approximation

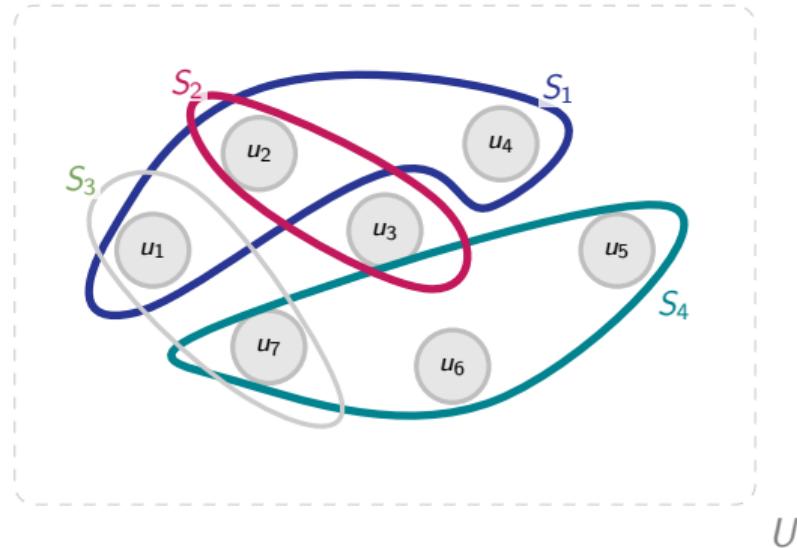
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Set	Elements	Count
S_3	u_1, u_7	0
S_1	Selected	-
S_4	Selected	-
S_2	Selected	-

Step 3: Pick S_2 . Covers $\{u_3\}$.

Done! All elements covered.



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- After k steps:

$$t_k \leq t_{k-1} \left(1 - \frac{1}{\text{OPT}}\right) \leq t_{k-2} \left(1 - \frac{1}{\text{OPT}}\right)^2 \leq \dots \leq n \left(1 - \frac{1}{\text{OPT}}\right)^k < n e^{-k/\text{OPT}}.$$

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- If k is sufficiently large then the number of uncovered elements should drop below 1:

$$k = \lceil \text{OPT} \cdot \ln n \rceil \implies t_k < n e^{-0k/\text{OPT}} \leq 1.$$

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Thus greedy uses at most $(\ln n + 1) \cdot \text{OPT}$ sets.

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- This is optimal up to constants unless $P = NP$.

References

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