1 Hybridization

Hybridization involves the weakening of Continuity constraints at inter-element boundaries to allow for:

- Larger solution space to achieve approximations in
- Decoupled systems (parallelizable)
- Local computations better stiffness matrices
- High order approximations through flux recovery

Some of the major hybridized methods are: Primal Hybrid, Dual/Mixed Hybrid, and Lagrangian Discontinuous Galerkin Hybrid. The major differences being in the form of the equation used and in the definition of flux terms used to complement the discontinuous function spaces. For a breakdown of many hybridized methods and a unified framework for analyzing some of these, see [1, 3]. In this work, we will focus on the Primal Hybrid formulation, with a specific post-processing technique for improved accuracy.

The model problem for this study is

$$-d^*du = f.$$

We will look at 2 and 3 dimension versions with d^*d as div grad, grad div, and curl curl. The primal formulation for this problem is derived as follows: Solve $-d^*du = f$ weakly. i.e. $\langle -d^*du, v \rangle = \langle f, v \rangle$ for all $v \in V$. This, in turn, can be written as a first-order system using the weak form:

$$\langle du, dv \rangle - \langle du, v \rangle_{\partial} = \langle f, v \rangle$$

where the $\langle,\rangle_{\partial}$ denotes inner product on the boundaries. The explicit formulation of this term comes from the Divergence/Stokes/Green's theorem and depends on the dimension of the domain and on the derivative d.

2 Postprocessing

With primal hybrid method, we end up with an approximate solution $u_h \in V_h$ to the function $-d^*du = f$. In most physically relevant problems, however, we are looking both for u and for $\sigma = -du$.

Now, rather than evaluating a numerical derivative of the computed solution u_h and leaving it at that, we post-process to achieve a much higher order of accuracy solution σ_h for -du.

There are many methods used for improving the approximation for σ_h using the information gained from solving for u_h . See, e.g., [2]. The one that we are considering here uses the trace values as well as computed values for u_h .

So, given the approximation u_h , we then solve the minimization problem: minimize the functional

$$J(\sigma) = \frac{1}{2} (||\sigma + du_h||^2 + ||d\sigma - f||^2)$$

over all $\sigma \in \Sigma_h$ subject to the constraints:

$$\begin{array}{rcl} \langle du_h, dv \rangle_K + \langle v, \sigma \rangle_{\partial K} & = & \langle f, v \rangle_K \\ \langle u, \tau \rangle_{\partial K} & = & 0 \end{array} \quad \forall (v, \sigma) \in W_h \times \Sigma_h$$

Here the equality is taken over each element $K \in T_h$, and W_h the approximation function space for u has weakened continuity constraints on the inter-element boundaries. This allows for a better approximation for σ while the boundary terms introduce lagrange multipliers that insure that u_h satisfies the equations.

3 Lagrange Multipliers

Recall the basic idea of Lagrange Multipliers from Calculus: to minimize F(x) subject to the constraint G(x) = H(x), solve $\nabla F = \lambda \nabla G$

In this case, we want to solve $\nabla J(\sigma) = 0$ while enforcing the original equation constraints on σ . So we solve for (σ_h, u_h) :

$$\langle \nabla J(\sigma_h), \tau \rangle = 0 \ \forall \tau \in \Sigma_h$$

and at the same time:

$$\langle u_h, v \rangle - \langle v, \sigma_h \rangle_{\partial} = \langle f, v \rangle, \quad \langle u_h, \tau \rangle_{\partial} = 0$$

References

- [1] Douglas N. Arnold et al. "Unified analysis of discontinuous Galerkin methods for ellipctic problems". In: SIAM J. Numer. Anal. 39.5 (2001/2), pp. 1749–1779.
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- [3] Bernardo Cockburn, Jayadeep Gopalakrishnan, and Raytcho Lazarov. "Unified analysis of discontinuous Galerkin, mixed, and continuous Galerkin methods for second order elliptic problems". In: SIAM J. Numer. Anal. 47.2 (2009), pp. 1319–1365.