

Q1] Consider

$$\begin{aligned}\frac{\partial u}{\partial t} &= D_1 \frac{\partial^2 u}{\partial x^2} + f(u, v) \\ \frac{\partial v}{\partial t} &= D_2 \frac{\partial^2 v}{\partial x^2} + g(u, v)\end{aligned}$$

a) Conditions for diffusion driven instability are

$$f_u + g_v < 0$$

$$f_u g_v - f_v g_u > 0$$

$$D_1 g_v + D_2 f_u > 0$$

$$(D_1 g_v + D_2 f_u)^2 > 4 D_1 D_2 (f_u g_v - f_v g_u)$$

$$\text{where } f_u = \left. \frac{\partial f}{\partial u} \right|_{(u_s, v_s)} \quad \text{and} \quad g_u = \left. \frac{\partial g}{\partial u} \right|_{(u_s, v_s)}$$

$$f_v = \left. \frac{\partial f}{\partial v} \right|_{(u_s, v_s)} \quad \text{and} \quad g_v = \left. \frac{\partial g}{\partial v} \right|_{(u_s, v_s)}$$

b) Consider  $f(u, v) = \alpha^2 u^2 v^2 - uv^5$ ,  $g(u, v) = uv - v^2$   
 $D_1 = 1$ ,  $D_2 = \delta$

Steady states are given by  $f(u, v) = 0$  and  $g(u, v) = 0$

$$\begin{aligned} \alpha^2 u^2 v^2 - uv^5 &= 0 \quad \text{if } u=0, v=0 \quad \text{or} \quad \alpha^2 u - v^3 = 0 \\ uv - v^2 &= 0 \quad \text{if } v=0 \quad \text{or} \quad u-v=0 \Rightarrow u=v \\ \text{thus } \alpha^2 u - u^3 &= 0 \Rightarrow u=0 \quad \text{or} \quad u=\alpha \end{aligned}$$

$$\text{thus } (u_s, v_s) = (\alpha, \alpha)$$

$$\text{Also } f_u = 2\alpha^2 u_s v_s^2 - v_s^5 = 2\alpha^5 - \alpha^5 = \alpha^5$$

$$f_v = 2\alpha^2 u_s^2 v_s - 5u_s v_s^4 = 2\alpha^5 - 5\alpha^5 = -3\alpha^5$$

$$g_u = v_s = \alpha$$

$$g_v = u_s - 2u_s = \alpha - 2\alpha = -\alpha$$

Then conditions:

$$\text{DDI 1: } f_u + g_v = \alpha^5 - \alpha < 0 \Rightarrow \alpha^5 < \alpha$$

$$\text{DDI 2: } f_u g_v - f_v g_u = -\alpha^6 + 3\alpha^6 = 2\alpha^6 > 0, \text{ which is true}$$

$$\text{DDI 3: } D_1 g_v + D_2 f_u = -\alpha + \delta \alpha^5 > 0 \Rightarrow \alpha > \sqrt[3]{\delta} \text{ or equivalently } \alpha^4 \delta > 1$$

$$(\delta \alpha^4 - 1)^2 > 8\delta \alpha^4$$

$$\delta^2 \alpha^8 - 2\delta \alpha^4 + 1 > 8\delta \alpha^4$$

$$\delta^2 \alpha^8 - 10\delta \alpha^4 + 1 > 0$$

Setting  $A = \alpha^4$ , then  $\delta^2 A^2 - 10\delta A + 1 = 0$  gives

$$A = \frac{10\delta \pm \sqrt{100\delta^2 - 48}}{2\delta^2}$$

$$\alpha^4 = \frac{5}{\delta} \pm \frac{\sqrt{96}}{2\delta} = \frac{5 \pm 2\sqrt{6}}{\delta}$$

$$\text{thus } \alpha^4 \delta < 5 - 2\sqrt{6} \quad \text{or} \quad \alpha^4 \delta > 5 + 2\sqrt{6}$$

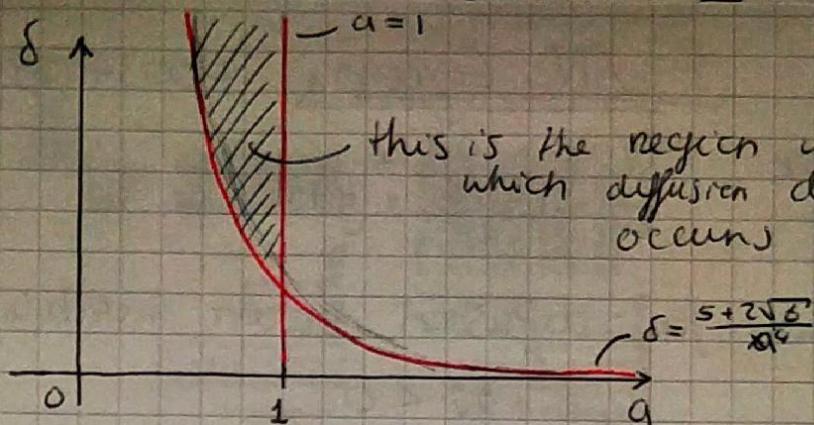
from DDI 3 we know  $\alpha^4 \delta > 1$ , thus  $\alpha^4 \delta < 5 - 2\sqrt{6}$  is not possible

thus conditions on  $\alpha$  and  $\delta$  for diffusion driven instability are

$$\alpha < 1 \text{ and } \alpha^4 \delta > 5 + 2\sqrt{6}$$

where  $\alpha, \delta > 0$  (constants)

c)



this is the region in which diffusion driven instability occurs

- a)  $f_u = a^5 > 0$  and  $g_v = -a < 0$   
thus  $u$  is the activator and  $v$  the inhibitor  
 $(f_u \ f_v) = \begin{pmatrix} a^5 & -3a^5 \\ a & -a \end{pmatrix} = \begin{pmatrix} + & - \\ + & - \end{pmatrix}$ , thus it is a pure activation-inhibition system

- e) wavenumbers  $k$  are defined by

$$Q(k^2) = D_1 D_2 k^4 - (D_2 f_u + D_1 g_v) k^2 + f_u g_v - f_v g_u$$

$$= \delta k^4 - (\delta a^5 - a) k^2 + 2a^6$$

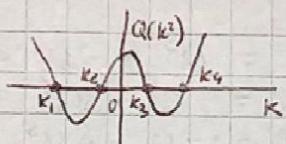
$Q(k^2) < 0$  one or two unstable wavenumbers, thus at critical wavenumber when DDI occurs  $Q(k^2) = 0$

$$\delta k^4 - a(\delta a^4 - 1) k^2 + 2a^6 = 0$$

$$k^2 = \frac{a(\delta a^4 - 1)}{2\delta} \pm \frac{\sqrt{a^2(\delta a^4 - 1)^2 - 4\delta 2a^6}}{2\delta}$$

$$= a \left( \frac{\delta a^4 - 1}{2\delta} \pm \frac{\sqrt{(\delta a^4 - 1)^2 - 8\delta a^6}}{2\delta} \right)$$

$Q(k^2)$  has shape



as  $Q(k^2) < 0$  for  $k_1 < k < k_2$  and  $k_3 < k < k_4$

where  $k_1, k_2, k_3, k_4$  are critical wave numbers at which diffusion driven instability could occur defined by

~~$$K_{1,2,3,4} = \pm \sqrt{a \left( \frac{\delta a^4 - 1}{2\delta} \pm \frac{\sqrt{(\delta a^4 - 1)^2 - 8\delta a^6}}{2\delta} \right)}$$~~

2) Consider  $\frac{dH}{dt} = 1 - H(t) - cH(t-T)$

- a) At steady state  $H(t) = H(t-T) = \text{constant}$ , ~~H~~  
thus ~~1 - H - cH = 0~~  $1 - H - cH = 0 \Rightarrow H_s = 1/(c+1)$

then we consider perturbations about steady state  
 $H(t) = H_s + h(t)$  and  $H(t-T) = H_s + h(t-T)$

where  $h(t)$  is a small perturbation  
substitution in the ODE gives and Taylor's expansion

$$\frac{dh(t)}{dt} = -h(t) - ch(t-T)$$

about  $(H_s, H_s)$  gives

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To find stability look for solutions of the form  $n(t) = Ke^{\lambda t}$   
 where  $K$  is a constant and  $\lambda$  are eigenvalues  
 substitution gives  $k\lambda e^{\lambda t} = -Ke^{\lambda t} - CKe^{\lambda(t-T)}$

$$\lambda = -1 - \frac{C}{k} e^{-\lambda T}$$

$$\lambda + 1 = -Ce^{-\lambda T}$$

where the steady state is stable if all solutions for  $\lambda$  have  $\operatorname{Re}(\lambda) < 0$

- b) for  $T=0$ ,  $\lambda = -1 - C < 0$ , thus the steady state is stable
- c) Let  $C = \sqrt{2}$ , then  $\lambda + 1 = -\sqrt{2}e^{-\lambda T}$

If we assume for some  $T > T_c$  the steady state is unstable, then at critical point  $T_c$ , we must have  $\operatorname{Re}(\lambda) = 0 \Rightarrow \lambda = i\omega$   
 substitution gives

$$i\omega + 1 = -\sqrt{2}e^{-i\omega T_c}$$

$$\text{Real part: } 1 = -\sqrt{2} \cos(\omega T_c) \Rightarrow \omega T_c = \cos^{-1}(-\frac{1}{\sqrt{2}})$$

$$\begin{aligned} \text{Imaginary part: } \omega &= \sqrt{2} \sin(\omega T_c) \\ &= \sqrt{2} \sqrt{1 - \cos^2(\omega T_c)} \end{aligned}$$

$$\text{as } \cos(\omega T_c) = -\frac{1}{\sqrt{2}} \rightarrow \omega = \sqrt{2} \sqrt{1 - \frac{1}{2}} = 1$$

$$\text{thus } T_c = \cos^{-1}(-\frac{1}{\sqrt{2}})$$

~~Substitution of  $T_c$  and  $\omega$  into  $\lambda + 1 = \sqrt{2}e^{-\lambda T}$  gives~~  
 Thus there is a critical value  $T_c$  for which  $\operatorname{Re}(\lambda) = 0$ . As the steady state is stable at  $T=0$  there is thus the steady state must be unstable for  $T > T_c$

Q3 Consider  $E + S \xrightleftharpoons[k_1]{k_2} 2P + E$

a) using the law of mass action, we can deduce

$$\frac{de}{dt} = -k_1 e s + k_2 c$$

$$\frac{ds}{dt} = -k_1 e s + k_2 c$$

$$\frac{dc}{dt} = k_1 e s - k_1 c - k_2 c$$

$$\frac{dp}{dt} = 2k_2 c$$

Consider  $s(0) = s_0$ ,  $e(0) = e_0$ ,  $p(0) = 0$

b) Because concentrations  $e, s, c$  are all independent of  $p$ , we can leave  $dp/dt$  out of the system of equations without consequences.

Secondly  $\frac{de}{dt} + \frac{dc}{dt} = 0$ , thus  $e(t) + c(t) = \text{constant}$

as  $e(t) + c(t)$  is a constant  $e(t) + c(t) = e(0) + c(0) = 2e_0$

thus we can replace  $e$  with  $2e_0 - c$  and also leave  $de/dt$  out of the system

this Ques

$$\frac{ds}{dt} = \cancel{k_1 s + k_2 c} - k_1 s(2e_0 - c) + k_2 c$$
$$\frac{dc}{dt} = k_1 s(2e_0 - c) \neq (k_1 + k_2)c$$

c) Given  $s^* = \frac{e_0}{S_0}$ ,  $c^* = \frac{e_0}{2e_0}$ ,  $t^* = k_1 e_0 t$ ,  $\epsilon = \frac{e_0}{S_0}$   
 $\alpha = k_1/(k_1 S_0)$   $\beta = (k_1 + k_2)/(k_1 S_0)$

Substitution of  $s = S_0 s^*$ ,  $c = 2e_0 c^*$  and  $t = t^*/(k_1 e_0)$  gives

$$\frac{ds^*}{dt^*} S_0 k_1 e_0 = -k_1 S_0 s^*(2e_0 - 2e_0 c^*) + k_2 2e_0 c^*$$

$$\frac{ds^*}{dt^*} = -2s^*(1 - c^*) + 2 \underbrace{\frac{k_2}{k_1 S_0}}_{= \alpha} c^*$$

thus  $\frac{ds^*}{dt^*} = -2s^*(1 - c^*) + 2\alpha c^*$

and  $\frac{dc^*}{dt^*} 2e_0 k_1 e_0 = k_1 S_0 s^*(2e_0 - 2e_0 c^*) + (k_1 + k_2) 2e_0 c^*$

$$\frac{dc^*}{dt^*} \cancel{\frac{e_0}{S_0}} = 2s^*(1 - c^*) \cancel{- \frac{k_1 + k_2}{k_1 S_0} c^*} \\ = \epsilon$$

thus  $\epsilon \frac{dc^*}{dt^*} = s^*(1 - c^*) - \beta c^*$

after dropping stars gives  $\frac{ds}{dt} = -2s(1 - c) + 2\alpha c$   
 $\epsilon \frac{dc}{dt} = s(1 - c) - \beta c$  as required

for initial conditions  $s(0) = \frac{s(0)}{S_0} = 1$   
and  $c(0) = \frac{c(0)}{2e_0} = \frac{1}{2}$

d) We can assume that  ~~$e_0 \gg S_0$~~   $S_0 \gg e_0$ , meaning that the initial amount of substrate greatly exceeds the amount of enzyme, which is true for the majority of reactions. as  $S_0 \gg e_0 \Rightarrow e_0/S_0 \ll 1$  and thus  $\epsilon = e_0/S_0 \ll 1$  is a

neglecting  $\epsilon$ -terms gives  $\epsilon \frac{dc}{dt} = 0$  and this is a reasonable assumption

$$s(1 - c) - \beta c = 0 \Rightarrow c(+) = \frac{s(+)}{\beta + s(+)}$$

substitution gives

$$\frac{ds}{dt} = -2s(1 - \frac{s}{\beta + s}) + 2\alpha \frac{s}{\beta + s}$$

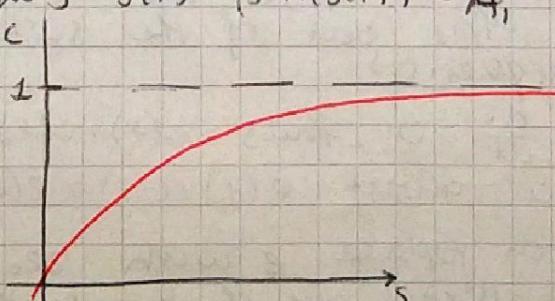
$$= -2\beta \frac{s}{\beta + s} + 2\alpha \frac{s}{\beta + s} = \frac{2s(\alpha - \beta)}{\beta + s}$$

$$\frac{\beta + s}{s} ds = 2(\alpha - \beta) dt$$

$$(\frac{\beta}{s} + 1)ds = 2(\alpha - \beta)dt$$

Integration gives  $s(+) + \beta \ln(s(+)) = A_1 + 2(\alpha - \beta)t$

$$C(+) = \frac{s(+)}{\beta + s(+)} \text{ gives}$$



initial condition give one  $S(0) = 1$ ,  $C(0) = \frac{1}{2}$

~~$$S(0) + \beta \ln(S(0)) = 1 + 2(\alpha - \beta)t = 0$$~~

$$C(0) = \frac{S(0)}{\beta + S(0)} = \frac{1}{\beta + 1} = \frac{1}{2}$$

$$\beta = 1$$

thus initial conditions can only both be satisfied if  $\beta = 1$

e) assume  $\beta > 1$ . Let  $\tau = t/\epsilon$ , then substitution gives

$$\frac{ds}{d\tau} = \epsilon(-2S(1-C) + 2\alpha C)$$

$$\frac{dc}{d\tau} = S(1-C) - \beta C$$

again neglecting  $\epsilon$ -terms goes  $\frac{ds}{d\tau} = 0 \Rightarrow S(\tau) = S(0) = 1$

$$\text{thus } \frac{dc}{d\tau} = 1 - C - \beta C \Rightarrow C(\tau) = \frac{Ae^{-(1+\beta)\tau}}{1+\beta} + \frac{1}{1+\beta}$$

$$\text{with initial condition } C(0) = \frac{A_2 + 1}{1+\beta} = \frac{1}{2} \Rightarrow A_2 = \frac{1}{2} \frac{\beta-1}{1+\beta}$$

$$\text{thus men solutions } S(t) = 1 \text{ and } C(t) = \frac{1}{2} e^{-\frac{(1+\beta)}{\epsilon} t} + \frac{1}{2(1+\beta)}$$

f) matching inner and outer solutions goes

$$\lim_{t \rightarrow 0} \frac{S(t)(1+C(t))}{S(t) + C(t)} = \lim_{t \rightarrow 0} \frac{1 - \frac{1}{2} e^{-\frac{(1+\beta)}{\epsilon} t}}{1 + \frac{1}{2} e^{-\frac{(1+\beta)}{\epsilon} t}}$$

$$\lim_{t \rightarrow 0} S(t) = \lim_{t \rightarrow 0} C(t) = \lim_{t \rightarrow 0} \frac{1}{2} e^{-\frac{(1+\beta)}{\epsilon} t} = \frac{1}{2(1+\beta)}$$

for inner solution  $S(t) = 1$ , thus  $\lim_{t \rightarrow 0} S(t) = 1$

using this as initial condition for outer solution goes

~~$$S(t) + \beta \ln(S(t)) = A_1 t$$~~

$$\text{also we note that } \lim_{t \rightarrow \infty} \frac{A_2 e^{-(1+\beta)\frac{t}{\epsilon}} + \frac{1}{2(1+\beta)}}{e^{-(1+\beta)\frac{t}{\epsilon}}} = \frac{1}{2(1+\beta)}$$

$$\lim_{t \rightarrow 0} \frac{S(t)}{B+S(t)} = \frac{S(0)}{B+S(0)} = \frac{1}{1+\beta}$$

thus solutions are already matched for  $C$

then composite solution:  $S_{\text{composite}} = S_{\text{inner}} + S_{\text{outer}} - S_{\text{outer}}$

$$= 1 + S_{\text{outer}} - 1$$

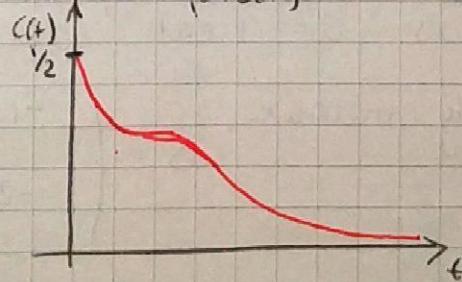
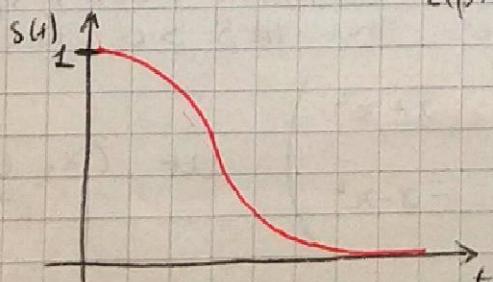
$$= S_{\text{outer}}$$

thus composite solution  $S(t)$  is determined by

$$S(t) + \beta \ln(S(t)) = 1 + 2(\alpha - \beta)t$$

$$\text{and } C(t) = \frac{\frac{\beta-1}{2(1+\beta)} e^{-\frac{(1+\beta)t}{\epsilon}} + \frac{1}{1+\beta} + \frac{S(t)}{B+S(t)} - \frac{1}{1+\beta}}{e^{-\frac{(1+\beta)t}{\epsilon}}}$$

$$= \frac{\frac{\beta-1}{2(1+\beta)} e^{-\frac{(1+\beta)t}{\epsilon}} + \frac{S(t)}{B+S(t)}}{e^{-\frac{(1+\beta)t}{\epsilon}}}$$



g)

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Q4 Consider  $\frac{dx}{dt} = -x + \alpha y + x^2 y$   
 $\frac{dy}{dt} = \beta - \alpha y - x^2 y$

First, we find steady states:  $-x + \alpha y + x^2 y = 0$  and  
 $\beta - \alpha y - x^2 y = 0$

$$y(\alpha + x^2) = \beta \Rightarrow y = \frac{\beta}{\alpha + x^2}$$

$$-x + \alpha \frac{\beta}{\alpha + x^2} + x^2 \frac{\beta}{\alpha + x^2} = 0 \Rightarrow x = \beta$$

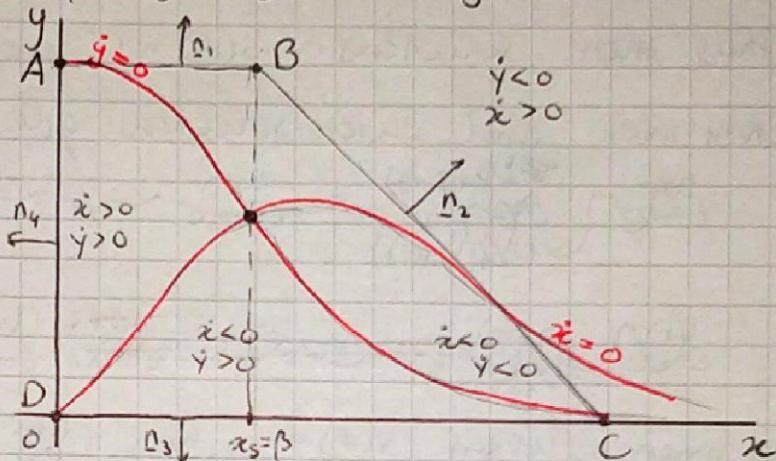
$$y = \frac{\beta}{\alpha + \beta^2}$$

Thus steady state  $(x_s, y_s) = (\beta, \frac{\beta}{\alpha + \beta^2})$

then we need to find a ~~closed set~~ closed curve (for which  $(\dot{x}, \dot{y}) \cdot \underline{n} < 0$  where  $\underline{n}$  is the outer unit normal)

to do this, we draw phase plane:

nullclines  $-x + \alpha y + x^2 y = 0 \Rightarrow y = \frac{x}{\alpha + x^2}$   
 $\beta - \alpha y - x^2 y = 0 \Rightarrow y = \frac{\beta}{\alpha + x^2}$



Let  $A = (0, \beta/\alpha)$ ,  $B = (\beta, \beta/(\alpha+\beta^2))$ ,  $C = (\beta, 0)$ , and  $D = (0, 0)$   
then  $ABCD$  defines a closed curve  
with  $\underline{n}_1 = (0, 1)$ ,  $\underline{n}_2 = \frac{1}{\sqrt{2}}(1, 1)$ ,  $\underline{n}_3 = (0, -1)$ ,  $\underline{n}_4 = (-1, 0)$

then along  $AB$ :  $\underline{n}_1 \cdot (\dot{x}, \dot{y}) = \dot{y} < 0$   
along  $BC$ :  $\underline{n}_2 \cdot (\dot{x}, \dot{y}) = \frac{1}{\sqrt{2}}(\dot{x} + \dot{y})$   
 $= \frac{1}{\sqrt{2}}(\beta - x) < 0$  as  $x > \beta$   
along  $CD$ :  $\underline{n}_3 \cdot (\dot{x}, \dot{y}) = -\dot{y} < 0$   
along  $DA$ :  $\underline{n}_4 \cdot (\dot{x}, \dot{y}) = -\dot{x} < 0$

thus we have that along  $ABCD$   $(\dot{x}, \dot{y}) \cdot \underline{n} < 0$  and  
thus  $ABCD$  is a confined set and the set  
that encloses the steady state  $(x_s, y_s)$

then the other condition for Poincaré-Bendixson theorem is  
that the steady state is an unstable node / spiral.  
thus we need  $\det S > 0$  and  $\text{tr } S > 0$ . for

stability matrix  $S = \begin{pmatrix} -1 + 2\alpha y & \alpha + x^2 \\ -2\alpha y & -\alpha - x^2 \end{pmatrix}$  at  $(x_s, y_s)$

$$S(x_s, y_s) = \begin{pmatrix} -1 + 2 \frac{\beta^2}{\alpha + \beta^2} & \alpha + \beta^2 \\ -2 \frac{\beta^2}{\alpha + \beta^2} & -\alpha - \beta^2 \end{pmatrix}$$

$$\text{TR } S = -1 + 2 \frac{\beta^2}{\alpha + \beta^2} - \alpha - \beta^2$$

$$= \frac{-\alpha - \beta^2 + 2\beta^2}{\alpha + \beta^2} - (\alpha + \beta^2) = \frac{\beta^2 - \alpha}{\alpha + \beta^2} - (\alpha + \beta^2) > 0$$

$$\beta^2 - \alpha > (\alpha + \beta^2)^2$$

$$\det S = \left( -1 + \frac{2\beta^2}{\alpha + \beta^2} \right) (-(\alpha + \beta^2)) - (\alpha + \beta^2) \left( -\frac{2\beta^2}{\alpha + \beta^2} \right)$$

$$= \alpha + \beta^2 - 2\beta^2 + 2\beta^2 = \alpha + \beta^2$$

as  $\alpha, \beta > 0$ , ~~as~~  $\det S > 0$

thus the condition ~~for~~ on  $\alpha$  and  $\beta$  for Poincaré-Bendixson theorem to hold is

$$\beta^2 - \alpha > (\alpha + \beta^2)^2$$

~~$$\beta^2 + 2\alpha\beta^2 + \alpha - \beta^2 + \alpha^2 < 0$$~~

$$\beta^4 + (2\alpha - 1)\beta^2 + \alpha(\alpha + 1) < 0$$

$$\beta^2 = \frac{1 - 2\alpha \pm \sqrt{(2\alpha - 1)^2 - 4\alpha(\alpha + 1)}}{2}$$

$$= \frac{1}{2} - \alpha \pm \frac{1}{2}\sqrt{4\alpha^2 - 4\alpha + 1 - 4\alpha^2 - 4\alpha}$$

$$= \frac{1}{2} - \alpha \pm \frac{1}{2}\sqrt{1 - 8\alpha}$$

$$< \frac{1}{2} - \alpha + \frac{1}{2} < 1$$

thus  $\beta < 1$  for the condition to hold

Q5] Consider  $\frac{\delta u}{\delta t} = D \frac{\partial^2 u}{\partial x^2} + \frac{k_1 u - k_2 u^2}{k_3 + u^2}$

where  $x$  in mm and  $t$  in hours

and  $u(x, t)$  the density of epidermal cells

a)  ~~$x = \tilde{x}$~~   $u = \tilde{u}$ ,  $t = \tilde{t}/T$ , then substitution gives

$$\frac{\delta \tilde{u}}{\delta \tilde{t}} U T = D \frac{\partial^2 \tilde{u}}{\partial \tilde{x}^2} U X^2 + U \frac{k_1 \tilde{u} - k_2 \tilde{u}^2 U}{k_3 + \tilde{u}^2 U^2}$$

$$\frac{\delta \tilde{u}}{\delta \tilde{t}} = D \frac{\partial^2 \tilde{u}}{\partial \tilde{x}^2} \frac{X^2}{T} + \frac{k_1}{k_3 T} \frac{\tilde{u} - \frac{k_2 U}{k_1} \tilde{u}^2}{1 + U^2/k_3 U^2}$$

then if  $T = k_1/k_3$ ,  $X^2 = T/D = k_1/(k_3 D)$ ,  $U = k_1/k_2$ ,  $\delta = \frac{U^2}{k_3} = \frac{k_1^2}{k_2^2 k_3}$

then  $\frac{\delta \tilde{u}}{\delta \tilde{t}} = \frac{\delta \tilde{u}}{\delta \tilde{x}^2} + \frac{\tilde{u} - \tilde{u}^2}{1 + \delta \tilde{u}^2}$

thus scalings are  $\tilde{x} = x \sqrt{\frac{k_1}{k_3 D}}$ ,  $\tilde{u} = \frac{k_2}{k_1} u$ ,  $\tilde{t} = \frac{k_1}{k_3} t$

with  $\delta = \frac{k_1^2}{k_2^2 k_3}$

b) travelling wave solution  $u(x, t) = U(z)$  where  $z = x - ct + \text{const}$

$$\frac{\delta U}{\delta t} = \frac{\delta U}{\delta z} \frac{\delta z}{\delta t} = -cU', \quad \frac{\delta^2 U}{\delta z^2} = U'', \quad \frac{\delta^3 U}{\delta z^3} = U'''$$

thus then  $-cU' = DU'' + \frac{k_1 U - k_2 U^2}{k_3 + U^2}$

$$DU''' + cU' + \frac{k_1 U - k_2 U^2}{k_3 + U^2} = 0$$

Define  $V = U'$ , then we get set of equations

$$\begin{aligned} U' &= V \\ V' &= -\frac{cV}{D} - \frac{k_1 U - k_2 U^2}{k_3 + U^2} \frac{1}{D} \end{aligned}$$

the system has steady state  $(0, 0)$  and  $(k_1/k_2, 0)$

and has stability matrix

$$S = \begin{pmatrix} 0 & 1 \\ \frac{k_1 U^2 + 2k_2 k_3 U - k_1 k_3}{(k_3 + U^2)^2} & -c/D \end{pmatrix}$$

thus  $S(0, 0) = \begin{pmatrix} 0 & 1 \\ -\frac{k_1}{k_3 D} & -c/D \end{pmatrix}$  gives  $\text{tr } S = -c/D < 0$   
 $\det S = \frac{k_1}{k_3 D} > 0$   
 thus  $(0, 0)$  is stable

$$S(k_1/k_2, 0) = \begin{pmatrix} 0 & 1 \\ \frac{k_1}{(k_3 + k_1/k_2)^2} & -c/D \end{pmatrix} \text{ gives } \text{tr } S = -c/D < 0$$

$$\det S = \frac{k_1}{(k_3 + k_1/k_2)^2} - \frac{k_1}{D(k_3 + k_1/k_2)^2} < 0$$

thus  $(k_1/k_2, 0)$  is unstable

Let  $f(U) = \frac{k_1 U - k_2 U^2}{D(k_3 + U^2)}$  with  $f'(U) = \frac{k_1 U^2 + 2k_2 k_3 U - k_1 k_3}{D(k_3 + U^2)^2}$  and  $f'(0) = \frac{k_1(k_1^2/k_2^2 + k_3)}{D(k_3 + k_1^2/k_2^2)^2}$

then eigenvalues at  $(0, 0)$  are given by

$$\lambda(-\gamma_D - \lambda) + f'(0) = 0 \Rightarrow \lambda^2 + \gamma_D \lambda + f'(0) = 0$$

which gives  $\lambda = \frac{1}{2}(-\gamma_D \pm \sqrt{(\gamma_D)^2 - 4f'(0)})$

as  $f'(0) > 0$ :

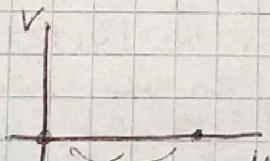
if  $(\gamma_D)^2 \geq 4f'(0)$ , eigenvalues one real and negative

thus  $(0, 0)$  is stable here

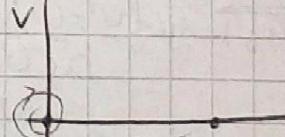
if  $(\gamma_D)^2 < 4f'(0)$ , eigenvalues one complex with negative real part thus  $(0, 0)$  a stable spiral

at  $(k_1/k_2, 0) \Rightarrow \lambda = \frac{1}{2}(-\gamma_D \pm \sqrt{(\gamma_D)^2 + 4f'(0)})$ , ~~thus as  $f'(0) > 0$~~   
 thus is a saddle always

phase planes then give



$$(\gamma_D)^2 \geq 4f'(0)$$



$$(\gamma_D)^2 < 4f'(0)$$

thus if  $(0, 0)$  is a spiral, there would be negative values of  $u$ , which is not biologically realistic as  $u$  is a density, thus we must have

$$(\gamma_D)^2 \geq 4f'(0) \Rightarrow c^2 \geq 4D \frac{k_1}{k_3 + k_1^2/k_2^2} \Rightarrow c \geq 2 \sqrt{\frac{k_1 D}{k_3 + k_1^2/k_2^2}}$$

c) thus  $c \geq 2 \sqrt{\frac{k_1 D}{k_3 + k_1^2/k_2^2}}$

~~so if you decrease  $k_1$~~

Therapy 1: decreasing  $k_1$  would mean

$$\lim_{k_1 \rightarrow 0} c = \lim_{k_1 \rightarrow 0} 2 \sqrt{\frac{k_1 D}{k_3 + k_1^2/k_2^2}} = 2 \sqrt{\frac{0 \cdot D}{k_3}} = 0 \quad \text{thus } c \rightarrow 0$$

Therapy 2: decreasing  $k_2$  would mean

$$\lim_{k_2 \rightarrow 0} c = \lim_{k_2 \rightarrow 0} 2 \sqrt{\frac{k_1 D}{k_3 + k_1^2/k_2^2}} = 2 \sqrt{\frac{k_1 D}{\infty}} = 0 \quad \text{thus } c \rightarrow 0$$

Therapy 3: decreasing  $k_3$  would mean

$$\lim_{k_3 \rightarrow 0} c = \lim_{k_3 \rightarrow 0} 2 \sqrt{\frac{k_1 D}{k_3 + k_1^2/k_2^2}} = 2 \sqrt{\frac{k_1 D}{k_1^2/k_2^2}} = 2k_2 \sqrt{Dk_1} \quad \text{thus } c \rightarrow 2k_2 \sqrt{Dk_1}$$

Thus only with therapy 3 the ~~to account healing rate~~ would ~~not~~ be longer than 0 as  $c \rightarrow 2k_2 \sqrt{Dk_1}$ , thus decreasing  $k_3$  is the most effective

Q6] a) Consider Maxey-Riley equation:

$$m'_{\text{drop}} \frac{d\mathbf{v}'}{dt'} = m'_{\text{air}} \frac{D\mathbf{u}'}{Dt'} + (m'_{\text{drop}} - m'_{\text{air}}) g' - 6\pi a' \mu' (\mathbf{v}' - \mathbf{u}') - \frac{m'_{\text{air}}}{2} \left[ \frac{d\mathbf{v}'}{dt'} - \frac{D\mathbf{u}'}{Dt'} \right] - 6\pi a'^2 \mu' \int_0^{t'} \frac{1}{\sqrt{\pi \nu(t+s)}} \frac{d}{ds} [\mathbf{v}' - \mathbf{u}'] ds'$$

a) Maxey-Riley equation is simply put in Newton's second law of motion  $m a = F$  where  $m = m'_{\text{drop}}$ ,

$$a = \frac{d\mathbf{v}'}{dt'}$$

and  $F$  is combined at the right hand side:

$m'_{\text{air}} \frac{D\mathbf{u}'}{Dt'}$  is the force due to the pressure gradient within undisturbed fluid flow

$(m'_{\text{drop}} - m'_{\text{air}}) g'$  is the buoyancy force felt by the droplet immersed in fluid

$6\pi a' \mu' (\mathbf{v}' - \mathbf{u}')$  is the Stokes drag force on the droplet

$-\frac{m'_{\text{air}}}{2} \left( \frac{d\mathbf{v}'}{dt'} - \frac{D\mathbf{u}'}{Dt'} \right)$  is the added mass force which results as the droplet accelerates surrounding the fluid

$6\pi a'^2 \mu' \int_0^{t'} \frac{1}{\sqrt{\pi \nu(t+s)}} \frac{d}{ds} [\mathbf{v}' - \mathbf{u}'] ds'$  is the Basset-Boussinesq term that accounts for the drag due to the production of vorticity as the particle accelerates from the rest

The Farben corrections are zero if  $\Delta \mathbf{u} = 0$

for example if  $\mathbf{u} = \frac{x}{12\pi t^{1/3}}$  where  $n$  is the number of dimensions for the example in 3 dimensions

for 1D:  $\mathbf{u} = \frac{x}{12\pi t} = 1$ , then  $\frac{\partial \mathbf{u}}{\partial x} = 0$

for 2D:  $\mathbf{u} = \frac{x}{12\pi t^2}$

if  $\mathbf{u} = \frac{x}{12\pi t^3}$ , then  $\Delta \mathbf{u} = 0$

b)

~~DOES NOT CONVERGE~~

$$(1) \frac{m'_{\text{part}}}{V'_{\text{part}}} \frac{dv'(t)}{dt'} = m'_{\text{fluid}} \frac{Du'}{Dt'} + (m'_{\text{part}} - m'_{\text{fluid}}) g' - 6\pi a'^2 \mu' [v' - u'] \quad \boxed{\text{PHYSICAL}}$$

$$\Rightarrow \frac{m'_{\text{part}}}{2} \left[ \frac{dv'}{dt'} - \frac{D}{Dt'} (u' + \cancel{\frac{a'^2}{12} \cancel{v''}}) \right]$$

$$- 6\pi a'^2 \mu' \int_0^{t'} \frac{1}{\sqrt{1 + v'(t-s')}} \frac{d}{ds'} [v' - u' - \cancel{\frac{a'^2}{12} \cancel{v''}}] ds'$$

divide by volume of particle  $V'_{\text{part}} = \frac{4}{3} \pi a'^3$

$$\frac{m'_{\text{part}}}{V'_{\text{part}}} \frac{dv'(t)}{dt'} = \frac{m'_{\text{fluid}}}{V'_{\text{part}}} \frac{Du'}{Dt'} + \frac{m'_{\text{part}} - m'_{\text{fluid}}}{V'_{\text{part}}} g' - \frac{6\pi a'^2 \mu'}{4\pi a'^3} [v' - u'] \quad \boxed{\text{PHYSICAL}}$$

$$- \frac{m'_{\text{part}}}{2V'_{\text{part}}} \left[ \frac{D}{Dt'} \frac{dv'}{dt'} - \frac{D}{Dt'} (u' + \cancel{\frac{a'^2}{12} \cancel{v''}}) \right]$$

$$- \frac{6\pi a'^2 \mu'}{4\pi a'^3} \int_0^{t'} \frac{1}{\sqrt{1 + v'(t-s')}} \frac{d}{ds'} [v' - u' - \cancel{\frac{a'^2}{12} \cancel{v''}}] ds'$$

we know  $\rho'_{\text{part}} = \frac{m'_{\text{part}}}{V'_{\text{part}}}$  and  $\rho'_{\text{fluid}} = \frac{m'_{\text{fluid}}}{V'_{\text{part}}}$ , thus

$$(2) \rho'_{\text{part}} \frac{dv'(t)}{dt'} = \rho'_{\text{fluid}} \frac{Du'}{Dt'} + (\rho'_{\text{part}} - \rho'_{\text{fluid}}) g' - \frac{18\mu' u'}{4a'^2} [v' - u'] \quad \boxed{\text{PHYSICAL}}$$

$$- \frac{\rho'_{\text{fluid}}}{2} \left[ \frac{dv'}{dt'} - \frac{D}{Dt'} (u' + \cancel{\frac{a'^2}{12} \cancel{v''}}) \right]$$

$$- \frac{18\mu' u'}{4a'^2 \sqrt{1+u'^2}} \int_0^{t'} \frac{1}{\sqrt{1+v'(t-s')}} \frac{d}{ds'} [v' - u' - \cancel{\frac{a'^2}{12} \cancel{v''}}] ds'$$

To nondimensionalise, we use  $U' V^* = v'$ ,  $U' U^* = u'$ ,  $L' X^* = x'$ ,  $(L'/U') t^* = t'$ ,  $(U'^2/U') g^* = g'$  which gives

$$\rho'_{\text{part}} \frac{dv'(t)}{L' U' dt^*} = \rho'_{\text{fluid}} \frac{U' Du^*}{L' U' Dt^*} + (\rho'_{\text{part}} - \rho'_{\text{fluid}}) \frac{U' g^*}{L' U' dt^*} - \frac{18\mu' u'}{4a'^2} [U' V^* - U' U^*] \quad \boxed{\text{PHYSICAL}}$$

$$- \frac{\rho'_{\text{fluid}}}{2} \left[ \frac{U' dv^*}{L' U' dt^*} - \frac{D}{L' U' dt^*} (U' U^* + \cancel{\frac{a'^2 b^*}{12} \cancel{v''}}) \right]$$

$$- \frac{18\mu' u'}{4a'^2 \sqrt{1+U'^2}} \int_0^{t^*} \frac{1}{\sqrt{1+U'(t-s^*)}} \frac{d}{ds^*} [U' V^* - U' U^* - \cancel{\frac{a'^2 b^*}{12} \cancel{v''}}] \frac{L'}{U'} ds^*$$

Thus

$$(3) \frac{\rho'_{\text{part}} U' dv^*}{L' U' dt^*} = \frac{\rho'_{\text{fluid}} U'}{L' U' Dt^*} \frac{Du^*}{Dt^*} + (\rho'_{\text{part}} - \rho'_{\text{fluid}}) \frac{U'^2}{L' U' dt^*} g^* - \frac{18\mu' U'}{4a'^2} [V^* - U^*] \quad \boxed{\text{PHYSICAL}}$$

$$- \frac{\rho'_{\text{fluid}}}{2} \left[ \frac{U' dv^*}{L' U' dt^*} - \frac{U'}{L' U' Dt^*} (U^* + \cancel{\frac{a'^2 b^*}{12} \cancel{v''}}) \right]$$

$$- \frac{18\mu' U'}{4a'^2 \sqrt{1+U'^2}} \int_0^{t^*} \frac{1}{\sqrt{1+U'(t-s^*)}} \frac{U'}{L' U' ds^*} [V^* - U^* - \cancel{\frac{a'^2 b^*}{12} \cancel{v''}}] \frac{L'}{U'} ds^*$$

Rearrange: and set  $b^* = 0$

$$\left( \frac{\rho'_{\text{part}} + \rho'_{\text{fluid}}}{2} \right) \frac{U'}{L' U'} \frac{dv^*}{dt^*} = (\rho'_{\text{fluid}} + \rho'_{\text{part}}) \frac{U'}{L' U' Dt^*} + (\rho'_{\text{part}} - \rho'_{\text{fluid}}) \frac{U'}{L' U' dt^*} g^*$$

$$- \frac{18\mu' U'}{4a'^2} (V^* - U^*) - \frac{18\mu' U'}{4a'^2 V^*} \frac{U' L'}{L' \sqrt{1+U'^2}} \int_0^{t^*} \frac{1}{\sqrt{1+U'(t-s^*)}} \frac{d}{ds^*} (V^* - U^*) ds^*$$

Divide by  $\frac{U'^2}{L' U'}$  and by  $\rho'_{\text{part}}$  and use  $\frac{1}{g} = \frac{2(\rho'_{\text{part}} - \rho'_{\text{fluid}})}{\mu' L'} dt^* \text{ (Stokes Law)}$

$$1/(2\rho'_{\text{part}}) (2\rho'_{\text{part}} + \rho'_{\text{fluid}}) \frac{dv^*}{dt^*} = \frac{3\rho'_{\text{fluid}}}{2\rho'_{\text{part}}} \frac{Du^*}{Dt^*} + \frac{\rho'_{\text{part}} - \rho'_{\text{fluid}}}{\rho'_{\text{part}}} g^* - \frac{g}{2} \frac{U' L'}{\rho'_{\text{part}} U'^2} (V^* - U^*)$$

use  $V^* = \frac{\rho'_{\text{part}} U'}{\rho'_{\text{fluid}}} \quad \boxed{\{}$

$$- \sqrt{\frac{g}{2\pi}} \frac{\rho'_{\text{fluid}}}{\rho'_{\text{part}} \sqrt{\frac{2(\rho'_{\text{part}} - \rho'_{\text{fluid}})}{\mu' L'}} \frac{U'}{V^*}} \int_0^{t^*} \frac{1}{\sqrt{1+U'(t-s^*)}} \frac{d}{ds^*} (V^* - U^*) ds^*$$

Now divide by  $\frac{2\rho'_{\text{part}} + \rho'_{\text{fluid}}}{2\rho'_{\text{part}}}$  to get

$$\begin{aligned} \frac{dv^*}{dt^*} &= \frac{3\rho'_{\text{part}}(2\rho'_{\text{part}} + \rho'_{\text{fluid}})g^*}{2\rho'_{\text{part}} + \rho'_{\text{fluid}}} \frac{Du^*}{Dt^*} + \frac{2(\rho'_{\text{part}} - \rho'_{\text{fluid}})}{2\rho'_{\text{part}} + \rho'_{\text{fluid}}} g^* \\ &\quad - \frac{9\mu' L'^2}{2U'^{1/2}(2\rho'_{\text{part}} + \rho'_{\text{fluid}})(V^* - U^*)} - \sqrt{\frac{g}{2\pi}} \frac{2\rho'_{\text{fluid}}}{(2\rho'_{\text{part}} + \rho'_{\text{fluid}}) \sqrt{\frac{2}{3} \left(\frac{U'}{U}\right)^2 \frac{du}{ds}}} \int_0^{t^*} \frac{1}{\sqrt{t^* - s^*}} \frac{d}{ds} (V^* - U^*) ds^* \\ &= \frac{3}{2} \frac{2\rho'_{\text{fluid}}}{\rho'_{\text{fluid}} + 2\rho'_{\text{part}}} \frac{Du^*}{Dt^*} + \left( \frac{\rho'_{\text{fluid}} + 2\rho'_{\text{part}}}{\rho'_{\text{fluid}} + 2\rho'_{\text{part}}} - \frac{3}{2} \frac{2\rho'_{\text{fluid}}}{\rho'_{\text{fluid}} + 2\rho'_{\text{part}}} \right) g^* \\ &\quad - \underbrace{\frac{2}{\rho'_{\text{fluid}} + 2\rho'_{\text{part}}} \frac{g}{2} \frac{L'^2}{q'^{1/2} U'^2} (V^* - U^*)}_{\text{Hence used } \boxed{\rho'_{\text{fluid}} \ll V' = \mu'}} - \sqrt{\frac{g}{2\pi}} \frac{2\rho'_{\text{fluid}}}{2\rho'_{\text{part}} + \rho'_{\text{fluid}}} \sqrt{\frac{9L'^2}{4q'^2} \frac{du}{ds}} \int_0^{t^*} \frac{1}{\sqrt{t^* - s^*}} \frac{d}{ds} (V^* - U^*) ds^* \end{aligned}$$

Hence used  $\boxed{\rho'_{\text{fluid}} \ll V' = \mu'}$  → True because of definition of kinematic viscosity

Defining  $R = \frac{2\rho'_{\text{fluid}}}{\rho'_{\text{fluid}} + 2\rho'_{\text{part}}}$ ,  $Re = \frac{U'L'}{V'}$ ,  $St = \frac{2}{g} \left(\frac{U'}{L'}\right)^2 Re$ , then

$$\frac{dv^*}{dt^*} = \frac{3}{2} R \frac{Du^*}{Dt^*} + \left(1 - \frac{3}{2} R\right) g^* - \frac{R}{St} (V^* - U^*) - \sqrt{\frac{g}{2\pi}} \frac{R}{\sqrt{St}} \int_0^{t^*} \frac{1}{\sqrt{t^* - s^*}} \frac{d}{ds} (V^* - U^*) ds^*$$

and then drop the stars to get

$$\frac{dv}{dt} = \frac{3}{2} R \frac{Du}{Dt} \left(1 - \frac{3}{2} R\right) g - \frac{R}{St} (v - u) - \sqrt{\frac{g}{2\pi}} \frac{R}{\sqrt{St}} \frac{1}{(t-s)} \frac{d}{ds} (v - u) ds$$

as required

c) By assuming  $St \ll 1$ , we get  $\frac{dv}{dt} = \frac{3}{2} R \frac{Du}{Dt} + \left(1 - \frac{3}{2} R\right) g - \frac{k}{St} (v - u)$

(i) If the surrounding airflow is still, then  $y=0$  and  $\frac{du}{dt}=0$   
thus

$$\frac{dv}{dt} = \left(1 - \frac{3}{2} R\right) g - \frac{R}{St} v$$

Solving this gives  $v(t) = C e^{-\frac{R}{St} t} + \frac{R}{St} \left(1 - \frac{3}{2} R\right) g$

with initial condition

$$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} C_x \\ C_y + \frac{R}{St} \left(1 - \frac{3}{2} R\right) g \\ C_z \end{pmatrix} \quad \text{where } g = -g \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

thus  $C_x = 1$ ,  $C_z = 0$  and

$$C_y = \frac{St}{R} \left(1 - \frac{3}{2} R\right) g, \text{ thus } C = \left(1, \frac{St}{R} \left(1 - \frac{3}{2} R\right) g, 0\right)$$

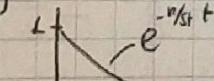
$$\text{thus } v(t) = \left(e^{-\frac{R}{St} t}, \frac{St}{R} \left(1 - \frac{3}{2} R\right) g (e^{-\frac{R}{St} t} - 1), 0\right)$$

(ii) terminal velocity of droplet is when reach  $w \rightarrow \infty$

$$\text{if } t \rightarrow \infty \quad v(t) \rightarrow (0, -\frac{St}{R} \left(1 - \frac{3}{2} R\right) g, 0)$$

if the timescale depends on when we can assume  $e^{-\frac{R}{St} t} = 0$

as



we know that often  $t = \frac{9.2 St}{R}$ ,  $e^{-\frac{R}{St} t} < 0.01$ .

thus if  $t \geq 10 \frac{St}{R}$ , droplet has reached terminal velocity can be assumed

(iii) the position of the droplet can be defined as  $\underline{x}(t) = \int \underline{v}(t) dt$   
thus integration of  $\underline{v}(t)$  gives

$$\underline{x}(t) = \left( A_x - \frac{St}{R} e^{-\frac{Rg}{2}t}, \frac{St}{R} \left( 1 - \frac{3}{2} R \right) g \left( A_y - \frac{St}{R} e^{-\frac{Rg}{2}t} - t \right), A_z \right)$$

assuming the initial position of the droplet is  $\underline{x}(0) = (0, 0, 0)$ ,  
then  $A_x = St/R$ ,  $A_y = St/R$ , &  $A_z = 0$ , thus

$$\underline{x}(t) = \frac{St}{R} \left( 1 - e^{-\frac{Rg}{2}t}, \left( 1 - \frac{3}{2} R \right) g \left( \frac{St}{R} - \frac{St}{R} e^{-\frac{Rg}{2}t} - t \right), 0 \right)$$

then as  $t \rightarrow \infty$ ,  $\underline{x}(t) \rightarrow (St/R, -\infty, 0)$

thus the horizontal distance covered is  $St/R$   
and time it takes them to reach this is, as  
computed before, roughly a  $t = 10 St/R$

(iv) horizontal range is given as  $\frac{St}{R} = x_{\max}$

in dimensional units this becomes

$$x_{\max} = \frac{2}{g} \left( \frac{a'}{L'} \right)^2 \frac{U' L'}{V'} \frac{\rho'_{\text{air}} + 2\rho'_{\text{dmg}}}{2 \rho'_{\text{air}}}$$

now suppose  $\rho'_{\text{air}} = 1.149 \text{ kg/m}^3$ ,  $\rho'_{\text{dmg}} = 1000 \text{ kg/m}^3$   
 $V' = 16.36 \times 10^{-6} \text{ m}^2/\text{s}$ ,  $a' = d'/2 = \cancel{5.5 \times 10^{-6}} \text{ to } 250 \mu\text{m}$

$$x_{\max} = \frac{2}{g} \left( \frac{5}{2} \cdot 10^{-6} \right)^2 \frac{1}{16.36 \cdot 10^{-6}} \frac{1.149 + 2000}{2.298} \frac{U' L'}{V'} \approx \frac{\cancel{1.149}}{7.39 \cdot 10^{-4}} \frac{U' L'}{V'} \text{ m}$$

$$\text{to } \frac{2}{g} \left( 250 \cdot 10^{-6} \right)^2 \frac{1}{16.36 \cdot 10^{-6}} = 0.739 \frac{U' L'}{V'} \text{ m}$$