Rules:

- Unless otherwise stated, all answers must be mathematically justified.
- Partial answers will be graded.
- Your submission has to be uploaded to Gradescope. In Gradescope, indicate the page on which each problem is written.
- You can work in groups but each student must write his/her/their own solution based on his/her/their own understanding of the problem. Please list on your submission the students you work with for the homework (this will not affect your grade).
- Problems with a (*) are extra credit, they will not (directly) contribute to your score of this homework. However, for every 4 extra credit questions successfully answered your lowest homework score get replaced by a perfect score.
- If you have any questions, feel free to contact me (mgabrie@nyu.edu) or to stop at the office hours.

Problem 2.1 (2 points). Which of the following are linear transformations? Justify.

(a)
$$T: \left| \begin{array}{ccc} \mathbb{R}^2 & \to & \mathbb{R} \\ (x,y) & \mapsto & x-y \end{array} \right|$$

(b)
$$T: \left| \begin{array}{ccc} \mathbb{R}^2 & \to & \mathbb{R}^2 \\ (x,y) & \mapsto & (3x+y,x-xy) \end{array} \right|$$

(c)
$$T: \begin{bmatrix} \mathbb{R}^{n \times n} \to \mathbb{R}^n \\ A \mapsto \operatorname{diag}(A) \end{bmatrix}$$
 where $\operatorname{diag}(A)$ is the diagonal of the matrix A , defined by

$$\operatorname{diag}(A) = (A_{1,1}, \dots A_{n,n}).$$

(d)
$$T: \begin{bmatrix} \mathbb{R}^{n \times n} \to \mathbb{R}^{n \times n} \\ A \mapsto A^{-1} \end{bmatrix}$$
 defined on the set of homothety matrices $S = \{\lambda \operatorname{Id}_n \mid \lambda \in \mathbb{R}^*\}$ (see slide 19 of lec 02), recall that \mathbb{R}^* is the set of real without 0.

Problem 2.2. Consider a matrix $A \in R^{m \times n}$ and denote by $(c_1, \ldots c_n)$ its columns (vectors in \mathbb{R}^m). Prove the equality of the sets

$$\operatorname{Im}(A) = \operatorname{Span}(c_1, \dots, c_n).$$

Recall that $\operatorname{Im}(A) \stackrel{def}{=} \{Ax \mid x \in \mathbb{R}^n\}.$

Problem 2.3 (3 points). (Wait for after next lab to complete this problem! or have a look at the last few slides we did not cover during class that are now completed on the website to find out what Gaussian elimination does.) Let

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 2 & 4 & 4 \\ 3 & 7 & k \end{pmatrix}$$

(a) Using Gaussian elimination solve Ax = 0 and give a basis of KerA (show all your steps). You will have to differentiate cases according to values of k.

- (b) Why does the system Ax = (1, 2, 3) has at least one solution (for any value of k)? Do not solve the system, use previous results of this HW to justify your answer. Find all values of k for which the system Ax = (1, 2, 3) has infinitely many solutions.
- (c) Find all values of k for which the system Ax = (10, 1, 2017) has exactly one solution. Give this solution as a function of k.

Problem 2.4 (2 points). Let B and P be the matrices of in $\mathbb{R}^{3\times 3}$:

$$P = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad B = \begin{pmatrix} B_{1,1} & B_{1,2} & B_{1,3} \\ B_{2,1} & B_{2,2} & B_{2,3} \\ B_{3,1} & B_{3,2} & B_{3,3} \end{pmatrix}$$

with arbitrary entries for B.

- (a) Compute the matrix product BP. Why is P called a permutation matrix?
- (b) Compute PB. What can you notice?

Problem 2.5 (*). Let
$$A = \begin{pmatrix} 2 & -1 \\ 2 & -1 \end{pmatrix} \in \mathbb{R}^{2 \times 2}$$
 and $T : \begin{pmatrix} \mathbb{R}^{n \times n} & \to & \mathbb{R}^{n \times n} \\ M & \mapsto & AM \end{pmatrix}$.

- (a) Show that T is linear.
- (b) Give a basis of Ker(T) and a basis of Im(T).