

Session 8: Linear Algebra for Graphs (& SVD)

Optimization and Computational Linear Algebra for Data Science

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1. Singular Value Decomposition

- ❖ Data matrix $A \in \mathbb{R}^{n \times m}$
- ❖ “Covariance matrix” $S = A^T A \in \mathbb{R}^{m \times m}$.
- ❖ S is symmetric (positive semi-definite).
- ❖ **Spectral Theorem:** there exists an orthonormal basis v_1, \dots, v_m of \mathbb{R}^m such that the v_i ’s are eigenvectors of S associated with the eigenvalues $\lambda_1 \geq \dots \geq \lambda_m \geq 0$ (positive semi-definite).

Definitions: Singular values/vectors

For $i = 1, \dots, m$:

- ❖ We define $\sigma_i = \sqrt{\lambda_i}$, called the i^{th} **singular value** of A .

Let $r = \text{rank}(A) = \text{number of non-zero } \lambda_i \text{'s (exercise!)}.$

For $i = 1, \dots, r$:

- ❖ We call $u_i = \frac{1}{\sigma_i} A v_i$ the i^{th} **left singular vector** of A .
- ❖ u_1, \dots, u_r are orthonormal.
- ❖ If $r < n$, we add u_{r+1}, \dots, u_n such that u_1, \dots, u_n is an orthonormal basis of \mathbb{R}^n .

For $i = 1, \dots, m$:

- ❖ Observe that we have $A v_i = \sigma_i u_i$ and $A^T u_i = \sigma_i v_i$.
- ❖ We call v_j the i^{th} **right singular vector** of A .

Singular Value decomposition

Theorem

Let $A \in \mathbb{R}^{n \times m}$. Then there exists two orthogonal matrices $U \in \mathbb{R}^{n \times n}$ and $V \in \mathbb{R}^{m \times m}$ and a matrix $\Sigma \in \mathbb{R}^{n \times m}$ such that $\Sigma_{1,1} \geq \Sigma_{2,2} \geq \dots \geq 0$ and $\Sigma_{i,j} = 0$ for $i \neq j$, that verify

$$A = U\Sigma V^T.$$

Remark: While eigendecomposition is for some square matrices, singular value decomposition exists for all rectangular matrices.

Remarks

- ❖ Right singular vectors v_i 's are eigenvectors of $A^T A \in \mathbb{R}^{m \times m}$, with eigenvalues $\lambda_i = \sigma_i^2$.
- ❖ Left singular vectors u_i 's are eigenvectors of $AA^T \in \mathbb{R}^{n \times n}$, with eigenvalues $\lambda_i = \sigma_i^2$.

Low-rank approximation

How can we approximate a matrix A by a matrix of "small" rank?

Questions?

Questions?

2. Graphs and Graph Laplacian

2.1 Definitions: Graphs

Consider a graph G made of n **nodes** with some **edges**:

Definition

The **adjacency matrix** A of G is the $n \times n$ matrix with entries

$$A_{i,j} = \begin{cases} 1 & \text{if edge between nodes } i \text{ and } j \\ 0 & \text{otherwise} \end{cases}$$

Definition

The **degree matrix** $D \in \mathbb{R}^{n \times n}$ of G is the diagonal matrix with

$$D_{i,i} = \#\{\text{neighbors of } i\} = \deg(i)$$

Graph Laplacian

Definition

The Laplacian matrix of G is defined as

$$L = D - A.$$

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$$L = D - A.$$

For all $x \in \mathbb{R}^n$,
$$x^\top Lx = \sum_{i \sim j} (x_i - x_j)^2.$$

Proof.

2.2 Properties of the Laplacian

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Algebraic connectivity

Proposition

- ❖ The multiplicity of the eigenvalue 0 of L (i.e. the number of i such that $\lambda_i = 0$) is equal to the number of connected components of G .
 - ❖ In particular, G is connected if and only if $\lambda_2 > 0$.
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- ❖ λ_2 is sometimes called the «algebraic connectivity» of G and measures somehow how well G is connected.
 - ❖ From now, we assume that G is connected, i.e. $\lambda_2 > 0$.

3. Application: Spectral graph clustering

3.1 Spectral clustering algorithm

Input: Graph Laplacian L , number of clusters k

1. Compute the first k orthonormal eigenvectors v_1, \dots, v_k of the Laplacian matrix L .
2. Associate to each node i the vector $x_i = (v_1(i), \dots, v_k(i))$.
3. Cluster the points x_1, \dots, x_n with (for instance) the k -means algorithm.¹
4. Deduce a clustering of the nodes of the graph.

¹Chap 13 - Elements of Statistical Learning (Hastie, Tibshirani, and Friedman

3.2 The case of two groups

For $k = 2$ groups:

1. Compute the second eigenvector v_2 of the Laplacian matrix L .
2. Associate to each node i the number $x_i = v_2(i)$.
3. Cluster the nodes in:

$$S = \{i \mid v_2(i) \geq \delta\} \quad \text{and} \quad S^c = \{i \mid v_2(i) < \delta\},$$

for some $\delta \in \mathbb{R}$.

How does this work?

Let $S \subset \{1, 2, \dots, n\}$.

Definition

The cut of S , denoted $\text{cut}(S)$ is defined as the number of edges between S and S^C .

Ex.

❖ We encode S by a vector $x \in \{+1, -1\}^n$ defined by

Minimal cut problem

Recall $x^\top Lx = \sum_{i \sim j} (x_i - x_j)^2$.

Proposition

For $x \in \{+1, -1\}^n$ representing the subset of nodes S ,

$$\text{cut}(S) = \frac{1}{4} x^\top Lx$$

Minimal cut problem

Recall $x^\top Lx = \sum_{i \sim j} (x_i - x_j)^2$.

Proposition

For $x \in \{+1, -1\}^n$ representing the subset of nodes S ,

$$\text{cut}(S) = \frac{1}{4} x^\top Lx$$

Goal. Find S (or equivalently $x \in \{+1, -1\}^n$) such that

- ❖ $\text{cut}(S)$ is small
- ❖ S and S^C have same number of nodes

« Min-Cut » is NP-Hard

Goal: minimize $x^{\top} L x$ subject to $\begin{cases} x \in \{-1, 1\}^n \\ x \perp (1, \dots, 1). \end{cases}$

Spectral clustering as a «relaxation»

Idea: We first solve the « relaxed » problem:

$$\text{minimize} \quad v^T L v \quad \text{subject to} \quad \begin{cases} \|v\| = \sqrt{n} \\ v \perp (1, \dots, 1). \end{cases}$$

Questions?

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