(3) LAPLACE FRANSFORM	S: -55A + 15A = -544
(a) x(t) = \frac{1}{5} t e^{-3t} u(-t)	10A = -1
x.(t) = e = 3t u(-t)	A = -1/10
4 {x.(4)} 1 Refr } < -3	10 (2+2) 01 + 10 (2+2) 01
DIFFERENTIATION	- 10 e st ult) = 11 e - 15t ult)
-t x(f) = (q x(1))	
dr [-11]	(4) LAPLACE TRANSFORM
(5+3)20 ROC ROLLOCO)	y(t) = x, (3t-7) * x3(-t+5)
37 2 37 3 45	LT { x, (t) } = LT {-e^{-2t}u(t)} = 1
(b) * (t) + e + m (st) u(t) + e - u(t)	17 { x = (t) } = 17 { c 4 u(t) } = 1
$=$ \times , (t) = e^{-4} \times , (t) \times	LT { x. (3t) } : TIME JCALE = 1 (1) = 95+36
x > (t) = e ^{-6t} ult)	LT {x, (st-7)} TIME SHIFT e 75 1
(S+4)3+4 Re(1)3>-4	11 { × 2 (-t) } TIME JCALE - 5+4
LT {x, (t)} - 1 Re { 5} > -16	
LINEARITY:	$e^{-75}\left(\frac{1}{95+36}\right)\left(\frac{1}{6}-255\right)\left(\frac{1}{5+4}\right)$ $\frac{1}{(95+36)(55+4)}$
(5+4) 2 + 4 + 5 + 6	- e-125
00+23+6 CI + 2C	(95+36)(5+4)
13 + 142 + 685 + 120 1 23 + 142 + 625 + 120	
5° + 201 + 32	
N3 + 14N2 + 68N + 120	(5) Z - TRANSFORM
UNING QUADRATIC [CALCULATOR]	y [n] - 9 y [n-1] + 2y [n-2] = x[n]
ROCTS - 4 ± 2i	APPLYING Z. TRANSFORM TO BOTH SIDES
ROC : - G 17 - 4	$Y(z) - \frac{Q}{2}z' Y(z) + 2z^{-2}Y(z) = x(z)$
	$\lambda(z)\left(1-\frac{3}{d}z^{-1}+3z^{-2}\right)=\lambda(z)$
(c) X(s) = 5+4 5+405+75	$H(z) = \frac{Y(z)}{X(z)} = \frac{1}{1 - \frac{9}{2}z^{-1} + 2z^{-2}}$
(0+5)(0+15)	1 2 - 9 z 1 > z 2 + 3
X+T + X+15	$= \frac{1}{\left(\frac{1}{12} - \frac{1}{12} - \frac{1}{12}\right)^2 + \left(\frac{1}{12}\right)^2}$
A(5+15) + B(5+5) = 5+4	= (\frac{1}{2} - \frac{15}{15} z^{-1})^{2} - (2\frac{1}{12})^{2}
3 = -15 2 -15B +5B = -15+4	(15 2 - 15) (15 - 15)
, -108 = -11 B · 10	12 427/12 13 4137