



MASSpace'24

International Workshop on Autonomous Agents and
Multi-Agent Systems for Space Applications

Steve A. Chien, Gauthier Picard, Itai Zilberstein

Motivations and objectives

- Disseminating and sharing **recent advances** in the use of agent-based and multi-agent-based models and techniques in the Space domain
- The use of agent-based and multi-agent systems in aerospace and space is **gaining traction**
- Promising approaches for **modeling and solving distributed, complex and dynamic problems**
- **Multiple applications:** multiple spacecraft operations and maintenance, onboard-ground coordination, mission simulation, multi-mission operation, autonomous navigation, collective robotics...
- **Cross-fertilization** of AAMAS and Space
 - Provide Space domain experts with the means to use these multi-agent models and techniques
 - Challenge multi-agents models and techniques with novel problems coming from the Space domain

Programme

<https://mas-space.github.io/aamas2024ws/#programme>

0855-0900	Introductory remarks
0900-1000	Invited talk
1000-1030	Coffee break
1030-1230	Session 1
1030-1055	<i>Lunar Leader: Persistent, Optimal Leader Election for Multi-Agent Exploration Teams</i>
1055-1120	<i>CADRE MoonDB: Distributed Database for Multi-Robot Information-Sharing and Map-Merging for Lunar Exploration</i>
1130-1155	<i>DRIFT: Deep Reinforcement Learning for Intelligent Floating Platforms Trajectories</i>
1155-1220	<i>Integrated Modeling and Planning for On-Orbit Assembly of Large Space Structures with Mobile Crawling Robots</i>
1230-1400	Lunch break
1400-1515	Session 2
1400-1425	<i>Going Beyond Mono-Mission Earth Observation: Using the Multi-Agent Paradigm to Federate Multiple Missions</i>
1425-1450	<i>Hierarchical Temporal Planning in an Earth Observation Satellite Software Architecture</i>
1450-1515	<i>Understanding Drill Data for Autonomous Application</i>
1515-1530	Closing remarks

Invited talk

“ Multi-agent autonomy on the Moon: NASA' Coordinated Autonomous Distributed Robotics Explorers (CADRE) mission”

Federico Rossi, NASA JPL, USA





Have a nice workshop!