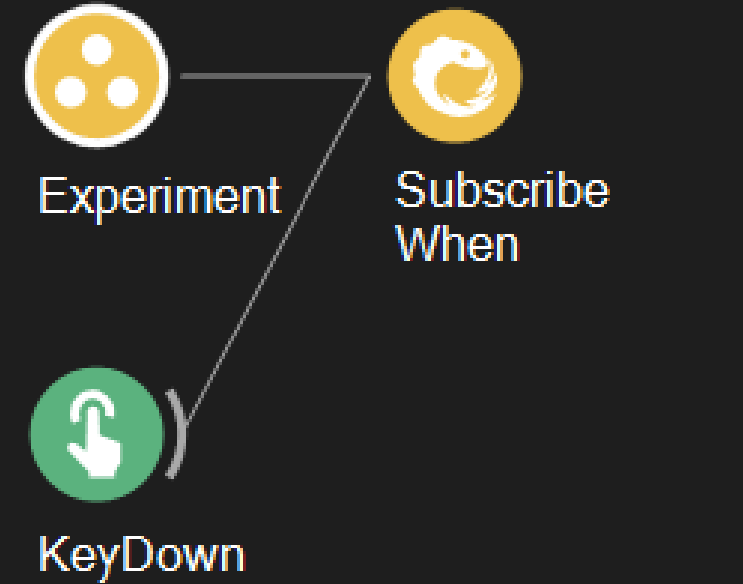


1. Start Bonsai
2. The program will track animals if present
3. Start Experiment workflow by striking "1"

## Workflow



Back up stop timer



Press I for picture of video feed

Captures picture of arena when key pressed



Enter Exp Information here



Tracking and video feed

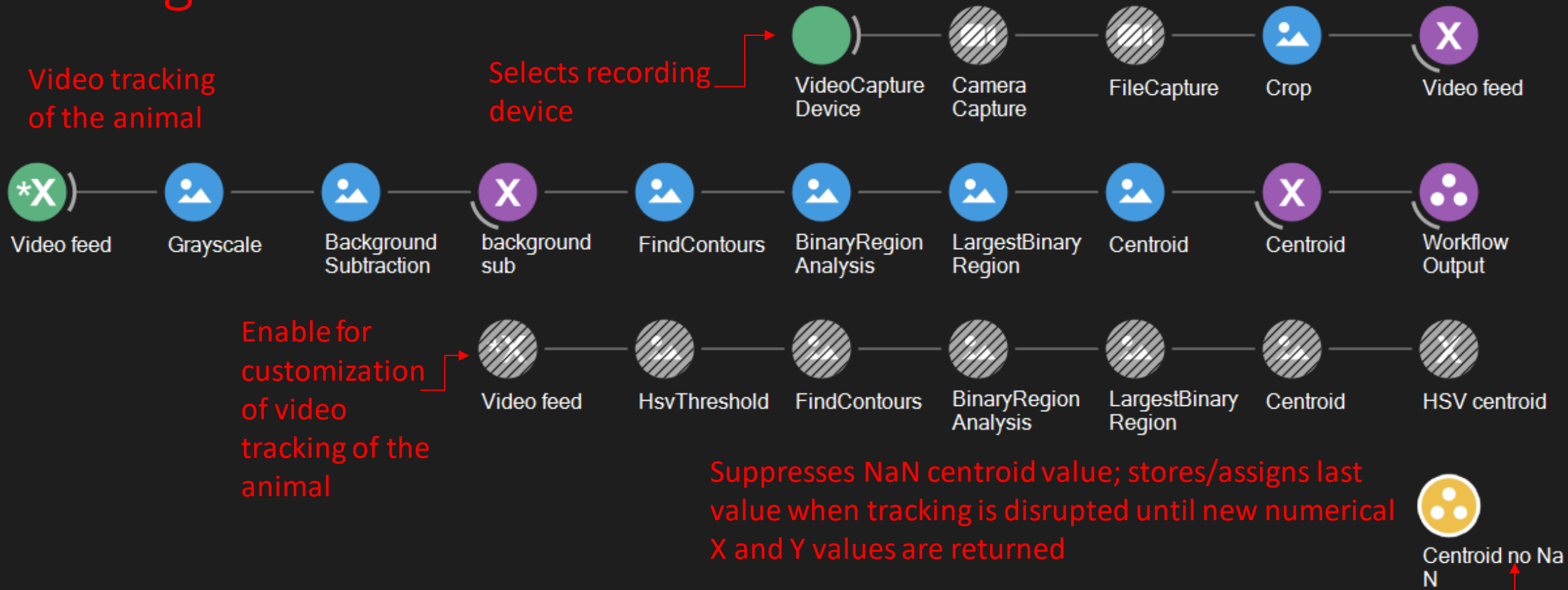


ard1  
Arduino with standard Firmata flashed

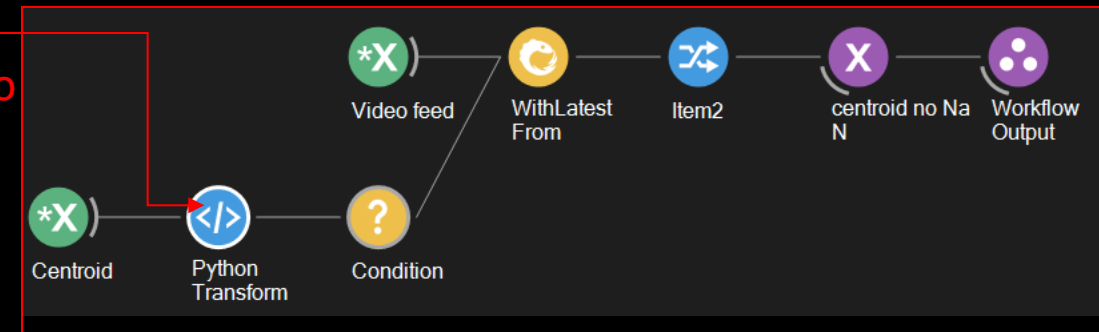


Video recorder  
Saves video of trial

# Tracking and Videofeed



Python Code  
To convert NaN to zero



# Experiment Naming

Base file  
naming to  
be assigned  
to all files

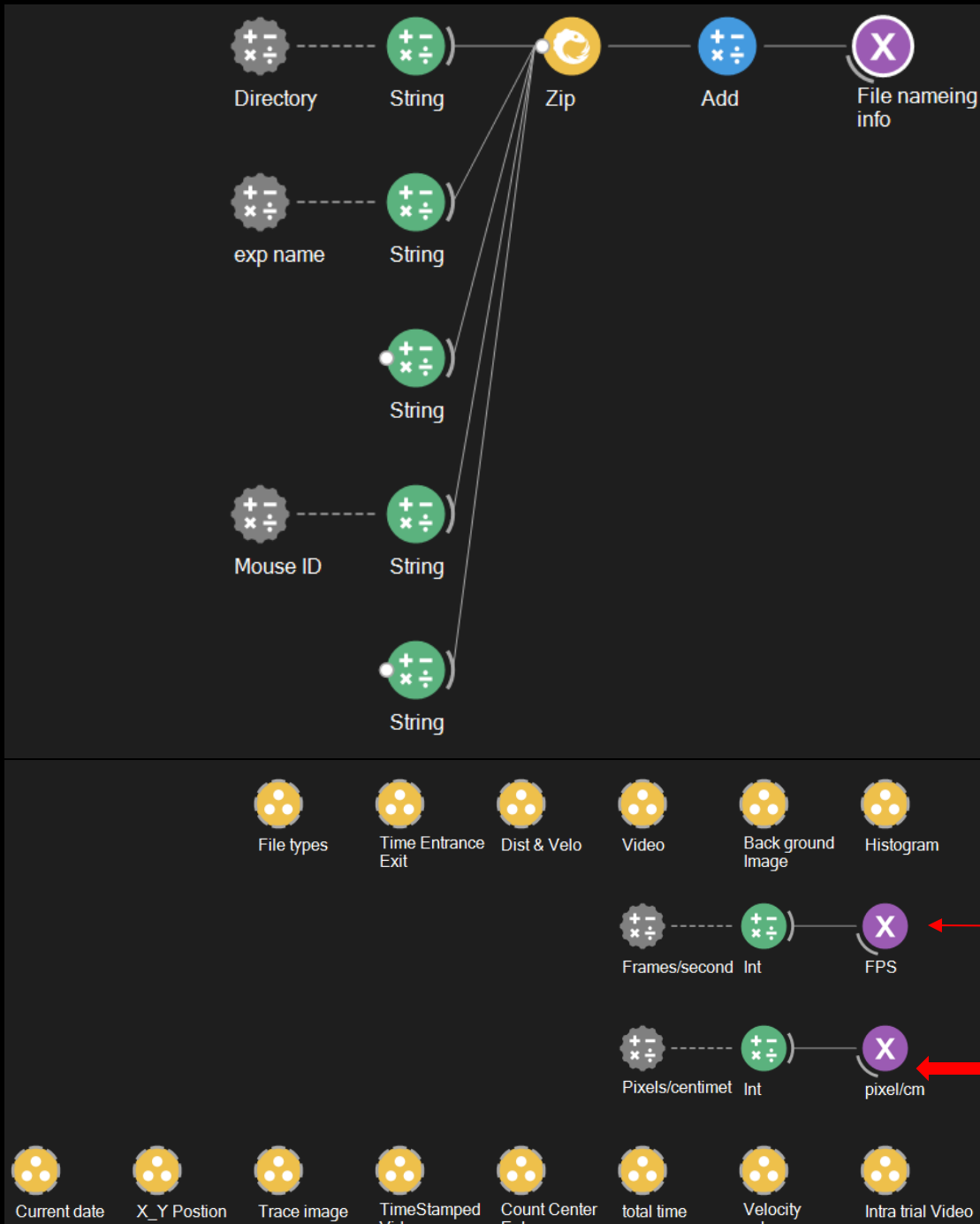
Enter pixels/centimeter  
here

Arena Videofeed Pixel  
Width/ Real Arena  
Distance Width (cm)

(in this case  $*360 / 50.8 = 7$ )

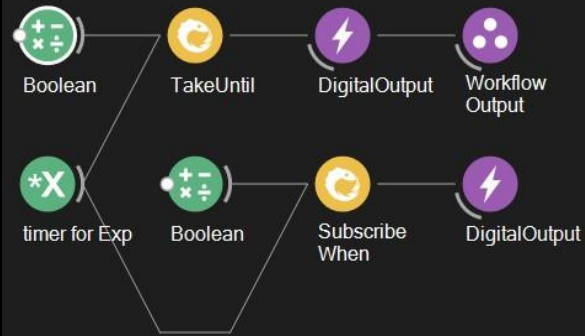
\*Specific to your video

Allows user to change FPS  
of video analysis  
(important to match video  
for velocity calculations)

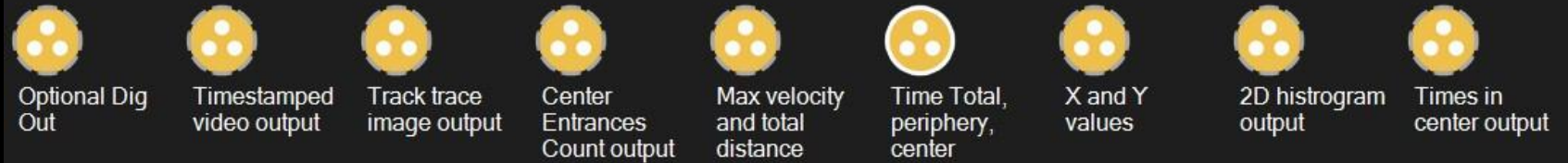


Example - Cyclops LED Driver is being used and reads pin 13 HIGH on the Arduino output and writes HIGH for stimulation pulse train (In place of the teensy in the cyclops a second Arduino could be used as function generator)

# Experiment Workflow

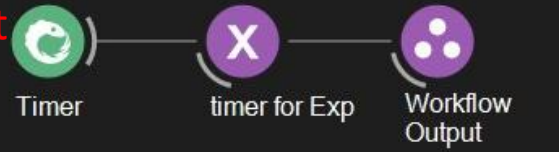


Nodes can be Enabled/Disabled for desired outputs files in Experiment name group to change output

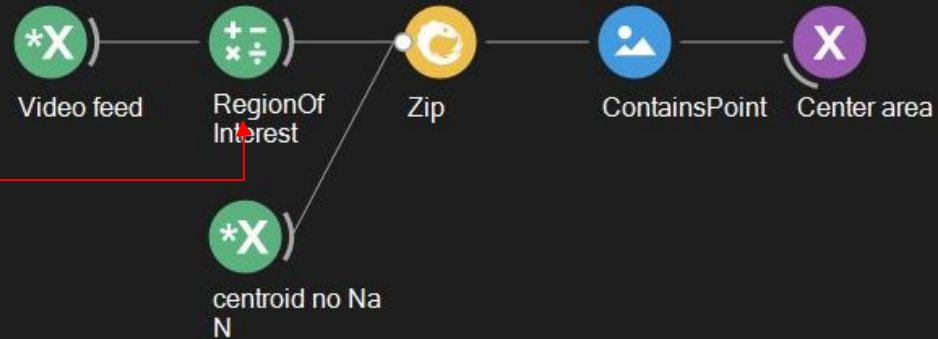
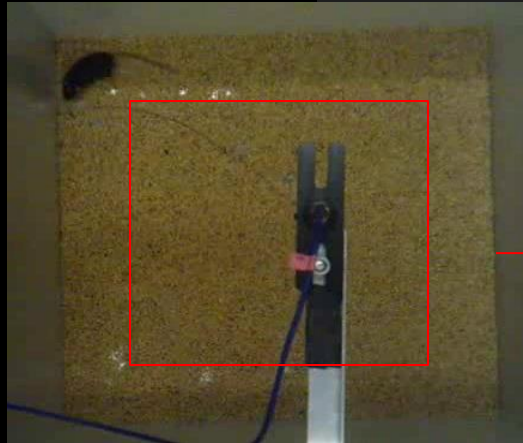




Timer for experiment



Assigning ROIs



Example-

For 50%/50% division  
360X360 Whole Arena  
129600 total pixels

255X255 or 254X254 Center Area  
64800 total pixel Center Area

Properties

**RegionOfInterest (PropertySource' 2)**  
Represents a data source created from an operator property.

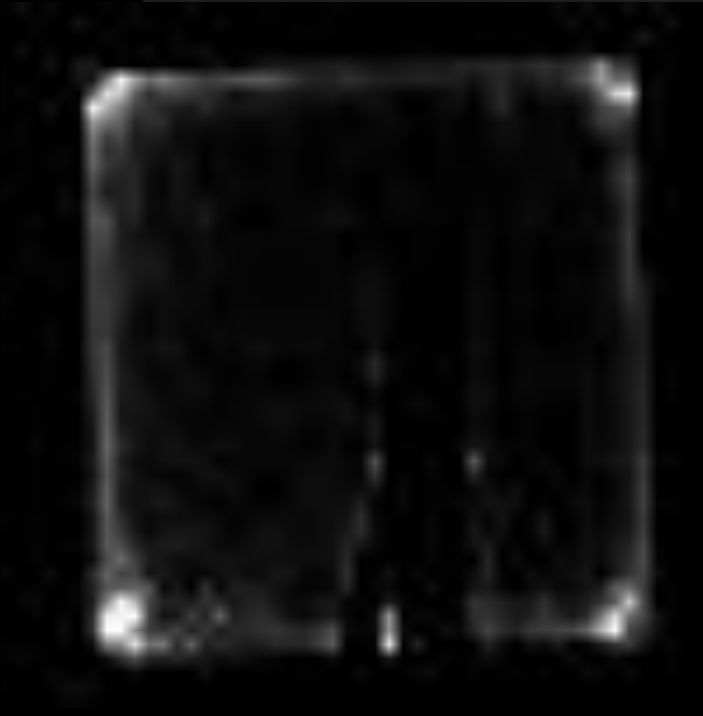
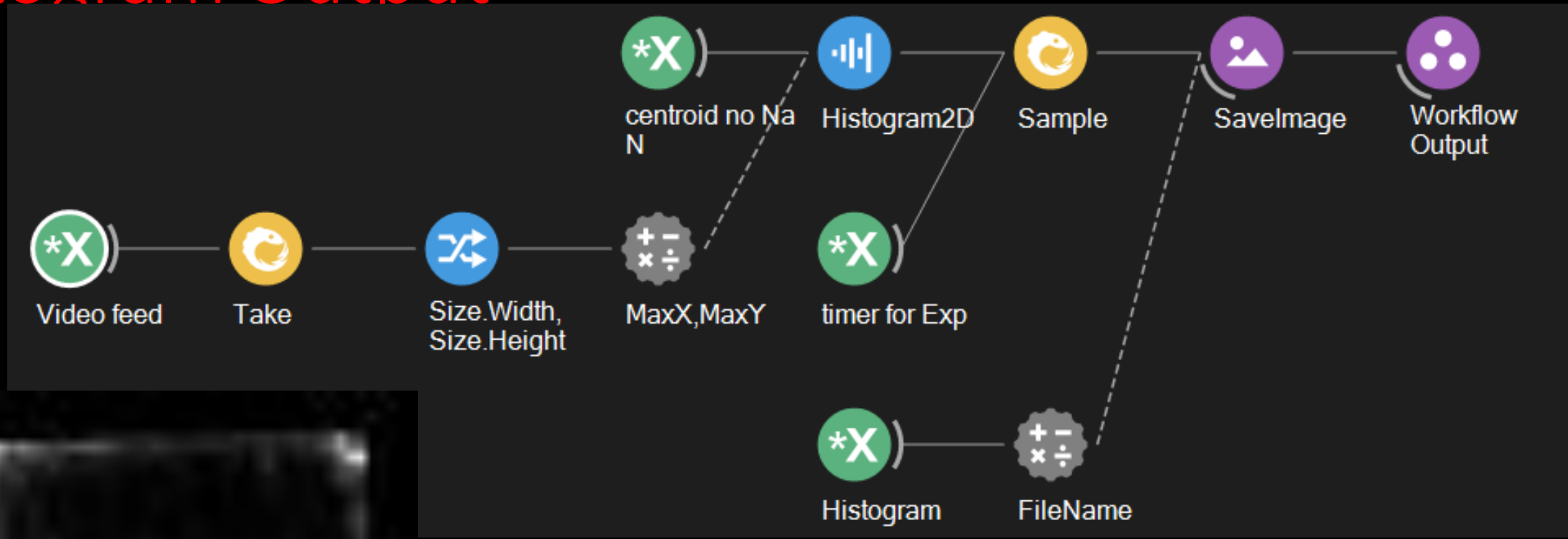


Misc

Value

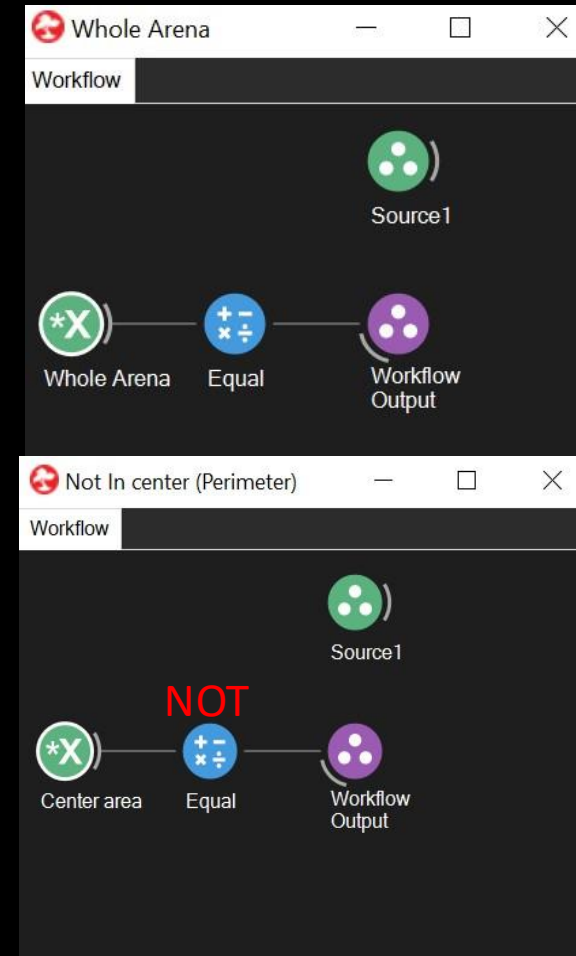
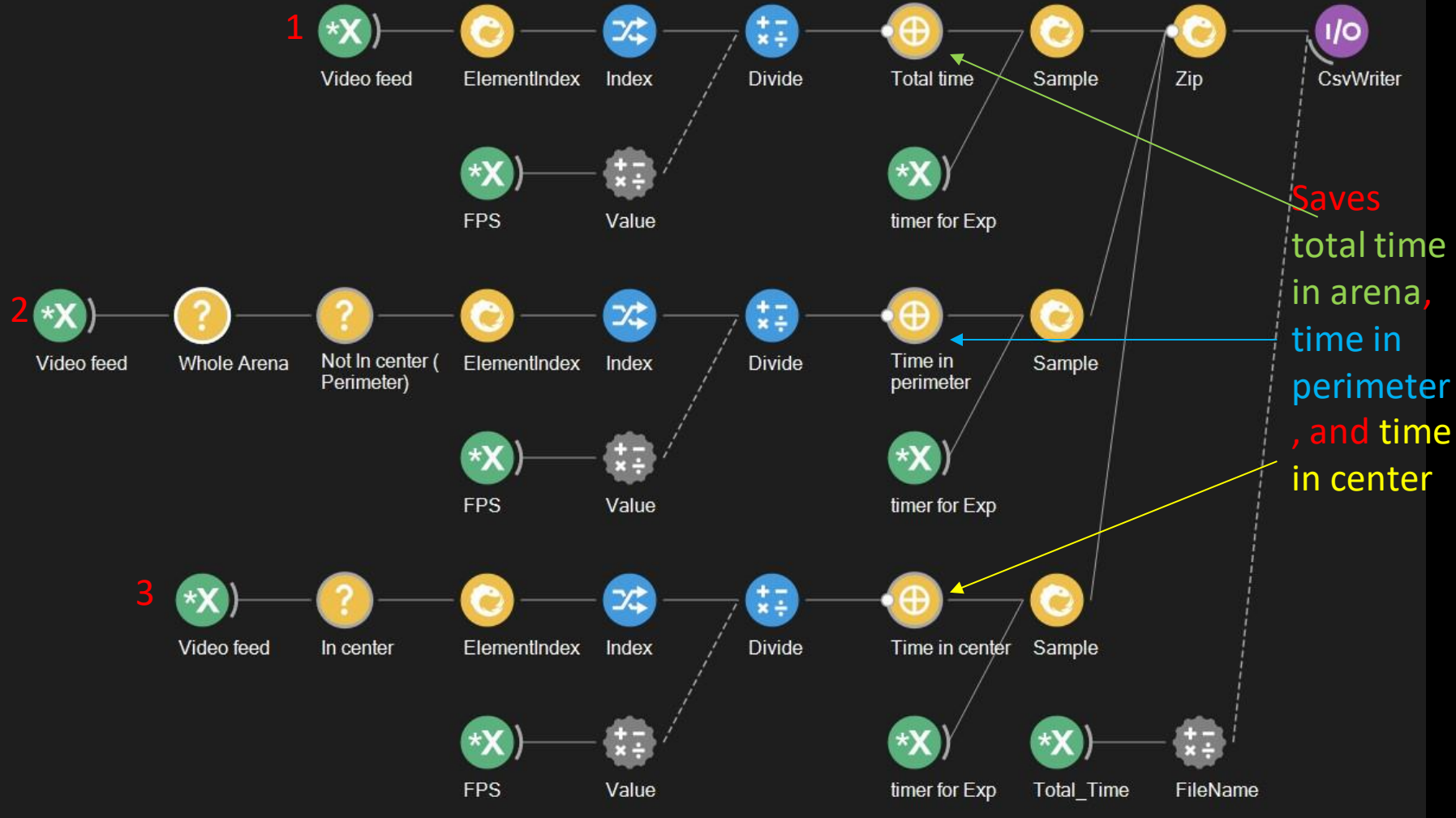
100,82,255,255

# 2D Histogram Output





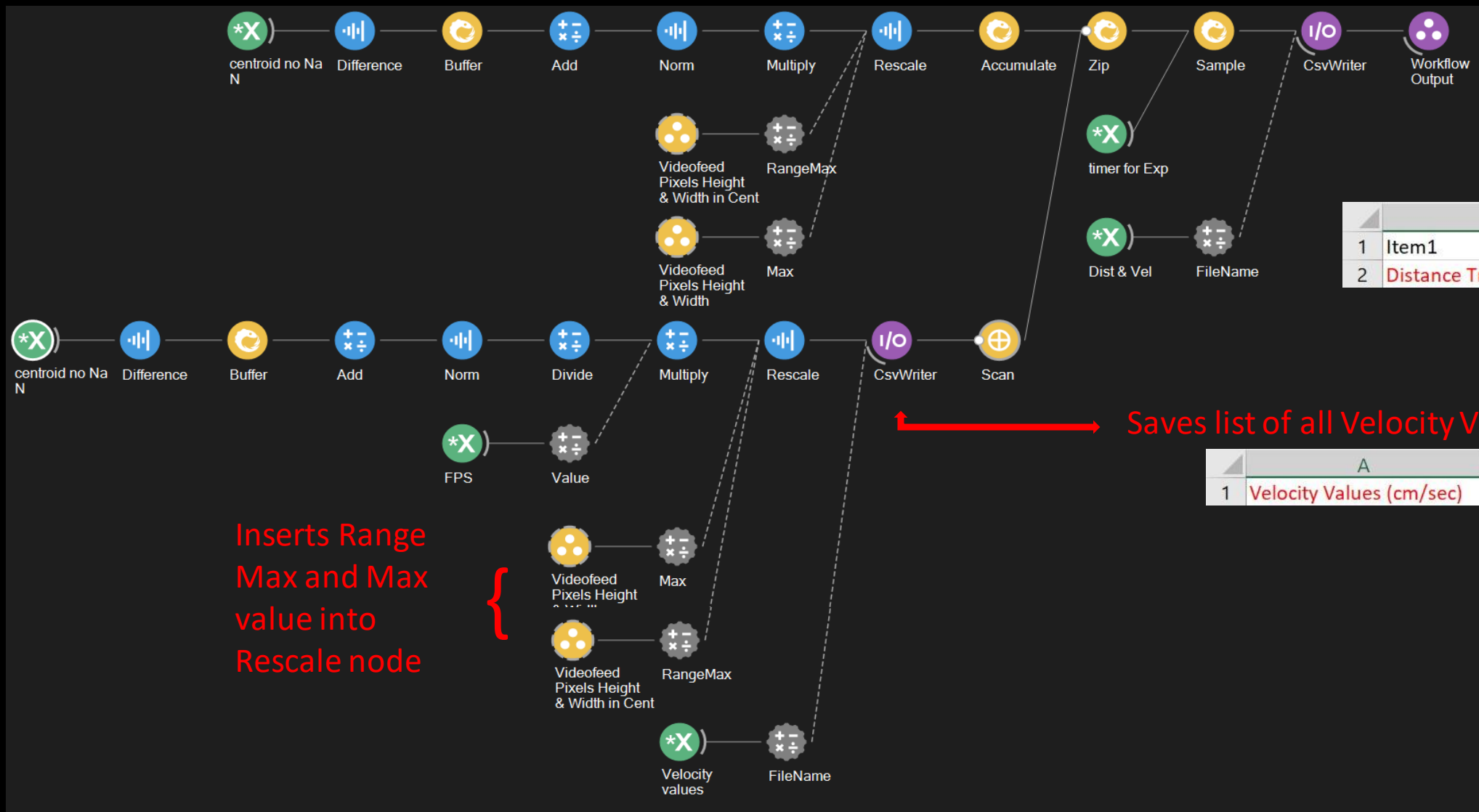
# Total Time, Perimeter, and Center Output



Key to cvs file output

1	2	3
A	B	C
Item1	Item2	Item3
Total Time (sec)	Time in perimeter (sec)	Time in Center Area (sec)

# Max Velocity and Distance Traveled Output



Saves Distance Traveled and Max Velocity

	A	B
1	Item1	Item2
2	Distance Travelled (cm)	Max Velocity (cm/s)

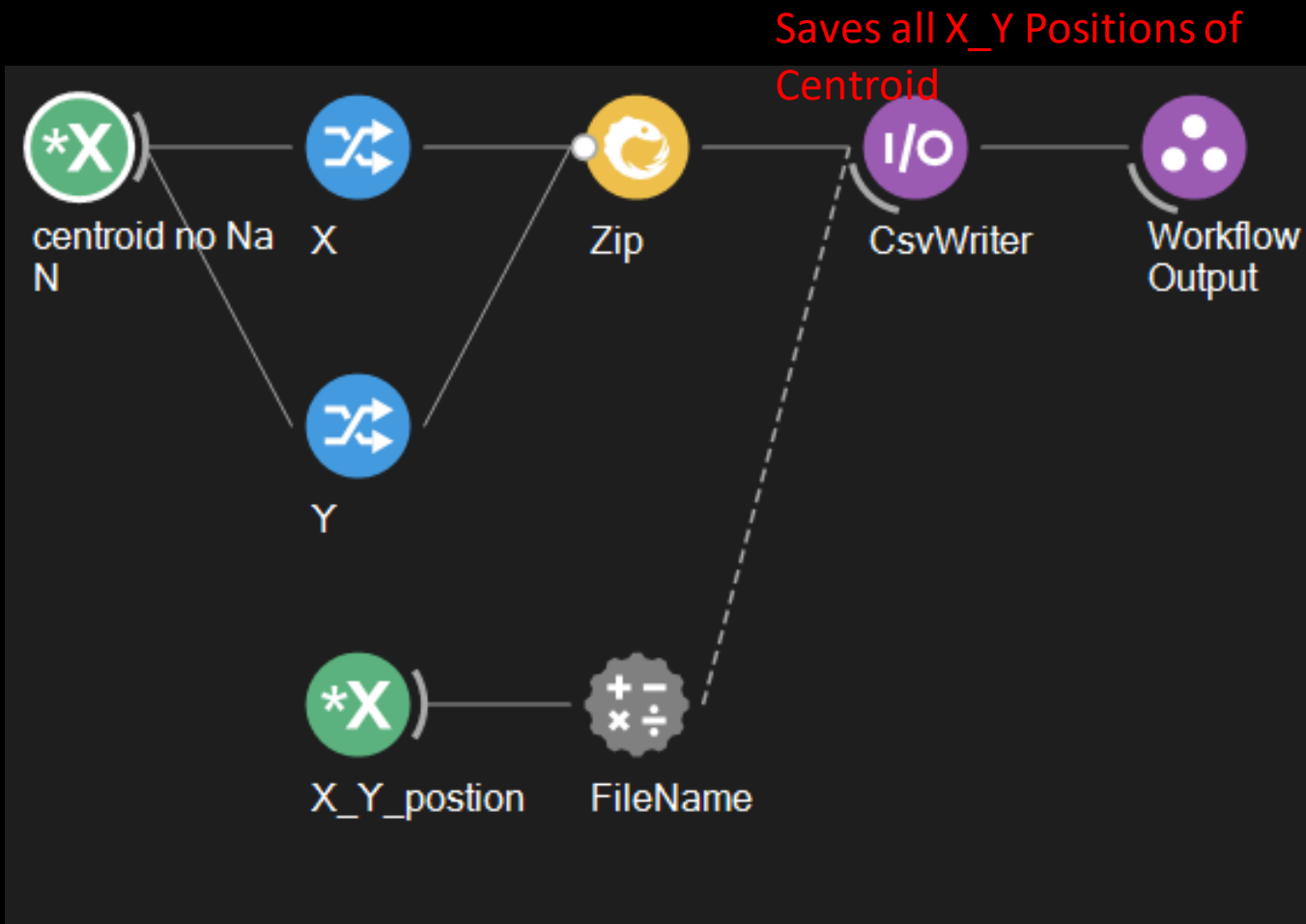
Saves list of all Velocity Values

	A
1	Velocity Values (cm/sec)

Inserts Range Max and Max value into Rescale node

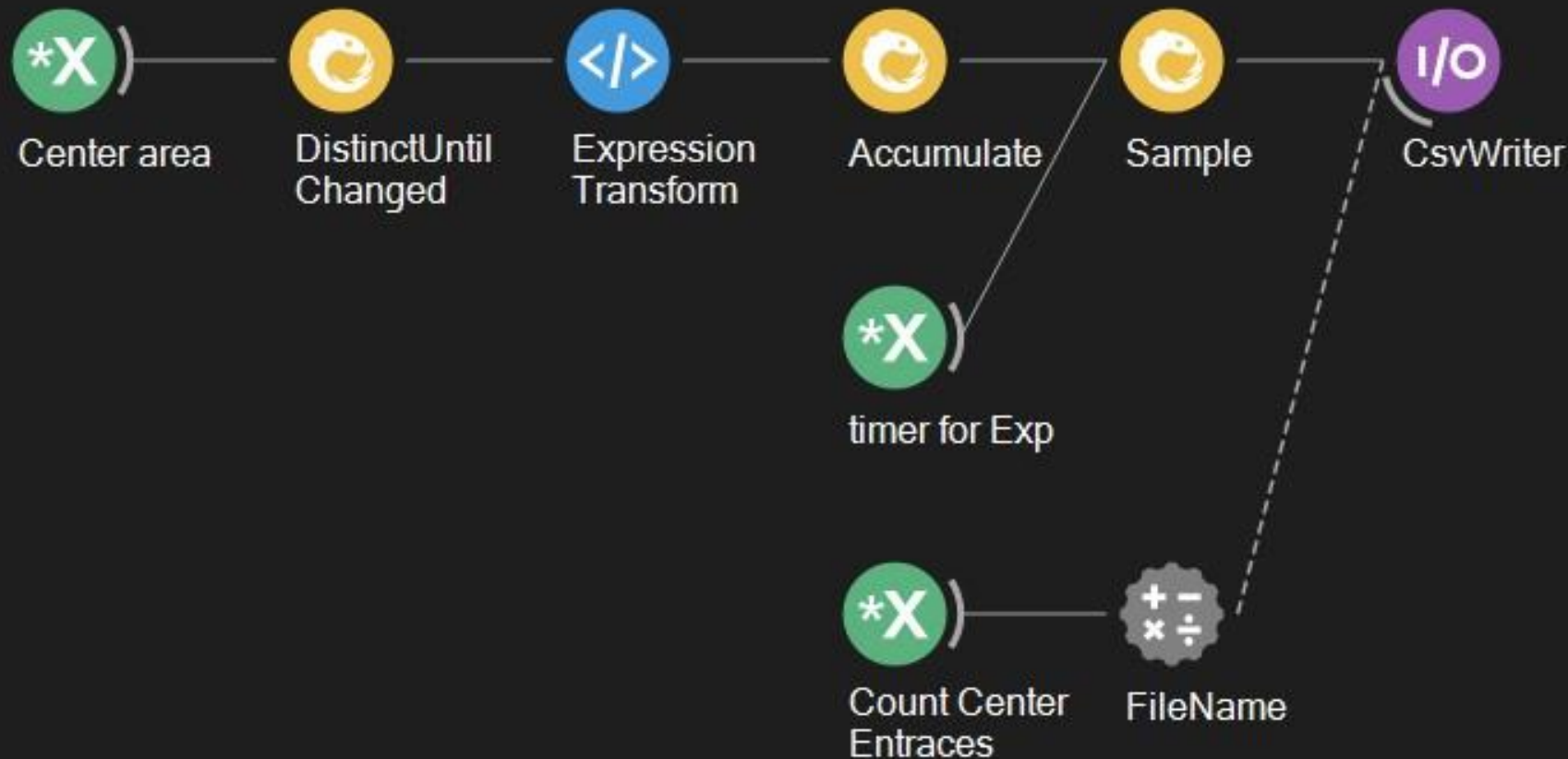


# X\_Y Position Output



	A	B
1	Item1	Item2
2	X Position	Y position

# Center Entrances Count Output

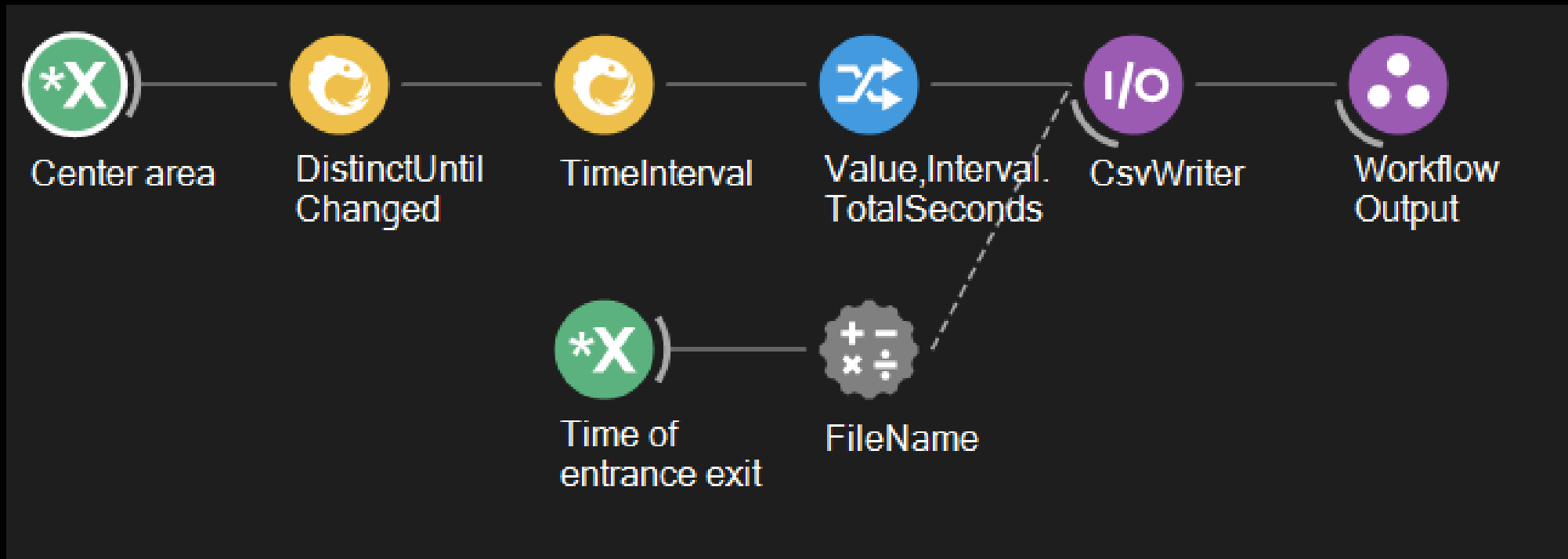


Saves total number of times centroid entered the Center Area

	A
1	# of center entrances

# Time of each episode in/out of center output

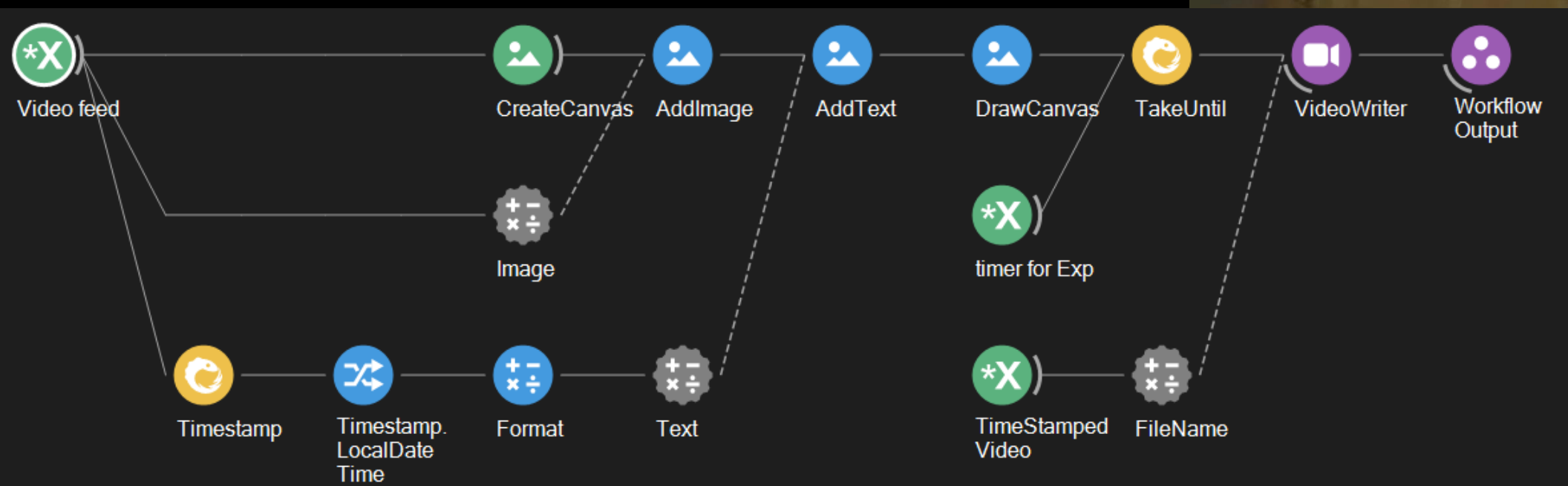
	A	B
1	Item1	Item2
2	TRUE	Time Interval in Center (sec)



04/14/2020 13:05:52

# Timestamp Video Output

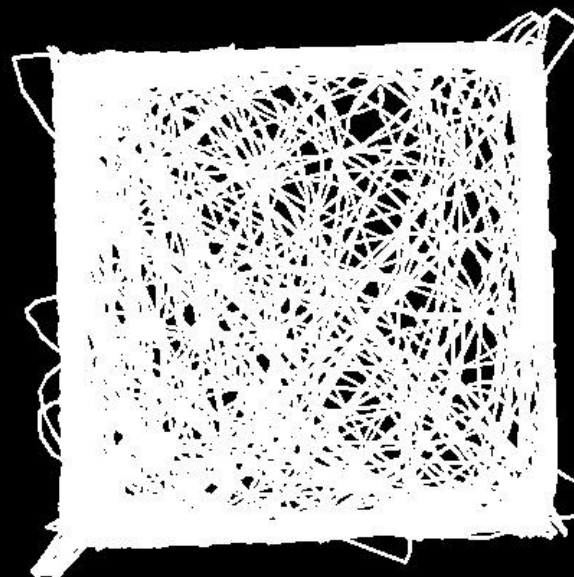
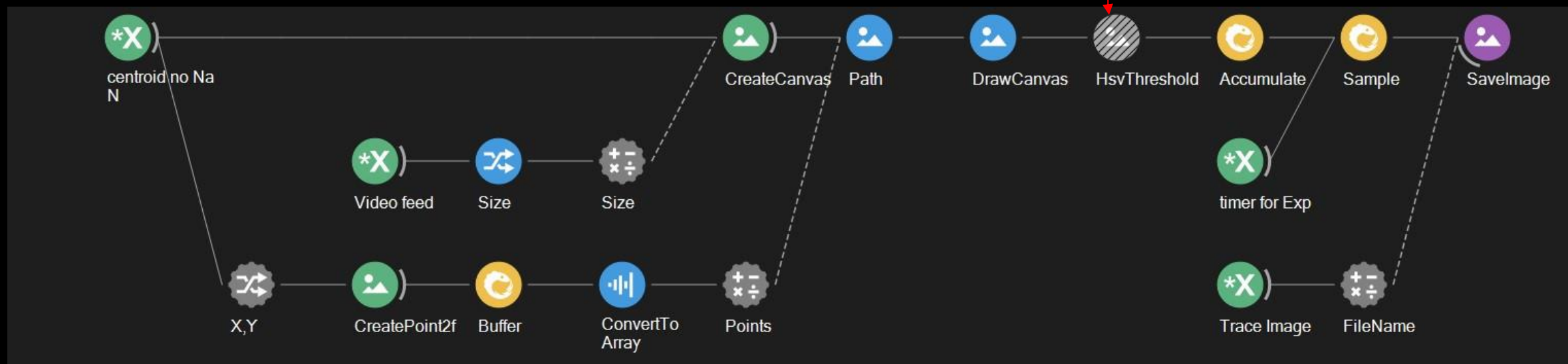
Based on system time



# Trace Image Output











Enable to change visualization  
aspect of saved image

Saves trace image of trial



# Output Files

Saves when you press "I"

-  VGlut cre C189 OFT\_M2\_Background Image\_2...
-  VGlut cre C189 OFT\_M2\_Count Center Entrance...
-  VGlut cre C189 OFT\_M2\_Distance & Velocity\_2...
-  VGlut cre C189 OFT\_M2\_Histogram\_2020\_4\_14...
-  VGlut cre C189 OFT\_M2\_Time\_Entrance\_Exit\_20...
-  VGlut cre C189 OFT\_M2\_TimeStampedVideo\_...
-  VGlut cre C189 OFT\_M2\_Total Time\_2020\_4\_14\_...
-  VGlut cre C189 OFT\_M2\_Trace Image\_2020\_4\_...
-  VGlut cre C189 OFT\_M2\_Velocity Values\_2020\_...
-  VGlut cre C189 OFT\_M2\_X\_Y\_Position\_2020\_4\_...

