Laplace Transform of the Convolution Integral

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There are several forms of the difinition of divergence and curl. One of them is using the integral form.

Definition 1 Divergence. *The divergence of a vector field $\vec{v}$ is defined as*

$$\nabla \cdot \vec{v} = \lim_{V \to 0} \frac{\displaystyle\int_{\partial\Omega} \vec{v} \cdot d\vec{S}}{V}$$

where $\partial\Omega$ is the closed surface and the volume inside $\partial\Omega$ is V

Definition 2 Curl. *The curl of a vector field $\vec{v}$ is defined as*

$$(\nabla \times \vec{v}) \cdot \vec{n} = \lim_{S \to 0} \frac{\displaystyle\oint_{C} \vec{v} \cdot d\vec{r}}{S}$$

where $\vec{n}$ is a unit vector in an arbitrary direction, S is an area of plane perpendicular to $\vec{n}$ and closed by curve C

Theorem Gauss Divergence Theorem.

$$\int_{\Omega} \nabla \cdot \vec{v}\, dV = \int_{\partial\Omega} \vec{v} \cdot d\vec{S}$$

Proof. First, we divide the region Ω into n regions. Each region is denoted as $\Omega_i (i = 1, 2, \cdots, n)$. We can write the RHS of the theorem as follows.

$$\int_{\partial\Omega} \vec{v} \cdot d\vec{S} = \sum_{i=1}^{n} \int_{\partial\Omega_i} \vec{v} \cdot d\vec{S}$$

This is because the surface integral on the boundary between Ω_i and Ω_j cancels out due to the opposite direction of $d\vec{S}$. Let V_i be the volume of the region Ω_i. In addition, we define $|\Delta| = \max\{V_i; 1 \leq i \leq n\}$. We can increase the number of division so that $|\Delta|$ becomes less

than any positive value. Therefore,

$$\int_{\partial\Omega} \vec{v} \cdot d\vec{S} = \sum_{i=1}^{n} \int_{\partial\Omega_i} \vec{v} \cdot d\vec{S}$$

$$= \sum_{i=1}^{n} \frac{\int_{\partial\Omega_i} \vec{v} \cdot d\vec{S}}{V_i} V_i$$

$$\rightarrow \int_{\Omega} \nabla \cdot \vec{v} dV \quad (|\Delta| \rightarrow 0)$$

$\square$

Theorem   Stokes' Theorem.

$$\int_{\Gamma} (\nabla \times \vec{v}) \cdot d\vec{s} = \oint_{C} \vec{v} \cdot d\vec{r}$$

Proof. First, we divide the surface Γ into n surfaces. Each surface is denoted as $\Gamma_i (i = 1, 2, \cdots, n)$, and the closed loop around Γ_i is C_i We can write the RHS of the theorem as follows.

$$\oint_{C} \vec{v} \cdot d\vec{r} = \sum_{i=1}^{n} \oint_{C_i} \vec{v} \cdot d\vec{r}$$

This is because the integral on the boundary between Γ_i and Γ_j cancels out due to the opposite direction of the integral. Let S_i be the are of the surface Γ_i. In addition, we define $|\Delta| = \max\{S_i; 1 \leq i \leq n\}$. We can increase the number of division so that $|\Delta|$ becomes less than any positive value. Therefore,

$$\oint_{C} \vec{v} \cdot d\vec{r} = \sum_{i=1}^{n} \oint_{C_i} \vec{v} \cdot d\vec{r}$$

$$= \sum_{i=1}^{n} \frac{\oint_{C_i} \vec{v} \cdot d\vec{r}}{S_i} S_i$$

$$\rightarrow \int_{\Gamma} (\nabla \times \vec{v}) \cdot d\vec{S} \quad (|\Delta| \rightarrow 0)$$

$\square$

We can derive the divergence in Cartesian coordinate by considering the rectangular prism shown in Figure 1.

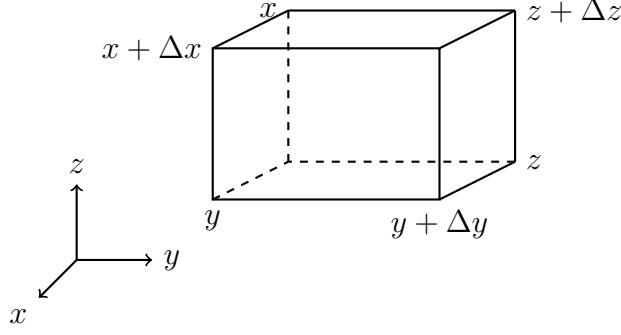Figure 1: Rectangular prism

Using the Gauss divergence theorem,

$$\int_\Omega \nabla \cdot \vec{v}\, dV = \int_{\partial\Omega} \vec{v} \cdot d\vec{S}$$

$$= \int_y^{y+\Delta y} \int_z^{z+\Delta z} \left(v_x(x+\Delta x, y', z') - v_x(x, y', z') \right) dz'\, dy'$$

$$+ \int_z^{z+\Delta z} \int_x^{x+\Delta x} \left(v_y(x', y+\Delta y, z') - v_y(x', y, z') \right) dx'\, dz'$$

$$+ \int_x^{x+\Delta x} \int_y^{y+\Delta y} \left(v_z(x', y', z+\Delta z) - v_z(x', y', z) \right) dy'\, dx'$$

$$= \int_y^{y+\Delta y} \int_z^{z+\Delta z} \int_x^{x+\Delta x} \frac{\partial v_x}{\partial x} dx'\, dz'\, dy'$$

$$+ \int_z^{z+\Delta z} \int_x^{x+\Delta x} \int_y^{y+\Delta y} \frac{\partial v_y}{\partial y} dy'\, dx'\, dz'$$

$$+ \int_x^{x+\Delta x} \int_y^{y+\Delta y} \int_z^{z+\Delta z} \frac{\partial v_z}{\partial z} dz'\, dy'\, dx'$$

$$= \int_x^{x+\Delta x} \int_y^{y+\Delta y} \int_z^{z+\Delta z} \left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \right) dz'\, dy'\, dx'$$

$$= \int_\Omega \left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \right) dV$$

The above equation has to hold at any region Ω. Therefore,

$$\nabla \cdot \vec{v} = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$$

The x component of the curl of $\vec{v}$ is

$$(\nabla \cdot \vec{v}) \cdot \vec{e_x} = \lim_{\Delta y, \Delta z \to 0} \frac{\oint_C \vec{v} \cdot \vec{dr}}{\Delta y \Delta z}$$

$$= \lim_{\Delta y, \Delta z \to 0} \frac{1}{\Delta y \Delta z} \left(\int_y^{y+\Delta y} v_y(x, y', z) dy' + \int_z^{z+\Delta z} v_z(x, y+\Delta y, z') dz' \right.$$

$$\left. + \int_{y+\Delta y}^y v_y(x, y', z+\Delta z) dy' + \int_{z+\Delta z}^z v_z(x, y, z') dz' \right)$$

$$= \lim_{\Delta y, \Delta z \to 0} \frac{\int_z^{z+\Delta z}(v_z(x, y+\Delta y, z') - v_z(x, y, z')) dz' - \int_y^{y+\Delta y}(v_y(x, y', z+\Delta z) - v_y(x, y', z)) dy'}{\Delta y \Delta z}$$

$$= \frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z}$$

Similarly, we can compute the y component and z component, and we can obtain

$$\nabla \times \vec{v} = \begin{pmatrix} \dfrac{\partial v_z}{\partial y} - \dfrac{\partial v_y}{\partial z} \\[2ex] \dfrac{\partial v_x}{\partial z} - \dfrac{\partial v_z}{\partial x} \\[2ex] \dfrac{\partial v_y}{\partial x} - \dfrac{\partial v_x}{\partial y} \end{pmatrix}$$

Theorem **Green's Theorem.**

$$\oint_C P dx + Q dy = \int_\Gamma \left(\frac{\partial P}{\partial y} - \frac{\partial Q}{\partial x} \right) dS$$

where $\Gamma \in \mathbb{R}^2$ which is closed by a contour C

Proof. Let $\vec{v}$ be defined as follows.

$$\vec{v} = \begin{pmatrix} P \\ Q \\ 0 \end{pmatrix}$$

Using the Stokes' theorem,

$$\oint_C \vec{v} \cdot \vec{dr} = \oint_C P dx + Q dy$$

$$= \int_\Gamma (\nabla \times \vec{v}) \cdot \vec{ds}$$

$$= \int_\Gamma \begin{pmatrix} -\dfrac{\partial Q}{\partial z} \\[2mm] \dfrac{\partial P}{\partial z} \\[2mm] \dfrac{\partial P}{\partial y} - \dfrac{\partial Q}{\partial x} \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} dS$$

$$= \int_\Gamma \left(\dfrac{\partial P}{\partial y} - \dfrac{\partial Q}{\partial x} \right) dS$$

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