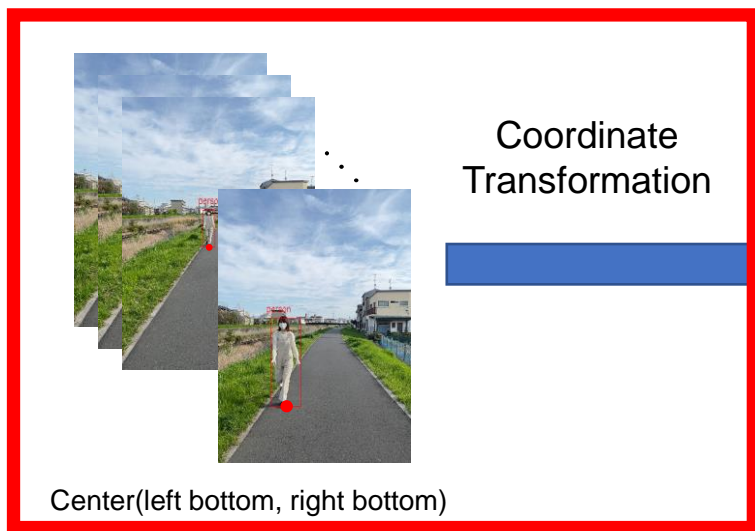
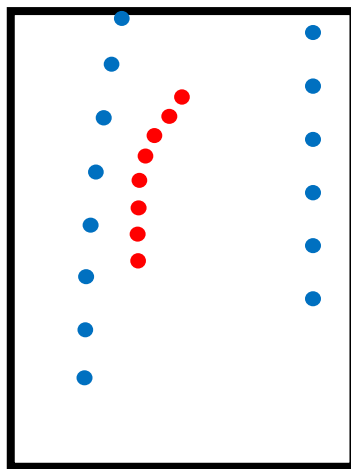


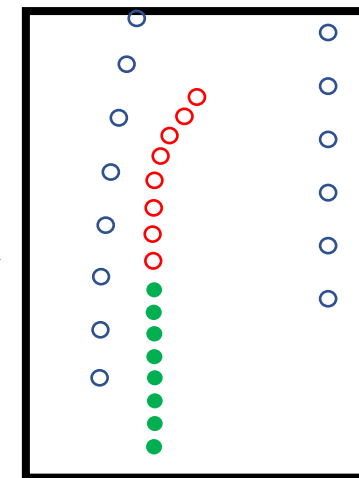
every frame



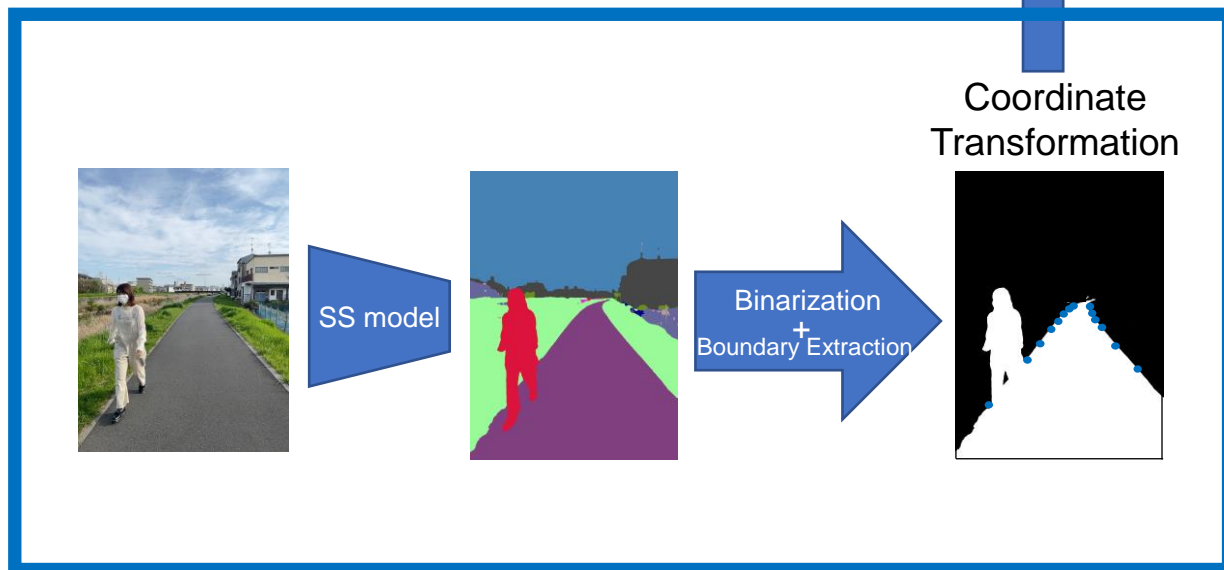
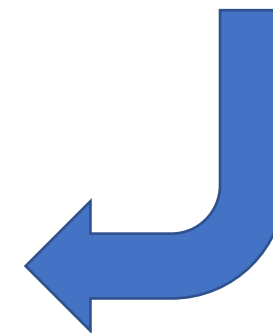
Bird's-eye view



Trajectory Prediction Model



Inverse Coordinate Transformation



every d frames