Human Activity Recognition using Smartphone Dataset Capstone Project

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Background and Objectives

- Explore, visualize, and to develop human activity recognition using smartphones sensors' reading data
- To what end? → Human Activity based Apps
 - Exercise assistance or healthcare apps
 - Augmented reality apps
 - Military
 - Security
 - Etc.



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About the Dataset (1/2)

The Source

- Obtained from UCI Repository
- Collected from Galaxy S Smartphone's Accelerometer & Gyroscope's Sensors Reading
- Experiments by 30 volunteers (age 19-48 years)
- 6 Activities:

STANDING, SITTING, LAYING, WALKING, WALKING UPSTAIRS, WALKING DOWNSTAIRS



About the Dataset (2/2)

Main Dataset Composition

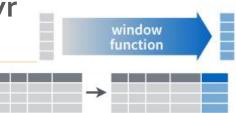
- All dataset divided : 70% training (7352 obs)
 30% test (2947 obs)
- Inertial Dataset: preprocessed & noise filtered raw sensors reading dataset (128 reading/windows)

- Engineered & normalized dataset with 561 variables mean, standard deviation, entropy, etc. Used for Machine Learning
- Variables naming of all 561 variables +
- Human Activity Assignment for all 10000 observations above are included in separate datasets

Data Wrangling

- Renaming the variables name by removing duplicates and replacing prohibited characters (space, bracket, etc)
- 2. Adding the Activity Label (WALKING, etc) for each observations.
- Creating time stamp or index variables for data visualization purpose
- 4. Combining all the data
- 5. Later splitting the dataset into training and test for machine learning.

All of the above was done using dplyr



Understanding The Data (1/2)

Min Max Normalization

- Data is normalized : -1 to +1 range (min-max normalization)
- Only normalized in respect to same group of dataset (either training or test)

$$normalized\ x = rac{x - max_{all\ x}}{max_{all\ x} - min_x} (new\ max_{all\ x} - new\ min_{all\ x}) + new\ min_{all\ x}$$

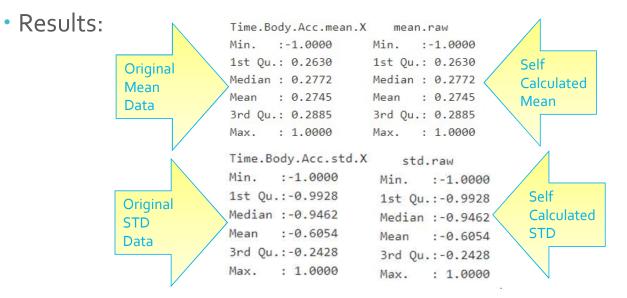
This means: each data is a **relative value**

- +1 = maximum value across all observations of 1 variable
- -1 = minimum value across all observations of 1 variable
- o = aprox. median value across all observations of 1 variable

Understanding The Data (2/2)

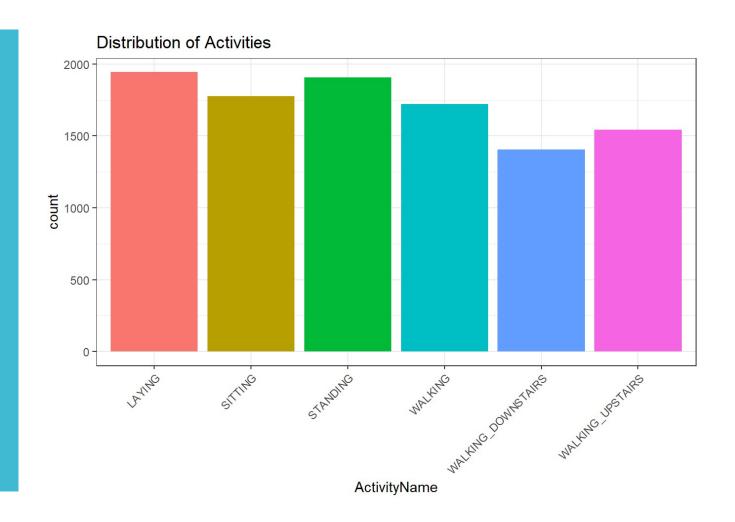
The Proof

- Self calculating the Mean and Standard Deviation from Inertial Signals Dataset (raw preprocessed sensors data)
- Normalizing above calculation using min-max formula
- Comparing with the same variable from original engineered dataset.



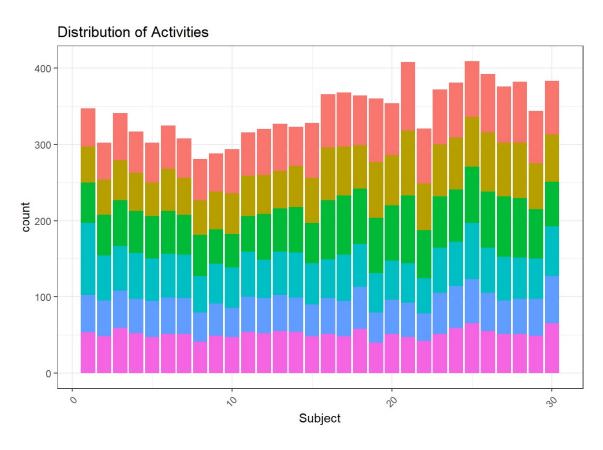
Data Exploratory (1/8)

Distributions for All Activities



Data Exploratory (2/8)

Durations of Experiment for each Subject

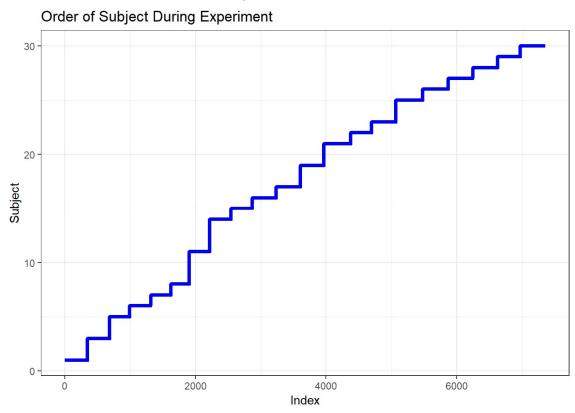


- All activities were not done in equal duration.
- Each subject also performs the experiment in different duration

Data Exploratory (3/8)

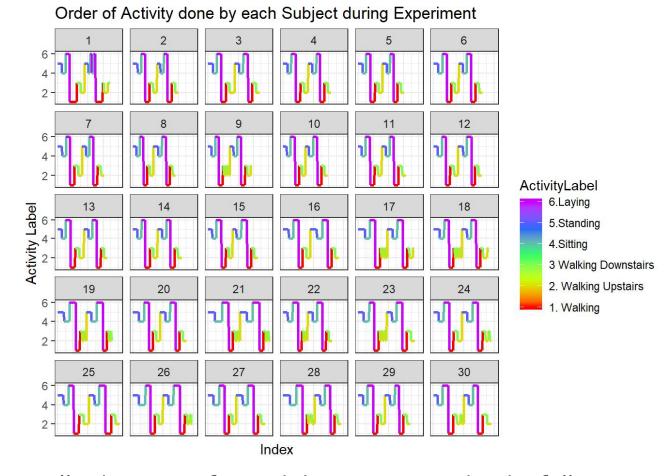
Order Subjects during Experiment

- Data has been sorted by the subjects of experiment
- No repetition of subject



Data Exploratory (4/8)

Order Activities Done by Each Subject



- All subjects performed the experiment by the following order:
- Standing → Sitting → Laying → Walking → Walking
 Downstairs → Walking Upstairs

Data Exploratory (5/8)

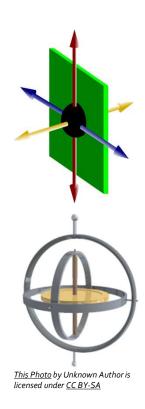
Time Series & Histogram Visualization of Variables

To Plot:

- Mean
- Standard Deviation
- Magnitude (Resultant of XYZ)

of three main sensors data:

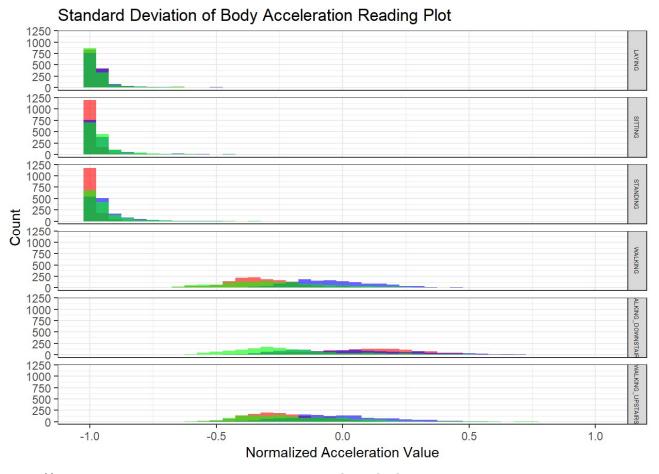
- Body Motion from Accelerometer
- Body Gyroscope Reading
- Body Gravity from Accelerometer



Only the most meaningful plot will be discussed in this presentation

Data Exploratory (6/8)

Moving vs. Stationary Activities



- All stationary activities' standard deviation at minimum value(-1) → Almost zero variance in raw sensors data
- Moving activities are more equally distributed

Data Exploratory (7/8)

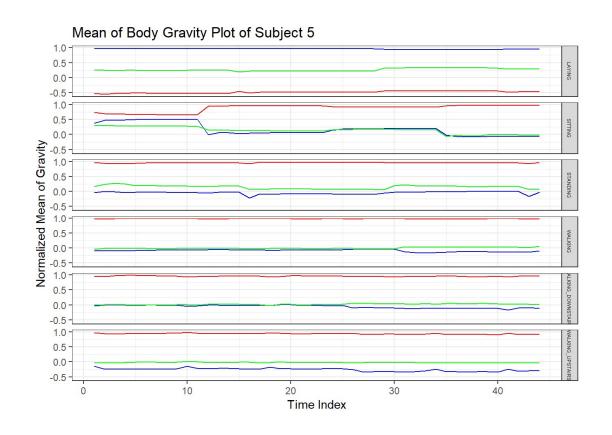
Laying vs. other Activities



- Mean body gravity for laying is more equally distributed to all values
- Also, x axis value of mean body gravity is relatively lower.

Data Exploratory (8/8)

Distinguishing Walking Upstairs



 Mean body gravity for walking upstairs is relatively lower compared to other moving activities

Machine Learning Classification Model

- Random Forest Multiclass Classification
- Tuned using Caret package.
- Number of variables randomly sampled as candidates at each split (mtry)=24.
- Number of trees to grow (ntree)=500.

Model Evaluation (1/2)

Confusion Matrix

Reference

Prediction	LAYING	SITTING	STANDING	WALKING	WALKING_DOWNSTAIRS
LAYING	537	0	0	0	0
SITTING	0	439	44	0	0
STANDING	0	52	488	0	0
WALKING	0	0	0	481	18
WALKING_DOWNSTAIRS	0	0	0	7	358
WALKING_UPSTAIRS	0	0	0	8	44

Reference

Prediction	WALKING_UPSTAIRS
LAYING	6
SITTING	6
STANDING	6
WALKING	36
WALKING_DOWNSTA	IRS 7
WALKING UPSTAIR	5 428

Overall Statistics

Accuracy: 0.9267

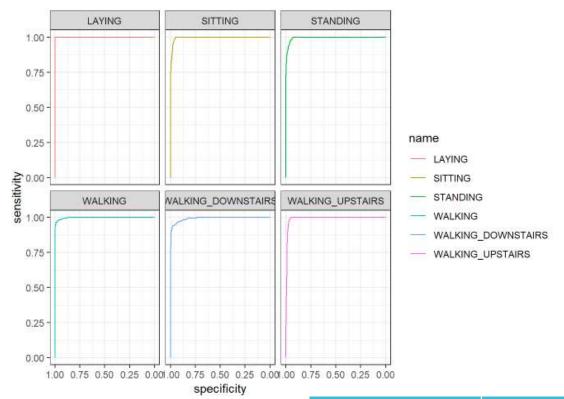
95% CI: (0.9167, 0.9359)

No Information Rate : 0.1822 P-Value [Acc > NIR] : < 2.2e-16

Kappa : 0.9119

Model Evaluation (2/2)

ROC and AUC



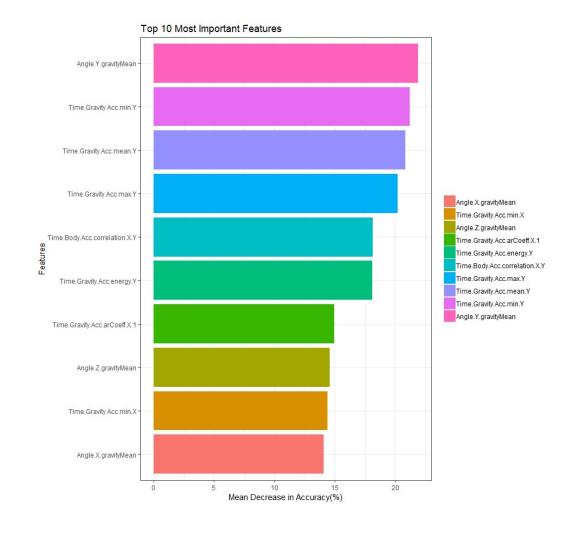
Area Under the Curve is close to 1

→ very capable in distinguishing between classes

Class	Area Under The Curve			
LAYING	1.000			
SITTING	0.995			
STANDING	0.996			
WALKING	0.997			
WALKING DOWNSTAIRS	0.992			
WALKING UPSTAIRS	0.992			

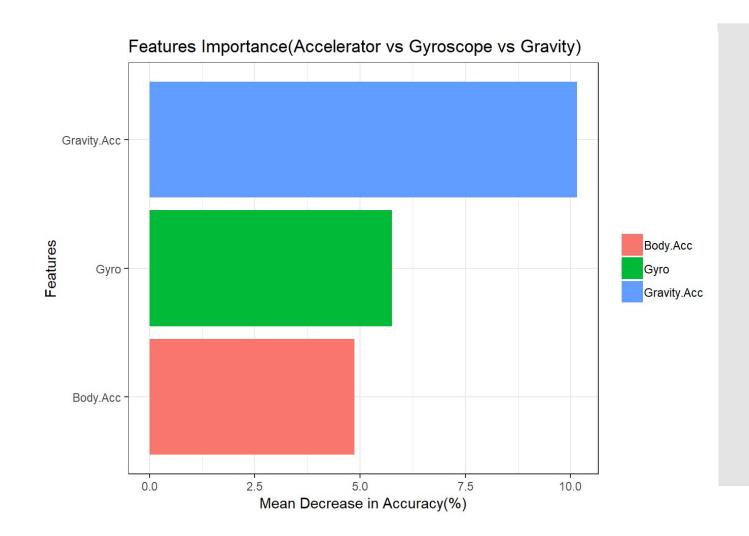
Variables' Importance (1/3)

Top 10 Most Important Features



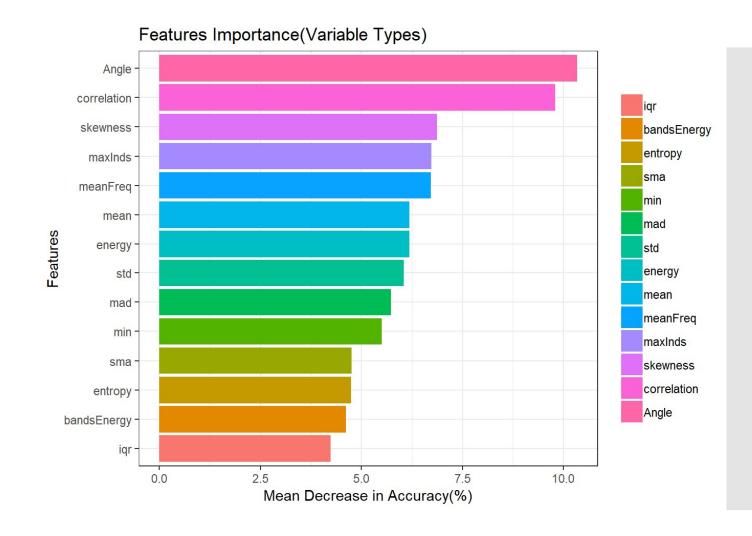
Variables' Importance (2/3)

Three Sensors ' Type's Reading Comparison



Variables' Importance (3/3)

Variables' Type Comparison



Conclusion

- Random forest model (mtry=24 and ntree = 500), achieved Accuracy of 92.7%, and the Kappa value of 91.2%. These are considered quite high.
- Area Under the Curve (AUC) very close to 1, which indicates that our model is very capable in distinguishing or classifying between classes of activities.
- Among all 561 variables Time.Body.Acc.correlation.X.Y is the most significant variable.
- Between Body Acceleration, Body Gravity, and Body Gyroscope, body's gravitational components from accelerometer is the most important.
- Among all engineered variables, Angle and correlations are the most important by large margins if compared to the other variables