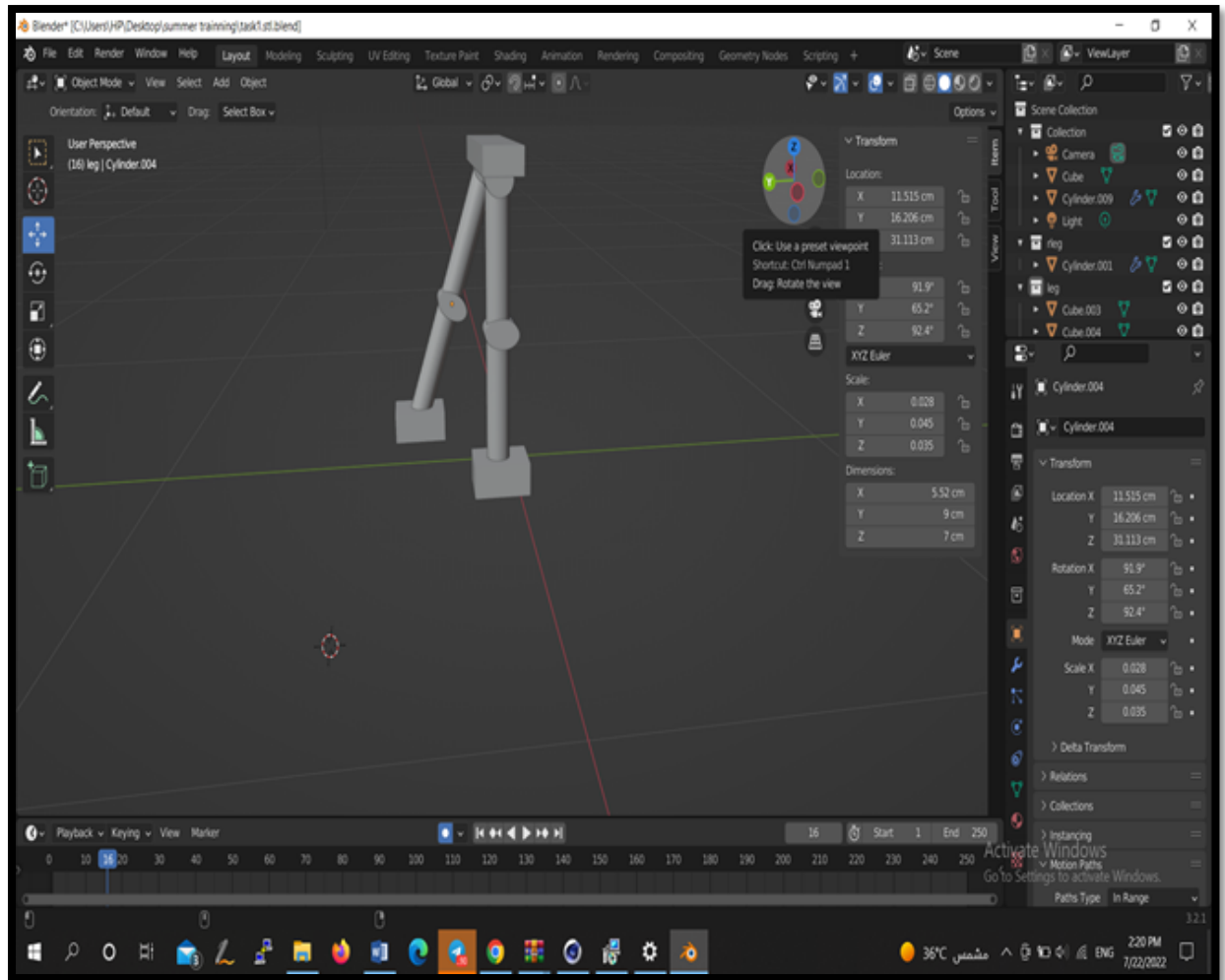


**Here The Stick model of robot legs
and the Calculation of the Rotation
Degree ,how to caculeter and how the
final result**

Step one :

Stick model of robot legs created by Blender:



Step two :I calculation in this wep

(<https://www.omnicalculator.com/math/trigonometry>)

Then i get this result :

