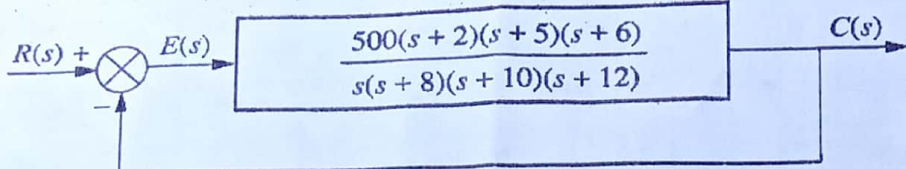


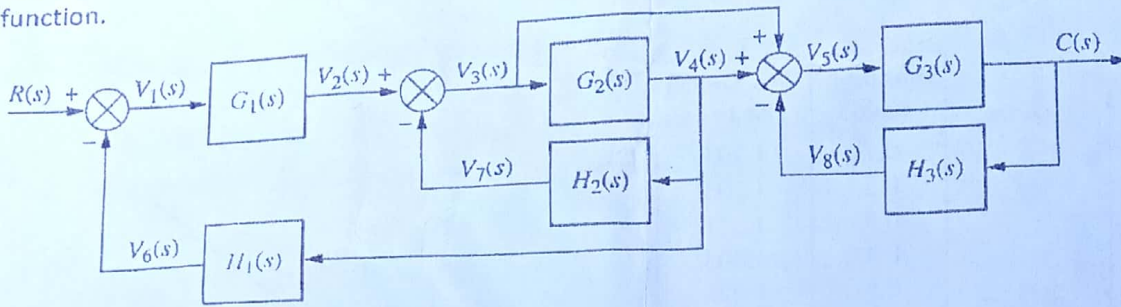
EE340 Control Systems
5th Semester(Session 2018)

Reg. No. 2018-EE-386

Q	Final-Term Exam Time:90 min , Marks=40	EE340 Control Systems 5th Semester(Session 2018)	Reg. No. 2018-EE-386	CLO2	PLO3	
1	Evaluate the static error constants and find the steady-state error for the standard step, ramp and parabolic input for the system given below.					8
2	Examine root locus of following functions (A)	$H(s)G(s) = \frac{1}{s^3 + 8s^2 + 17s + 10}$		CLO3	PLO2	16
	(B)	$H(s)G(s) = \frac{1}{s^4 + 2s^3 + 2s^2}$				
3	Calculate a compensator to get $E_{ss} = 0.2$ of given function which should have minimum effect on root locus	$G(s) = \frac{5s^3 + 9s^2 + 20s + 10}{32s^3 + 84s^2 + 2s + 19}$		CLO3	PLO2	4
4	Analyze the effect of PID controller to the unity feedback closed loop of following function	$G(s) = \frac{\omega_n^2}{s^2 + 2\xi\omega_n s}$		CLO3	PLO2	6
5	Examine the bode plot of	$H(s) = \frac{50j\omega}{(j\omega + 4)(j\omega + 10)^2}$		CLO3	PLO2	6

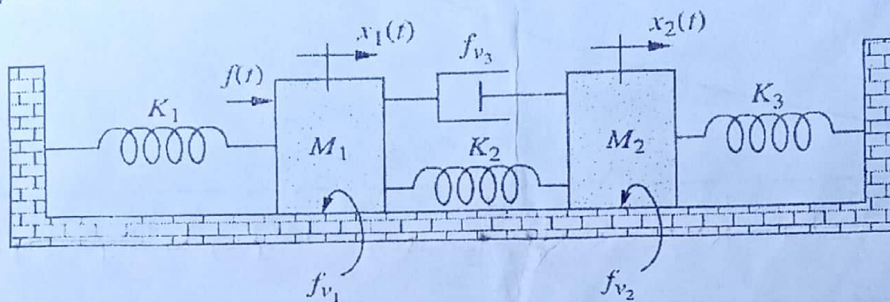
Mid Term Exam,
Time: 1Hr, Marks=30

1 Apply block diagram reduction techniques to reduce the system given below in single transfer function.



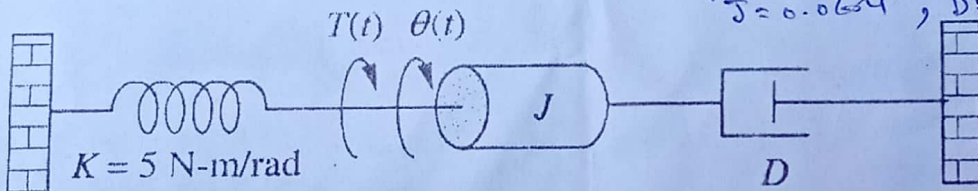
CLO1 Cognitive 08
Level 3
PLO1

2 Apply the mechanical modelling techniques to find the transfer function $X_2(s)/F(s)$ of the following system.



CLO1 Cognitive 08
Level 3
PLO1

3 Select the values of J and D to yield 20% overshoot and a settling time of 2 sec for a step input of torque T(t) for the system given below



$$\zeta = 0.22, \omega_n = 9.09$$

$$J = 0.0654, D = 0.2415$$

CLO2 Cognitive 06
Level 5
PLO3

Evaluate the natural frequency, damping ratio, settling time and rise time of the system whose transfer function is given below and if the response is underdamped also find the peak time and percentage overshoot for the system. Mention the response type.

$$G(s) = \frac{100}{s^2 + 15s + 100}$$

CLO2 Cognitive 0
Level 5
PLO 3

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UET, FSD Campus

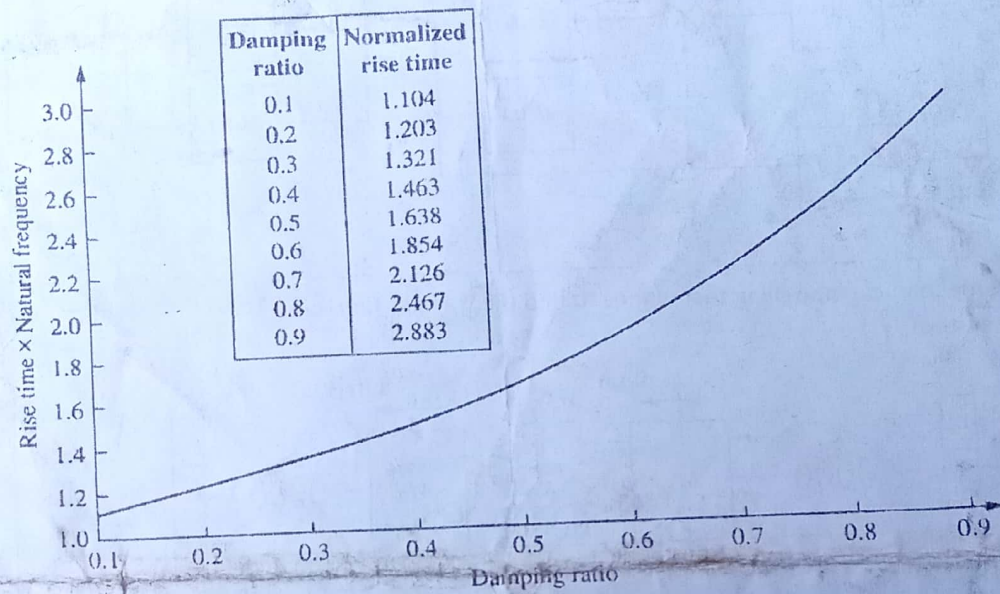


Figure 1: Normalized rise time versus damping ratio for a second order underdamped response.