

University of Engineering & Technology Lahore

Experiment # 4

Title: Z Transform-I

Equipment Required: Personal computer (PC) with windows operating system and MATLAB software

Theory:

Z transform is an important tool for the analysis and design of discrete time signals. It transforms a signal of time domain into a function of variable z. For discrete time signal $x(n)$, z transform is defining as,

$$X[Z] = \sum_{n=-\infty}^{\infty} x[n]Z^{-n}$$

The properties of the z-transform are generalizations of the properties of the discrete-time Fourier transform.

1. Linearity:

$$\mathcal{Z}[a_1x_1(n) + a_2x_2(n)] = a_1X_1(z) + a_2X_2(z); \quad \text{ROC: } \text{ROC}_{x_1} \cap \text{ROC}_{x_2}$$

2. Sample shifting:

$$\mathcal{Z}[x(n - n_0)] = z^{-n_0}X(z); \quad \text{ROC: } \text{ROC}_x$$

3. Frequency shifting:

$$\mathcal{Z}[a^n x(n)] = X\left(\frac{z}{a}\right); \quad \text{ROC: } \text{ROC}_x \text{ scaled by } |a|$$

4. Folding:

$$\mathcal{Z}[x(-n)] = X(1/z); \quad \text{ROC: Inverted } \text{ROC}_x$$

5. Complex conjugation:

$$\mathcal{Z}[x^*(n)] = X^*(z^*); \quad \text{ROC: } \text{ROC}_x$$

6. Differentiation in the z -domain:

$$\mathcal{Z}[nx(n)] = -z \frac{dX(z)}{dz}; \quad \text{ROC: ROC}_x$$

This property is also called the *multiplication-by-a-ramp property*.

7. Multiplication:

$$\mathcal{Z}[x_1(n)x_2(n)] = \frac{1}{2\pi j} \oint_C X_1(\nu)X_2(z/\nu)\nu^{-1}d\nu;$$
$$\text{ROC: ROC}_{x_1} \cap \text{Inverted ROC}_{x_2}$$

where C is a closed contour that encloses the origin and lies in the common ROC.

8. Convolution:

$$\mathcal{Z}[x_1(n) * x_2(n)] = X_1(z)X_2(z); \quad \text{ROC: ROC}_{x_1} \cap \text{ROC}_{x_2}$$

Example 1:

Find z transform of $x(n) = (1/4)^n u(n)$.

```
>> syms z n
```

```
>> ztrans((1/4)^n)
```

Task#01:

i) $x(n) = (1/4)^n u(-n)$.

MATLAB Code:

```
DSPLab5task1a.m  x  +
1
2    %LAB#5 Task#1 (a)
3 -    syms z n;
4 -    ztrans(1/4^-n,z^-1)
5    |
```

Output:

```
Command Window
>> DSPLab5task1a

ans =

1/(z*(1/z - 4))
```

Handwritten Solution:

Task #1 :

$$\textcircled{1} \quad x(n) = \left(\frac{1}{4}\right)^n U(-n).$$

$$X(z) = \sum_{-\infty}^0 \left(\frac{1}{4}\right)^n z^n$$

$$= \sum_0^{\infty} \left(\frac{1}{4}\right)^{-n} z^n$$

$$= \frac{1}{1 - \left(\frac{1}{4}\right)^{-1} z} \Rightarrow \frac{1}{1 - 4z}.$$

$$= \frac{1}{z\left(\frac{1}{z} - 4\right)}.$$

ii) $x(n) = (0.8)^n u(-n - 1)$.

MATLAB Code:

```
1
2 %LAB#5 Task#1(b)
3 - syms z n;
4 - ztrans(0.8^-n, z^-1) * z^-1 * 4^1
5
```

Handwritten Solution:

$$\textcircled{ip} \quad x(n) = (0.8)^n u(-n-1).$$

$$X(z) = \sum_{n=-\infty}^{-1} (0.8)^n z^{-n}.$$

$$X(z) = \sum_{n=1}^{\infty} (0.8)^{-n} z^n$$

$$= \sum_{n=0}^{\infty} (0.8)^{-(n+1)} z^{n+1}.$$

$$= \sum_{n=0}^{\infty} (0.8)^{-n} \cdot (0.8)^{-1} \cdot z^n \cdot z^1.$$

$$= (0.8)^{-1} \cdot z \sum_{n=0}^{\infty} (0.8)^{-n} z^n.$$

$$= (0.8)^{-1} \cdot z \left[\frac{1}{1 - (0.8)^{-1} z} \right].$$

$$= (0.8)^{-1} z \times \sum_{n=0}^{\infty} (0.8)^{-n} z^n$$

$$= \left(\frac{4}{5}\right)^{-1} z \times \left[\frac{1}{1 - \left(\frac{4}{5}\right)^{-1} z} \right].$$

$$= \frac{5}{4} z \left[\frac{1}{1 - \frac{5}{4} z} \right].$$

$$= \frac{5}{4} z \left[\frac{4}{4 - 5z} \right] = \frac{5z}{4 - 5z}.$$

iii) $x(n) = (4^n) u(1-n).$

MATLAB Code:

```
1
2 %LAB#5 Task#1(c)
3 - syms z n;
4 - ztrans(4^-n, z^-1)*z^-1*4^1
5 |
```

Output:

Command Window

```
>> DSPLab5task1c

ans =

4/(z^2*(1/z - 1/4))
```

Handwritten Solution:

$$\begin{aligned}
 \textcircled{??}: \quad x(n) &= (4)^n u(1-n) \\
 X(z) &= \sum_{n=-\infty}^{+1} (4)^n z^{-n} \\
 X(z) &= \sum_{n=-1}^{\infty} (4)^{-n} z^{-n} = X(z) = \sum_{n=0}^{\infty} (4)^{-(n-1)} z^{-(n-1)} \\
 X(z) &= \sum_{n=0}^{\infty} (4)^{-n} \cdot 4^1 \cdot z^n \cdot z^{-1} \\
 &= \frac{4}{z} \sum_{n=0}^{\infty} (4)^{-n} z^n = \frac{4}{z} \left[\frac{1}{1 - \left(\frac{1}{4}\right)z} \right] \\
 &= \frac{4}{z} \left[\frac{4}{4-z} \right] = \frac{16}{z(4-z)} \\
 &= \frac{16}{4z - z^2}
 \end{aligned}$$

iv) $x(n) = (n + 1)(3^{n-2}) u(n)$.

MATLAB Code:

```
1
2 %LAB#5 Task#1(e)
3 - syms z n;
4 - ztrans((n+1)*(3^(n-2)))
5
```

Output:

Command Window

```
>> DSPLAB5taskle
```

```
ans =
```

```
z/(9*(z - 3)) + z/(3*(z - 3)^2)
```

Handwritten Solution:

$$(iv) \quad x(n) = (n+1)(3^{n-2}) u(n)$$

$$X(z) = [n(3^{n-2}) + (3^{n-2})] u(n).$$

$$X(z) = [n(3^{n-2}) u(n) + (3^{n-2}) u(n)].$$

As z-transform of $(3^{n-2}) u(n)$ is

$$\begin{aligned} X(z) &= \sum_{n=0}^{\infty} (3^{n-2}) u(n) = 3^{-2} \sum_{n=0}^{\infty} (3^n) z^{-n} \\ &= \frac{1}{9(1-3z^{-1})}. \end{aligned}$$

$$X(z) = [n(3^{n-2}) + 3^{n-2}] u(n).$$

$$\begin{aligned} AS = -z \frac{dX(z)}{dz} &= -z \frac{d}{dz} \left[\frac{1}{9(1-3z^{-1})} \right] \\ &= \frac{z^{-1}}{3(1-3z^{-1})^2}. \end{aligned}$$

$$X(z) = \frac{z^{-1}}{3(1-3z^{-1})^2} + \frac{1}{9(1-3z^{-1})}.$$

$$X(z) = \frac{z}{3(1-3z)^2} + \frac{z}{9(z-3)} = \frac{z}{3(z-3)^2} + \frac{z}{9(z-3)}.$$

$$v) \ x(n) = n \sin(\pi n/3) u(n) + (0.9)^n u(n-1)$$

MATLAB Code:

```

1
2 %LAB#5 Task#1(f)
3 - syms z n;
4 - ztrans(n*sin(pi*n/3))+ztrans(0.9^n)*z^-1
5
6

```

Output:

Command Window

```

>> DSPLAB5task1f

ans =

1/(z - 9/10) + (3^(1/2)*z*(z^2 - 1))/(2*(z^2 - z + 1)^2)

```

Handwritten Solution:

$$\textcircled{V}: n \sin(\pi/3) u(n) + (2.9)^n u(n-1).$$

$$x(n) = \sin(\pi/3^n) u(n).$$

$$= \sum_{n=0}^{\infty} \left[\frac{1}{2j} \left(e^{j\pi/3^n} - e^{-j\pi/3^n} \right) \right] u(n).$$

$$X(z) = \frac{1}{2j} \sum_{n=0}^{\infty} \left[e^{j\pi/3^n} z^{-1} - e^{-j\pi/3^n} z^{-1} \right].$$

$$= \frac{1}{2j} \left[\frac{1}{1 - e^{j\pi/3} z^{-1}} - \frac{1}{1 - e^{-j\pi/3} z^{-1}} \right].$$

$$= \frac{1}{2j} \left[\frac{1 - e^{-j\pi/3} z^{-1} - (1 - e^{j\pi/3} z^{-1})}{(1 - e^{j\pi/3} z^{-1})(1 - e^{-j\pi/3} z^{-1})} \right]$$

$$= \frac{1}{2j} \left[\frac{1 - e^{-j\pi/3} z^{-1} - 1 + e^{j\pi/3} z^{-1}}{1 - e^{j\pi/3} z^{-1} - e^{-j\pi/3} z^{-1} + z^{-2}} \right].$$

$$= \frac{1}{2j} \left[\frac{z^{-1} [e^{j\pi/3} - e^{-j\pi/3}]}{1 - (e^{j\pi/3} + e^{-j\pi/3}) z^{-1} + z^{-2}} \right].$$

$$= \frac{1}{2j} \left[\frac{z^{-1} \left[\frac{e^{j\pi/3} - e^{-j\pi/3}}{2j} \right]}{1 - 2z^{-1} \left(\frac{e^{j\pi/3} + e^{-j\pi/3}}{2} \right) + z^{-2}} \right].$$

$$= \frac{z^{-1} \sin(\pi/3)}{1 - 2z^{-1} \cos(\pi/3) + z^{-2}} = \frac{z^{-1} (\sqrt{3}/2)}{1 - 2z^{-1} (1/2) + z^{-2}}$$

$$= \sin(\pi/3) u(n) = \frac{\sqrt{3}}{2} \left[\frac{z^{-1}}{z^2 - z + 1} \right].$$

$$= \frac{\sqrt{3}}{2} \left[\frac{z(2z-1) - (z^2 - z + 1)}{(z^2 - z + 1)^2} \right]$$

$$= \frac{\sqrt{3}}{2} \left[\frac{2z^2 - \cancel{z} - z^2 + \cancel{z} - 1}{(z^2 - z + 1)^2} \right]$$

$$= \frac{\sqrt{3}}{2} \left[\frac{z^2 - 1}{(z^2 - z + 1)^2} \right] \Rightarrow \left[\frac{\sqrt{3} \times z \times (z^2 - 1)}{2 \times (z^2 - z + 1)^2} \right]$$

$$= \frac{\sqrt{3}}{2} \left[\frac{(z(z^2 - 1))}{(z^2 - z + 1)^2} \right]$$

$$x_2(n) = (0.9)^n u(n-1)$$

$$X_2(z) = \sum_{n=1}^{\infty} (0.9)^n \cdot z^{-n}$$

$$X_2(z) = \frac{z^{-1}}{1 - 0.9z^{-1}} = \frac{1}{z - 0.9}$$

$$Y(z) = X_1(z) + X_2(z)$$

$$= \frac{\sqrt{3}(z)(z^2 - 1)}{2 \times (z^2 - z + 1)^2} + \frac{1}{z - 0.9}$$

Task#02:

Let $X_1(z) = 2 + 3z^{-1} + 4z^{-2}$ and $X_2(z) = 3 + 4z^{-1} + 5z^{-2} + 6z^{-3}$. Determine $X_3(z) = X_1(z)X_2(z)$.

MATLAB Code:

```
1
2 %LAB#5 Task#2
3 - X1=[2 3 4];
4 - X2=[3 4 5 6];
5 - X3=conv(X1,X2)
6
```

Output:

```
Command Window

>> DSPLab5task2

X1 =

    2     3     4

X2 =

    3     4     5     6

X3 =

    6    17    34    43    38    24
```

Handwritten Solution:

Task #2

$$X_1(z) = 2 + 3z^{-1} + 4z^{-2}$$

$$X_2(z) = 3 + 4z^{-1} + 5z^{-2} + 6z^{-3}$$

$$X_3(z) = X_1(z)X_2(z)$$

$$X_3(z) = (2 + 3z^{-1} + 4z^{-2})(3 + 4z^{-1} + 5z^{-2} + 6z^{-3})$$

$$= 6 + 8z^{-1} + 10z^{-2} + 12z^{-3} + 9z^{-1} + 12z^{-2} + 15z^{-3} \\ + 18z^{-4} + 12z^{-2} + 16z^{-3} + 20z^{-4} + 24z^{-5}$$

$$= 6 + 17z^{-1} + 34z^{-2} + 43z^{-3} + 38z^{-4} + 24z^{-5}$$