

WELCOME BACK IN
NEW SEMESTER!

Instructor: Ali Raza

"Never stop doing your best just because someone doesn't give you credit."



Instructor : Engr. Ali Raza
ealiraza1@gmail.com

Teacher's Introduction

Mr. Ali Raza
ealiraza1@gmail.com
Office: First Floor
Antenna and Communication Lab

MS in Electrical Engineering - RF
and Microwaves, NUST-SEECS

EE-220 Signals and Systems

Session 2019

Week 1

Objective

- ❑ To prepare the student for core courses in communication, control and signal processing by giving the student a thorough working knowledge of these techniques.



CLOs

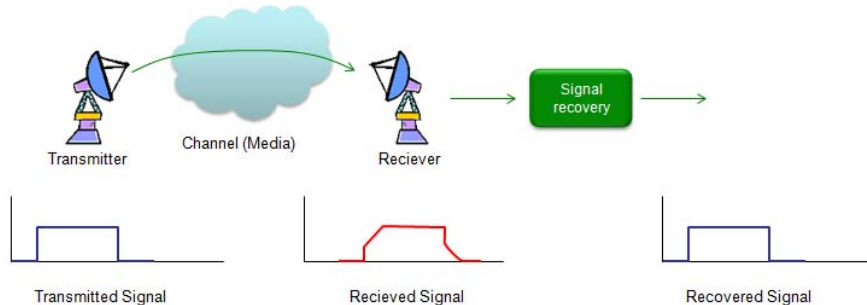
- ❑ Define continuous-time signals, discrete-time sequences, corresponding Transforms, their properties, their frequency domain behavior and LTI systems (C1)
- ❑ Analyze signals and systems using the Fourier and z transforms (C4)
- ❑ Analyze and design LTI systems via software (C3)

Grading Policy

- Quizzes and Assignments = 30%
- Mid Exam = 30%
- Final Exam = 40%

- ❑ **Tentatively** there will be 2 quizzes and 2 assignments

Why should we study Signals and Systems ????



Course Books

REQUIRED:

- ❑ Signals and Systems by A. V. Oppenheim, A. S. Willsky and S. H. Nawab, 2nd Edition.

OPTIONAL:

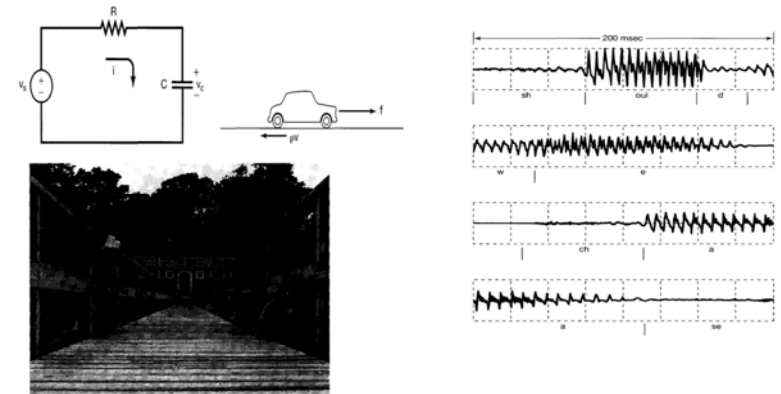
- ❑ Digital Signal Processing – Principles, Algorithms and Applications by J. G. Proakis and D. G. Manolakis, 4th Edition, Prentice Hall, 2006.
- ❑ Fundamentals of Signals and Systems by M. J. Roberts, McGraw Hill, 2007.
- ❑ Linear Systems and Signals by B. P. Lathi, 2nd Edition, Oxford, 2004.

What is a Signal?

- A signal is a pattern of variation of some form
- It can be thought of as variations in a waveform or a sequence that conveys some information

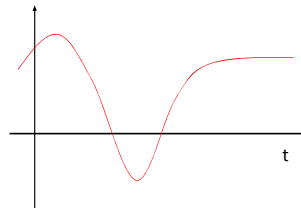
- Electrical signals
 - Voltages and currents in a circuit
- Acoustic signals
 - Sound over time
- Mechanical signals
 - Velocity of a car over time
- Image signals
 - Intensity level of a pixel of image over time/space

Example



Signal Representation

- Mathematically, signals are represented as a function of one or more independent variables e.g. time, space
- For instance a black and white video signal intensity is dependent on x, y coordinates and time t, $f(x,y,t)$
- In this course, we shall be exclusively concerned with signals that are a function of a single variable: time



Signal Classifications

- There are two basic types of signals
 - Continuous time signals
 - Discrete-time signals.

Signal Classifications

- **Continuous-Time Signals**

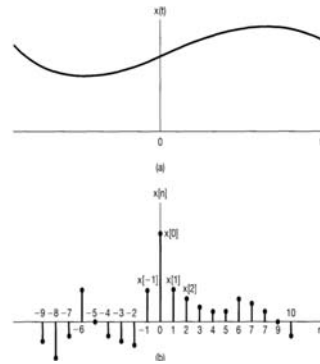
- Most signals in the real world are continuous time as the scale is infinitesimally fine, for example voltage, velocity...
- Denoted by $x(t)$, where the time interval may be bounded (finite) or infinite

- **Discrete-Time Signals**

- Some real world and many digital signals are discrete time as they are sampled, for example pixels, daily stock price (anything that a digital computer processes)
- Denoted by $x[n]$, where n is an integer value that varies discretely

- **Sampled continuous signal**

- $x[n] = x(nt)$, where n is sample time

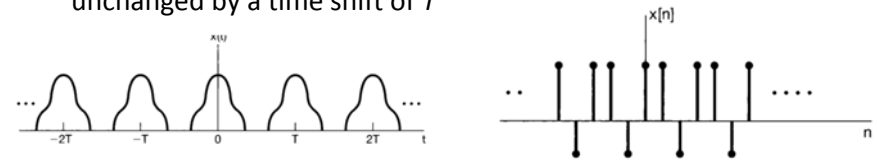


Periodic Signals

- A periodic continuous-time signal $x(t)$ has the property that there is a positive value of T for which

$$x(t) = x(t + T)$$

- In other words, a periodic signal has the property that it is unchanged by a time shift of T

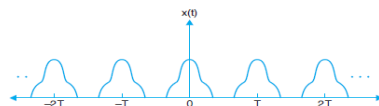


Periodic Signals

- **Continuous Time Periodic signals:** A periodic signal has the property that it is unchanged by a time shift of T

$$x(t) = x(t + T), \text{ for all value of } t.$$

- Then $x(t)$ is periodic with time period T .
- The **fundamental period** T_0 is the smallest positive value of T for which the above equation holds.
- Thus $x(t)$ is also periodic with period $2T, 3T, \dots$

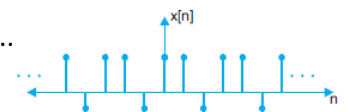


Periodic Signals

- **Discrete Time Periodic Signals:** A periodic discrete-time signal $x[n]$ has the property that for a positive integer N ,

- $x[n] = x[n + N]$, for all values of n .

- The discrete time signal $x[n]$ is periodic with period N if it is unchanged by a time shift of N .
- The **fundamental period** N_0 is the smallest positive value of N for which the above equation holds.
- Thus $x[n]$ is periodic with period $2N, 3N, \dots$



What is a System?

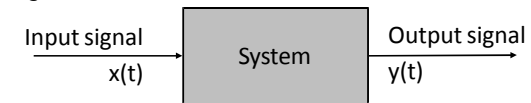
□ Systems **processes** input signals to produce output signals.

□ Examples:

- A **circuit** involving a capacitor can be viewed as a system that transforms the source voltage (signal) to the voltage (signal) across the capacitor
- A **CD player** takes the signal on the CD and transforms it into a signal sent to the loud speaker
- A **communication system** is generally composed of three sub-systems, the transmitter, the channel and the receiver. The channel typically attenuates and adds noise to the transmitted signal which must be processed by the receiver

How is a System Represented?

□ A system takes a signal as an input and transforms it into another signal



- In a very broad sense, a system can be represented as the ratio of the output signal over the input signal
- That way, when we “multiply” the system by the input signal, we get the output signal
 - This concept will be firmed up in the coming weeks

Signal Energy and Power

- We are more concerns with the signal strength (Energy/Power) of the signal.
- If $v(t)$ and $i(t)$ are, respectively, the voltage and current across a resistor with resistance R , then the instantaneous power is

$$p(t) = v(t)i(t) = \frac{1}{R}v^2(t).$$

- The total *energy* expended over the time interval $t_1 < t < t_2$ is

$$\int_{t_1}^{t_2} p(t) dt = \int_{t_1}^{t_2} \frac{1}{R} v^2(t) dt, \quad \frac{1}{t_2 - t_1} \int_{t_1}^{t_2} p(t) dt = \frac{1}{t_2 - t_1} \int_{t_1}^{t_2} \frac{1}{R} v^2(t) dt.$$

Signal Energy and Power

- In this case, the total energy over the time interval $t_1 < t < t_2$ in a continuous-time signal $x(t)$ is defined as

$$\int_{t_1}^{t_2} |x(t)|^2 dt, \quad \sum_{n=n_1}^{n_2} |x[n]|^2,$$

- Power is calculated by dividing total time **t2-t1**, or **n2-n1+1**

Signal Energy and Power

- Furthermore, in many systems we will be interested in examining power and energy in signals over an infinite time interval,

$$E_{\infty} \triangleq \lim_{T \rightarrow \infty} \int_{-T}^T |x(t)|^2 dt = \int_{-\infty}^{+\infty} |x(t)|^2 dt, \quad E_{\infty} \triangleq \lim_{N \rightarrow \infty} \sum_{n=-N}^{+N} |x[n]|^2 = \sum_{n=-\infty}^{+\infty} |x[n]|^2.$$

$$P_{\infty} \triangleq \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt$$

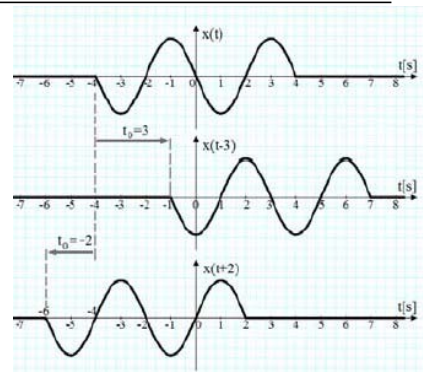
$$P_{\infty} \triangleq \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^{+N} |x[n]|^2$$

Signal Transformation

- Modification in time axis, independent variable
 - Time shifting
 - Time scaling
 - Time reversal

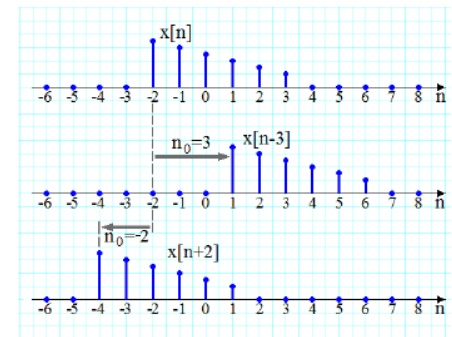
Signal Transformations Continuous Time

- Time Shifting** (Shifting the Independent variable)
- Delayed/advanced form of original signal
- $x(t-t_0)$: Right Shift if $t_0 > 0$, Left Shift if $t_0 < 0$.



Signal Transformations Discrete Time

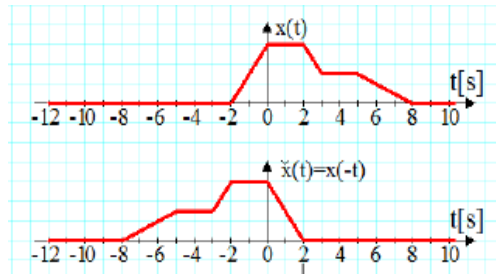
- Time Shifting** (Shifting the Independent variable)
- $x[n-n_0]$: Right Shift if $n_0 > 0$, Left Shift if $n_0 < 0$.



Signal Transformations

- **Time Reversal** (flipping the signal around $t=0$)

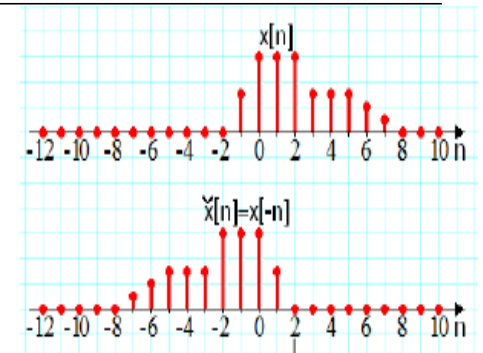
- a) $x(t)$
b) $x(-t)$



Signal Transformations

- **Time Reversal** (flipping the signal around $n=0$)

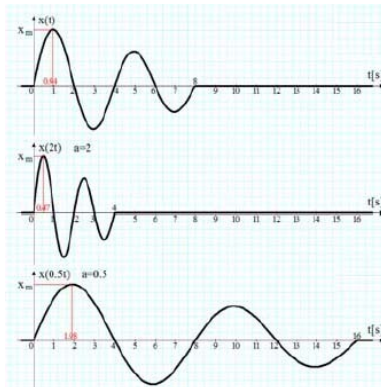
- a) $x[n]$
b) $x[-n]$



Signal Transformations

- **Time Scaling** (Scaling the Independent variable)
- Compresses or expands the signal by multiplying the time variable by a constant

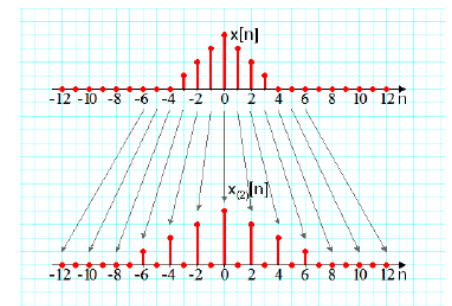
- $y(t) = x(at)$:
1. $a = 1$
 2. $a = 2$
 3. $a = \frac{1}{2} = 0.5$



Signal Transformations

- **Time Scaling** (Scaling the Independent variable)

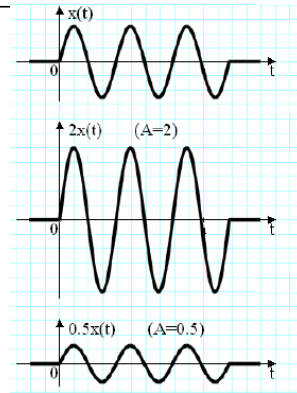
$$x_{(k)}[n] = \begin{cases} x\left[\frac{n}{k}\right], & \text{if } k \text{ divides } n \\ 0, & \text{otherwise} \end{cases}$$



Signal Transformations

- **Weighting** (Scaling the dependent variable)

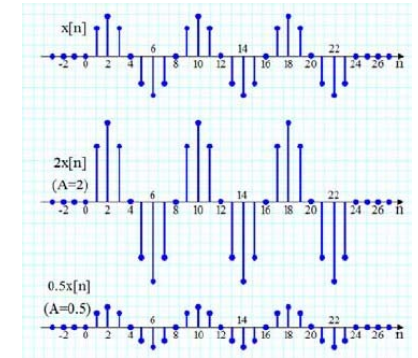
- a) Amplification
- b) Attenuation



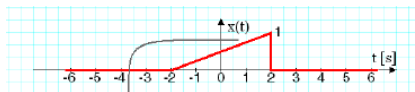
Signal Transformations

- **Weighting** (Scaling the dependent variable)

- a) Amplification
- b) Attenuation



Example – Signal Transformation



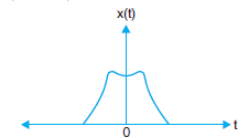
$$x(t) \longrightarrow 2x(-2t - 2)$$

- ❑ **Remember: Shift before you scale or invert !!**
- ❑ Also solve Examples 1.1, 1.2 and 1.3 for practice

Even Signals

- ❑ A continuous signal $f(t)$ is referred to as an even signal if it is identical to its **time-reversed** counterpart, i.e., with its reflection about the origin.

$$f(t) = f(-t); \text{ for all } t$$



- ❑ The discrete signal $f[n]$ is said to be even if

$$f[n] = f[-n]; \text{ for all } n$$



Odd Signals

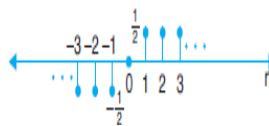
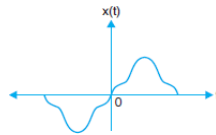
- A continuous signal $f(t)$ is referred to as an odd signal if it is not identical to its time-reversed counterpart, as shown below:

$$f(-t) = -f(t); \text{ for all } t$$

- It may be noted that an odd continuous time signal will be **zero at origin**, i.e., $f(0) = 0$ at $t = 0$.

- The signal $f[n]$ is said to be odd if:

$$f[-n] = -f[n]; \text{ for all } n$$



Even and Odd Signal Decomposition

- A signal can be **decomposed into its even and odd components**.
- Decomposition of continuous signal $f(t)$ can be done as:

$$f(t) = f_e(t) + f_o(t)$$

- Here, $f_e(t)$ is the even and $f_o(t)$ is the odd component of continuous signal $f(t)$.
- Obviously, the even function has the property: $f_e(-t) = f_e(t)$

- And the odd function has the property: $f_o(-t) = -f_o(t)$

- Replacing t by $-t$ in the expression of $f(t)$, we get:

$$f(-t) = f_e(-t) + f_o(-t) = f_e(t) - f_o(t)$$

- Solving from the expression of $f(t)$ and $f(-t)$, we get:

$$f_e(t) = \frac{1}{2} [f(t) + f(-t)] \quad \text{and} \quad f_o(t) = \frac{1}{2} [f(t) - f(-t)]$$

Even and Odd Signal Decomposition

- Decomposition of discrete signal $f[n]$ can be done as in the case of continuous time signal as follows:

$$f[n] = f_e[n] + f_o[n]$$

- Here, $f_e[n]$ is the even and $f_o[n]$ is the odd component of discrete signal $f[n]$.
- Obviously, the even function as usual has the property: $f_e[-n] = f_e[n]$

- And the odd function as usual has the property: $f_o[-n] = -f_o[n]$

- Replacing n by $-n$ in the expression of $f[n]$, we get:

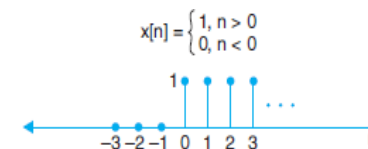
$$f[-n] = f_e[-n] + f_o[-n] = f_e[n] - f_o[n]$$

- Solving from the expression of $f[n]$ and $f[-n]$, we get:

$$f_e[n] = \frac{1}{2} [f[n] + f[-n]] \quad \text{and} \quad f_o[n] = \frac{1}{2} [f[n] - f[-n]]$$

Signal Decomposition - Example

- Find the Even and Odd signal components of the signal below:



Continuous-Time Exponential and Sinusoidal Signals

$$z = re^{j\theta}$$

$$z = x + jy$$

$$r = |z|$$

$$|z| = \sqrt{x^2 + y^2}$$

$$x = r \cos \theta \quad y = r \sin \theta$$

$$\theta = \tan^{-1}(y/x)$$

$$e^{j\theta} = \cos \theta + j \sin \theta$$

$$|e^{j\theta}| = 1$$

$$\cos \theta = \frac{e^{j\theta} + e^{-j\theta}}{2}$$

$$\sin \theta = \frac{e^{j\theta} - e^{-j\theta}}{2j}$$

Continuous-Time Exponential and Sinusoidal Signals

- The continuous-time *complex exponential signal* is of the form

$$x(t) = Ce^{at},$$

- where C and a are, in general, complex numbers.
- Depending upon the values of these parameters, the complex exponential can exhibit several different characteristics.

Real Exponential Signals

- If C and a are real number. ($a > 0$, $a < 0$)

