

EE-220 Signals and Systems

Session 2019

Week 6

Instructor: Engr. Ali Raza
ediraaz1@gmail.com

Last Week

- ☐ Linear Constant-Coefficient Differential Equations
- ☐ Block Diagram Representation
- ☐ Basic Functions
 - ☐ Sine, Exponential

© A Raza, 2021

Fourier Series of a Periodic Continuous-Time Signal

- ☐ This pair of equations, then, defines the Fourier series of a periodic continuous-time signal:

$$x(t) = \sum_{k=-\infty}^{+\infty} a_k e^{jk\omega_0 t} = \sum_{k=-\infty}^{+\infty} a_k e^{jk(2\pi/T)t},$$

$$a_k = \frac{1}{T} \int_T x(t) e^{-jk\omega_0 t} dt = \frac{1}{T} \int_T x(t) e^{-jk(2\pi/T)t} dt,$$

$$a_0 = \frac{1}{T} \int_T x(t) dt,$$

© A Raza, 2021

Example 3.3

$$x(t) = \sin \omega_0 t,$$

$$\sin \omega_0 t = \frac{1}{2j} e^{j\omega_0 t} - \frac{1}{2j} e^{-j\omega_0 t}.$$

$$a_1 = \frac{1}{2j}, \quad a_{-1} = -\frac{1}{2j},$$

$$a_k = 0, \quad k \neq \pm 1 \text{ or } -1.$$

© A Raza, 2021

Example 3.4

$$x(t) = 1 + \sin \omega_0 t + 2 \cos \omega_0 t + \cos \left(2\omega_0 t + \frac{\pi}{4} \right).$$

$$x(t) = 1 + \frac{1}{2j} [e^{j\omega_0 t} - e^{-j\omega_0 t}] + [e^{j\omega_0 t} + e^{-j\omega_0 t}] + \frac{1}{2} [e^{j(2\omega_0 t + \pi/4)} + e^{-j(2\omega_0 t + \pi/4)}].$$

$$x(t) = 1 + \left(1 + \frac{1}{2j} \right) e^{j\omega_0 t} + \left(1 - \frac{1}{2j} \right) e^{-j\omega_0 t} + \left(\frac{1}{2} e^{j(\pi/4)} \right) e^{j2\omega_0 t} + \left(\frac{1}{2} e^{-j(\pi/4)} \right) e^{-j2\omega_0 t}.$$

© A Raza, 2021

Example 3.4

$$x(t) = 1 + \left(1 + \frac{1}{2j} \right) e^{j\omega_0 t} + \left(1 - \frac{1}{2j} \right) e^{-j\omega_0 t} + \left(\frac{1}{2} e^{j(\pi/4)} \right) e^{j2\omega_0 t} + \left(\frac{1}{2} e^{-j(\pi/4)} \right) e^{-j2\omega_0 t}.$$

$$a_0 = 1,$$

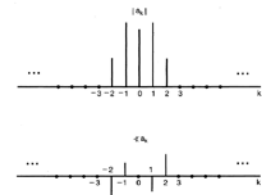
$$a_1 = \left(1 + \frac{1}{2j} \right) = 1 - \frac{1}{2}j,$$

$$a_{-1} = \left(1 - \frac{1}{2j} \right) = 1 + \frac{1}{2}j,$$

$$a_2 = \frac{1}{2} e^{j(\pi/4)} = \frac{\sqrt{2}}{4} (1 + j),$$

$$a_{-2} = \frac{1}{2} e^{-j(\pi/4)} = \frac{\sqrt{2}}{4} (1 - j),$$

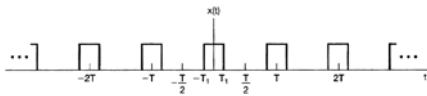
$$a_k = 0, \quad |k| > 2.$$



© A Raza, 2021

Example 3.5

$$x(t) = \begin{cases} 1, & |t| < T_1 \\ 0, & T_1 < |t| < T/2 \end{cases}$$



$$a_0 = \frac{1}{T} \int_{-T_1}^{T_1} dt = \frac{2T_1}{T}, \quad a_k = \frac{1}{T} \int_{-T_1}^{T_1} e^{-jk\omega_0 t} dt = \frac{1}{jk\omega_0 T} e^{-jk\omega_0 t} \Big|_{-T_1}^{T_1}, \quad a_k = \frac{2}{k\omega_0 T} \left[\frac{e^{jk\omega_0 T_1} - e^{-jk\omega_0 T_1}}{2j} \right]$$

© A. Razza, 2021.

Example 3.5

$$a_k = \frac{2}{k\omega_0 T} \left[\frac{e^{jk\omega_0 T_1} - e^{-jk\omega_0 T_1}}{2j} \right]$$

$$a_k = \frac{2 \sin(k\omega_0 T_1)}{k\omega_0 T} = \frac{\sin(k\omega_0 T_1)}{k\pi}, \quad k \neq 0,$$

- For $T = 4T_1$, $x(t)$ is a square wave that is unity for half the period and zero for half the period

$$\omega_0 T_1 = \pi/2$$

© A. Razza, 2021.

Example 3.5

$$a_k = \frac{\sin(\pi k/2)}{k\pi}, \quad k \neq 0,$$

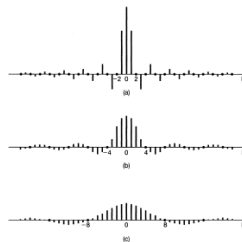
$$a_0 = \frac{1}{2},$$

$$a_1 = a_{-1} = \frac{1}{\pi},$$

$$a_3 = a_{-3} = -\frac{1}{3\pi},$$

$$a_5 = a_{-5} = \frac{1}{5\pi},$$

...



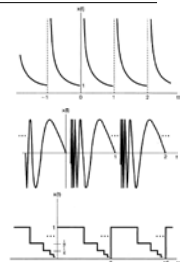
© A. Razza, 2021.

CONVERGENCE OF THE FOURIER SERIES

1. Over any period, $x(t)$ must be *absolutely integrable*; that is,

$$\int_T |x(t)| dt < \infty.$$

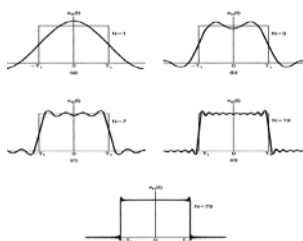
2. In any finite interval of time, $x(t)$ is of bounded variation; that is, there are no more than a finite number of maxima and minima during any single period of the signal.
3. In any finite interval of time, there are only a finite number of discontinuities. Furthermore, each of these discontinuities is finite.



© A. Razza, 2021.

Gibbs Phenomenon

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t} = \sum_{k=-\infty}^{\infty} a_k e^{jk(2\pi/T)t}$$



© A. Razza, 2021.

Gibbs Phenomenon

- Thus, as N increases, the ripples in the partial sums become compressed toward the discontinuity, but for *any* finite value of N , the peak amplitude of the ripples remains constant. This behavior has come to be known as the *Gibbs phenomenon*.
- The implication is that the truncated Fourier series approximation $X_N(t)$ of a discontinuous signal $x(t)$ will in general exhibit high-frequency ripples and overshoot $x(t)$ near the discontinuities.
- A large enough value of N should be chosen so as to guarantee that the total energy in these ripples is insignificant.

© A. Razza, 2021.

PROPERTIES OF CONTINUOUS-TIME FOURIER SERIES

Linearity:

$$\begin{aligned}x(t) &\xleftrightarrow{\text{FS}} a_k, \\y(t) &\xleftrightarrow{\text{FS}} b_k, \\z(t) = Ax(t) + By(t) &\xleftrightarrow{\text{FS}} c_k = Aa_k + Bb_k.\end{aligned}$$

Time Shifting:

$$\begin{aligned}x(t) &\xleftrightarrow{\text{FS}} a_k, \\x(t - t_0) &\xleftrightarrow{\text{FS}} e^{-jk\omega_0 t_0} a_k = e^{-jk(2\pi/T)t_0} a_k.\end{aligned}$$

© A. Razaf, 2021.

PROPERTIES OF CONTINUOUS-TIME FOURIER SERIES

Time Reversal:

$$\begin{aligned}x(t) &\xleftrightarrow{\text{FS}} a_k, \\x(-t) &\xleftrightarrow{\text{FS}} a_{-k}.\end{aligned}$$

Time Scaling:

- $x(at)$, where a is a positive real number, is periodic with period T/a and fundamental frequency $a\omega_0$

$$x(at) = \sum_{k=-\infty}^{+\infty} a_k e^{jk(a\omega_0)t}$$

© A. Razaf, 2021.

PROPERTIES OF CONTINUOUS-TIME FOURIER SERIES

Multiplication:

$$\begin{aligned}x(t) &\xleftrightarrow{\text{FS}} a_k, \\y(t) &\xleftrightarrow{\text{FS}} b_k, \\x(t)y(t) &\xleftrightarrow{\text{FS}} h_k = \sum_{l=-\infty}^{\infty} a_l b_{k-l}.\end{aligned}$$

- Multiplication in time-domain = Convolution in Frequency Domain
- Convolution in time-domain = Multiplication in Frequency Domain

© A. Razaf, 2021.

PROPERTIES OF CONTINUOUS-TIME FOURIER SERIES

Conjugation and Conjugate Symmetry:

$$\begin{aligned}x(t) &\xleftrightarrow{\text{FS}} a_k, \\x^*(t) &\xleftrightarrow{\text{FS}} a_{-k}^*.\end{aligned}$$

- For real $x(t)$ $x(t) = x^*(t)$ $a_{-k} = a_k^*$
- For real and even $x(t)$ $a_k = a_{-k}$ $a_k = a_{-k}^*$

© A. Razaf, 2021.

Parseval's Relation for Continuous-Time Periodic Signals

- Total average power in a periodic signal equals the sum of the average powers in all of its harmonic components

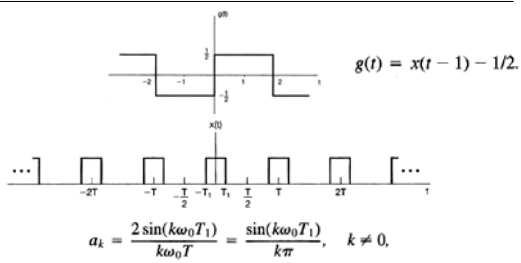
$$\begin{aligned}\frac{1}{T} \int_T |x(t)|^2 dt &= \sum_{k=-\infty}^{+\infty} |a_k|^2, \\ \frac{1}{T} \int_T |a_k e^{jk\omega_0 t}|^2 dt &= \frac{1}{T} \int_T |a_k|^2 dt = |a_k|^2.\end{aligned}$$

© A. Razaf, 2021.

Linearity	3.5.1	$Ax(t) + By(t)$	$Aa_k + Bb_k$
Time Shifting	3.5.2	$x(t - t_0)$	$a_k e^{-jk\omega_0 t_0} = a_k e^{-jk(2\pi/T)t_0}$
Frequency Shifting		$e^{j\omega_0 t} x(t) = x(t)$	a_{k-m}
Conjugation	3.5.6	$x^*(t)$	a_{-k}^*
Time Reversal	3.5.3	$x(-t)$	a_{-k}
Time Scaling	3.5.4	$x(at), a > 0$ (periodic with period T/a)	a_k
Periodic Convolution		$\int_T x(t)y(t - \tau) d\tau$	$T a_k b_k$
Multiplication	3.5.5	$x(t)y(t)$	$\sum_{l=-\infty}^{\infty} a_l b_{k-l}$
Differentiation		$\frac{dx(t)}{dt}$	$jk\omega_0 a_k = jk \frac{2\pi}{T} a_k$
Integration		$\int_{-\infty}^{\infty} x(t) dt$ (finite value and periodic only if $a_0 = 0$)	$\left(\frac{1}{j\omega_0}\right) a_k = \left(\frac{1}{jk(2\pi/T)}\right) a_k$
Conjugate Symmetry for Real Signals	3.5.6	$x(t)$ real	$\begin{cases} a_{-k} = a_k^* \\ \text{Re}\{a_k\} = \text{Re}\{a_{-k}\} \\ \text{Im}\{a_k\} = -\text{Im}\{a_{-k}\} \\ a_k = a_{-k} \\ \angle a_k = -\angle a_{-k} \end{cases}$
Real and Even Signals	3.5.6	$x(t)$ real and even	a_k real and even
Real and Odd Signals	3.5.6	$x(t)$ real and odd	a_k purely imaginary and odd
Even-Odd Decomposition of Real Signals		$\begin{cases} x_e(t) = \frac{1}{2}(x(t) + x(-t)) \\ x_o(t) = \frac{1}{2}(x(t) - x(-t)) \end{cases}$	$\begin{cases} \text{Re}\{a_k\} \\ \text{Im}\{a_k\} \end{cases}$

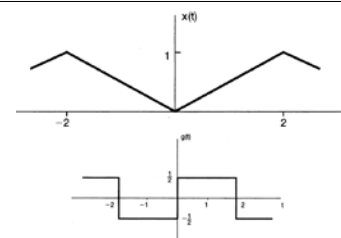
18

Example 3.6



© A. Razza, 2021.

Example 3.7



© A. Razza, 2021.

Example 3.8

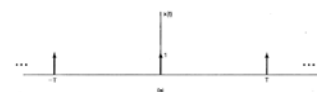
$$x(t) = \sum_{k=-\infty}^{\infty} \delta(t - kT);$$

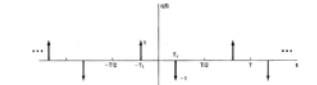

$$a_k = \frac{1}{T} \int_{-T/2}^{T/2} \delta(t) e^{-jk\omega_0 t} dt = \frac{1}{T}.$$


In other words, all the Fourier series coefficients of the impulse train are identical.

© A. Razza, 2021.

Example 3.8

$$q(t) = x(t + T_1) - x(t - T_1).$$


$$b_k = e^{jk\omega_0 T_1} a_k - e^{-jk\omega_0 T_1} a_k,$$


$$b_k = \frac{1}{T} [e^{jk\omega_0 T_1} - e^{-jk\omega_0 T_1}] = \frac{2j \sin(k\omega_0 T_1)}{T}.$$


© A. Razza, 2021.

Example 3.8

$$q(t) = \frac{d}{dt} g(t)$$

$$b_k = (jk\omega_0) c_k$$

$$c_k = (1 / jk\omega_0) b_k$$

$$c_k = \left(\frac{1}{jk\omega_0} \right) \frac{1}{T} [2j \sin(k\omega_0 T_1)]$$

$$c_k = \frac{1}{k\pi} [\sin(k\omega_0 T_1)], \quad k \neq 0$$

$$c_0 = \frac{2T_1}{T}, \quad k = 0$$

© A. Razza, 2021.