

Moscow IPT

# Ctrl+XD

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Northern Eurasia Finals 2024 2024.12.15

# Numerical (1)

#### 1.1 Newton's method

To compute  $B = \frac{1}{A}$  modulo  $x^m$ : define  $B_1 = \{inv(A[0])\}$  and  $B_{2n} = B_n(2 - A \cdot B_n)$ .

To compute  $B = \sqrt{A}$  modulo  $x^m$ : define  $B_1 = \{\sqrt{A[0]}\}$  and  $B_{2n} = \frac{B_n}{2} + \frac{A}{2B_n}$ .

To compute  $B = \log(1 + xA)$  modulo  $x^m$ :  $B = \int \frac{(1+xA)'}{1+xA}$ .

If T is EGF for some objects then  $C = -\log(1 - T) = \sum_{k=1}^{+\infty} \frac{T^k}{k}$  is EGF for cycles of them.

To compute  $B = e^{xA}$  modulo  $x^m$ : define  $B_1 = \{1\}$  and  $B_{2n} = B_n(1 + A - \log B_n)$ .

If T is EGF for some objects then  $F = e^T = \sum_{k=0}^{\infty} \frac{T^k}{k!}$  is EGF for their unordered combinations.

In general case you have equation P(B, x) = 0. (f.e.  $\log B - A(x) = 0$ ).

The transition is  $B_{2n-\alpha} = B_n - \frac{P(B,x)}{P'_B(B,x)}$ . (if  $P'_B(B,x)$  is divisible by  $x^{\alpha}$ ).

### 1.2 Additional modulos for FFT

Modulo	Other form	Roots
998244353	(119 << 23) + 1	3,62
167772161	(5 << 25) + 1	3,62
469762049	(7 << 26) + 1	3,62
1004535809	(479 << 21) + 1	3,62
1012924417	(483 << 21) + 1	62

### FFT

**Description:** Applies the discrete Fourier transform to a sequence of numbers modulo MOD. **Time:**  $\mathcal{O}(n \log n)$ 

```
int rev[N], root[N];

void init(int n) {
    static int last_init = -1;
    if (n == last_init) return;
    last_init = n;
    for (int i = 1; i < n; ++i) {
        rev[i] = (rev[i >> 1] >> 1) | (i & 1) * (n >> 1);
    }
}
```

```
const int root_n = binpow(ROOT, (MOD - 1) / n);
    for (int i = 0, cur = 1; i < n / 2; ++i) {
        root[i + n / 2] = cur;
        cur = mul(cur, root n);
    for (int i = n / 2 - 1; i >= 0; --i) {
        root[i] = root[i << 1];
void dft(int* f, int n, bool inverse = false) {
    init(n);
    for (int i = 0; i < n; ++i) {</pre>
        if (i < rev[i]) swap(f[i], f[rev[i]]);</pre>
    for (int k = 1; k < n; k <<= 1)</pre>
        for (int i = 0; i < n; i += (k << 1))
            for (int j = 0; j < k; ++j) {
                 int z = mul(f[i + j + k], root[j + k]);
                f[i + j + k] = add(f[i + j], MOD - z);
                f[i + j] = add(f[i + j], z);
    if (inverse) {
        reverse (f + 1, f + n);
        const int inv n = inv(n);
        for (int i = 0; i < n; ++i) f[i] = mul(f[i], inv_n);</pre>
```

## Middle product

 $\textbf{Description:} \ \ \text{Calculates middle-product of two arrays using Tellegen's principle.}$ 

Time:  $\mathcal{O}(n \log n)$ 

```
vector<int> mulT(const vector<int>& a, const vector<int>& b) {
   int n = sz(a), m = sz(b), k = 1;
   while (k < n) k <<= 1;
   fill_n(fft1, k, 0), fill_n(fft2, k, 0);
   copy(all(a), fft1), copy(all(b), fft2);
   dft(fft1, k, true), dft(fft2, k);
   for (int i = 0; i < k; ++i) fft1[i] = mul(fft1[i], fft2[i]);
   dft(fft1, k);
   return {fft1, fft1 + n - m + 1};
}</pre>
```

## Polynomial division

**Description:** Finds first n coefficients of 1/a modulo MOD.

Time:  $\mathcal{O}(n \log n)$ 

```
vector<int> inv(vector<int> a, int n) {
    assert(a[0] != 0);
    vector res{inv(a[0])};
    for (int k = 1; k < n; k <<= 1) {
        auto tmp = mul(res, res);
        if ((int)tmp.size() > n) {
            tmp.resize(n);
        }
        tmp = mul(tmp, {a.begin(), a.begin() + min(2 * k, sz(a))});
        tmp.resize(2 * k);
        for (int i = 0; i < k; ++i) {
            tmp[i] = sub(add(res[i], res[i]), tmp[i]);
            tmp[k + i] = sub(0, tmp[k + i]);
        }
        res.swap(tmp);
    }
    res.resize(n);
    return res;
}</pre>
```

# Berlekamp-Massey

**Description:** Returns the polynomial of a recurrent sequence of order n from the first 2n terms.

Usage: berlekamp\_massey({0, 1, 1, 3, 5, 11}) // {1, -1, -2} Time:  $\mathcal{O}(n^2)$ 

```
vector<int> berlekamp_massey(vector<int> s) {
   int n = sz(s), L = 0, m = 0;
   vector<int> c(n), b(n), t;
   c[0] = b[0] = 1;
   int eval = 1;
   for (int i = 0; i < n; ++i) {
        m++;
        int delta = 0;
        for (int j = 0; j <= L; ++j) {
            delta = add(delta, mul(c[j], s[i - j]));
        }
        if (delta == 0) continue;
        t = c;
        int coef = mul(delta, inv(eval));
        for (int j = m; j < n; ++j) {
            c[j] = sub(c[j], mul(coef, b[j - m]));
        }
}</pre>
```

```
if (2 * L > i) continue;
L = i + 1 - L, m = 0, b = t, eval = delta;
}
c.resize(L + 1);
return c;
```

#### 1.3 Linear recurrence

Let A be generating function for our recurrence, C be its characteristic polynomial and k = |C|.

Let  $D = C \cdot A$ . Then  $D \mod x^k = D$ 

$$A = \frac{(A \mod x^k)C \mod x^k}{C} = \frac{A_0C \mod x^k}{C}$$
$$[x^n]\frac{P(x)}{Q(x)} = [x^n]\frac{P(x)Q(-x)}{Q(x)Q(-x)}$$

# $\underline{\text{Flows}}$ (2)

#### Dinitz

**Description:** Finds maximum flow using Dinitz algorithm.

Time:  $\mathcal{O}\left(n^2m\right)$ 

```
struct Edge {
    int to, cap, flow;
};
vector<Edge> E;
vector<int> gr[N];
int n;
int d[N], ptr[N];
bool bfs(int v0 = 0, int cc = 1) {
    fill(d, d + n, -1);
    d[v0] = 0;
    vector<int> q{v0};
    for (int st = 0; st < sz(q); ++st) {
        int v = q[st];
        for (int id : gr[v]) {
            auto [to, cp, fl] = E[id];
            if (d[to] != -1 || cp - fl < cc) continue;
            d[to] = d[v] + 1;
```

```
q.emplace_back(to);
        }
    }
    return d[n - 1] != -1;
int dfs(int v, int flow, int cc = 1) {
    if (v == n - 1 || !flow) return flow;
    for (; ptr[v] < sz(gr[v]); ++ptr[v]) {</pre>
        auto [to, cp, fl] = E[gr[v][ptr[v]]];
        if (d[to] != d[v] + 1 || cp - fl < cc) continue;</pre>
        int pushed = dfs(to, min(flow, cp - fl), cc);
        if (pushed) {
            int id = gr[v][ptr[v]];
            E[id].flow += pushed;
            E[id ^ 1].flow -= pushed;
            return pushed;
        }
    return 0;
ll dinitz() {
    11 \text{ flow} = 0;
    for (int c = INF; c > 0; c >>= 1) {
        while (bfs(0, c)) {
            fill(ptr, ptr + n, 0);
            while (int pushed = dfs(0, INF, c))
                 flow += pushed;
        }
    return flow;
MCMF
```

**Description:** Finds Minimal Cost Maximal Flow.

```
struct Edge {
    ll to, f, c, w;
};

vector<Edge> E;
vector<int> gr[N];

void add_edge(int u, int v, ll c, ll w) {
    gr[u].push_back(sz(E));
```

```
E.emplace_back(v, 0, c, w);
    gr[v].push_back(sz(E));
    E.emplace_back(u, 0, 0, -w);
pair<ll, ll> mcmf(int n) {
    vector<ll> dist(n);
    vector<ll> pr(n);
    vector<ll> phi(n);
    auto dijkstra = [&] {
        fill(all(dist), INF);
        dist[0] = 0;
        priority_queue<pair<11, int>, vector<pair<11, int>>,
           greater<>> pq;
        pq.emplace(0, 0);
        while (!pq.empty()) {
            auto [d, v] = pq.top();
            pq.pop();
            if (d != dist[v]) continue;
            for (int idx : qr[v]) {
                if (E[idx].c == E[idx].f) continue;
                int to = E[idx].to;
                ll w = E[idx].w + phi[v] - phi[to];
                if (dist[to] > d + w) {
                    dist[to] = d + w;
                    pr[to] = idx;
                    pq.emplace(d + w, to);
    };
    11 total_cost = 0, total_flow = 0;
    while (true) {
        dijkstra();
        if (dist[n - 1] == INF) break;
        11 min_cap = INF;
        int cur = n - 1;
        while (cur != 0) {
            min_cap = min(min_cap, E[pr[cur]].c - E[pr[cur]].f);
            cur = E[pr[cur] ^ 1].to;
        }
        cur = n - 1;
        while (cur != 0) {
            E[pr[cur]].f += min_cap;
            E[pr[cur] ^ 1].f -= min_cap;
```

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```
total_cost += min_cap * E[pr[cur]].w;
    cur = E[pr[cur] ^ 1].to;
}
total_flow += min_cap;
for (int i = 0; i < n; ++i) {
    phi[i] += dist[i];
}
return {total_flow, total_cost};</pre>
```

# Number Theory (3)

### Extended GCD

**Description:** Finds two integers x and y, such that ax + by = gcd(a, b).

```
ll exgcd(ll a, ll b, ll &x, ll &y) {
   if (!b) return x = 1, y = 0, a;
   ll d = euclid(b, a % b, y, x);
   return y -= a/b * x, d;
}
```

#### CRT

**Description:** Chinese Remainder Theorem. crt(a, m, b, n) computes x s.t.  $x \equiv a \mod m, x \equiv b \mod n$ .

Time:  $\mathcal{O}(\log n)$ 

```
ll crt(ll a, ll m, ll b, ll n) {
   if (n > m) swap(a, b), swap(m, n);
   ll x, y, g = exgcd(m, n, x, y);
   assert((a - b) % g == 0); // else no solution
   x = (b - a) % n * x % n / g * m + a;
   return x < 0 ? x + m * n / g : x;
}</pre>
```

# Miller-Rabin

**Description:** Deterministic Miller-Rabin primality test. Guaranteed to work for numbers up to  $7 \cdot 10^{18}$ 

**Time:** 7 times the complexity of  $a^b \mod c$ .

```
bool is_prime(ll n) {
   if (n < 2 || n % 6 % 4 != 1) return (n | 1) == 3;
   ll A[] = {2, 325, 9375, 28178, 450775, 9780504, 1795265022};
   ll s = __builtin_ctzll(n - 1), d = n >> s;
   for (ll a : A) {
```

#### Pollard-Rho

**Description:** Pollard-rho randomized factorization algorithm. Returns prime factors of a number, in arbitrary order.

**Time:**  $\mathcal{O}(n^{1/4})$ , less for numbers with small factors.

```
1l pollard(ll n) {
    auto f = [n](ll x) { return mul(x, x, n) + 1; };
    ll x = 0, y = 0, t = 30, prd = 2, i = 1, q;
    while (t++ % 40 || __gcd(prd, n) == 1) {
        if (x == y) x = ++i, y = f(x);
        if ((q = mul(prd, max(x,y) - min(x,y), n))) prd = q;
        x = f(x), y = f(f(y));
    }
    return __gcd(prd, n);
}

vector<ll> factor(ll n) {
    if (n == 1) return {};
    if (is_prime(n)) return {n};
    ll x = pollard(n);
    auto l = factor(x), r = factor(n / x);
    l.insert(l.end(), all(r));
    return l;
}
```

### 3.1 Möbius function

$$\mu(n) = \begin{cases} 0, n \text{ is not square free} \\ 1, n \text{ has even number of prime factors} \\ -1, n \text{ has odd number of prime factors} \end{cases}$$

$$\sum_{d|n} \mu(d) = \operatorname{int}(n=1)$$

Möbius inversion:

$$g(n) = \sum_{d|n} f(d) \iff f(n) = \sum_{d|n} \mu(d)g(n/d) = \sum_{d|n} \mu(n/d)g(d)$$

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# 3.2 Sums of powers

$$\sum_{s=1}^{n} s^{k} = \sum_{s=1}^{k} s! S(k, s) C_{n+1}^{s+1}$$

$$\sum_{s=1}^{n} s^1 = 1 \frac{(n+1)n}{2!}$$

$$\sum_{s=1}^{n} s^2 = 1 \frac{(n+1)n}{2!} + 2 \frac{(n+1)n(n-1)}{3!} = \frac{n(n+1)(2n+1)}{6}$$
$$\sum_{s=1}^{n} s^3 = 1 \frac{(n+1)n}{2!} + 6 \frac{(n+1)n(n-1)}{3!} + 6 \frac{(n+1)n(n-1)(n-2)}{4!} = \frac{(n+1)^2 n^2}{4}$$

# 3.3 Floor sum

$$f(a, b, c, n) = \sum_{x=0}^{n} \left\lfloor \frac{ax + b}{c} \right\rfloor$$

Let  $m = \lfloor \frac{an+b}{c} \rfloor$ . When a < c and b < c, we have:

$$f(a, b, c, n) = mn - f(c, c - b - 1, a, m - 1)$$

Otherwise:

$$f(a,b,c,n) = \frac{n(n+1)}{2} \left\lfloor \frac{a}{c} \right\rfloor + (n+1) \left\lfloor \frac{b}{c} \right\rfloor + f(a \bmod c, b \bmod c, c, n)$$

# 3.4 Square of floor sum

$$g(a, b, c, n) = \sum_{x=0}^{n} x \left\lfloor \frac{ax + b}{c} \right\rfloor$$

$$h(a, b, c, n) = \sum_{x=0}^{n} \left\lfloor \frac{ax + b}{c} \right\rfloor^{2}$$

Let  $m = \lfloor \frac{an+b}{c} \rfloor$ . When a < c and b < c, we have:

$$g(a,b,c,n) = \frac{mn(n+1)}{2} - \frac{f(c,c-b-1,a,m-1)}{2} - \frac{h(c,c-b-1,a,m-1)}{2}$$

$$h(a,b,c,n) = mn(m+1) - 2g(c,c-b-1,a,m-1) - 2f(c,c-b-1,a,m-1) - f(a,b,c,n)$$

Otherwise:

$$g(a,b,c,n) = \frac{n(n+1)(2n+1)}{6} \left\lfloor \frac{a}{c} \right\rfloor + \frac{n(n+1)}{2} \left\lfloor \frac{b}{c} \right\rfloor + g(a \bmod c, b \bmod c, c, n)$$

$$h(a,b,c,n) = \frac{n(n+1)(2n+1)}{6} \left\lfloor \frac{a}{c} \right\rfloor^2 + (n+1) \left\lfloor \frac{b}{c} \right\rfloor^2 + n(n+1) \left\lfloor \frac{a}{c} \right\rfloor \left\lfloor \frac{b}{c} \right\rfloor +$$

$$+h(a \bmod c, b \bmod c, c, n) + 2 \left\lfloor \frac{b}{c} \right\rfloor f(a \bmod c, b \bmod c, c, n) +$$

 $+2 \left| \frac{a}{c} \right| g(a \bmod c, b \bmod c, c, n)$ 

# Combinatorics (4)

# 4.1 Derangements

Number of n-permutations that none of the elements appears in their original position.

$$D_n = (n-1)(D_{n-1} + D_{n-2}) = nD_{n-1} + (-1)^n \approx \frac{n!}{e}$$

## 4.2 Burnside's lemma

Given a group G of symmetries and a set  $\Omega$ , the number of elements of  $\Omega$  up to symmetry equal

$$\frac{1}{|G|} \sum_{g \in G} N(g)$$

where N(g) is the number of elements fixed by g(g(x) = x).

# 4.3 Stirling numbers (first kind)

Unsigned Stirling numbers of the first kind  $c_{n,k}$  is the number of permutations of n elements with k cycles as well as the coefficient on  $x^k$  in the expansion  $x(x+1)(x+2)\dots(x+(n-1))$ .

Signed Stirling numbers of the first kind  $s_{n,k}$  is the coefficient on  $x^k$  in the expansion x(x-1)(x-2)...(x-(n-1)).

$$c_{0,0} = s_{0,0} = 1$$
  $c_{k,0} = s_{k,0} = 0$   $c_{n,k} = s_{n,k} = 0$  for  $k > n$ 

$$c_{n,k} = c_{n-1,k-1} + (n-1)c_{n-1,k}$$

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$$s_{n,k} = s_{n-1,k-1} - (n-1)s_{n-1,k}$$

$$s_{n,k} = (-1)^{n+k}c_{n,k}$$
EGF: 
$$\sum_{n=0}^{\infty} \sum_{k=0}^{n} s_{n,k} \frac{x^n}{n!} y^k = (1+x)^y$$

EGF: 
$$\sum_{n=k}^{\infty} s_{n,k} \frac{x^n}{n!} = \frac{(\log(1+x))^k}{k!}$$

# 4.4 Stirling numbers (second kind)

The Stirling numbers of the second kind S(n, k), count the number of ways to partition a set of n labelled objects into k nonempty unlabelled subsets.

$$S(n,n) = 1 \text{ for } n \ge 0 \quad S(0,n) = S(n,0) = 0 \text{ for } n > 0$$

$$S(n+1,k) = k \cdot S(n,k) + S(n,k-1)$$

$$S(n,k) = \sum_{t=0}^{k} \frac{(-1)^{k-t}t^n}{(k-t)!t!}$$

$$EGF: \sum_{n=0}^{\infty} \sum_{k=0}^{n} S(n,k) \frac{x^n}{n!} y^k = e^{y(e^x-1)}$$

$$EGF: \sum_{n=k}^{\infty} S(n,k) \frac{x^n}{n!} = \frac{(e^x-1)^k}{k!}$$

#### 4.5 Bell numbers

Bell number  $B_n$  is the number of partitions of n labeled elements.

$$B_0 = B_1 = 1$$

$$B_n = \sum_{k=0}^{n-1} C_{n-1}^k B_k = \sum_{k=0}^n S(n, k)$$

$$EGF: \sum_{n=1}^{\infty} \frac{B_n}{n!} x^n = e^{e^x - 1}$$

## 4.6 Narayana numbers

Narayana number N(n, k) is the number of correct bracket sequences with length 2n and exactly k distinct nestings. Also the number of unlabeled ordered rooted trees with n+1 vertices and k leaves.

$$N(n,k) = \frac{1}{n} C_n^k C_n^{k-1}$$

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#### 4.7 Labeled unrooted trees

Every tree on n vertices has unique sequence of n-2 integers from  $\{1 \dots n\}$  associated with the tree.

Vertex with degree d appears in sequence d-1 times.

On n vertices:  $n^{n-2}$ .

With degrees  $d_1, d_2, \ldots, d_n$ :  $\frac{(n-2)!}{(d_1-1)! \ldots (d_n-1)!}$ .

# Strings (5)

#### KMP

**Description:** Calculates prefix function and Z-function of the given string.

Time:  $\mathcal{O}\left(n\right)$ 

```
vector<int> pi(const string& s) {
    vector<int> p(sz(s));
    for (int i = 1; i < sz(s); ++i) {
        int g = p[i - 1];
        while (g && s[i] != s[g]) g = p[g - 1];
        p[i] = g + (s[i] == s[g]);
    }
    return p;
}

vector<int> zf(const string& s) {
    vector<int> z(sz(s));
    int l = -1, r = -1;
    for (int i = 1; i < sz(s); ++i) {
        z[i] = i >= r ? 0 : min(r - i, z[i - 1]);
        while (i + z[i] < sz(s) && s[i + z[i]] == s[z[i]]) ++z[i];
        if (i + z[i] > r) l = i, r = i + z[i];
    }
    return z;
```

```
Manacher
```

```
Description: Manacher's algorithm
```

Time:  $\mathcal{O}\left(n\right)$ 

```
vector<int> manacher(const std::string& s) {
   int n = s.size();
   vector<int> res(2 * n + 1);
   int longest = 0, root_longest = 0;
   for (int i = 1; i < 2 * n + 1; ++i) {
        int pal;
        if (i > longest) {
            pal = 1;
        } else {
            pal = min(longest - i, res[2 * root_longest - i]);
       while (pal < i && i + pal < 2 * n && s[(i - pal - 2) / 2]
           == s[(i + pal) / 2]) {
           pal += 2;
        res[i] = pal;
        if (i + pal > longest) {
           longest = i + pal;
            root_longest = i;
   return res;
```

#### Aho-Corasick

**Description:** Builds Aho-Corasick

Time:  $\mathcal{O}(nC)$ 

```
const int C = 26;
struct node {
    int nx[C], first = -1, suff = -1; //, zsuff = -1;
    vector<int> idx;
    node() {
        fill(nx, nx + C, -1);
    }
};
vector<node> t(1);
void add_word(string& s, int id) {
    int v = 0;
    for (char ch : s) {
        int x = ch - 'a';
        if (t[v].nx[x] == -1) {
            t[v].nx[x] = sz(t);
    }
}
```

```
t.emplace_back();
        v = t[v].nx[x];
    t[v].idx.emplace back(id);
void build aho() {
    vector<pair<int, int>> q;
    for (int x = 0; x < C; ++x) {
        if (t[0].nx[x] == -1) {
            t[0].nx[x] = 0;
        } else {
            q.emplace_back(0, x);
    }
    for (int st = 0; st < sz(q); ++st) {
        auto [par, x] = q[st];
        int a = t[par].nx[x];
        if (t[par].suff == -1) {
            t[a].suff = 0;
        } else {
            t[a].suff = t[t[par].suff].nx[x];
            // t[a]. zsuff = t[t[a]. suff]. idx. empty() ? t[t[a]. suff
               |.zsuff:t/a|.suff;
        for (int y = 0; y < C; ++y) {
            if (t[a].nx[y] == -1) {
                t[a].nx[y] = t[t[a].suff].nx[y];
            } else {
                g.emplace back(a, y);
```

# Suffix array

**Description:** Calculates suffix array, inverse suffix array and LCP array of the given string. **Time:**  $\mathcal{O}(n \log n)$ 

```
const int M = 1e5 + 10;
vector<int> sa, pos, lcp;

void suffix_array(string& s) {
   int n = sz(s);
   vector<int> c(n), cur(n);
   sa.resize(n), pos.resize(n), lcp.resize(n);
```

```
for (int i = 0; i < n; ++i) {
    sa[i] = i, c[i] = s[i];
sort(all(sa), [&](int i, int j) { return c[i] < c[j]; });
vector<int> cnt(M);
for (int k = 1; k < n; k <<= 1) {
    fill(all(cnt), 0);
    for (int x : c) cnt[x]++;
    for (int i = 1; i < M; ++i) cnt[i] += cnt[i - 1];</pre>
    for (int i : sa) {
        int c2 = c[(i - k + n) % n] - 1;
        cur[cnt[c2]++] = (i - k + n) % n;
    swap(cur, sa);
    int x = -1, y = -1, p = 0;
    for (int i : sa) {
        if (c[i] != x || c[(i + k) % n] != y) {
            x = c[i], y = c[(i + k) % n], p++;
        cur[i] = p;
    swap(cur, c);
for (int i = 0; i < n; ++i) pos[sa[i]] = i;
int 1 = 0;
for (int i = 0; i < n; ++i) {
    if (pos[i] == n - 1) {
        1 = 0;
    } else {
        while (s[(i + 1) % n] == s[(sa[pos[i] + 1] + 1) % n])
           ++1;
        lcp[pos[i]] = 1;
        1 = \max(0, 1 - 1);
```

#### Minimal rotation

**Description:** Rotates the given string until it is lexicographically minimal, returns shift. **Time:**  $\mathcal{O}(n)$ 

```
int min_rotation(string& s, int len) {
    s += s;
    int i = 0, ans = 0;
    while (i < len) {
        ans = i;
    }
}</pre>
```

```
int j = i + 1, k = i;
while (j < len * 2 && s[k] <= s[j]) {
    if (s[k] < s[j]) {
        k = i;
    } else {
        k += 1;
    }
    j += 1;
}
while (i <= k) {
    i += j - k;
}
s = s.substr(ans, len);
return ans;
}</pre>
```

#### Palindromic tree

**Description:** Maintains palindromic tree with support of adding new symbols to the end. **Time:**  $\mathcal{O}(n)$ 

```
template<int C> struct EERTREE {
    int top = 1, last = 0, sz = 2;
    vector<int> str, suff, len;
    vector<array<int, C>> nx;
    EERTREE (int n) : str(n + 1, -1), suff(n + 2)
                    , len(n + 2), nx(n + 2, array < int, C > ()) {
        len[1] = -1, suff[0] = 1;
    int get_link(int v) {
        while (str[top - len[v] - 2] != str[top - 1]) v = suff[v];
        return v;
    void add_letter(int c) {
        str[top++] = c;
        last = get_link(last);
        if (!nx[last][c]) {
            len[sz] = len[last] + 2;
            suff[sz] = nx[get_link(suff[last])][c];
            nx[last][c] = sz++;
        last = nx[last][c];
};
```

# Graphs (6)

#### Directed MST

**Description:** Finds a minimum spanning tree/arborescence of a directed graph, given a root node. If no MST exists, returns -1.

Time:  $\mathcal{O}\left(E\log V\right)$ 

```
struct RollbackUF {
    vi e; vector<pii> st;
    RollbackUF(int n) : e(n, -1) {}
    int size(int x) { return -e[find(x)]; }
    int find(int x) { return e[x] < 0 ? x : find(e[x]); }</pre>
    int time() { return sz(st); }
    void rollback(int t) {
        for (int i = time(); i --> t;)
            e[st[i].first] = st[i].second;
        st.resize(t);
    bool join(int a, int b) {
        a = find(a), b = find(b);
        if (a == b) return false;
        if (e[a] > e[b]) swap(a, b);
        st.push_back({a, e[a]});
        st.push_back({b, e[b]});
        e[a] += e[b]; e[b] = a;
        return true;
};
struct Edge { int a, b; ll w; };
struct Node {
    Edge key;
    Node *1, *r;
    ll delta;
    void prop() {
        key.w += delta;
        if (1) 1->delta += delta;
        if (r) r->delta += delta;
        delta = 0;
    Edge top() { prop(); return key; }
};
Node *merge(Node *a, Node *b) {
    if (!a || !b) return a ?: b;
    a->prop(), b->prop();
    if (a->key.w > b->key.w) swap(a, b);
```

```
swap(a - > 1, (a - > r = merge(b, a - > r)));
    return a;
void pop(Node * \& a) \{ a - prop(); a = merge(a - > 1, a - > r); \}
pair<ll, vi> dmst(int n, int r, vector<Edge>& q) {
    RollbackUF uf(n);
    vector<Node*> heap(n);
    for (Edge e : g) heap[e.b] = merge(heap[e.b], new Node{e});
    11 \text{ res} = 0;
    vi seen(n, -1), path(n), par(n);
    seen[r] = r;
    vector<Edge> Q(n), in(n, \{-1,-1\}), comp;
    deque<tuple<int, int, vector<Edge>>> cycs;
    rep(s,0,n) {
        int u = s, qi = 0, w;
        while (seen[u] < 0) {
            if (!heap[u]) return {-1, {}};
            Edge e = heap[u] \rightarrow top();
            heap[u]->delta -= e.w, pop(heap[u]);
            Q[qi] = e, path[qi++] = u, seen[u] = s;
            res += e.w, u = uf.find(e.a);
            if (seen[u] == s) {
                Node * cyc = 0;
                int end = qi, time = uf.time();
                do cyc = merge(cyc, heap[w = path[--qi]]);
                while (uf.join(u, w));
                u = uf.find(u), heap[u] = cyc, seen[u] = -1;
                cycs.push front({u, time, {&Q[qi], &Q[end]}});
        }
        rep(i, 0, qi) in[uf.find(Q[i].b)] = Q[i];
    for (auto& [u,t,comp] : cycs) { // restore sol (optional)
        uf.rollback(t);
        Edge inEdge = in[u];
        for (auto& e : comp) in[uf.find(e.b)] = e;
        in[uf.find(inEdge.b)] = inEdge;
    rep(i,0,n) par[i] = in[i].a;
    return {res, par};
```

#### Link-Cut

**Description:** Represents a forest of unrooted trees. You can add and remove edges (as long as the result is still a forest), and check whether two nodes are in the same tree.

**Time:** All operations take amortized  $\mathcal{O}(\log N)$ .

```
struct Node { // Splay tree. Root's pp contains tree's parent.
    Node *p = 0, *pp = 0, *c[2];
    bool flip = 0;
    Node() { c[0] = c[1] = 0; fix(); }
    void fix() {
        if (c[0]) c[0]->p = this;
        if (c[1]) c[1]->p = this;
        // (+ update sum of subtree elements etc. if wanted)
    void pushFlip() {
        if (!flip) return;
        flip = 0; swap(c[0], c[1]);
        if (c[0]) c[0]->flip ^= 1;
        if (c[1]) c[1]->flip ^= 1;
    int up() { return p ? p->c[1] == this : -1; }
    void rot(int i, int b) {
        int h = i ^ b;
        Node *x = c[i], *y = b == 2 ? x : x -> c[h], *z = b ? y : x;
        if ((y->p = p)) p->c[up()] = y;
        c[i] = z -> c[i ^ 1];
        if (b < 2) {
            x->c[h] = y->c[h ^ 1];
            y - > c[h ^ 1] = x;
        z \rightarrow c[i ^1] = this;
        fix(); x\rightarrow fix(); y\rightarrow fix();
        if (p) p->fix();
        swap (pp, y->pp);
    void splay() {
        for (pushFlip(); p; ) {
            if (p->p) p->p->pushFlip();
            p->pushFlip(); pushFlip();
            int c1 = up(), c2 = p->up();
            if (c2 == -1) p->rot(c1, 2);
            else p->p->rot(c2, c1 != c2);
    Node* first() {
        pushFlip();
```

```
return c[0] ? c[0]->first() : (splay(), this);
};
struct LinkCut {
    vector<Node> node;
    LinkCut(int N) : node(N) {}
    void link(int u, int v) { // add an edge (u, v)
        assert(!connected(u, v));
        makeRoot(&node[u]);
        node[u].pp = &node[v];
    void cut (int u, int v) { // remove \ an \ edge \ (u, \ v)
        Node *x = &node[u], *top = &node[v];
        makeRoot(top); x->splay();
        assert(top == (x->pp ?: x->c[0]));
        if (x->pp) x->pp = 0;
        else {
            x->c[0] = top->p = 0;
            x \rightarrow fix();
        }
    }
    bool connected (int u, int v) { // are u, v in the same tree?
        Node* nu = access(&node[u])->first();
        return nu == access(&node[v])->first();
    void makeRoot(Node* u) {
        access(u);
        u->splay();
        if(u->c[0]) {
            u - c[0] - p = 0;
            u - c[0] - flip ^= 1;
            u - c[0] - pp = u;
            u - c[0] = 0;
            u \rightarrow fix();
        }
    Node* access(Node* u) {
        u->splay();
        while (Node* pp = u->pp) {
            pp->splay(); u->pp = 0;
            if (pp->c[1]) {
                pp->c[1]->p = 0; pp->c[1]->pp = pp; }
            pp - c[1] = u; pp - fix(); u = pp;
```

```
return u;
};
```

# Maximum Clique

**Description:** Quickly finds a maximum clique of a graph (given as symmetric bitset matrix; self-edges not allowed). Can be used to find a maximum independent set by finding a clique of the complement graph.

**Time:** Runs in about 1s for n=155 and worst case random graphs (p=.90). Runs faster for sparse graphs.

```
typedef vector<br/>bitset<200>> vb;
struct Maxclique {
    double limit=0.025, pk=0;
    struct Vertex { int i, d=0; };
   typedef vector<Vertex> vv;
   vb e;
   vv V;
   vector<vi> C;
   vi qmax, q, S, old;
   void init(vv& r) {
        for (auto \& v : r) v.d = 0;
        for (auto v : r) for (auto j : r) v.d += e[v.i][j.i];
        sort(all(r), [](auto a, auto b) { return a.d > b.d; });
        int mxD = r[0].d;
        rep(i, 0, sz(r)) r[i].d = min(i, mxD) + 1;
   void expand(vv& R, int lev = 1) {
        S[lev] += S[lev - 1] - old[lev];
        old[lev] = S[lev - 1];
        while (sz(R)) {
            if (sz(q) + R.back().d <= sz(qmax)) return;</pre>
            q.push_back(R.back().i);
            vv T;
            for(auto v:R) if (e[R.back().i][v.i]) T.push_back({v.i}
               );
            if (sz(T)) {
                if (S[lev]++ / ++pk < limit) init(T);
                int j = 0, mxk = 1, mnk = max(sz(qmax) - sz(q) + 1,
                     1);
                C[1].clear(), C[2].clear();
                for (auto v : T) {
                    int k = 1;
                    auto f = [&](int i) { return e[v.i][i]; };
                    while (any\_of(all(C[k]), f)) k++;
                    if (k > mxk) mxk = k, C[mxk + 1].clear();
```

```
if (k < mnk) T[j++].i = v.i;
                     C[k].push_back(v.i);
                }
                if (\dot{j} > 0) T[\dot{j} - 1].d = 0;
                rep(k, mnk, mxk + 1) for (int i : C[k])
                     T[j].i = i, T[j++].d = k;
                expand(T, lev + 1);
            } else if (sz(q) > sz(qmax)) qmax = q;
            q.pop_back(), R.pop_back();
        }
    }
    vi maxClique() { init(V), expand(V); return qmax; }
    Maxclique(vb conn) : e(conn), C(sz(e)+1), S(sz(C)), old(S) {
        rep(i, 0, sz(e)) V.push_back({i});
    }
};
```

#### Dominator Tree

**Description:** Finds dominators for all vertices in a graph for a given starting vertex.

Usage: Look at example(). Modify rmax if N > 1e6.

Time:  $\mathcal{O}(M \log N)$ 

```
class Dominator {
public:
    Dominator(vector<vector<int>> h, int s) {
        n = sz(h);
        newId.assign(n, -1);
        q = h;
        timer = 0;
        parent.resize(n);
        dfs(s);
        n = timer;
        vector<vector<int>> tmp(n);
        for (int i = 0; i < sz(newId); ++i) {</pre>
            if (newId[i] == -1) {
                 continue;
            }
            for (int to : g[i]) {
                tmp[newId[i]].push_back(newId[to]);
            }
        }
        q.swap(tmp);
        gr.resize(n);
        for (int i = 0; i < n; ++i) {
            for (int to : q[i]) {
                gr[to].push_back(i);
```

```
}
        sdom.resize(n);
        label.resize(n);
        dsu.resize(n);
        for (int i = 0; i < n; ++i) {</pre>
            label[i] = i;
            dsu[i] = i;
        for (int w = n - 1; w >= 0; --w) {
            sdom[w] = w;
            for (int v : gr[w]) {
                if (v < w) {
                    sdom[w] = min(sdom[w], v);
                } else {
                    pair<int, int> p = getDSU(v);
                    sdom[w] = min(sdom[w], sdom[p.second]);
            if (w) {
                dsu[w] = parent[w];
        calcIdom();
    void get(vector<int>& res1, vector<int>& res2) const {
        res1 = newId;
        res2 = idom;
private:
    vector<int> newId;
    vector<vector<int>> q, qr;
    vector<int> sdom;
    vector<int> idom;
    int timer;
    const int rmax = 20;
    vector<vector<int>> shifts;
    vector<int> parent;
    vector<int> label;
    vector<int> dsu;
    vector<int> depth;
    int n;
    void dfs(int v) {
        newId[v] = timer++;
```

```
for (int to : q[v]) {
        if (newId[to] == -1) {
            dfs(to);
            parent[newId[to]] = newId[v];
   }
}
pair<int, int> getDSU(int v) {
    if (dsu[v] == v) {
        return {-1, -1};
    pair<int, int> p = getDSU(dsu[v]);
    if (p.first == -1) {
        return {v, label[v]};
    int u = p.second;
    if (sdom[u] < sdom[label[v]]) {</pre>
        label[v] = u;
    dsu[v] = p.first;
    return {p.first, label[v]};
int lca(int u, int v) {
    if (depth[u] > depth[v]) {
        swap(u, v);
    for (int r = rmax - 1; r >= 0; --r) {
        if (depth[v] - (1 << r) >= depth[u]) {
            v = shifts[r][v];
        }
    assert(depth[u] == depth[v]);
    if (u == v) {
        return u;
    for (int r = rmax - 1; r >= 0; --r) {
        if (shifts[r][u] != shifts[r][v]) {
            u = shifts[r][u];
            v = shifts[r][v];
        }
    assert(u != v \&\& shifts[0][u] == shifts[0][v]);
    return shifts[0][u];
```

```
void calcIdom() {
        idom.resize(n);
        depth.resize(n);
        shifts = vector<vector<int>>(rmax, vector<int>(n));
        for (int i = 0; i < n; ++i) {
            if (i == 0) {
                idom[i] = i;
                depth[i] = 0;
            } else {
                idom[i] = lca(parent[i], sdom[i]);
                depth[i] = depth[idom[i]] + 1;
            shifts[0][i] = idom[i];
            for (int r = 0; r + 1 < rmax; ++r) {
                int j = shifts[r][i];
                shifts[r + 1][i] = shifts[r][j];
};
void example() {
    vector<vector<int>> q(n);
    // ...
    Dominator D(g, starting_vertex);
    vector<int> newId, idom;
    D.get(newId, idom);
    for (int i = 0; i < sz(edges); ++i) {
        int u = edges[i].first, v = edges[i].second;
        u = newId[u], v = newId[v];
        // ...
```

# Miscellaneous (7)

### Integrate

**Description:** Function integration over an interval using Simpson's rule. The error is proportional to  $h^4$ .

```
double integrate(double a, double b, auto&& f, int n = 1000) {
    double h = (b - a) / 2 / n, rs = f(a) + f(b);
    for (int i = 1; i < n * 2; ++i) {
        rs += f(a + i * h) * (i & 1 ? 4 : 2);
    }
}</pre>
```

```
return rs * h / 3;
Fractional binary search
Description: Finds the smallest fraction p/q \in [0,1] s.t. f(p/q) is true and p,q < N.
Time: \mathcal{O}(\log N)
struct frac { ll p, q; };
frac fracBS(auto&& f, ll N) {
    bool dir = true, A = true, B = true;
    frac lo\{0, 1\}, hi\{1, 1\}; // Set hi to 1/0 to search (0, N]
    if (f(lo)) return lo;
    assert(f(hi));
    while (A | | B) {
        11 \text{ adv} = 0, step = 1;
        for (int si = 0; step; (step *= 2) >>= si) {
             adv += step;
             frac mid{lo.p * adv + hi.p, lo.q * adv + hi.q};
             if (abs(mid.p) > N || mid.q > N || dir == !f(mid)) {
                 adv -= step; si = 2;
        hi.p += lo.p * adv;
        hi.q += lo.q * adv;
        dir = !dir;
         swap(lo, hi);
        A = B; B = !!adv;
    return dir ? hi : lo;
```